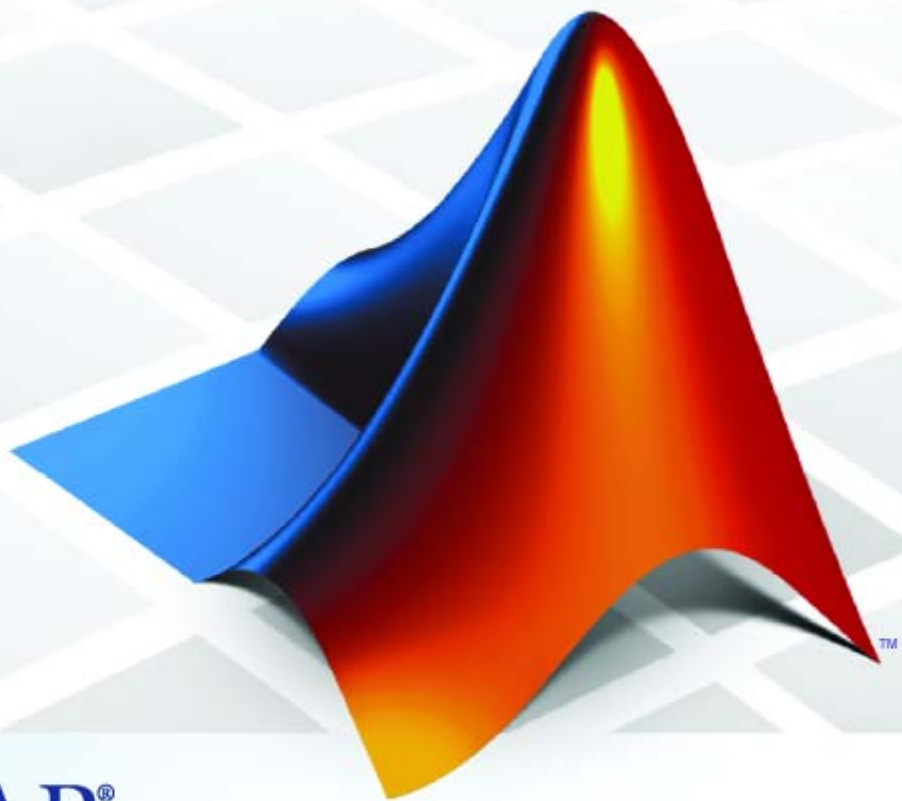


# Mapping Toolbox™ 3

## Reference



MATLAB®

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# Function Reference

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Geospatial Data Import and Access (p. 1-2)	Readers, writers and associated utilities for geospatial file and data product formats
Web Map Service (p. 1-6)	Finding layers in internal database; retrieving maps from WMS servers
Vector Map Data and Geographic Data Structures (p. 1-7)	Manipulating polygons, geographic data structures and other vector geodata
Georeferenced Images and Data Grids (p. 1-9)	Constructing, georeferencing, analyzing, and manipulating raster geodata
Map Projections and Coordinates (p. 1-12)	Specifying, using, and analyzing map projections and geospatial coordinate transformations
Map Display and Interaction (p. 1-15)	Displaying geographic objects on maps and interacting with them
Geographic Calculations (p. 1-23)	Plane, spherical and ellipsoidal geometry
Utilities (p. 1-28)	Basic tasks, including angle and distance conversions
GUIs (p. 1-31)	GUI tools for selecting data and directly manipulating the content and appearance of maps

## Geospatial Data Import and Access

Standard File Formats (p. 1-2)	Reading and writing vector and raster geodata in widely used exchange formats
Gridded Terrain and Bathymetry Products (p. 1-3)	For reading raster data products distributed in special file formats
Vector Map Products (p. 1-4)	For reading vector data products distributed in special file formats
Miscellaneous Data Sets (p. 1-5)	For reading other data products distributed in special file formats
GUIs for Data Import (p. 1-5)	GUIs for browsing data products and selecting areas and objects of interest
File Reading Utilities (p. 1-5)	Low-level access functions for text and other data files
Ellipsoids, Radii, Areas, and Volumes (p. 1-5)	Geometric parameters of Earth, planets, Sun, and Moon

### Standard File Formats

arcgridread	Read gridded data set in Arc ASCII Grid Format
geotiffinfo	Information about GeoTIFF file
geotiffread	Read georeferenced image from GeoTIFF file
getworldfilename	Derive worldfile name from image filename
kmlwrite	Write geographic data to KML file
makeattribspec	Attribute specification from geographic data structure
sdtsemread	Read data from SDTS raster/DEM data set

sdtsinfo	Information about SDTS data set
shapeinfo	Information about shapefile
shaperead	Read vector features and attributes from shapefile
shapewrite	Write geographic data structure to shapefile
worldfileread	Read worldfile and return referencing matrix
worldfilewrite	Construct worldfile from referencing matrix

## **Gridded Terrain and Bathymetry Products**

dted	Read U.S. Department of Defense Digital Terrain Elevation Data (DTED)
dteds	DTED filenames for latitude-longitude quadrangle
etopo	Read gridded global relief data (ETOPO products)
globedem	Read Global Land One-km Base Elevation (GLOBE) data
globedems	GLOBE data filenames for latitude-longitude quadrangle
gtopo30	Read 30-arc-second global digital elevation data (GTOPO30)
gtopo30s	GTOPO30 data filenames for latitude-longitude quadrangle
satbath	Read 2-minute terrain/bathymetry from Smith and Sandwell
tbase	Read 5-minute global terrain elevations from TerrainBase

usgs24kdem	Read USGS 7.5-minute (30-m or 10-m) Digital Elevation Models
usgsdem	Read USGS 1-degree (3-arc-second) Digital Elevation Model
usgsdems	USGS 1-degree (3-arc-sec) DEM filenames for latitude-longitude quadrangle

## **Vector Map Products**

dcwdata	Read selected DCW worldwide basemap data
dcwgaz	Search DCW worldwide basemap gazette file
dcwread	Read DCW worldwide basemap file
dcwrhead	Read DCW worldwide basemap file headers
fipsname	Read Federal Information Processing Standard (FIPS) name file used with TIGER thinned boundary files
gshhs	Read Global Self-Consistent Hierarchical High-Resolution Shoreline
tgrline	Read TIGER/Line data
vmap0data	Read selected data from Vector Map Level 0
vmap0read	Read Vector Map Level 0 file
vmap0rhead	Read Vector Map Level 0 file headers

## Miscellaneous Data Sets

avhrrgoode	Read AVHRR data product stored in Goode Projection
avhrrlambert	Read AVHRR data product stored in eqaazim projection
egm96geoid	Read 15-minute gridded geoid heights from EGM96
readfk5	Read Fifth Fundamental Catalog of Stars

## GUIs for Data Import

demdataui	UI for selecting digital elevation data
vmap0ui	UI for selecting data from Vector Map Level 0

## File Reading Utilities

grepfields	Identify matching fields in fixed record length files
readfields	Read fields or records from fixed-format files
readmtx	Read matrix stored in file
spcread	Read columns of data from ASCII text file

## Ellipsoids, Radii, Areas, and Volumes

almanac	Parameters for Earth, planets, Sun, and Moon
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## Web Map Service

WMS Server and Layer Information (p. 1-6)	For searching local database for relevant layers and servers
WMS Capabilities Information (p. 1-6)	For retrieving capabilities information from WMS server
WMS Map Rendering (p. 1-7)	For rendering WMS map

### WMS Server and Layer Information

disp (WMSLayer)	Display properties
refine (WMSLayer)	Refine search
refineLimits (WMSLayer)	Refine search based on geographic limits
servers (WMSLayer)	Return URLs of unique servers
serverTitles (WMSLayer)	Return titles of unique servers
updateLayers (WebMapServer)	Update layer properties
WebMapServer	Web map server object
WMSCapabilities	Web Map Service capabilities object
wmsfind	Search local database for Web map servers and layers
WMSLayer	Web Map Service layer object
wmsupdate	Synchronize WMSLayer object with server

### WMS Capabilities Information

disp (WMSCapabilities)	Display properties
getCapabilities (WebMapServer)	Get capabilities document from server
WebMapServer	Web map server object

WMSCapabilities	Web Map Service capabilities object
wmsinfo	Information about WMS server from capabilities document

## WMS Map Rendering

boundImageSize (WMSMapRequest)	Bound size of raster map
getMap (WebMapServer)	Get raster map from server
WebMapServer	Web map server object
WMSMapRequest	Web Map Service map request object
wmsread	Retrieve WMS map from server

## Vector Map Data and Geographic Data Structures

Geographic Data Structures (p. 1-7)	For updating and obtaining fields from data structures
Data Manipulation (p. 1-8)	For altering, combining, and analyzing polygon and line data
Utilities for NaN-Separated Polygons and Lines (p. 1-8)	For structuring vectors defining multiple line or polygon objects

## Geographic Data Structures

extractfield	Field values from structure array
extractm	Coordinate data from line or patch display structure
updategeostruct	Convert line or patch display structure to geostruct

## Data Manipulation

bufferm	Buffer zones for latitude-longitude polygons
flatearthpoly	Insert points along date line to pole
interp	Densify latitude-longitude sampling in lines or polygons
intrplat	Interpolate latitude at given longitude
intrplon	Interpolate longitude at given latitude
ispolycw	True if polygon vertices are in clockwise order
nanclip	Clip vector data with NaNs at specified pen-down locations
poly2ccw	Convert polygon contour to counterclockwise vertex ordering
poly2cw	Convert polygon contour to clockwise vertex ordering
poly2fv	Convert polygonal region to patch faces and vertices
polycut	Polygon branch cuts for holes
polymerge	Merge line segments with matching endpoints
reducem	Reduce density of points in vector data

## Utilities for NaN-Separated Polygons and Lines

closePolygonParts	Close all rings in multipart polygon
isShapeMultipart	True, if polygon or line has multiple parts



polyjoin	Convert line or polygon parts from cell arrays to vector form
polysplit	Convert line or polygon parts from vector form to cell arrays
removeExtraNaNSeparators	Clean up NaN separators in polygons and lines

## Georeferenced Images and Data Grids

Spatial Referencing (p. 1-9)	Computing bounds and converting between geographic and raster coordinates for spatially referenced images and grids
Terrain Analysis (p. 1-10)	Computing slope, aspect, lines of sight, and terrain visibility
Other Analysis/Access (p. 1-11)	Computing areas and profiles, and selecting subsets of values from data grids
Construction and Modification (p. 1-11)	Constructing, encoding, seeding, reorienting, and converting data grids
Initialization (p. 1-12)	Generating data grids containing uniform values

### Spatial Referencing

latlon2pix	Convert latitude-longitude coordinates to pixel coordinates
limitm	Determine latitude and longitude limits of regular data grid
makerepmat	Construct affine spatial-referencing matrix

map2pix	Convert map coordinates to pixel coordinates
mapbbox	Compute bounding box of georeferenced image or data grid
mapoutline	Compute outline of georeferenced image or data grid
meshgrat	Construct map graticule for surface object display
pix2map	Convert pixel coordinates to map coordinates
pixcenters	Compute pixel centers for georeferenced image or data grid
refmat2vec	Convert referencing matrix to referencing vector
refvec2mat	Convert referencing vector to referencing matrix
setltn	Convert data grid rows and columns to latitude-longitude
setpostn	Convert latitude-longitude to data grid rows and columns

## **Terrain Analysis**

gradientm	Calculate gradient, slope and aspect of data grid
los2	Line-of-sight visibility between two points in terrain
viewshed	Areas visible from point on terrain elevation grid

## Other Analysis/Access

areamat	Surface area covered by nonzero values in binary data grid
filterm	Filter latitudes and longitudes based on underlying data grid
findm	Latitudes and longitudes of nonzero data grid elements
ltln2val	Extract data grid values for specified locations
mapprofile	Interpolate heights between waypoints on regular data grid

## Construction and Modification

changem	Substitute values in data array
encodem	Fill in regular data grid from seed values and locations
geoloc2grid	Convert geolocated data array to regular data grid
imbedm	Encode data points into regular data grid
neworig	Orient regular data grid to oblique aspect
resizem	Resize regular data grid
sizem	Row and column dimensions needed for regular data grid
vec2mtx	Convert latitude-longitude vectors to regular data grid

## Initialization

nanm	Construct regular data grid of NaNs
onem	Construct regular data grid of 1s
spzerom	Construct sparse regular data grid of 0s
zerom	Construct regular data grid of 0s

## Map Projections and Coordinates

Available Map Projections (p. 1-13)	Lists of map projections and characteristics
Map Projection Transformations (p. 1-13)	Forward and inverse map projection functions
Map Trimming (p. 1-13)	For trimming lines, polygons, and data grids to latitude-longitude quadrangles
Angles, Scales, and Distortions (p. 1-14)	Computing directions, angles, and distortions on projected maps
Visualizing Map Distortions (p. 1-14)	Generating displays of distortion statistics and Tissot ellipses
UTM System (p. 1-14)	Selecting zones and ellipsoids for the Universal Transverse Mercator system
Coordinate Rotation on the Sphere (p. 1-14)	Reorienting map data by solid-body rotations on the sphere
Trimming and Clipping (p. 1-15)	Removing and replacing data that extends outside a map frame

For specific map projections, see “Map Projections Reference”.

## Available Map Projections

maplist	Available Mapping Toolbox™ map projections
maps	List available map projections and verify names
projlist	Map projections supported by projfwd and projinv

## Map Projection Transformations

mfwdtran	Project geographic features to map coordinates
minvtran	Unproject features from map to geographic coordinates
projfwd	Forward map projection using PROJ.4 map projection library
projinv	Inverse map projection using PROJ.4 map projection library

## Map Trimming

maptriml	Trim lines to latitude-longitude quadrangle
maptrimp	Trim polygons to latitude-longitude quadrangle
maptrims	Trim regular data grid to latitude-longitude quadrangle

## Angles, Scales, and Distortions

<code>distortcalc</code>	Distortion parameters for map projections
<code>vfdtran</code>	Direction angle in map plane from azimuth on ellipsoid
<code>vinvtran</code>	Azimuth on ellipsoid from direction angle in map plane

## Visualizing Map Distortions

<code>mdistort</code>	Display contours of constant map distortion
<code>tissot</code>	Project Tissot indicatrices on map axes

## UTM System

<code>utmgeoid</code>	Select ellipsoids for given UTM zone
<code>utmzone</code>	Select UTM zone given latitude and longitude

## Coordinate Rotation on the Sphere

<code>newpole</code>	Origin vector to place specific point at pole
<code>org2pol</code>	Location of north pole in rotated map
<code>putpole</code>	Origin vector to place north pole at specified point

## Trimming and Clipping

<code>clipdata</code>	Clip data at $\pm \pi$ in longitude, $\pm \pi$ in latitude
<code>trimcart</code>	Trim graphic objects to map frame
<code>trimdata</code>	Trim map data exceeding projection limits
<code>undoclip</code>	Remove object clips introduced by <code>clipdata</code>
<code>undotrim</code>	Remove object trims introduced by <code>trimdata</code>

## Map Display and Interaction

Map Creation and High-Level Display (p. 1-16)	Top-level functions that create map axes, project map data onto them, and control symbolization
Vector Symbolization (p. 1-17)	Functions that draw symbols for points, lines, and polygons (coordinate lists and geostrucTs)
Lines and Contours (p. 1-17)	Lower level line plotting and higher level contour plotting functions
Patch Data (p. 1-17)	Lower-level functions for plotting polygons as patches on map axes
Data Grids (p. 1-18)	For mapping regular and geolocated data grids in 2-D and 3-D
Light Objects and Lighted Surfaces (p. 1-18)	For mapping regular and geolocated data grids using lighting and shading
Thematic Maps (p. 1-18)	For making scatter, quiver, comet, and stem maps

Map Annotation (p. 1-19)	For adding north arrows, graphic scales, text and other annotations to maps
Colormaps for Map Displays (p. 1-20)	For constructing colormaps appropriate for map displays
Interactive Map Positions (p. 1-20)	For graphic interaction with data in map axes
Interactive Track and Circle Definition (p. 1-20)	For constructing great and small circles, rhumb lines and other geographic tracks
GUIs (p. 1-20)	GUIs for specific functions and general GUIs for interactive mapping
Map Object and Projection Properties (p. 1-21)	For querying, setting, and modifying map axes objects and properties
Map Appearance (p. 1-22)	For controlling the view and map scale
Display Clearing (p. 1-23)	For showing, hiding, and removing objects from map axes

## **Map Creation and High-Level Display**

axesm	Define map axes and set map properties
displaym	Display geographic data from display structure
geoshow	Display map latitude and longitude data
grid2image	Display regular data grid as image
mapview	Interactive map viewer



usamap	Construct map axes for United States of America
worldmap	Construct map axes for given region of world

## Vector Symbolization

makesymbolspec	Construct vector layer symbolization specification
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## Lines and Contours

contour3m	Project 3-D contour plot of map data
contourfm	Project filled 2-D contour plot of map data
contourm	Project 2-D contour plot of map data
linem	Project line object on map axes
plot3m	Project 3-D lines and points on map axes
plotm	Project 2-D lines and points on map axes

## Patch Data

fill3m	Project filled 3-D patch objects on map axes
fillm	Project filled 2-D patch objects on map axes
patchesm	Project patches on map axes as individual objects
patchm	Project patch objects on map axes

## Data Grids

meshm	Project regular data grid on map axes
pcolorm	Project regular data grid on map axes in $z = 0$ plane
surfacem	Project and add geolocated data grid to current map axes
surfm	Project geolocated data grid on map axes

## Light Objects and Lighted Surfaces

lightm	Project light objects on map axes
meshlsrm	3-D lighted shaded relief of regular data grid
shaderel	Construct <code>cdata</code> and <code>colormap</code> for shaded relief
surflm	3-D shaded surface with lighting on map axes
surflsrm	3-D lighted shaded relief of geolocated data grid

## Thematic Maps

comet3m	Project 3-D comet plot on map axes
cometm	Project 2-D comet plot on map axes
quiverm	Project 2-D quiver plot on map axes
scatterm	Project point markers with variable color and area

stem3m	Project stem plot map on map axes
symbolm	Project point markers with variable size

## Map Annotation

clabelm	Add contour labels to map contour display
framem	Toggle and control display of map frame
gridm	Toggle and control display of graticule lines
lcolorbar	Colorbar with text labels
mlabel	Toggle and control display of meridian labels
mlabelzero22pi	Convert meridian labels to 0-360 degree range
northarrow	Add graphic element pointing to geographic north pole
plabel	Toggle and control display of parallel labels
rotatetext	Rotate text to projected graticule
scaleruler	Add or modify graphic scale on map axes
textm	Project text annotation on map axes

## Colormaps for Map Displays

contourcmap	Contour colormap and colorbar current axes
demcmap	Colormaps appropriate to terrain elevation data
polcmap	Colormaps appropriate to political regions

## Interactive Map Positions

gcpmap	Current mouse point from map axes
gtextm	Place text on map using mouse
inputm	Latitudes and longitudes of mouse-click locations

## Interactive Track and Circle Definition

scircleg	Small circle defined via mouse input
sectorg	Sector of small circle defined via mouse input
trackg	Great circle or rhumb line defined via mouse input

## GUIs

clrmenu	Add colormap menu to figure window
colorm	Create index map colormaps
colorui	Interactively define RGB color
getseeds	Interactively assign seeds for data grid encoding

lightmui	Control position of lights on globe or 3-D map
maptool	Add menu activated tools to map figure
maptrim	Interactively trim and convert map data from vector to raster format
mayers	GUI to control plotting of display structure elements
mobjects	Manipulate object sets displayed on map axes
originui	Interactively modify map origin
panzoom	Pan and zoom on map axes
parallelui	Interactively modify map parallels
qrydata	GUI to interactively perform data queries
rootlayr	Construct cell array of workspace variables for mayers tool
seedm	GUI to fill data grids with seeded values
surfdist	Interactive distance, azimuth, and reckoning calculations
uimaptbx	Handle buttondown callbacks for mapped objects
utmzoneui	Choose or identify UTM zone by clicking map

## Map Object and Projection Properties

cart2grn	Transform projected coordinates to Greenwich system
defaultm	Initialize or reset map projection structure

<code>gcm</code>	Current map projection structure
<code>geotiff2mstruct</code>	Convert GeoTIFF information to map projection structure
<code>getm</code>	Map object properties
<code>handlem</code>	Handles of displayed map objects
<code>ismap</code>	True for axes with map projection
<code>ismapped</code>	True, if object is projected on map axes
<code>makemapped</code>	Convert ordinary graphics object to mapped object
<code>namem</code>	Determine names of valid graphics objects
<code>project</code>	Project displayed map graphics object
<code>restack</code>	Restack objects within map axes
<code>rotatem</code>	Transform vector map data to new origin and orientation
<code>setm</code>	Set properties of map axes and graphics objects
<code>tagm</code>	Set property of map graphics object
<code>zdatam</code>	Adjust <i>z</i> -plane of displayed map objects

## **Map Appearance**

<code>axesscale</code>	Resize axes for equivalent scale
<code>camposm</code>	Set camera position using geographic coordinates
<code>camtargm</code>	Set camera target using geographic coordinates

camupm	Set camera up vector using geographic coordinates
daspectm	Control vertical exaggeration in map display
paperscale	Set figure properties for printing at specified map scale
previewmap	View map at printed size
tightmap	Remove white space around map

## Display Clearing

clma	Clear current map axes
clmo	Clear specified graphics objects from map axes
hidem	Hide specified graphic objects on map axes
showaxes	Toggle display of map coordinate axes
showm	Specify graphic objects to display on map axes

## Geographic Calculations

Geometry of Sphere and Ellipsoid (p. 1-24)	Distances, deviations, areas, and curves on the sphere or ellipsoid
3-D Coordinates (p. 1-25)	For converting between different 3-D coordinate systems
Ellipsoids and Latitudes (p. 1-25)	For converting ellipsoid parameters and auxiliary latitudes

Geometric Object Overlay (p. 1-26)	For determining if, how, and where points, lines, circles, and areas intersect
Geographic Statistics (p. 1-27)	For computing geographic means, standard deviations, and histograms
Navigation (p. 1-27)	For determining positions, headings, drift, and navigational fixes and way points

## **Geometry of Sphere and Ellipsoid**

antipode	Point on opposite side of globe
areaint	Surface area of polygon on sphere or ellipsoid
areaquad	Surface area of latitude-longitude quadrangle
azimuth	Azimuth between points on sphere or ellipsoid
departure	Departure of longitudes at specified latitudes
distance	Distance between points on sphere or ellipsoid
ellipse1	Geographic ellipse from center, semimajor axes, eccentricity, and azimuth
gc2sc	Center and radius of great circle
meridianarc	Ellipsoidal distance along meridian
meridianfwd	Reckon position along meridian
reckon	Point at specified azimuth, range on sphere or ellipsoid
scircle1	Small circles from center, range, and azimuth



scircle2	Small circles from center and perimeter
track1	Geographic tracks from starting point, azimuth, and range
track2	Geographic tracks from starting and ending points

### 3-D Coordinates

ecef2geodetic	Convert geocentric (ECEF) to geodetic coordinates
ecef2lv	Convert geocentric (ECEF) to local vertical coordinates
elevation	Local vertical elevation angle, range, and azimuth
geodetic2ecef	Convert geodetic to geocentric (ECEF) coordinates
lv2ecef	Convert local vertical to geocentric (ECEF) coordinates

### Ellipsoids and Latitudes

axes2ecc	Eccentricity of ellipse with given axis lengths
convertlat	Convert between geodetic and auxiliary latitudes
ecc2flat	Flattening of ellipse with given eccentricity
ecc2n	n-value of ellipse with given eccentricity
flat2ecc	Eccentricity of ellipse with given flattening

geocentric2geodeticLat	Convert geocentric to geodetic latitude
geodetic2geocentricLat	Convert geodetic to geocentric latitude
majaxis	Semimajor axis of ellipse given semiminor axis and eccentricity
minaxis	Semiminor axis of ellipse given semimajor axis and eccentricity
n2ecc	Eccentricity of ellipse with given n-value
rcurve	Radii of curvature of ellipsoid
rsphere	Radii of auxiliary spheres

## **Geometric Object Overlay**

circcirc	Intersections of circles in Cartesian plane
gcxgc	Intersection points for pairs of great circles
gcxsc	Intersection points for great and small circle pairs
ingeoquad	True for points inside or on lat-lon quadrangle
intersectgeoquad	Intersection of two latitude-longitude quadrangles
linecirc	Intersections of circles and lines in Cartesian plane
outlinegeoquad	Polygon outlining geographic quadrangle
polybool	Set operations on polygonal regions
polyxpoly	Intersection points for lines or polygon edges

rhxrh	Intersection points for pairs of rhumb lines
scxsc	Intersection points for pairs of small circles

## Geographic Statistics

combntns	All possible combinations of set of values
eqa2grn	Convert from equal area to Greenwich coordinates
grn2eqa	Convert from Greenwich to equal area coordinates
hista	Histogram for geographic points with equal-area bins
meanm	Mean location of geographic coordinates
stdist	Standard distance for geographic points
stdm	Standard deviation for geographic points

## Navigation

crossfix	Cross-fix positions from bearings and ranges
dreckon	Dead reckoning positions for track
driftcorr	Heading to correct for wind or current drift
driftvel	Wind or current from heading, course, and speeds

gcwaypts	Equally spaced waypoints along great circle
legs	Courses and distances between navigational waypoints
navfix	Mercator-based navigational fix
timezone	Time zone based on longitude
track	Track segments to connect navigational waypoints

## Utilities

Angle Conversions (p. 1-29)	For converting angles between different units and encodings
Conversion Factors for Angles and Distances (p. 1-29)	Function to compute factor for converting between units of distance and angles
Data Precision (p. 1-29)	For managing data precision
Distance Conversions (p. 1-30)	For converting distances between different units and encodings
Image Conversion (p. 1-30)	Function for changing indexed images to uint8 true-color images
String Formatters (p. 1-30)	For formatting angles and distances as text suitable for annotations
Longitude or Azimuth Wrapping (p. 1-30)	For forcing angles to lie within specified intervals

## Angle Conversions

degrees2dm	Convert degrees to degrees-minutes
degrees2dms	Convert degrees to degrees-minutes-seconds
degtorad	Convert angles from degrees to radians
dm2degrees	Convert degrees-minutes to degrees
dms2degrees	Convert degrees-minutes-seconds to degrees
fromDegrees	Convert angles from degrees
fromRadians	Convert angles from radians
radtodeg	Convert angles from radians to degrees
str2angle	Convert strings to angles in degrees
toDegrees	Convert angles to degrees
toRadians	Convert angles to radians

## Conversion Factors for Angles and Distances

unitsratio	Unit conversion factors
------------	-------------------------

## Data Precision

epsm	Accuracy in angle units for certain map computations
roundn	Round to multiple of 10

## Distance Conversions

<code>deg2km, deg2nm, deg2sm</code>	Convert distance from degrees to kilometers, nautical miles, or statute miles
<code>km2deg, nm2deg, sm2deg</code>	Convert from distance units to degrees
<code>km2nm, km2sm, nm2km, nm2sm, sm2km, sm2nm</code>	Convert distance between kilometers and miles
<code>km2rad, nm2rad, sm2rad</code>	Convert from distance units to radians
<code>rad2km, rad2nm, rad2sm</code>	Convert distance from radians to kilometers, nautical miles, or statute miles

## Image Conversion

<code>ind2rgb8</code>	Convert indexed image to uint8 RGB image
-----------------------	--

## String Formatters

<code>angl2str</code>	Format angle strings
<code>dist2str</code>	Format distance strings

## Longitude or Azimuth Wrapping

<code>unwrapMultipart</code>	Unwrap vector of angles with NaN-delimited parts
<code>wrapTo180</code>	Wrap angle in degrees to [-180 180]
<code>wrapTo2Pi</code>	Wrap angle in radians to [0 2*pi]

wrapTo360	Wrap angle in degrees to [0 360]
wrapToPi	Wrap angle in radians to [-pi pi]

## GUIs

Map Definition Tools (p. 1-31)	Selecting vector and raster data, defining map axes, and projection parameters
Mapping Tools (p. 1-32)	Displaying maps, manipulating layers, and querying map objects
Display Manipulation Tools (p. 1-32)	Controlling zoom levels, colormaps, and lighting
Object Property Tools (p. 1-33)	Showing, hiding, tagging, and clearing objects, and customizing colormaps
Track Tools (p. 1-33)	Plotting small and great circles, rhumb lines, and other navigational tracks
Map Data Construction Tools (p. 1-34)	Setting limits, trimming maps, and seeding grid values

### Map Definition Tools

axesm, axesmui	Define map axes and modify map projection and display properties
demdataui	UI for selecting digital elevation data
originui	Interactively modify map origin
parallelui	Interactively modify map parallels

utmzoneui	Choose or identify UTM zone by clicking map
vmap0ui	UI for selecting data from Vector Map Level 0

## Mapping Tools

maptool	Add menu activated tools to map figure
maptrim	Interactively trim and convert map data from vector to raster format
mapview	Interactive map viewer
mlayers	GUI to control plotting of display structure elements
mobjects	Manipulate object sets displayed on map axes
qrydata	GUI to interactively perform data queries

## Display Manipulation Tools

clrmenu	Add colormap menu to figure window
hidem-ui	Hide specified mapped objects
lightmui	Control position of lights on globe or 3-D map
panzoom	Pan and zoom on map axes



## Object Property Tools

clmo	Clear specified graphics objects from map axes
colorui	Interactively define RGB color
handlem	Handles of displayed map objects
handlem-ui	GUI for handles of specified mapped objects
hidem	Hide specified graphic objects on map axes
property editors	GUIs to edit properties of mapped objects
showm	Specify graphic objects to display on map axes
tagm	Set property of map graphics object
zdatam	Adjust z-plane of displayed map objects

## Track Tools

scircleg	Small circle defined via mouse input
scirclui	GUI to display small circles on map axes
sectorg	Sector of small circle defined via mouse input
surfdist	Interactive distance, azimuth, and reckoning calculations
trackg	Great circle or rhumb line defined via mouse input
trackui	GUI to display great circles and rhumb lines on map axes

## **Map Data Construction Tools**

colorm

Create index map colormaps

seedm

GUI to fill data grids with seeded values

# Class Reference

---

## Web Map Service

### In this section...

“WebMapServer” on page 2-2

“WMSCapabilities” on page 2-2

“WMSLayer” on page 2-2

“WMSMapRequest” on page 2-3

### WebMapServer

getCapabilities	Get capabilities document from server
getMap	Get raster map from server
updateLayers	Update layer properties
WebMapServer	Web map server object

### WMSCapabilities

disp	Display properties
WMSCapabilities	Web Map Service capabilities object

### WMSLayer

disp	Display properties
refine	Refine search
refineLimits	Refine search based on geographic limits
servers	Return URLs of unique servers
serverTitles	Return titles of unique servers
WMSLayer	Web Map Service layer object

## **WMSMapRequest**

boundImageSize

Bound size of raster map

WMSMapRequest

Web Map Service map request object



# Functions — Alphabetical List

---

# almanac

---

**Purpose** Parameters for Earth, planets, Sun, and Moon

**Syntax**

```
almanac
almanac(body)
data = almanac(body,parameter)
data = almanac(body,parameter,units)
data = almanac(parameter,units,referencebody)
```

**Description** `almanac` displays the names of the celestial objects available in the `almanac`.

`almanac(body)` lists the options, or parameters, available for each celestial body. Valid *body* strings are

```
'earth'      'pluto'
'jupiter'    'saturn'
'mars'       'sun'
'mercury'    'uranus'
'moon'       'venus'
'neptune'
```

`data = almanac(body,parameter)` returns the value of the requested parameter for the celestial body specified by *body*.

Valid *parameter* strings are 'radius' for the planetary radius, 'ellipsoid' or 'geoid' for the two-element ellipsoid vector, 'surfarea' for the surface area, and 'volume' for the planetary volume.

For the Earth, *parameter* can also be any valid predefined ellipsoid string. In this case, the two-element ellipsoid vector for that ellipsoid model is returned. Valid ellipsoid definition strings for the Earth are

```
'everest'      1830 Everest ellipsoid
'bessel'       1841 Bessel ellipsoid
'airy'         1849 Airy ellipsoid
'clarke66'     1866 Clarke ellipsoid
```



'clarke80'	1880 Clarke ellipsoid
'international'	1924 International ellipsoid
'krasovsky'	1940 Krasovsky ellipsoid
'wgs60'	1960 World Geodetic System ellipsoid
'iau65'	1965 International Astronomical Union ellipsoid
'wgs66'	1966 World Geodetic System ellipsoid
'iau68'	1968 International Astronomical Union ellipsoid
'wgs72'	1972 World Geodetic System ellipsoid
'grs80'	1980 Geodetic Reference System ellipsoid
'wgs84'	1984 World Geodetic System ellipsoid

For the Earth, the *parameter* strings 'ellipsoid' and 'geoid' are equivalent to 'grs80'.

`data = almanac(body,parameter,units)` specifies the units to be used for the output measurement, where *units* is any valid distance units string. Note that these are linear units, but the result for surface area is in square units, and for volume is in cubic units. The default units are 'kilometers'.

`data = almanac(parameter,units,referencebody)` specifies the source of the information. This sets the assumptions about the shape of the celestial body used in the calculation of volumes and surface areas. A *referencebody* string of 'actual' returns a tabulated value rather than one dependent upon a ellipsoid model assumption. Other possible *referencebody* strings are 'sphere' for a spherical assumption and 'ellipsoid' for the default ellipsoid model. The default reference body is 'sphere'.

For the Earth, any of the preceding predefined ellipsoid definition strings can also be entered as a reference body.

For Mercury, Pluto, Venus, the Sun, and the Moon, the eccentricity of the ellipsoid model is zero, that is, the 'ellipsoid' reference body is actually a sphere.

## Examples

The radius of the Earth (treated as a sphere) in kilometers is

```
almanac('earth','radius')
```

```
ans =  
6371
```

The default ellipsoid model for the Earth ([semimajor axis eccentricity]) is

```
almanac('earth','ellipsoid')
```

```
ans =  
1.0e+03 *  
6.3781    0.0001
```

Note that the radius returned for any ellipsoid model reference body is the semimajor axis:

```
almanac('earth','radius','kilometers','ellipsoid')
```

```
Warning: Semimajor axis returned for radius parameter  
ans =  
6.3781e+03
```

Compare the tabulated values of the Earth's surface area with a spherical assumption and with the 1966 World Geodetic System ellipsoid model:

```
format long e  
almanac('earth','surfarea','statutemiles','actual')
```

```
ans =  
1.969499232704451e+008
```

```
almanac('earth','surfarea','statutemiles','sphere')
```

```
ans =  
1.969362058529953e+008
```

```
almanac('earth', 'surfarea', 'statutemiles', 'wgs66')
```

```
ans =  
1.969371331484438e+008
```

Note that these values are so close that long notation is required to differentiate them.

Some lunar measurements are

```
format  
almanac('moon', 'radius')
```

```
ans =  
1738
```

```
almanac('moon', 'surfarea')
```

```
ans =  
3.7959e+07
```

```
almanac('moon', 'volume')
```

```
ans =  
2.1991e+10
```

## Remarks

Take care when using angular arc length units for distance measurements. All planets have a radius of 1 radian, for example, and an area unit of *square degrees* indicates unit squares, 1 degree of arc length on a side, not 1-degree-by-1-degree quadrangles.

## See Also

distance

# angl2str

---

**Purpose** Format angle strings

**Syntax**

```
str = angl2str(angle)
str = angl2str(angle,signcode)
str = angl2str(angle,signcode,units)
str = angl2str(angle,signcode,units,n)
```

**Description** `str = angl2str(angle)` converts a numerical vector of angles in degrees to a string matrix.

`str = angl2str(angle,signcode)` uses the string *signcode* to specify the method for indicating that a given angle is positive or negative. *signcode* may be one of the following:

- 'ew' east/west notation; trailing 'e' (positive longitudes) or 'w' (negative longitudes)
- 'ns' north/south notation; trailing 'n' (positive latitudes) or 's' (negative latitudes)
- 'pm' plus/minus notation; leading '+' (positive angles) or '-' (negative angles)
- 'none' blank/minus notation; leading '-' for negative angles or sign omitted for positive angles (the default value)

`str = angl2str(angle,signcode,units)` uses the string *units* to indicate both the units in which angle is provided *and* to control the output format. *units* can be 'degrees' (the default value), 'radians', 'degrees2dm', or 'degrees2dms'. *units* may be abbreviated and is case-insensitive. The interpretations of *units* are as follows:

Units	Units of Angle	Output Format
'degrees'	degrees	decimal degrees
'degrees2dm'	degrees	degrees + decimal minutes

Units	Units of Angle	Output Format
'degrees2dms'	degrees	degrees + minutes + decimal seconds
'radians'	radians	decimal radians

`str = angl2str(angle, signcode, units, n)` uses the integer `n` to control the number of significant digits provided in the output. `n` is the power of 10 representing the last place of significance in the number of degrees, minutes, seconds, or radians -- for `units` of 'degrees', 'degrees2dm', 'degrees2dms', and 'radians', respectively. For example, if `n = -2` (the default), `angl2str` rounds to the nearest hundredth. If `n = -0`, `angl2str` rounds to the nearest integer. And if `n = 1`, `angl2str` rounds to the tens place, although positive values of `n` are of little practical use. In all cases, the interpretation of the parameter `n` is consistent between `angl2str` and `roundn`.

## Remarks

The purpose of this function is to make angular-valued variables into strings suitable for map display. In general, the interpretation of the parameter `n` by `angl2str` is consistent with that of `roundn`.

## Examples

Create a string matrix to represent a series of values in DMS units, using the north-south format:

```
a = -3:1.5:3;
str = angl2str(a, 'ns', 'degrees2dms', -3)
```

```
str =
 3^{\circ} 00' 00.000" S
 1^{\circ} 30' 00.000" S
 0^{\circ} 00' 00.000"
 1^{\circ} 30' 00.000" N
 3^{\circ} 00' 00.000" N
```

These LaTeX strings are displayed (using either `text` or `textm`) as

# angl2str

---

```
3" 00' 00.000" S
1" 30' 00.000" S
0" 00' 00.000"
1" 30' 00.000" N
3" 00' 00.000" N
```

**See Also**      `str2angle, dist2str`

**Purpose** Convert angles units

---

**Note** The `angledim` function has been replaced by four, more specific, functions: `fromRadians`, `fromDegrees`, `toRadians`, and `toDegrees`. However, `angledim` will be maintained for backward compatibility. The functions `degtorad`, `radtodeg`, and `unitsratio` provide additional alternatives.

---

**Syntax** `angleOut = angledim(angleIn, from, to)`

**Description** `angleOut = angledim(angleIn, from, to)` returns the value of the input angle `angleIn`, which is in units specified by the valid angle units string `from`, in the desired units given by the valid angle units string `to`. Angle units strings are 'degrees' for “decimal” degrees or 'radians' for radians

**Example** Convert from degrees to radians:

```
angledim(23.45134, 'degrees', 'radians')  
  
ans =  
    0.4093
```

**See Also** `degrees2dms`, `degtorad`, `fromDegrees`, `fromRadians`, `toDegrees`, `toRadians`, `radtodeg`, `unitsratio`

# antipode

---

**Purpose** Point on opposite side of globe

**Syntax**  
`[newlat,newlon] = antipode(lat,lon)`  
`[newlat,newlon] = antipode(lat,lon,angleunits)`

**Description** `[newlat,newlon] = antipode(lat,lon)` returns the geographic coordinates of the points exactly opposite on the globe from the input points given by `lat` and `lon`. All angles are in degrees.

`[newlat,newlon] = antipode(lat,lon,angleunits)` specifies the input and output units with the string `angleunits`. The string `angleunits` can be either 'degrees' or 'radians'. It can be abbreviated and is case-insensitive.

## Examples

### Example 1

Given a point (43°N, 15°E), find its antipode:

```
[newlat,newlong] = antipode(43,15)
newlat =
    -43
newlong =
   -165
```

or (43°S, 165°W).

### Example 2

Perhaps the most obvious antipodal points are the North and South Poles. The function `antipode` demonstrates this:

```
[newlat,newlong] = antipode(90,0,'degrees')
newlat =
   -90
newlong =
    180
```

Note that in this case longitudes are irrelevant because all meridians converge at the poles.



### Example 3

Find the antipode of the location of the Mathworks corporate headquarters in Natick, Massachusetts. Map the headquarters location and its antipode in an orthographic projection. Begin by specifying latitude and longitude as degree-minutes-seconds and then convert to decimal degrees.

```
mwlats = dms2degrees([ 42 18 2.5])
mwlons = dms2degrees([-71 21 7.9])

mwlats =
    42.3007
mwlons =
   -71.3522

[amwlats amwlons] = antipode(mwlats,mwlons)

amwlats =
   -42.3007
amwlons =
   108.6478
```

Prove that these points are antipodes:

```
dist = distance(mwlats,mwlons,amwlats,amwlons)

dist =
    180.0000
```

The distance function shows them to be 180 degrees apart.

Generate a map centered on the original point:

```
subplot(1,2,1)
axesm('MapProjection','ortho','origin',[mwlats mwlons],...
      'frame','on','grid','on')
load coast
geoshow(lat,long,'displaytype','polygon')
```

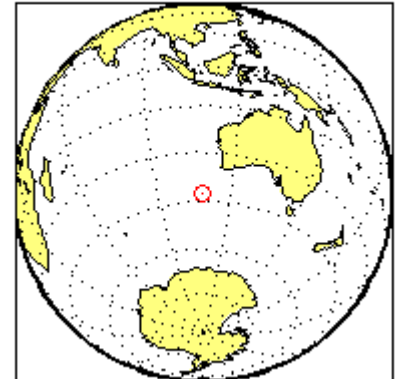
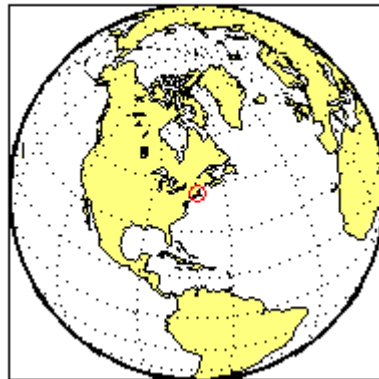
# antipode

```
geoshow(mwlat,mwlon,'Marker','o','Color','red')
s = ['Looking down at (' angl2str(mwlat,'ns') ...
    ', ' angl2str(mwlon,'ew') ')'];
title(s)
```

Add a second map centered on the computed antipodal point:

```
subplot(1,2,2)
axesm ('MapProjection','ortho','origin',[amwlat amwlon],...
    'frame','on','grid','on')
geoshow(lat,long,'displaytype','polygon')
geoshow(amwlat,amwlon,'Marker','o','Color','red')
t = ['Looking down at (' angl2str(amwlat,'ns') ...
    ', ' angl2str(amwlon,'ew') ')'];
title(t)
```

Looking down at ( 42.30° N , 71.35° W )      Looking down at ( 42.30° S , 108.65° E )



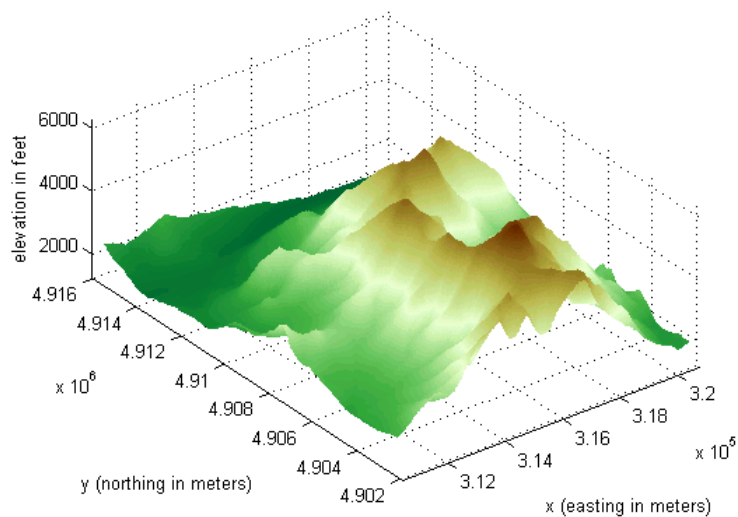
**Purpose** Read gridded data set in Arc ASCII Grid Format

**Syntax** `[Z,R] = arcgridread(filename)`

**Description** `[Z,R] = arcgridread(filename)` reads a grid from a file in Arc ASCII Grid format. Z is a 2-D array containing the data values. R is a referencing matrix (see `makrefmat`). NaN is assigned to elements of V corresponding to null data values in the grid file.

**Example**

```
[Z,R] = arcgridread('MtWashington-ft.grd');  
mapshow(Z,R,'DisplayType','surface');  
xlabel('x (easting in meters)'); ylabel('y (northing in meters)')  
colormap(demcmap(Z))  
  
% View the terrain in 3-D  
axis normal; view(3); axis equal; grid on  
zlabel('elevation in feet')
```



# arcgridread

---

## **See Also**

makereformat, mapshow, sdtstsemread

**Purpose**

Surface area of polygon on sphere or ellipsoid

**Syntax**

```
area = areaint(lat,lon)
area = areaint(lat,lon,ellipsoid)
area = areaint(lat,lon,units)
area = areaint(lat,lon,ellipsoid,units)
```

**Description**

`area = areaint(lat,lon)` calculates the spherical surface area of the polygon specified by the input vectors `lat` and `lon`. The calculation uses a line integral approach. The output, `area`, is the fraction of surface area covered by the polygon on a unit sphere. To supply multiple polygons, separate the polygons by NaNs in the input vectors. Accuracy of the integration method is inversely proportional to the distance between `lat/lon` points.

`area = areaint(lat,lon,ellipsoid)` uses the two-element ellipsoid vector `ellipsoid` to describe the sphere or ellipsoid. The output, `area`, is in square units corresponding to the units of `ellipsoid`.

`area = areaint(lat,lon,units)` uses the units defined by the input string `units`. If omitted, default units of degrees are assumed.

`area = areaint(lat,lon,ellipsoid,units)` uses both the inputs `ellipsoid` and `units` in the calculation.

**Examples**

Consider the area enclosed by a 30° lune from pole to pole and bounded by the prime meridian and 30°E. You can use the function `areaquad` to get an exact solution:

```
area = areaquad(90,0,-90,30)
area =
    0.0833
```

This is 1/12 the spherical area. The more points used to define this polygon, the more integration steps `areaint` takes, improving the estimate. This first attempt takes a point every 30° of latitude:

```
lats = [-90:30:90,60:-30:-60]';
lons = [zeros(1,7), 30*ones(1,5)]';
```

# areaint

---

```
area = areaint(lats,lons)
area =
    0.0792
```

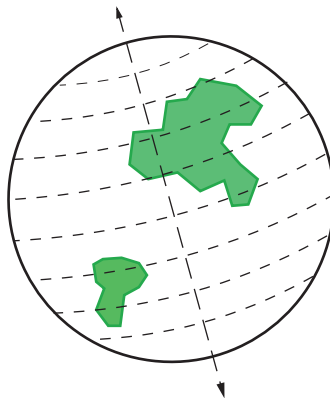
Now, calculate a better estimate, with one point every 1° of latitude:

```
lats = [-90:1:90,89:-1:-89]';
lons = [zeros(1,181), 30*ones(1,179)]';
area = areaint(lats,lons)
area =
    0.0833
```

## Algorithm

This function enables the measurement of areas enclosed by arbitrary polygons. This is a numerical estimate, using a line integral based on Green's Theorem. As such, it is limited by the accuracy and resolution of the input data.

Areas are computed for arbitrary polygons on the ellipsoid or sphere



An area is returned for each NaN-separated polygon

Given sufficient data, the `areaint` function is the best method for determining the areas of complex polygons, such as continents, cloud cover, and other natural or derived features. The calculations in this

function employ a spherical Earth assumption. For nonspherical ellipsoids, the latitude data is converted to the auxiliary authalic sphere.

**See Also**

almanac | areamat | areaquad

# areamat

---

**Purpose** Surface area covered by nonzero values in binary data grid

**Syntax**

```
A = areamat(BW,R)
A = areamat(BW,refvec,ellipsoid)
[A, cellarea] = areamat(...)
```

**Description** `A = areamat(BW,R)` returns the surface area covered by the elements of the binary regular data grid `BW`, which contain the value 1 (true). `BW` can be the result of a logical expression such as `BW = (topo > 0)`. `R` is a 1-by-3 vector containing elements: `[cells/degree northern_latitude_limit western_longitude_limit]` or a 3-by-2 referencing matrix that transforms raster row and column indices to/from geographic coordinates according to:

$$[\text{lon lat}] = [\text{row col 1}] * R$$

where `lat` and `lon` are in units of degrees. If `R` is a referencing matrix, it must define a (non-rotational, non-skewed) relationship in which each column of the data grid falls along a meridian and each row falls along a parallel. The output `A` expresses surface area as a fraction of the surface area of the unit sphere ( $4*\pi$ ), so the result ranges from 0 to 1.

`A = areamat(BW,refvec,ellipsoid)` uses the input `ellipsoid` vector to describe the sphere or reference ellipsoid. `ellipsoid` has the form `[semi-major-axis-length, eccentricity]`. The units of the output, `A`, are the square of the length units in which the semi-major axis is provided. For example, if `ellipsoid` is replaced with `almanac('earth','wgs84','kilometers')`, then `A` is in square kilometers.

`[A, cellarea] = areamat(...)` returns a vector, `cellarea`, describing the area covered by the data cells in `BW`. Because all the cells in a given row are exactly the same size, only one value is needed per row. Therefore `cellarea` has size `M-by-1`, where `M = size(BW,1)` is the number of rows in `BW`.

**Remarks** Given a regular data grid that is a logical 0-1 matrix, the `areamat` function returns the area corresponding to the true, or 1, elements. The



input data grid can be a logical statement, such as `(topo>0)`, which is 1 everywhere that `topo` is greater than 0 meters, and 0 everywhere else. This is an illustration of that matrix:



This calculation is based on the `areaquad` function and is therefore limited only by the granularity of the cellular data.

## Examples

```
load topo
area = areamat((topo>127),topolegend)

area =
    0.2411
```

Approximately 24% of the Earth has an altitude greater than 127 meters. What is the surface area of this portion of the Earth in square kilometers if a spherical ellipsoid is assumed? (Use the `almanac` function with the sphere as its reference body.)

```
earthgeoid = almanac('earth','ellipsoid','km','sphere');
area = areamat((topo>127),topolegend,earthgeoid)

area =
    1.2299e+08
```

To illustrate the `cellarea` output, consider a smaller map:

```
BW = ones(9,18);
refvec = [.05 90 0] % each cell 20x20 degrees
```

## areamat

---

```
[area,cellarea] = areamat(BW,refvec)
```

```
area =  
    1.0000  
cellarea =  
    0.0017  
    0.0048  
    0.0074  
    0.0091  
    0.0096  
    0.0091  
    0.0074  
    0.0048  
    0.0017
```

Each entry of `cellarea` represents the portion of the unit sphere's total area a cell in that row of `BW` would contribute. Since the column extends from pole to pole in this case, it is symmetric.

### See Also

`almanac`, `areaaint`, `areaquad`

**Purpose**

Surface area of latitude-longitude quadrangle

**Syntax**

```
area = areaquad(lat1,lon1,lat2,lon2)
area = areaquad(lat1,lon1,lat2,lon2,ellipsoid)
area = areaquad(lat1,lon1,lat2,lon2,ellipsoid,units)
```

**Description**

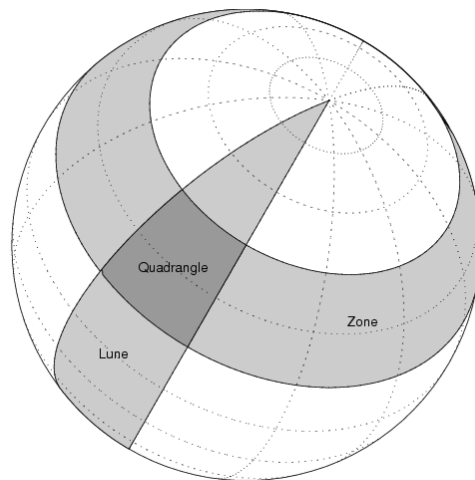
`area = areaquad(lat1,lon1,lat2,lon2)` returns the surface area bounded by the parallels `lat1` and `lat2` and the meridians `lon1` and `lon2`. The output area is a fraction of the unit sphere's area of  $4\pi$ , so the result ranges from 0 to 1.

`area = areaquad(lat1,lon1,lat2,lon2,ellipsoid)` allows the specification of the ellipsoid model with the two-element ellipsoid vector `ellipsoid`. When `ellipsoid` is input, the resulting area is given in terms of the (squared) units of the ellipsoid. For example, if the ellipsoid `almanac('earth','ellipsoid','kilometers')` is used, the resulting area is in  $\text{km}^2$ . The default ellipsoid is the unit sphere.

`area = areaquad(lat1,lon1,lat2,lon2,ellipsoid,units)` specifies the units of the inputs. The default is 'degrees'.

**Definitions**

A latitude-longitude quadrangle is a region bounded by two meridians and two parallels. In spherical geometry, it is the intersection of a *lune* (a section bounded by two meridians) and a *zone* (a section bounded by two parallels).



## Examples

Find the fraction of the Earth's surface that lies between 30°N and 45°N, and also between 25°W and 60°E:

```
area = areaquad(30, -25, 45, 60)
```

```
area =  
0.0245
```

Assuming a spherical ellipsoid, find the surface area of the Earth in square kilometers. (Use the `almanac` function with the sphere as its reference body.)

```
earthellipsoid = almanac('earth', 'ellipsoid', 'km', 'sphere');  
area = areaquad(-90, -180, 90, 180, earthellipsoid)
```

```
area =  
5.1006e+08
```

For comparison,

```
almanac('earth', 'surfarea', 'km')
```

```
ans =  
5.1006e+08
```

## Algorithm

The areaquad calculation is exact, being based on simple spherical geometry. For nonspherical ellipsoids, the data is converted to the auxiliary authalic sphere.

## See Also

[almanac](#) | [areaint](#) | [areamat](#)

# avhrrgoode

---

## Purpose

Read AVHRR data product stored in Goode Projection

## Syntax

```
[latgrat,longrat,z] = avhrrgoode(region,filename)
[...] = avhrrgoode(region,filename,scalefactor)
[...] = avhrrgoode(region,filename,scalefactor,latlim,lonlim)
[...] = avhrrgoode(region,filename,scalefactor,latlim,lonlim,
    gsize)
[...] = avhrrgoode(region,filename,scalefactor,latlim,lonlim,gsize,...
    nrows,ncols)
[...] = avhrrgoode(region,filename,scalefactor,latlim,lonlim,gsize,...
    nrows,ncols,resolution)
[...] = avhrrgoode(region,filename,scalefactor,latlim,lonlim,gsize,...
    nrows,ncols,resolution,precision)
```

## Description

[latgrat,longrat,z] = avhrrgoode(region,filename) reads data from an Advanced Very High Resolution Radiometer (AVHRR) data set with a nominal resolution of 1 km that is stored in the Goode projection. Data in this format includes a nondimensional vegetation index (NDVI) and Global Land Cover Characteristics (GLCC) data sets. *region* is a string that specifies the geographic coverage of the file. Valid region strings are:

- 'g' or 'global'
- 'af' or 'africa'
- 'ap' or 'australia/pacific'
- 'ea' or 'eurasia'
- 'na' or 'north america'
- 'sa' or 'south america'

*filename* is a string specifying the name of the data file. Output *Z* is a geolocated data grid with coordinates *latgrat* and *longrat* in units of degrees. *Z*, *latgrat*, and *longrat* are of class double. Projected coordinates that lie within the interrupted areas of the projection are

set to NaN. A scale factor of 100 is applied to the original data set, so that Z contains every 100<sup>th</sup> point in both X and Y directions.

[...] = avhrrgoode(region,filename,scalefactor) uses the integer scalefactor to downsample the data. A scale factor of 1 returns every point. A scale factor of 10 returns every 10<sup>th</sup> point. The default value is 100.

[...] = avhrrgoode(region,filename,scalefactor,latlim,lonlim) returns data for the specified region. The returned data can extend somewhat beyond the requested area. Limits are two-element vectors in units of degrees, with latlim in the range [-90 90] and lonlim in the range [-180 180]. latlim and lonlim must be ascending. If latlim and lonlim are empty, the entire area covered by the data file is returned. If the quadrangle defined by latlim and lonlim (when projected to form a polygon in the appropriate Goode projection) fails to intersect the bounding box of the data in the projected coordinates, then Z, latgrat, and longrat are returned as empty.

[...] = avhrrgoode(region,filename,scalefactor,latlim,lonlim,gsize) controls the size of the graticule matrices. gsize is a two-element vector containing the number of rows and columns desired. By default, latgrat, and longrat have the same size as Z.

[...] = avhrrgoode(region,filename,scalefactor,latlim,lonlim,gsize,... nrows,ncols) overrides the dimensions for the standard file format for the selected region. This syntax is useful for data stored on CD-ROM, which may have been truncated to fit. Some global data sets were distributed with 16347 rows and 40031 columns of data on CD-ROMs. The default size for global data sets is 17347 rows and 40031 columns of data.

[...] = avhrrgoode(region,filename,scalefactor,latlim,lonlim,gsize,... nrows,ncols,resolution) reads a data set with the spatial resolution specified in meters. Specify resolution as either 1000 or 8000

(meters). If empty, the full resolution of 1000 meters is assumed. Data is also available at 8000-meter resolution. Nondimensional vegetation index data at 8-km spatial resolution has 2168 rows and 5004 columns.

```
[...] =  
avhrrgoode(region, filename, scalefactor, latlim, lonlim, gsize, ...  
nrows, ncols, resolution, precision) reads a data set expecting the  
integer precision specified. If empty, 'uint8' is assumed. 'uint16'  
is appropriate for some files. Check the metadata (.txt or README) file  
in the GLCC ftp directory for specification of the file format and  
contents. In either case, Z is converted to class double.
```

## Background

The United States maintains a family of satellite-based sensors to measure climate change under the Earth Observing System (EOS) program. The precursors to the EOS data are the data sets produced by NOAA and NASA under the Pathfinder program. These are data derived from the Advanced High Resolution Radiometer sensor flown on the NOAA Polar Orbiter satellites, NOAA-7, -9, and -11, and have spatial resolutions of about 1 km. The data from the AVHRR sensor is processed into separate land, sea, and atmospheric indices. Land area data is processed to a nondimensional vegetation index (NDVI) or land cover classification and stored in binary files in the Plate Carrée, Goode, and Lambert projections. Sea data is processed to surface temperatures and stored in HDF formats. `avhrrgoode` reads land data saved in the Goode projection with global and continental coverage at 1 km. It can also read 8 km data with global coverage.

## Remarks

This function reads the binary files as is. You should not use byte-swapping software on these files.

The AVHRR project and data sets are described in and provided by various U.S. Government Web sites. See the entry for Global Land Cover Characteristics (GLCC) in the tech note referred to below.



---

**Note** For details on locating map data for download over the Internet, see the following documentation at the MathWorks Web site: <http://www.mathworks.com/support/tech-notes/2100/2101.html>.

---

## Limitations

Most files store the data in scaled integers. Though this function returns the data as double, the scaling from integer to float is not performed. Check the data's README file for the appropriate scaling parameters.

## Examples

### Example 1 – Downsampled Classified Global GLCC Coverage

Read and display every 50th point from the Global Land Cover Characteristics (GLCC) file covering the entire globe with the USGS classification scheme, named `gusgs2_0g.img`. (To run the example, you must first download the file.)

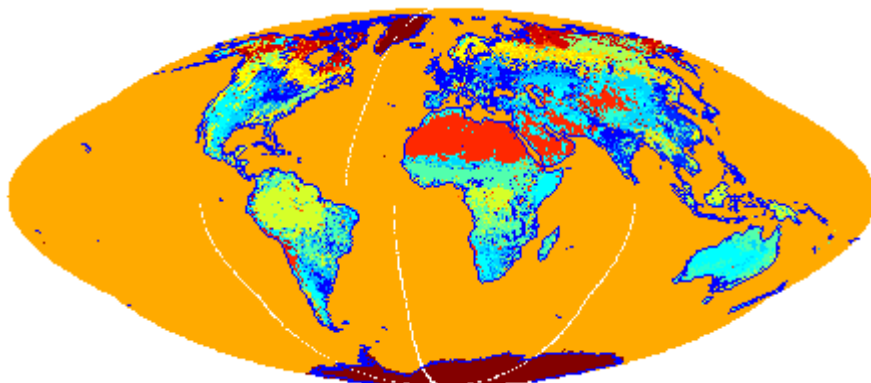
```
[latgrat, longrat, Z] = avhrrgoode('global', ...
    'gusgs2_0g.img',50);

% Convert the geolocated data grid to an geolocated image.
uniqueClasses = unique(Z);
RGB = ind2rgb8(uint8(Z), jet(numel(uniqueClasses)));

% Display the data as an image using the Goode projection.
origin = [0 0 0];
ellipsoid = [6370997 0];
figure('Renderer','zbuffer')
axesm('MapProjection','goode','Origin',origin,...
    'Geoid',ellipsoid)
geoshow(latgrat, longrat, RGB, 'DisplayType','image');
axis image off

% Plot the coastlines.
hold on
load coast
```

```
plotm(lat,long)
```

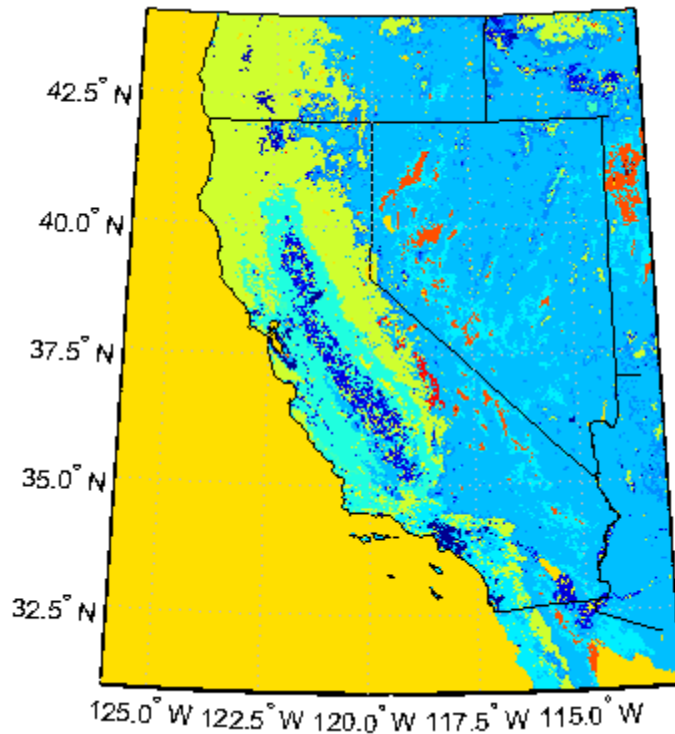


## Example 2 – Classified GLCC Data for California

Read and display every point from the Global Land Cover Characteristics (GLCC) file covering California with the USGS classification scheme, named `nausgs1_2g.img`. You must first download the file to run this example.

```
figure
usamap california
mstruct = gcm;
latlim = mstruct.maplatlimit;
lonlim = mstruct.maplonlimit;
scalefactor = 1;
[latgrat, longrat, Z] = ...
    avhrrgoode('na', 'nausgs1_2g.img', scalefactor, latlim, lonlim);
geoshow(latgrat, longrat, Z, 'DisplayType', 'texturemap');

% Overlay vector data from usastatehi.shp.
california = shaperead('usastatehi', 'UseGeoCoords', true,...
    'BoundingBox', [lonlim;latlim]);
geoshow([california.Lat], [california.Lon], 'Color', 'black');
```



**See Also** [avhrrlambert](#)

# avhrrlambert

---

**Purpose** Read AVHRR data product stored in eqaazim projection

**Syntax**

```
[latgrat,longrat,Z] = avhrrlambert(region,filename)  
[...] = avhrrlambert(region,filename, scalefactor)  
[...] = avhrrlambert(region,filename, scalefactor, latlim,  
lonlim)  
[...] = avhrrlambert(region,filename, scalefactor, latlim,  
lonlim, gsize)  
[...] = avhrrlambert(region,filename, scalefactor, latlim,  
lonlim, gsize,precision)
```

**Description** [latgrat,longrat,Z] = avhrrlambert(*region*,*filename*) reads data from an Advanced Very High Resolution Radiometer (AVHRR) data set with a nominal resolution of 1 km that is stored in the Lambert Equal Area Azimuthal projection. Data of this type includes the Global Land Cover Characteristics (GLCC). *region* specifies the coverage of the file. Valid regions are listed in the following table. *filename* is a string specifying the name of the data file. *Z* is a geolocated data grid with coordinates *latgrat* and *longrat* in units of degrees. A scale factor of 100 is applied to the original data set such that *Z* contains every 100th point in both X and Y.

Region Specifiers
'a' or 'asia'
'af' or 'africa'
'ap' or 'australia/pacific'
'e' or 'europe'
'na' or 'north america'
'sa' or 'south america'

[...] = avhrrlambert(*region*,*filename*, scalefactor) uses the integer *scalefactor* to downsample the data. A scale factor of 1 returns every point. A scale factor of 10 returns every 10th point. The default value is 100.

[...] = avhrrlambert(*region*, *filename*, *scalefactor*, *latlim*, *lonlim*) returns data for the specified region. The result may extend somewhat beyond the requested area. The limits are two-element vectors in units of degrees, with *latlim* in the range [-90 90] and *lonlim* in the range [-180 180]. If *latlim* and *lonlim* are empty, the entire area covered by the data file is returned. If the quadrangle defined by *latlim* and *lonlim* (when projected to form a polygon in the appropriate Lambert Equal Area Azimuthal projection) fails to intersect the bounding box of the data in the projected coordinates, then *latgrat*, *longrat*, and *Z* are empty.

[...] = avhrrlambert(*region*, *filename*, *scalefactor*, *latlim*, *lonlim*, *gsize*) controls the size of the graticule matrices. *gsize* is a two-element vector containing the number of rows and columns desired. If omitted or empty, a graticule the size of the grid is returned.

[...] = avhrrlambert(*region*, *filename*, *scalefactor*, *latlim*, *lonlim*, *gsize*, *precision*) reads a data set with the integer *precision* specified. If omitted, 'uint8' is assumed. 'uint16' is appropriate for some files. Check the metadata (.txt or README) file in the ftp directory for specification of the file format and contents.

## Background

The United States plans to build a family of satellite-based sensors to measure climate change under the Earth Observing System (EOS) program. Early precursors to the EOS data are the data sets produced by NOAA and NASA under the Pathfinder program. These are data derived from the Advanced High Resolution Radiometer sensor flown on the NOAA Polar Orbiter satellites, NOAA-7, -9, and -11 with a spatial resolution of about 1 km. The data from the AVHRR sensor is processed into separate land, sea, and atmospheric indices. Land area data is processed to a nondimensional vegetation index or land cover classification and stored in binary files in the Plate Carrée, Goode, and Lambert Equal Area Azimuthal projections. Sea data is processed to surface temperatures and stored in HDF formats. This function reads land cover data for the continents saved in the Lambert Equal Area Azimuthal projection at 1 km.

## Remarks

This function reads the binary files as is. You should not use byte-swapping software on these files.

The AVHRR project and data sets are described in and provided by various U.S. Government Web sites.

---

**Note** For details on locating map data for download over the Internet, see the following documentation at the MathWorks Web site: <http://www.mathworks.com/support/tech-notes/2100/2101.html>.

---

## Examples

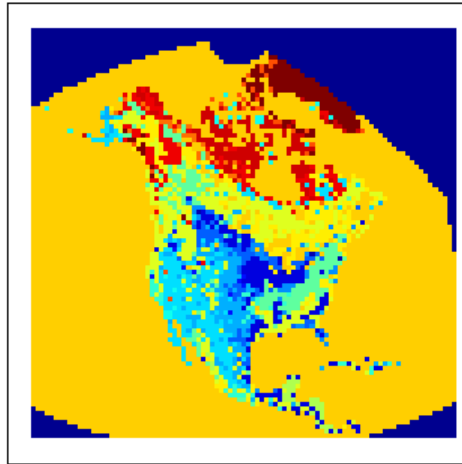
### Example 1

Read and display every 100th point from the Global Land Cover Characteristics (GLCC) file covering North America with the USGS classification scheme, named `nausgs1_21.img`.

```
[latgrat, longrat, Z] = avhrrlambert('na','nausgs1_21.img');
```

Display the data using the Lambert Equal Area Azimuthal projection.

```
origin = [50 -100 0];  
ellipsoid = [6370997 0];  
figure  
axesm('MapProjection', 'eqaazim', 'Origin', ...  
      origin, 'Geoid', ellipsoid)  
geoshow(latgrat, longrat, Z, 'DisplayType', 'texturemap');
```



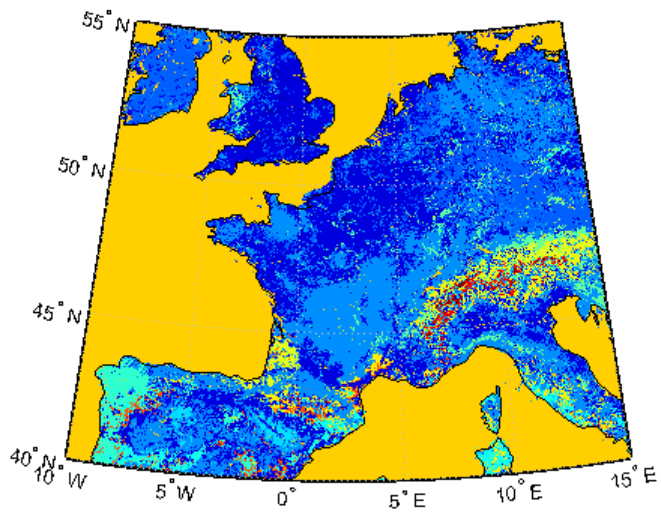
## Example 2

Read and display every other point from the Global Land Cover Characteristics (GLCC) file covering Europe with the USGS classification scheme, named `eausgs1_21e.img`.

```
figure
worldmap france
mstruct = gcm;
latlim = mstruct.maplatlimit;
lonlim = mstruct.maplonlimit;
scalefactor = 2;
[latgrat, longrat, Z] = avhrrlambert('e', 'eausgs1_21e.img', ...
    scalefactor, latlim, lonlim);
geoshow(latgrat, longrat, Z, 'DisplayType', 'texturemap');
geoshow('landareas.shp', 'FaceColor', 'none', 'EdgeColor', 'black')
```

# avhrrlambert

---



**See Also** [avhrrgoode](#)



---

<b>Purpose</b>	Eccentricity of ellipse with given axis lengths
<b>Syntax</b>	<pre>eccentricity = axes2ecc(semimajor,semiminor) eccentricity = axes2ecc(axes)</pre>
<b>Description</b>	<p>Eccentricity, the second element of the standard Mapping Toolbox ellipsoid vector, can be determined given both the semimajor and semiminor axes.</p> <p><code>eccentricity = axes2ecc(semimajor,semiminor)</code> returns the eccentricity associated with the input axes.</p> <p><code>eccentricity = axes2ecc(axes)</code> allows the axes inputs to be packed into a single two-column input of the form <code>[semimajor, semiminor]</code>.</p>
<b>Examples</b>	<p>Using the axes for the default GRS 80 Earth model,</p> <pre>ecc = axes2ecc(6378.1370,6356.7523) ecc =     0.08181921804834</pre> <p>This is the eccentricity returned by <code>almanac('earth','ellipsoid')</code>.</p>
<b>See Also</b>	<code>almanac</code> , <code>ecc2n</code> , <code>majaxis</code> , <code>minaxis</code>

**Purpose** Define map axes and set map properties

**Syntax**

```
axesm  
axesm(PropertyName,PropertyValue,...)  
axesm(ProjectionFcn,PropertyName,PropertyValue,...)
```

**Description** axesm with no input arguments, initiates the axesmui map axes graphical user interface, which can be used to set map axes properties. This is detailed on the axesmui reference page.

axesm(*PropertyName*,*PropertyValue*,...) creates a map axes using the specified properties. Properties may be specified in any order, but the MapProjection property must be included.

axesm(*ProjectionFcn*,*PropertyName*,*PropertyValue*,...) allows omission of the MapProjection property name. The first input must be the identifying string of an available projection. For a list of these strings, see the table of projections in “Summary and Guide to Projections”.

The axesm function creates a map axes into which both vector and raster geographic data can be projected using functions such as plotm and geoshow. Properties specific to map axes can be assigned upon creation with axesm, and for an existing map axes they can be queried and changed using getm and setm. Use the standard get and set methods to query and control the standard MATLAB® axes properties of a map axes.

**Axes Definition** Map axes are standard MATLAB axes with different default settings for some properties and a data structure for storing projection parameters and other data. The main differences in default settings are

- Axes properties XGrid, YGrid, XTick, YTick are set to 'off'.
- The properties XColor, YColor, and ZColor are set to the background color.
- The hold mode is on.

The map data structure stores the map axes properties, which, in addition to the special standard axes settings described here, allow Mapping Toolbox functions to recognize an axes or an opened FIG-file as a map axes. See “Map Axes Object Properties” on page 3-37, below, for descriptions of the map axes properties.

## Examples

Create map axes for a Mercator projection, with selected latitude limits:

```
axesm('MapProjection','mercator','MapLatLimit',[-70 80])
```

In the preceding example, all properties not explicitly addressed in the call are set to either fixed or calculated defaults. The file `mercator.m` defines a projection function, so the same result could have been achieved with the function

```
axesm('mercator','MapLatLimit',[-70 80])
```

Each projection function includes default values for all properties. Any following property name/property value pairs are treated as overrides.

In either of the above examples, data displayed in the given map axes is in a Mercator projection. Any data falling outside the prescribed limits is not displayed.

---

**Note** The names of projection files are case sensitive. The projection files included in Mapping Toolbox software use only lowercase letters and Arabic numerals.

---

## Map Axes Object Properties

- “Properties That Control the Map Projection” on page 3-38
- “Properties That Control the Frame” on page 3-43
- “Properties That Control the Grid” on page 3-46
- “Properties That Control Grid Labeling” on page 3-49

## Properties That Control the Map Projection

### AngleUnits

{degrees} | radians

*Angular unit of measure* — Controls the units of measure used for angles (including latitudes and longitudes) in the map axes. All input data are assumed to be in the given units; 'degrees' is the default. For more information on angle units, see “Working with Angles: Units and Representations” in the *Mapping Toolbox User’s Guide*.

### Aspect

{normal} | transverse

*Display aspect* — Controls the orientation of the base projection of the map. When the aspect is 'normal' (the default), *north* in the base projection is up. In a transverse aspect, north is to the right. A cylindrical projection of the whole world would look like a *landscape* display under a 'normal' aspect, and like a *portrait* under a 'transverse' aspect. Note that this property is not the same as projection aspect, which is controlled by the `Origin` property vector discussed later.

### FalseEasting

scalar {0}

*Coordinate shift for projection calculations* — Modifies the position of the map within the axes. The projected coordinates are shifted in the *x*-direction by the amount of `FalseEasting`. The `FalseEasting` is in the same units as the projected coordinates, that is, the units of the first element of the `Geoid` map axes property. False eastings and northings are sometimes used to ensure nonnegative values of the projected coordinates. For example, the Universal Transverse Mercator uses a false easting of 500,000 meters.

FalseNorthing  
scalar {0}

*Coordinate shift for projection calculations* — Modifies the position of the map within the axes. The projected coordinates are shifted in the  $y$ -direction by the amount of FalseNorthing. The FalseNorthing is in the same units as the projected coordinates, that is, the units of the first element of the Geoid map axes property. False eastings and northings are sometimes used to ensure nonnegative values of the projected coordinates. For example, the Universal Transverse Mercator uses a false northing of 0 in the northern hemisphere and 10,000,000 meters in the southern.

FixedOrient  
scalar {[]} (read-only)

*Projection-based orientation* — This read-only property fixes the orientation of certain projections (such as the Cassini and Wetch). When empty, which is true for most projections, the user can alter the orientation of the projection using the third element of the Origin property. When fixed, the fixed orientation is always used.

Geoid  
[semimajor\_axis eccentricity]

*Planet ellipsoid definition* — Sets the ellipsoid for calculating the projections of any displayed map objects. In the toolbox, the ellipsoid is approximated by a spheroid. The default ellipsoid is a sphere with a radius of 1. This is represented as [1 0]. Any semimajor axis, in any distance units, can be entered; eccentricity lies between 0 and 1.

MapLatLimit  
[southern\_limit northern\_limit]

*Geographic latitude limits of the display area* — Expressed as a two element vector of the form [southern\_limit

`northern_limit`]. This property can be set for many typical projections and geometries, but cannot be used with oblique projections or with `globe`, for example. When applicable, the `MapLatLimit` property may affect the origin latitude if the `Origin` property is not set explicitly when calling `axesm`. It may also determine the value used for `FlatLimit`. See “Accessing and Manipulating Map Axes Properties” for a more complete description of the applicability of `MapLatLimit` and its interaction with the origin, frame limits, and other properties.

#### `MapLonLimit`

`[western_limit eastern_limit]`

*Geographic longitude limits of the display area* — Expressed as a two element vector of the form `[western_limit eastern_limit]`. This property can be set for many typical projections and geometries, but cannot be used with oblique projections or with `globe`, for example. When applicable, the `MapLonLimit` property may affect the origin longitude if the `Origin` property is not set explicitly when calling `axesm`. It may also determine the value used for `FLonLimit`. See “Accessing and Manipulating Map Axes Properties” for a more complete description of the applicability of `MapLonLimit` and its interaction with the origin, frame limits, and other properties.

#### `MapParallels`

`[lat] | [lat1 lat2]`

*Projection standard parallels* — Sets the standard parallels of projection. It can be an empty, one-, or two-element vector, depending upon the projection. The elements are in the same units as the map axes `AngleUnits`. Many projections have specific, defining standard parallels. When a map axes object is based upon one of these projections, the parallels are set to the appropriate defaults. For conic projections, the default standard parallels are set to 15°N and 75°N, which biases the projection toward the northern hemisphere.

For projections with one defined standard parallel, setting the parallels to an empty vector forces recalculation of the parallel to the middle of the map latitude limits. For projections requiring two standard parallels, setting the parallels to an empty vector forces recalculation of the parallels to one-sixth the distance from the latitude limits (e.g., if the map latitude limits correspond to the northern hemisphere [0 90], the standard parallels for a conic projection are set to [15 75]). For azimuthal projections, the `MapParallels` property always contains an empty vector and cannot be altered.

See the *Mapping Toolbox User's Guide* for more information on standard parallels.

#### MapProjection

`projection_name` {no default}

*Map projection* — Sets the projection, and hence all transformation calculations, for the map axes object. It is required in the creation of map axes. The projection name is a string corresponding to a MATLAB file appropriate to the projection. It must be a member of the recognized projection set, which you can list by typing `getm('MapProjection')` or `maps`. For more information on projections, see the *Mapping Toolbox User's Guide*. Some projections set their own defaults for other properties, such as parallels and trim limits.

#### Origin

[latitude longitude orientation]

*Origin and orientation for projection calculations* — Sets the map origin for all projection calculations. The latitude, longitude, and orientation should be in the map axes `AngleUnits`. Latitude and longitude refer to the coordinates of the map origin; orientation refers to an angle of skewness or rotation about the axis running through the origin point and the center of the earth. The default origin is 0° latitude and a longitude centered between the map longitude limits. If a scalar is entered, it is assumed to refer

to the longitude; if a two-element vector is entered, the default orientation is 0°, a normal projection. If an empty origin vector is entered, the origin is centered on the map longitude limits. For more information on the origin, see the *Mapping Toolbox User's Guide*.

**Parallels**

0, 1, or 2 (read-only, projection-dependent)

*Number of standard parallels* — This read-only property contains the number of standard parallels associated with the projection. See the *Mapping Toolbox User's Guide* for more information on standard parallels.

**ScaleFactor**

scalar {1}

*Scale factor for projection calculations* — Modifies the size of the map in projected coordinates. The geographic coordinates are transformed to Cartesian coordinates by the map projection equations and multiplied by the scale factor. Scale factors are sometimes used to minimize the scale distortion in a map projection. For example, the Universal Transverse Mercator uses a scale factor of 0.996 to shift the line of zero scale distortion to two lines on either side of the central meridian.

**Zone**

ZoneSpec | {[ ] or 31N}

*Zone for certain projections* — Specifies the zone for certain projections. A zone is a region on the globe that has a special set of projection parameters. In the Universal Transverse Mercator Projection, the world is divided into quadrangles that are generally 6 degrees wide and 8 degrees tall. The number in the zone designation refers to the longitude range, while the letter refers to the latitude range. Most projections use the same parameters for the entire globe, and do not require a zone.



## Properties That Control the Frame

### Frame

on | {off}

*Frame visibility* — Controls the visibility of the display frame box. When the frame is 'off' (the default), the frame is not displayed. When the frame is 'on', an enclosing frame is visible. The frame is a patch that is plotted as the lowest layer of displayed map objects. Regardless of its display status, the frame always operates in terms of trimming map data.

### FFill

*scalar plotting point density* {100}

*Frame plotting precision* — Sets the number of points to be used in plotting the frame for display. The default value is 100, which for a rectangular frame results in a plot with 100 points for each side, or a total of 400 points. The number of points required for a reasonable display varies with the projection. Cylindrical projections such as the Miller require very few. Projections resulting in more complex frames, such as the Werner, look better with higher densities. The default value is generally sufficient.

### FEdgeColor

ColorSpec | {[0 0 0]}

*Color of the displayed frame edge* — Specifies the color used for the displayed frame. You can specify a color using a vector of RGB values or a MATLAB colorspec name. By default, the frame edge is displayed in black ([0 0 0]).

### FFaceColor

ColorSpec | {none}

*Color of the displayed frame face* — Specifies the color used for the displayed frame face. You can specify a color using a vector of RGB values or a MATLAB colorspec name. By default, the

frame face is 'none', meaning no face color is filled in. Another useful color is 'cyan' ([0 1 1]), which looks like water.

`FLatLimit`  
[southern\_limit northern\_limit]

*Latitude limits of map frame relative to projection origin* — The map frame encloses the area in which data and graticule lines are plotted and beyond which they are trimmed. For non-oblique and non-azimuthal projections, which have quadrangular frames, this property controls the north-south extent of the frame. If a projection is made oblique by the inclusion of a non-zero rotation angle (the third element of the `Origin` vector), `FLatLimit` still applies, but in the rotated latitude-longitude system rather than in the geographic system. In the case of azimuthal projections, which have circular frames, `FLatLimit` takes the special form `[-Inf radius]` where `radius` is the spherical distance (in degrees or radians, depending on the `AngleUnits` property of the projection) from the projection origin to the edge of the frame.

---

**Note** In most common situations, including non-oblique cylindrical and conic projections and polar azimuthal projections, there is no need to set `FLatLimit`; use `MapLatLimit` instead.

---

`FLineWidth`  
*scalar* {2}

*Frame edge line width* — Sets the line width of the displayed frame edge. The value is a scalar representing points, which is 2 by default.

`FLonLimit`  
[western\_limit eastern\_limit]

*Latitude limits of map frame relative to projection origin* — The map frame encloses the area in which data and graticule lines

are plotted and beyond which they are trimmed. For non-oblique and non-azimuthal projections, which have quadrangular frames, this property controls the east-west extent of the frame. If a projection is made oblique by the inclusion of a non-zero rotation angle (the third element of the `Origin` vector), `FLonLimit` still applies, but in the rotated latitude-longitude system rather than in the geographic system. The `FLonLimit` property is ignored for azimuthal projections.

---

**Note** In most common situations, including non-oblique cylindrical and conic projections, there is no need to set `FLonLimit`; use `MapLonLimit` instead.

---

#### TrimLat

```
[southern_limit northern_limit]
(read-only, projection-dependent)
```

*Bounds on FLatLimit* — This read-only property sets bounds on the values that `axesm` and `setm` will accept for the `MapLatLimit` and `FLatLimit` properties, which is necessary because some map projections cannot display the entire globe without extending to infinity. For example, `TrimLat` is `[-90 90]` degrees for most cylindrical projections and `[-86 86]` degrees for the Mercator projection because the north-south scale becomes infinite as one approaches either pole.

#### TrimLon

```
[western_limit eastern_limit]
(read-only, projection-dependent)
```

*Bounds on FLonLimit* — This read-only property sets bounds on the values that `axesm` and `setm` will accept for the `MapLonLimit` and `FLonLimit` properties, which is necessary because some map projections cannot display the entire globe without extending to

infinity. For example, `TrimLon` is `[-135 135]` degrees for most conic projections.

### **Properties That Control the Grid**

`Grid`

`on` | `{off}`

*Grid visibility* — Controls the visibility of the display grid. When the grid is 'off' (the default), the grid is not displayed. When the grid is 'on', meridians and parallels are visible. The grid is plotted as a set of line objects.

`GAltitude`

scalar z-axis value `{Inf}`

*Grid z-axis setting* — Sets the z-axis location for the grid when displayed. Its default value is infinity, which is displayed above all other map objects. However, you can set this to some other value for stacking objects above the grid, if desired.

`GColor`

`ColorSpec` | `{[0 0 0]}`

*Color of the displayed grid* — Specifies the color used for the displayed grid. You can specify a color using a vector of RGB values or one of the MATLAB `colormap` names. By default, the map grid is displayed in black (`[0 0 0]`).

`GLineStyle`

`LineStyle` `{:}`

*Grid line style* — Determines the style of line used when the grid is displayed. You can specify any line style supported by the MATLAB line function. The default line style is a dotted line (that is, `':'`).

`GLineWidth`

scalar `{0.5}`

*Grid line width* — Sets the line width of the displayed grid. The value is a scalar representing points, which is 0.5 by default.

#### MLineException

vector of longitudes {[]}

*Exceptions to grid meridian limits* — Allows specific meridians of the displayed grid to extend beyond the grid meridian limits to the poles. The value must be a vector of longitudes in the appropriate angle units. For longitudes so specified, grid lines extend from pole to pole regardless of the existence of any grid meridian limits. This vector is empty by default.

#### MLineFill

scalar plotting point density {100}

*Grid meridian plotting precision* — Sets the number of points to be used in plotting the grid meridians. The default value is 100 points. The number of points required for a reasonable display varies with the projection. Cylindrical projections such as the Miller require very few. Projections resulting in more complex shapes, such as the Werner, look better with higher densities. The default value is generally sufficient.

#### MLineLimit

[north south] | [south north] {[]}

*Grid meridian limits* — Establishes latitudes beyond which displayed grid meridians do not extend. By default, this property is empty, so the meridians extend to the poles. There are two exceptions to the meridian limits. No meridian extends beyond the map latitude limits, and exceptions to the meridian limits for selected meridians are allowed (see above).

#### MLineLocation

scalar interval or specific vector {30°}

*Grid meridian interval or specific locations* — Establishes the interval between displayed grid meridians. When a scalar

interval is entered in the map axes `MLineLocation`, meridians are displayed, starting at 0° longitude and repeating every interval in both directions, which by default is 30°. Alternatively, you can enter a vector of longitudes, in which case a meridian is displayed for each element of the vector.

**PLineException**

vector of latitudes `{[]}`

*Exceptions to grid parallel limits* — Allows specific parallels of the displayed grid to extend beyond the grid parallel limits to the International Date Line. The value must be a vector of latitudes in the appropriate angle units. For latitudes so specified, grid lines extend from the western to the eastern map limit, regardless of the existence of any grid parallel limits. This vector is empty by default.

**PLineFill**

scalar plotting point density `{100}`

*Grid parallel plotting precision* — Sets the number of points to be used in plotting the grid parallels. The default value is 100. The number of points required for a reasonable display varies with the projection. Cylindrical projections such as the Miller require very few. Projections resulting in more complex shapes, such as the Bonne, look better with higher densities. The default value is generally sufficient.

**PLineLimit**

`[east west] | [west east] {[]}`

*Grid parallel limits* — Establishes longitudes beyond which displayed grid parallels do not extend. By default, this property is empty, so the parallels extend to the date line. There are two exceptions to the parallel limits. No parallel extends beyond the map longitude limits, and exceptions to the parallel limits for selected parallels are allowed (see above).

**PLineLocation**

scalar interval or specific vector {15°}

*Grid parallel interval or specific locations* — Establishes the interval between displayed grid parallels. When a scalar interval is entered in the map axes PLineLocation, parallels are displayed, starting at 0° latitude and repeating every interval in both directions, which by default is 15°. Alternatively, you can enter a vector of latitudes, in which case a parallel is displayed for each element of the vector.

**Properties That Control Grid Labeling****FontAngle**

{normal} | italic | oblique

*Select italic or normal font for all grid labels* — Selects the character slant for all displayed grid labels. 'normal' specifies nonitalic font. 'italic' and 'oblique' specify italic font.

**FontColor**

ColorSpec | {black}

*Text color for all grid labels* — Sets the color of all displayed grid labels. ColorSpec is a three-element vector specifying an RGB triple or a predefined MATLAB color string (colorspec).

**FontName**

courier | {helvetica} | symbol | times

*Font family name for all grid labels* — Sets the font for all displayed grid labels. To display and print properly, FontName must be a font that your system supports.

**FontSize**

scalar in units specified in FontUnits {9}

*Font size* — An integer specifying the font size to use for all displayed grid labels, in units specified by the `FontUnits` property. The default point size is 9.

**FontUnits**

`{points} | normalized | inches | centimeters | pixels`

*Units used to interpret the `FontSize` property* — When set to `normalized`, the toolbox interprets the value of `FontSize` as a fraction of the height of the axes. For example, a `normalized` `FontSize` of 0.1 sets the text characters to a font whose height is one-tenth of the axes' height. The default units (`points`) are equal to 1/72 of an inch.

**FontWeight**

`bold | {normal}`

*Select bold or normal font* — The character weight for all displayed grid labels.

**LabelFormat**

`{compass} | signed | none`

*Labeling format for grid* — Specifies the format of the grid labels. If `'compass'` is employed (the default), meridian labels are suffixed with an “E” for east and a “W” for west, and parallel labels are suffixed with an “N” for north and an “S” for south. If `'signed'` is used, meridian labels are prefixed with a “+” for east and a “-” for west, and parallel labels are suffixed with a “+” for north and a “-” for south. If `'none'` is selected, straight latitude and longitude numerical values are employed, so western meridian labels and southern parallel labels will have a “-”, but no symbol precedes eastern and northern (positive) labels.

**LabelRotation**

`on | {off}`

*Label Rotation* — Determines whether the meridian and parallel labels are displayed without rotation (the default) or rotated to



align to the graticule. This option is not available for the Globe display.

#### LabelUnits

{degrees} | dm | dms | radians

*Specify units and formatting for grid labels* — The display of meridian and parallel labels is controlled by the map axes LabelUnits property, as described in the following table.

LabelUnits value	Label format
'degrees'	decimal degrees
'dm'	degrees/decimal minutes
'dms'	degrees/minutes/decimal seconds
'radians'	decimal radians

LabelUnits does not have a default of its own; instead it defaults to the value of AngleUnits at the time the map axes is constructed, which itself defaults to degrees. Although you can specify 'dm' and 'dms' for LabelUnits, these values are not accepted when setting AngleUnits.

#### MeridianLabel

on | {off}

*Toggle display of meridian labels* — Specifies whether the meridian labels are visible or not.

#### MLabelLocation

scalar interval or vector of longitudes

*Specify meridians for labeling* — Meridian labels need not coincide with the displayed meridian lines. Labels are displayed at intervals if a scalar in the map axes MLabelLocation is entered, starting at the prime meridian and repeating at every interval in both directions. If a vector of longitudes is entered, labels are displayed at those meridians. The default locations

coincide with the displayed meridian lines, as specified in the `MLineLocation` property.

`MLabelParallel`  
`{north} | south | equator | scalar latitude`

*Specify parallel for meridian label placement* — Specifies the latitude location of the displayed meridian labels. If a latitude is specified, all meridian labels are displayed at that latitude. If 'north' is specified, the maximum of the `MapLatLimit` is used; if 'south' is specified, the minimum of the `MapLatLimit` is used. If 'equator' is specified, a latitude of 0° is used.

`MLabelRound`  
`integer scalar {0}`

*Specify significant digits for meridian labels* — Specifies to which power of ten the displayed labels are rounded. For example, if `MLabelRound` is -1, labels are displayed down to the *tenths*. The default value of `MLabelRound` is 0; that is, displayed labels have no decimal places, being rounded to the *ones* column ( $10^0$ ).

`ParallelLabel`  
`on | {off}`

*Toggle display of parallel labels* — Specifies whether the parallel labels are visible or not.

`PLabelLocation`  
`scalar interval or vector of latitudes`

*Specify parallels for labeling* — Parallel labels need not coincide with the displayed parallel lines. Labels are displayed at intervals if a scalar in the map axes `PLabelLocation` is entered, starting at the equator and repeating at every interval in both directions. If a vector of latitudes is entered, labels are displayed at those parallels. The default locations coincide with the displayed parallel lines, as specified in the `PLineLocation` property.

**PLabelMeridian**

east | {west} | prime | scalar longitude

*Specify meridian for parallel label placement* — Specifies the longitude location of the displayed parallel labels. If a longitude is specified, all parallel labels are displayed at that longitude. If 'east' is specified, the maximum of the `MapLonLimit` is used; if 'west' is specified, the minimum of the `MapLonLimit` is used. If 'prime' is specified, a longitude of  $0^\circ$  is used.

**PLabelRound**

integer scalar {0}

*Specify significant digits for parallel labels* — Specifies to which power of ten the displayed labels are rounded. For example, if `PLabelRound` is -1, labels are displayed down to the tenths. The default value of `PLabelRound` is 0; that is, displayed labels have no decimal places, being rounded to the ones column ( $10^0$ ).

**See Also**

`axes` (MATLAB function), `gcm`, `getm`, `setm`

# axesscale

---

**Purpose** Resize axes for equivalent scale

**Syntax**  
axesscale  
axesscale(hbase)  
axesscale(hbase,hother)

**Description** axesscale resizes all axes in the current figure to have the same scale as the current axes (gca). In this context, scale means the relationship between axes  $x$ - and  $y$ -coordinates and figure and paper coordinates. When axesscale is used, a unit of length in  $x$  and  $y$  is printed and displayed at the same size in all the affected axes. The XLimMode and YLimMode of the axes are set to 'manual' to prevent autoscaling from changing the scale.

axesscale(hbase) uses the axes hbase as the reference axes, and rescales the other axes in the current figure.

axesscale(hbase,hother) uses the axes hbase as the base axes, and rescales only the axes in hother.

**Examples** Display the conterminous United States, Alaska, and Hawaii in separate axes in the same figure, with a common scale.

```
% Read state names and coordinates, extract Alaska and Hawaii
states = shaperead('usastatehi', 'UseGeoCoords', true);
statenames = {states.Name};
alaska = states(strmatch('Alaska', statenames));
hawaii = states(strmatch('Hawaii', statenames));

% Create a figure for the conterminous states
f1 = figure; hconus = usamap('conus'); tightmap
geoshow(states, 'FaceColor', [0.5 1 0.5]);
framem off; gridm off; mlabel off; plabel off
load conus gtlakelat gtlakelon
geoshow(gtlakelat, gtlakelon,...
'DisplayType', 'polygon', 'FaceColor', 'cyan')
gridm off;
```

```
% Working figure for additional calls to usamap
f2 = figure('Visible','off');

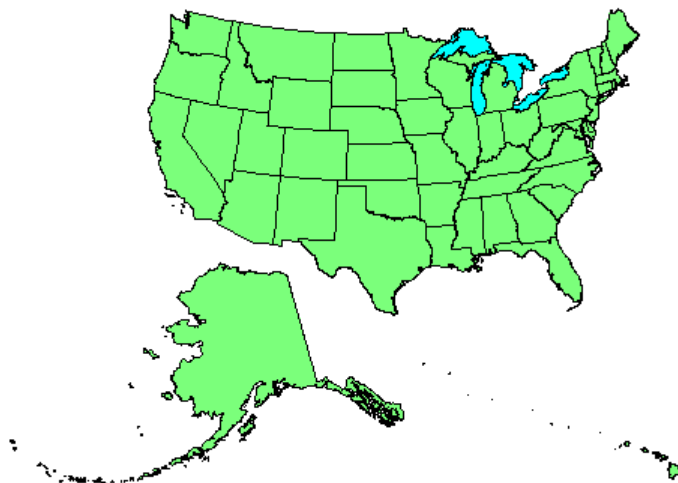
halaska = axes; usamap('alaska'); tightmap;
geoshow(alaska, 'FaceColor', [0.5 1 0.5]);
gridm off;
framem off; mlabel off; plabel off; gridm off;
set(halaska,'Parent',f1)

hhawaii = axes; usamap('hawaii'); tightmap;
geoshow(hawaii, 'FaceColor', [0.5 1 0.5]);
gridm off;
framem off; mlabel off; plabel off; gridm off;
set(hhawaii,'Parent',f1)

close(f2)

% Arrange the axes as desired
set(hconus,'Position',[0.1 0.25 0.85 0.6])
set(halaska,'Position',[0.019531 -0.020833 0.2 0.2])
set(hhawaii,'Position',[0.5 0 .2 .2])

% Resize alaska and hawaii axes
axesscale(hconus)
hidem([halaska hhawaii])
```

**Limitations**

The equivalence of scales holds only as long as no commands are issued that can change the scale of one of the axes. For example, changing the units of the ellipsoid or the scale factor in one of the axes would change the scale.

**Remarks**

To ensure the same map scale between axes, use the same ellipsoid and scale factors.

**See Also**

`paperscale`

**Purpose**

Azimuth between points on sphere or ellipsoid

**Syntax**

```
az = azimuth(lat1,lon1,lat2,lon2)
az = azimuth(lat1,lon1,lat2,lon2,ellipsoid)
az = azimuth(lat1,lon1,lat2,lon2,units)
az = azimuth(lat1,lon1,lat2,lon2,ellipsoid,units)
az = azimuth(track,...)
```

**Description**

`az = azimuth(lat1,lon1,lat2,lon2)` calculates the great circle azimuth from point 1 to point 2, for pairs of points on the surface of a sphere. The input latitudes and longitudes can be scalars or arrays of matching size. If you use a combination of scalar and array inputs, the scalar inputs will be automatically expanded to match the size of the arrays. The function measures azimuths clockwise from north and expresses them in degrees or radians.

`az = azimuth(lat1,lon1,lat2,lon2,ellipsoid)` computes the azimuth assuming that the points lie on the ellipsoid defined by the input `ellipsoid`. The `ellipsoid` vector is of the form `[semimajor_axis_length, eccentricity]`. The default ellipsoid is a unit sphere (`[1 0]`).

`az = azimuth(lat1,lon1,lat2,lon2,units)` uses the input string `units` to define the angle units of `az` and the latitude-longitude coordinates. Use 'degrees' (the default value), in the range from 0 to 360, or 'radians', in the range from 0 to  $2\pi$ .

`az = azimuth(lat1,lon1,lat2,lon2,ellipsoid,units)` specifies both the ellipsoid vector and the units of `az`.

`az = azimuth(track,...)` uses the input string `track` to specify either a great circle or a rhumb line azimuth calculation. Enter 'gc' for the `track` string (the default value), to obtain great circle azimuths for a sphere or geodesic azimuths for an ellipsoid. (Hint to remember string name: the letters “g” and “c” are in both great circle and geodesic.) Enter 'rh' for the `track` string to obtain rhumb line azimuths for either a sphere or an ellipsoid.

## Definitions

### Azimuth

An *azimuth* is the angle at which a smooth curve crosses a meridian, taken clockwise from north. The North Pole has an azimuth of  $0^\circ$  from every other point on the globe. You can calculate azimuths for great circles or rhumb lines.

### Geodesic

A *geodesic* is the shortest distance between two points on a curved surface, such as an ellipsoid.

### Great Circle

A *great circle* is a type of geodesic that lies on a sphere. It is the intersection of the surface of a sphere with a plane passing through the center of the sphere. For great circles, the azimuth is calculated at the starting point of the great circle path, where it crosses the meridian. In general, the azimuth along a great circle is not constant.

### Rhumb Line

A *rhumb line* is a curve that crosses each meridian at the same angle. For rhumb lines, the azimuth is the *constant* angle between true north and the entire rhumb line passing through the two points.

For more information on the distinction between great circles and rhumb lines, see “Great Circles, Rhumb Lines, and Small Circles” in the *Mapping Toolbox* documentation.

## Examples

Find the azimuth between two points on the same parallel, for example,  $(10^\circ\text{N}, 10^\circ\text{E})$  and  $(10^\circ\text{N}, 40^\circ\text{E})$ . The azimuth between two points depends on the *track* string selected.

```
% Try the 'gc' track string.  
az = azimuth('gc',10,10,10,40)
```

```
% Compare to the result obtained from the 'rh' track string.  
az = azimuth('rh',10,10,10,40)
```

---



Find the azimuth between two points on the same meridian, say (10°N, 10°E) and (40°N, 10°E):

```
% Try the 'gc' track string.  
az = azimuth(10,10,40,10)  
  
% Compare to the 'rh' track string.  
az = azimuth('rh',10,10,40,10)
```

Rhumb lines and great circles coincide along meridians and the Equator. The azimuths are the same because the paths coincide.

## Algorithm

### Azimuths over Long Geodesics

Azimuth calculations for geodesics degrade slowly with increasing distance and can break down for points that are nearly antipodal or for points close to the Equator. In addition, for calculations on an ellipsoid, there is a small but finite input space. This space consists of pairs of locations in which both points are nearly antipodal *and* both points fall close to (but not precisely on) the Equator. In such cases, you will receive a warning and az will be set to NaN for the “problem pairs.”

### Eccentricity

Geodesic azimuths on an ellipsoid are valid only for small eccentricities typical of the Earth (for example, 0.08 or less).

## Alternatives

If you are calculating both the distance and the azimuth, you can call just the `distance` function. The function returns the azimuth as the second output argument. It is unnecessary to call `azimuth` separately.

## See Also

`distance` | `elevation` | `reckon` | `track` | `track1` | `track2`

# bufferm

---

**Purpose** Buffer zones for latitude-longitude polygons

**Syntax**

```
[latb,lonb] = bufferm(lat,lon,dist,direction)
[latb,lonb] = bufferm(lat,lon,dist,direction,npts)
[latb,lonb] = bufferm(lat,lon,dist,direction,npts,
    outputformat)
```

**Description** [latb,lonb] = bufferm(lat,lon,dist,direction) computes the buffer zone around a polygon. A buffer zone for a closed polygon is defined as the locus of points that are a certain distance in or out of the polygon. A buffer zone for an open polygon is the locus of points a certain distance out from the polygon. The polygon is specified as vectors of latitude and longitude in units of degrees. The distance is a scalar specified in degrees of arc along the surface. Valid direction strings are 'in' and 'out'. The result is returned as NaN-clipped vectors in units of degrees.

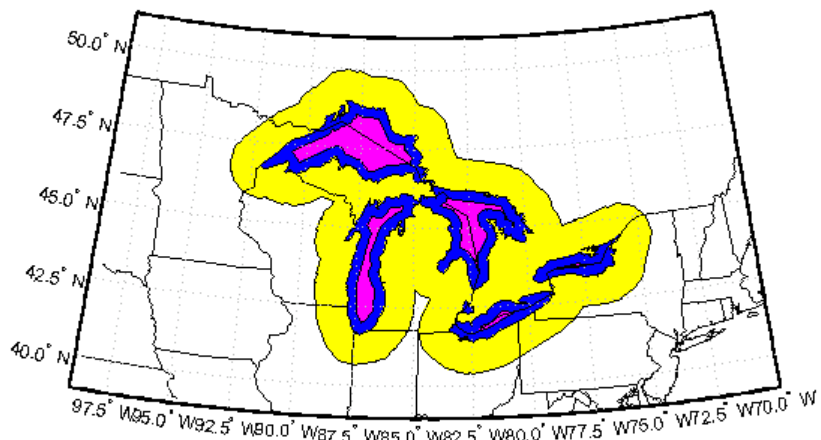
[latb,lonb] = bufferm(lat,lon,dist,direction,npts) controls the number of points used to construct circles about the vertices of the polygon. A larger number of points produces smoother buffers, but requires more time. If omitted, 13 points per circle are used.

[latb,lonb] = bufferm(lat,lon,dist,direction,npts,outputformat) controls the format of the returned buffer zones. outputformat 'vector' returns NaN-clipped vectors. outputformat 'cutvector' returns NaN-clipped vectors with cuts connecting holes to the exterior of the polygon. outputformat 'cell' returns cell arrays in which each element of the cell array is a separate polygon. Each polygon can consist of an outer contour followed by holes separated with NaNs.

**Examples** Load the coordinates for the conterminous U.S. and its great lakes. Construct a 1-degree buffer zone around the great lakes, another buffer one-third of a degree wide inside the great lakes, and display the resulting buffers over the lake and state boundaries using geoshow:

```
load conus
tol = 0.1; % Tolerance for simplifying polygon outlines
```

```
[reducedlat, reducedlon] = reducem(gtlakelat, gtlakelon, tol);  
dist = 1; % Buffer distance in degrees  
[latb, lonb] = bufferm(reducedlat, reducedlon, dist, 'out');  
[lati, loni] = bufferm(reducedlat, reducedlon, 0.3*dist, 'in');  
usamap({'MN','NY'})  
geoshow(latb, lonb, 'DisplayType', 'polygon',...  
         'FaceColor', 'yellow')  
geoshow(gtlakelat, gtlakelon,...  
         'DisplayType', 'polygon', 'FaceColor', 'blue')  
geoshow(lati, loni, 'DisplayType', 'polygon',...  
         'FaceColor', 'magenta')  
geoshow(uslat, uslon)  
geoshow(statelat, statelon)
```



**See Also**

polybool

# camposm

---

**Purpose** Set camera position using geographic coordinates

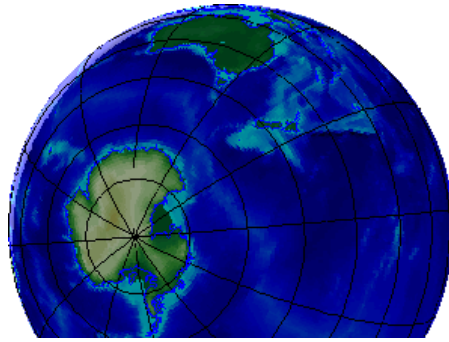
**Syntax**  
`camposm(lat, long, alt)`  
`[x, y, z] = camposm(lat, long, alt)`

**Description** `camposm(lat, long, alt)` sets the axes `CameraPosition` property of the current map axes to the position specified in geographic coordinates. The inputs `lat` and `long` are assumed to be in the angle units of the current map axes.

`[x, y, z] = camposm(lat, long, alt)` returns the camera position in the projected Cartesian coordinate system.

**Examples** Look at northern Australia from a point south and one Earth radius above New Zealand:

```
figure
axesm('globe', 'galt', 0)
gridm('glinestyle', '-')
load topo
geoshow(topo, topolegend, 'DisplayType', 'texturemap');
demcmap(topo)
camlight;
material(0.6*[ 1 1 1])
plat = -50; plon = 160;
tlat = -10; tlon = 130;
camtargm(tlat, tlon, 0);
camposm(plat, plon, 1);
camupm(tlat, tlon)
set(gca, 'CameraViewAngle', 75)
land = shaperead('landareas.shp', 'UseGeoCoords', true)
linem([land.Lat], [land.Lon])
axis off
```



**See Also**

camtargm, camupm, campos, camva

# camtargm

---

**Purpose** Set camera target using geographic coordinates

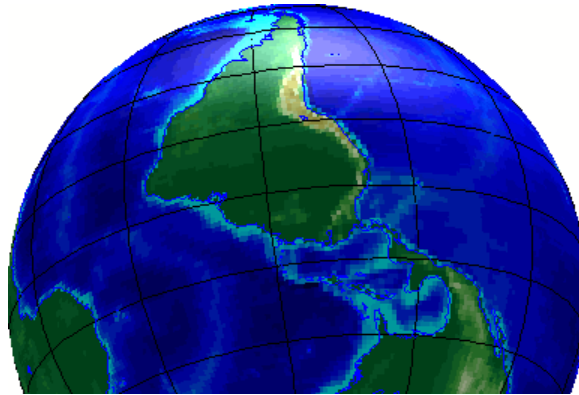
**Syntax**  
`camtargm(lat, long, alt)`  
`[x, y, z] = camtargm(lat, long, alt)`

**Description** `camtargm(lat, long, alt)` sets the axes `CameraTarget` property of the current map axes to the position specified in geographic coordinates. The inputs `lat` and `long` are assumed to be in the angle units of the current map axes.

`[x, y, z] = camtargm(lat, long, alt)` returns the camera target in the projected Cartesian coordinate system.

**Examples** Look down the spine of the Andes from a location three Earth radii above the surface:

```
figure
axesm('globe', 'galt', 0)
gridm('glinestyle', '-')
load topo
geoshow(topo, topolegend, 'DisplayType', 'texturemap');
demcmap(topo)
lightm(-80, -180);
material(0.6*[ 1 1 1])
plat = 10; plon = -65;
tlat = -30; tlon = -70;
camtargm(tlat, tlon, 0);
camposm(plat, plon, 3);
camupm(tlat, tlon);
camva(20)
set(gca, 'CameraViewAngle', 30)
land = shaperead('landareas.shp', 'UseGeoCoords', true)
linem([land.Lat], [land.Lon])
axis off
```



**See Also**

camposm, camupm, camtarget, camva

**Purpose** Set camera up vector using geographic coordinates

**Syntax**  
`camupm(lat, long)`  
`[x,y,z] = camupm(lat, long)`

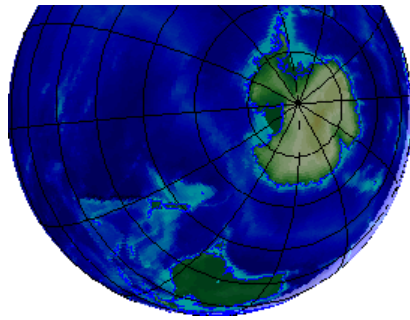
**Description** `camupm(lat, long)` sets the axes `CameraUpVector` property of the current map axes to the position specified in geographic coordinates. The inputs `lat` and `long` are assumed to be in the angle units of the current map axes.

`[x,y,z] = camupm(lat, long)` returns the camera position in the projected Cartesian coordinate system.

**Examples** Look at northern Australia from a point south of and one Earth radius above New Zealand. Set `CameraUpVector` to the antipode of the camera target for that *down under* view:

```
figure
axesm('globe','galt',0)
gridm('glinestyle','-')
load topo
geoshow(topo,topolegend,'DisplayType','texturemap');
demcmap(topo)
camlight;
material(0.6*[ 1 1 1])
plat = -50; plon = 160;
tlat = -10; tlon = 130;
[alat,alon] = antipode(tlat,tlon);
camtargm(tlat,tlon,0);
camposm(plat,plon,1);
camupm(alat,alon)
set(gca,'CameraViewAngle',80)
land = shaperead('landareas.shp','UseGeoCoords',true)
linem([land.Lat],[land.Lon])
axis off
```





**See Also**

cantargm, camposm, camup, camva

**Purpose** Transform projected coordinates to Greenwich system

**Syntax**

```
[lat,lon,alt] = cart2grn  
[lat,lon,alt] = cart2grn(hndl)  
[lat,lon,alt] = cart2grn(hndl,mstruct)
```

**Description** When objects are projected and displayed on map axes, they are plotted in Cartesian coordinates appropriate for the selected projection. This function transforms those coordinates back into the Greenwich frame, in which longitude is measured positively East from Greenwich (longitude 0), England and negatively West from Greenwich.

[lat,lon,alt] = cart2grn returns the latitude, longitude, and altitude data in geographic coordinates of the current map object, removing any clips or trims introduced during the display process from the output data.

[lat,lon,alt] = cart2grn(hndl) specifies the displayed map object desired with its handle hndl. The default handle is gco.

[lat,lon,alt] = cart2grn(hndl,mstruct) specifies the map structure associated with the object. The map structure of the current axes is the default.

**See Also** gcm, mfwdtran, minvtran, project

**Purpose** Substitute values in data array

**Syntax** `mapout = changem(Z,newcode,oldcode)`

**Description** `mapout = changem(Z,newcode,oldcode)` returns a data grid `mapout` identical to the input data grid, except that each element of `Z` with a value contained in the vector `oldcode` is replaced by the corresponding element of the vector `newcode`.

`oldcode` is 0 (scalar) by default, in which case `newcode` must be scalar. Otherwise, `newcode` and `oldcode` must be the same size.

**Examples** Invent a map:

```
A = magic(3)
```

```
A =
     8     1     6
     3     5     7
     4     9     2
```

Replace instances of 8 or 9 with 0s:

```
B = changem(A,[0 0],[9 8])
```

```
B =
     0     1     6
     3     5     7
     4     0     2
```

# circirc

---

**Purpose** Intersections of circles in Cartesian plane

**Syntax** `[xout,yout] = circirc(x1,y1,r1,x2,y2,r2)`

**Description** `[xout,yout] = circirc(x1,y1,r1,x2,y2,r2)` finds the points of intersection (if any), given two circles, each defined by center and radius in  $x$ - $y$  coordinates. In general, two points are returned. When the circles do not intersect or are identical, NaNs are returned.

When the two circles are tangent, two identical points are returned. All inputs must be scalars.

**See Also** `linecirc`

**Purpose** Add contour labels to map contour display

**Syntax**

```
h1 = clabelm(c,h)
h1 = clabelm(c,h,v)
h1 = clabelm(c,h,'manual')
h1 = clabelm(c), h1 = clabelm(c,v)
```

**Description** `h1 = clabelm(c,h)` rotates the labels and inserts them in line with the contour lines. The handles of the labels can be returned in `h1`.

`h1 = clabelm(c,h,v)` creates inline labels only for those levels specified in the vector `v`.

`h1 = clabelm(c,h,'manual')` places contour labels at locations you select with a mouse. You press the left mouse button (the only mouse button on a single-button mouse), or the space bar to label a contour at the closest location beneath the center of the cursor. Press the **Return** key while the cursor is within the figure window to terminate labeling. The labels are inserted in line with the contour lines.

`h1 = clabelm(c)`, `h1 = clabelm(c,v)`, and `h1 = clabelm(c,'manual')` operate as above, except that instead of rotating the labels and placing them in line with the contours, the labels are upright, and a + indicates the contour line the label is annotating.

The `clabelm` function adds height labels to a two-dimensional contour plot. By default, `clabelm` labels all displayed contours and randomly selects label positions.

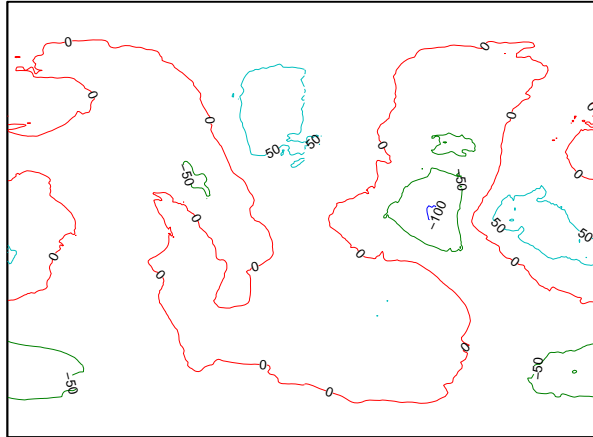
`c` is the contour matrix as described on the `contourm` reference page of this guide; `h` is the vector of handles for the displayed contours.

**Example**

```
load geoid
axesm miller
framem
tightmap
[c,h] = contourm(geoid,geoidlegend,-100:50:80);
clabelm(c,h)
```

# clabelm

---



## See Also

`clegendm`, `contourm`, `contour3m`, `clabel` (MATLAB function)

**Purpose** Add legend labels to map contour display

**Syntax**

```
clegendm(cs,h)
clegendm(cs,h,pos)
clegendm(...,unitstr)
clegendm(...,str)
```

**Description** The `clegendm` function displays a legend for a displayed contour map. `clegendm(cs,h)` displays a legend for the contour map defined by the two-column contour definition matrix, `cs`, and the handle(s) `h`. Both of these inputs are produced as the outputs of either `contourm` or `contour3m`. `clegendm(cs,h,pos)` allows you to specify the position of the legend in the display. The input `pos` can be any of the following integers, with the indicated result:

0	Automatic placement (this is the default)
1	Upper right corner
2	Upper left corner
3	Lower left corner
4	Lower right corner
-1	To the right of the plot

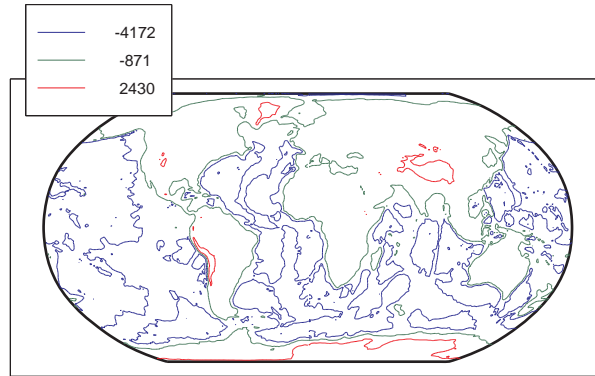
`clegendm(...,unitstr)` appends the character string `unitstr` to each entry in the legend.

`clegendm(...,str)` uses the strings specified in cell array `str` to label the legend. The cell array must have same number of entries as `h`.

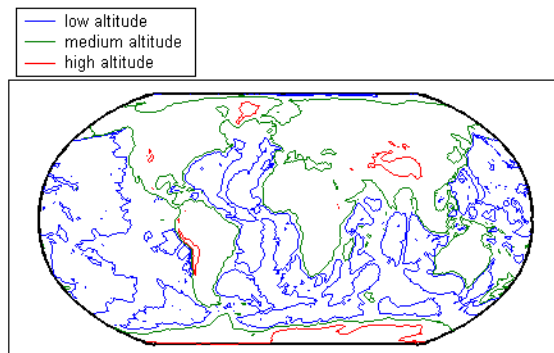
**Examples**

```
load topo
axesm robinson; framem
[cs,h] = contourm(topo,topolegend,3);
clegendm(cs,h,2)
```

# clegendm



```
% Example showing legend string usage
% Load topographic data measured in meters
load topo;
axesm robinson; framem
[cs,h] = contourm(topo,topolegend,3);
% Create Legend with user specified string
str = {'low altitude','medium altitude','high altitude'}
clegendm(cs,h,2,str);
```





**See Also**      `clabelm`, `contourm`, `contour3m`, `contourc` (MATLAB function)

# clipdata

---

**Purpose** Clip data at  $\pm \pi$  in longitude,  $\pm \pi$  in latitude

**Syntax** `[lat,long,splitpts] = clipdata(lat,long,'object')`

**Description** `[lat,long,splitpts] = clipdata(lat,long,'object')` inserts NaNs at the appropriate locations in a map object so that a displayed map is clipped at the appropriate edges. It assumes that the clipping occurs at  $\pm \pi/2$  radians in the latitude ( $y$ ) direction and  $\pm \pi$  radians in the longitude ( $x$ ) direction.

The input data must be in radians and properly transformed for the particular aspect and origin so that it fits in the specified clipping range.

The output data is in radians, with clips placed at the proper locations. The output variable `splitpts` returns the row and column indices of the clipped elements (columns 1 and 2 respectively). These indices are necessary to restore the original data if the map parameters or projection are ever changed.

Allowable object strings are:

- `surface` for clipping graticules
- `light` for clipping lights
- `line` for clipping lines
- `patch` for clipping patches
- `text` for clipping text object location points
- `point` for clipping point data
- `none` to skip all clipping operations

**See Also** `trimdata`, `undoclip`, `undotrim`

---

<b>Purpose</b>	Clear current map axes
<b>Syntax</b>	<code>clma</code> <code>clma all</code> <code>clma purge</code>
<b>Description</b>	<p><code>clma</code> deletes all displayed map objects from the current map axes but leaves the frame if it is displayed.</p> <p><code>clma all</code> deletes all displayed map objects, including the frame, but it leaves the map structure intact, thereby retaining the map axes.</p> <p><code>clma purge</code> clears all displayed map objects and converts the map axes to standard axes. This is equivalent to <code>cla reset</code>.</p>
<b>See Also</b>	<code>cla</code> (MATLAB function), <code>clmo</code> , <code>handlem</code> , <code>hidem</code> , <code>namem</code> , <code>showm</code> , <code>tagm</code>

# clmo

---

**Purpose** Clear specified graphics objects from map axes

**Syntax** `clmo`  
`clmo(handle)`  
`clmo(object)`

**Description** `clmo` deletes all displayed graphics objects on the current axes.  
`clmo(handle)` deletes those objects specified by their handles.  
`clmo(object)` deletes those objects with names identical to the input string. This can be any string recognized by the `handlem` function, including entries in the `Tag` property of each object, or the object `Type` if the `Tag` property is empty.

**See Also** `clma`, `handlem`, `hidem`, `namem`, `showm`, `tagm`

## Purpose

Close all rings in multipart polygon

## Syntax

```
[xdata, ydata] = closePolygonParts(xdata, ydata)
[lat, lon] = closePolygonParts(lat, lon, angleunits)
```

## Description

`[xdata, ydata] = closePolygonParts(xdata, ydata)` ensures that each ring in a multipart (NaN-separated) polygon is “closed” by repeating the start point at the end of each ring, unless the start and end points are already identical. Coordinate vectors `xdata` and `ydata` must match in size and have identical NaN locations.

`[lat, lon] = closePolygonParts(lat, lon, angleunits)` works with latitude-longitude data and accounts for longitude wrapping with a period of 360 if *angleunits* is 'degrees' and  $2\pi$  if *angleunits* is 'radians'. For a ring to be considered closed, the latitudes of its first and last vertices must match exactly, but their longitudes need only match modulo the appropriate period. Such rings are returned unaltered.

## Examples

### Closing a polygon in plane coordinates

```
xOpen = [1 0 2 NaN 0.5 0.5 1 1];
yOpen = [0 1 2 NaN 0.8 1 1 0.8];
[xClosed, yClosed] = closePolygonParts(xOpen, yOpen)
xClosed =
    Columns 1 through 7
    1.0000    0    2.0000    1.0000    NaN    0.5000    0.5000
    Columns 8 through 10
    1.0000    1.0000    0.5000

yClosed =
    Columns 1 through 7
    0    1.0000    2.0000    0    NaN    0.8000    1.0000
    Columns 8 through 10
    1.0000    0.8000    0.8000

whos
```

# closePolygonParts

---

Name	Size	Bytes	Class	Attributes
xClosed	1x10	80	double	
xOpen	1x8	64	double	
yClosed	1x10	80	double	
yOpen	1x8	64	double	

## Closing a polygon in latitude-longitude coordinates

```
% Construct a two-part polygon based on coast.mat. The first ring
% is Antarctica. The longitude of its first vertex is -180 and the
% longitude of its last vertex is 180. The second ring is a small
% island from which the last vertex, a replica of the first vertex,
% is removed.
c = load('coast.mat');
[latparts, lonparts] = polysplit(c.lat, c.long);
latparts{2}(end) = [];
lonparts{2}(end) = [];
latparts(3:end) = [];
lonparts(3:end) = [];
[lat, lon] = polyjoin(latparts, lonparts);

% Examine how closePolygonParts treats the two rings. In both
% cases, the first and last vertices differ. However, Antarctica
% remains unchanged while the small island is closed back up.
[latClosed, lonClosed] = closePolygonParts(lat, lon, 'degrees');
[latpartsClosed, lonpartsClosed] = polysplit(latClosed, lonClosed);
lonpartsClosed{1}(end) - lonpartsClosed{1}(1) % Result is 360
lonpartsClosed{2}(end) - lonpartsClosed{2}(1) % Result is 0
```

## See Also

`isshapemultipart`, `removeextrananseseparators`

**Purpose** Interactively define RGB color

---

**Note** colorui will be removed in a future release. Use `uicolor` instead.

---

**Syntax**

```
c = colorui
c = colorui(InitClr)
c = colorui(InitClr, FigTitle)
```

**Description** `c = colorui` will create an interface for the definition of an RGB color triplet. On Windows® platforms, `colorui` will produce the same interface as `uicolor`. On other machines, `colorui` produces a platform-independent dialog for specifying the color values.

`c = colorui(InitClr)` will initialize the color value to the RGB triple given in `initclr`.

`c = colorui(InitClr, FigTitle)` will use the string in `FigTitle` as the window label.

The output value `c` is the selected RGB triple if the **Accept** or **OK** button is pushed. If the user presses **Cancel**, then the output value is set to 0.

**See Also** `uicolor`

# combntns

---

**Purpose** All possible combinations of set of values

**Syntax** `combos = combntns(set,subset)`

**Description** `combos = combntns(set,subset)` returns a matrix whose rows are the various combinations that can be taken of the elements of the vector `set` of length `subset`. Many combinatorial applications can make use of a vector `1:n` for the input set to return generalized, indexed combination subsets.

The `combntns` function provides the combinatorial subsets of a set of numbers. It is similar to the mathematical expression *a choose b*, except that instead of the number of such combinations, the actual combinations are returned. In combinatorial counting, the ordering of the values is not significant.

The numerical value of the mathematical statement *a choose b* is `size(combos,1)`.

## Examples

How can the numbers 1 to 5 be taken in sets of three (that is, what is *5 choose 3*)?

```
combos = combntns(1:5,3)
```

```
combos =
```

```
1     2     3
1     2     4
1     2     5
1     3     4
1     3     5
1     4     5
2     3     4
2     3     5
2     4     5
3     4     5
```

```
size(combos,1) % "5 choose 3"
```

```
ans =
```



10

Note that if a value is repeated in the input vector, each occurrence is treated as independent:

```
combos = combntns([2 2 5],2)
```

```
combos =  
     2     2  
     2     5  
     2     5
```

**Remarks**

This is a recursive function.

# comet3m

---

**Purpose** Project 3-D comet plot on map axes

**Syntax** `comet3m(lat,lon,z)`  
`comet3m(lat,lon,z,p)`

**Description** `comet3m(lat,lon,z)` traces a comet plot through the points specified by the input latitude, longitude, and altitude vectors.  
`comet3m(lat,lon,z,p)` specifies a comet body of length `p*length(lat)`. The input `p` is 0.1 by default.

A comet plot is an animated graph in which a circle (the comet *head*) traces the data points on the screen. The comet *body* is a trailing segment that follows the head. The *tail* is a solid line that traces the entire function.

**Examples** Create a 3-D comet plot of the coastlines data:

```
load coast
z = (1:length(lat))'/3000;
axesm miller
framem; gridm;
setm(gca,'galtitude',max(z)+.5)
view(3)
comet3m(lat,long,z,0.01)
```

**See Also** `comet3`, `cometm`

---

<b>Purpose</b>	Project 2-D comet plot on map axes
<b>Syntax</b>	<pre>cometm(lat,lon) cometm(lat,lon,p)</pre>
<b>Description</b>	<p><code>cometm(lat,lon)</code> traces a comet plot through the points specified by the input latitude and longitude vectors.</p> <p><code>cometm(lat,lon,p)</code> specifies a comet body of length <math>p \times \text{length}(\text{lat})</math>. The input <code>p</code> is 0.1 by default.</p> <p>A comet plot is an animated graph in which a circle (the comet <i>head</i>) traces the data points on the screen. The comet <i>body</i> is a trailing segment that follows the head. The <i>tail</i> is a solid line that traces the entire function.</p>
<b>Examples</b>	<p>Create a comet plot of the coastlines data:</p> <pre>load coast axesm miller framem cometm(lat,lon,0.01)</pre>
<b>See Also</b>	<code>comet</code> , <code>comet3m</code>

**Purpose** Project 3-D contour plot of map data

**Syntax**

```
contour3m(Z,R)
contour3m(lat,lon,Z)
contour3m(Z,R,n) or contour3m(lat,lon,Z,n)
contour3m(Z,V,R) or contour3m(lat,lon,Z,V)
contour3m(..., linespec)
contour3m(..., prop1, val1, prop2, val2,...)
C = contour3m(...)
[C,h] = contour3m(...)
```

**Description** `contour3m(Z,R)` displays a contour plot of the regular M-by-N data grid, Z. R is either a 1-by-3 vector containing elements:

```
[cells/degree northern_latitude_limit western_longitude_limit]
```

or a 3-by-2 referencing matrix that transforms raster row and column indices to or from geographic coordinates according to:

```
[lon lat] = [row col 1] * R
```

If R is a referencing matrix, it must define a (non-rotational, non-skewed) relationship in which each column of the data grid falls along a meridian and each row falls along a parallel. If the current axis is a map axis, the coordinates of Z will be projected using the projection structure from the axis. The contours are drawn at their corresponding Z level. For more information about referencing vectors and matrices, see the section “Understanding Raster Geodata” in the User’s Guide.

`contour3m(lat,lon,Z)` displays a contour plot of the geolocated M-by-N data grid, Z. `lat` and `lon` can be the size of Z or can specify the corresponding row and column dimensions for Z.

`contour3m(Z,R,n)` or `contour3m(lat,lon,Z,n)` where `n` is a scalar, draws `n` contour levels.

`contour3m(Z,V,R)` or `contour3m(lat,lon,Z,V)` where `V` is a vector, draws contours at the levels specified by the input vector `v`. Use `V = [v v]` to compute a single contour at level `v`.

`contour3m(..., linespec)` uses any valid `LineStyle` string to draw the contour lines.

`contour3m(..., prop1, val1, prop2, val2,...)` specifies property/value pairs that modify `LINE` graphics properties. Property names can be abbreviated and are case-insensitive.

`C = contour3m(...)` returns a standard contour matrix, `C`, with the first row representing longitude data and the second row representing latitude data.

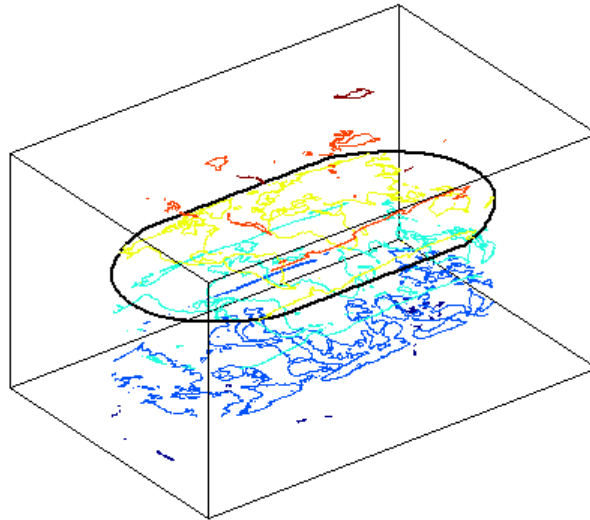
`[C,h] = contour3m(...)` returns the contour matrix and the line handles to the contour lines drawn onto the current axes.

## Examples

### Example 1

Make a default contour map of world topography data

```
load topo
axesm robinson; framem; view(3)
contour3m(topo,topolegend)
set(gca,'DataAspectRatio',[1 1 3000])
```

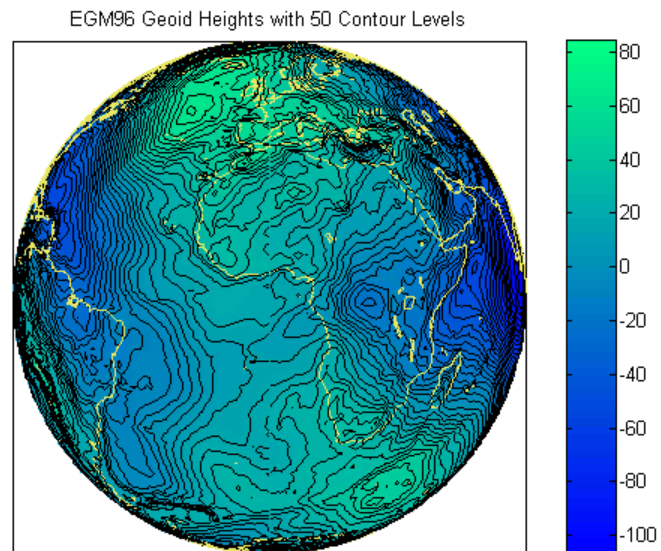


## Example 2

Contour EGM96 geoid heights as a 3-D surface with 50 levels, set contour patch edge color to black, show the geoid surface under and coastlines above the contour lines on an orthographic projection.

```
load geoid
axesm ortho
% Contour the geoid surface in black using 50 levels
[c,h]=contour3m(geoid, geoidrefvec, 50,'EdgeColor','black');
% Add the geoid surface.
hold on
geoshow(geoid,geoidrefvec,'DisplayType','surface')
% Add a title and colorbar.
title('EGM96 Geoid Heights with 50 Contour Levels');
colorbar
% Set the colormap to blue - green
colormap('winter')
% Set the Z-datum so that all contours show
zdatam(handlem('surface'),min(geoid(:)));
```

```
% Get world coastlines and plot them in gold
landareas = shaperead('landareas.shp','UseGeoCoords',true);
geoshow(landareas,'DisplayType','Polygon',...
        'FaceColor','None','EdgeColor',[.9 .9 .4])
```



### Example 3

Display the EGM96 geoid height contours in a default world map.

```
load geoid
figure
worldmap('world');

% Contour the geoid height with 10 levels and
% set the color to magenta.
[c,h]=contour3m(geoid, geoidrefvec, 10,'m');
```

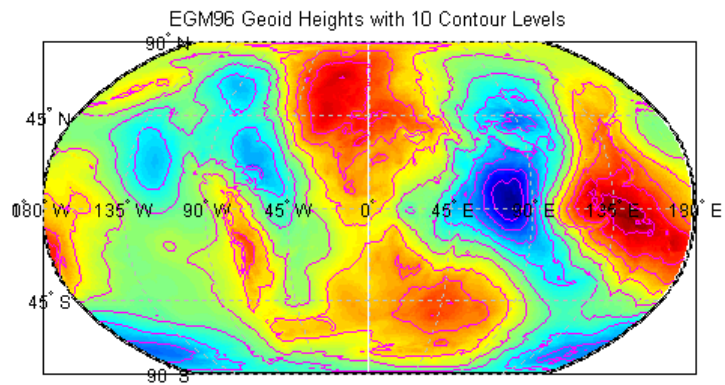
## contour3m

---

```
% Add the geoid surface.
hold on
geoshow(geoid,geoidrefvec,'DisplayType','surface')

% Set the surface to the minimum height of the geoid.
% to keep the contours visible.
zdatam(handlem('surface'),min(geoid(:)));

% Add a title.
title('EGM96 Geoid Heights with 10 Contour Levels');
```



### See Also

`clabel`, `clabelm`, `clegendm`, `contour`, `contour3`, `contourm`, `geoshow`, `plot`



<b>Purpose</b>	Contour colormap and colorbar current axes
<b>Syntax</b>	<pre>contourcmap(cdelta,cmap) contourcmap(cdelta,cmap,property,value,...) hcb = contourcmap(...)</pre>
<b>Description</b>	<p><code>contourcmap(cdelta,cmap)</code> creates a contour colormap for the current axes. A contour colormap is a colormap with color changes aligned to the color data. If <code>cdelta</code> is a scalar, contours are generated at multiples of <code>cdelta</code>. If <code>cdelta</code> is a vector of evenly spaced values, contours are generated at those values. The string input <code>cmap</code> is the name of the colormap function used in the surface. Valid entries for <code>cmap</code> include 'pink', 'hsv', 'jet', or any similar colormap function.</p> <p><code>contourcmap(cdelta,cmap,property,value,...)</code> allows you to add a colorbar and control the colorbar's properties. You turn the colorbar on with the property-value pair 'Colorbar' and 'on'. The location of the colorbar is controlled by the 'Location' property. Valid entries for Location are 'vertical' (the default) or 'horizontal'. Properties 'TitleString', 'XLabelString', 'YLabelString' and 'ZLabelString' set the respective strings. Property 'ColorAlignment' controls whether the colorbar labels are centered on the color bands or the color breaks. Valid values for ColorAlignment are 'center' or 'ends'. Property 'SourceObject' controls which object is used to determine the color limits for the colormap. The SourceObject value is the handle of a currently displayed object. If omitted, gca is used. Other valid property-value pairs are any properties and values that can be applied to the title and labels of the colorbar axes.</p> <p><code>hcb = contourcmap(...)</code> returns a handle to the colorbar.</p>
<b>Example</b>	<p>Create a colormap and set color limits to make the color changes occur at multiples of 20 for the geoid.</p> <pre>load geoid figure worldmap(geoid, geoidrefvec) contourm(geoid, geoidrefvec, -120:20:100);</pre>

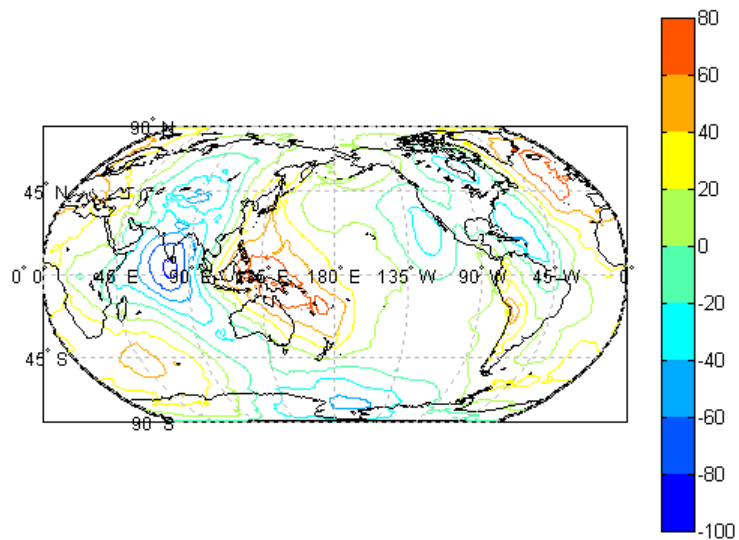
# contourmap

Add a colorbar, controlling the labels and font properties.

```
contourmap(20, 'jet', 'colorbar', 'on');
```

Load and plot coastlines on top.

```
load coast  
plotm(lat, long, 'k')
```



## See Also

`contourfm`, `contourm`, `lcolorbar`, `demcmap`

**Purpose**

Project filled 2-D contour plot of map data

**Syntax**

```
contourfm(lat,lon,Z)
contourfm(Z,R)
contourfm(lat,lon,Z,n,...)
contourfm(...,v,...)
contourfm(...,LineSpec)
c = contourfm(...)
[c,h] = contourfm(...)
```

**Description**

`contourfm(lat,lon,Z)` produces a contour plot of map data projected onto the current map axes. The input latitude and longitude vectors can be the size of `Z` (as in a geolocated data grid), or can specify the corresponding row and column dimensions for the map.

`contourfm(Z,R)` creates a contour plot of the regular data grid, `Z`. `R` is either a 1-by-3 vector containing elements:

```
[cells/degree northern_latitude_limit western_longitude_limit]
```

or a 3-by-2 referencing matrix that transforms raster row and column indices to or from geographic coordinates according to:

```
[lon lat] = [row col 1] * R
```

If `R` is a referencing matrix, it must define a (non-rotational, non-skewed) relationship in which each column of the data grid falls along a meridian and each row falls along a parallel. For more information about referencing vectors and matrices, see the section “Understanding Raster Geodata” in the User’s Guide.

`contourfm(lat,lon,Z,n,...)` draws `n` contour levels, where `n` is a scalar.

`contourfm(...,v,...)` draws contours at the levels specified by the input vector `v`.

`contourfm(...,LineSpec)` uses any valid *LineSpec* string to draw the contour lines.

# contourfm

---

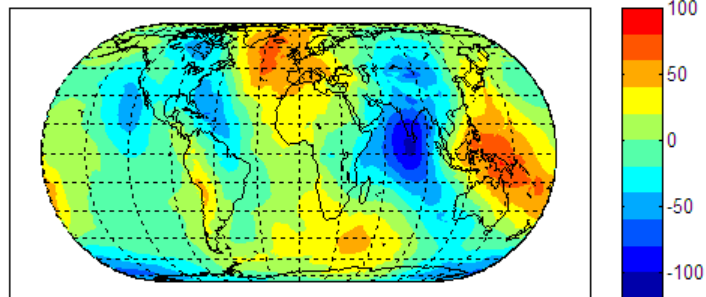
`c = contourfm(...)` returns a standard contour matrix, with the first row representing longitude data and the second row representing latitude data.

`[c,h] = contourfm(...)` returns the contour matrix and an array of handles to the contour patches drawn.

## Examples

Plot the Earth's geoid with filled contours. The data is in meters.

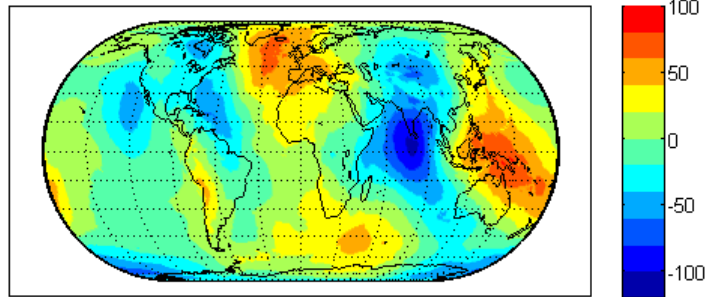
```
load geoid
figure
axesm eckert4
framem;gridm
load coast
plotm(lat,long,'k')
caxis([-120 100]);colormap(jet(11));colorbar
contourfm(geoid,geoidrefvec,-120:20:100);
```



You can reproduce the filled contour display by using a surface instead of the patches created by `contourfm`.

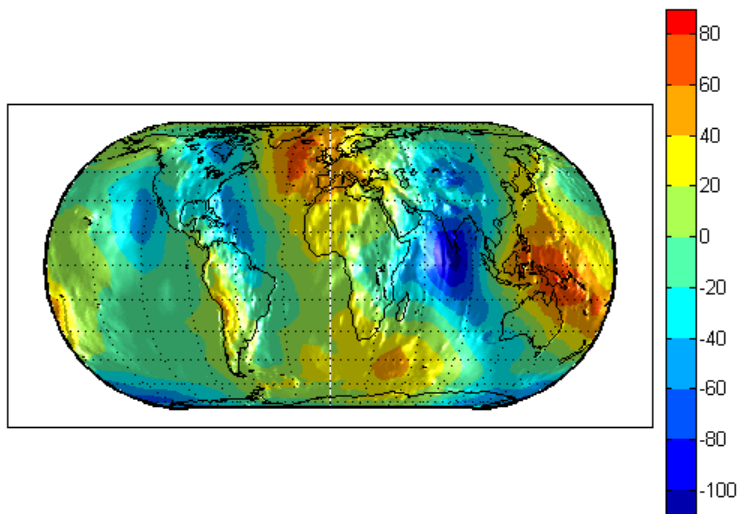
```
figure
axesm eckert4
framem;gridm
load coast
plotm(lat,long,'k')
```

```
meshm(geoid,geoidrefvec,size(geoid),'Facecolor','interp')
contourcmap(20,'jet');colorbar
```



Surfaces also allow use of lighting to bring out the smaller variations in the data.

```
clmo surface
meshm(geoid,geoidrefvec,size(geoid),geoid,'Facecolor','interp')
light;lighting phong; material(0.6*[ 1 1 1])
set(gca,'dataaspectratio',[ 1 1 200])
gridm reset
zdatam(handlem('line'),max(geoid(:)))
```



## Limitations

`contourfm` might not fill properly with azimuthal projections.

## Remarks

By default, filled contour patches are displayed with no edge lines. To add contour lines, supply a `lineSpec` or specify an `EdgeColor` to `contourfm`. An `EdgeColor` may also be set later.

In most circumstances, contour plots made with surfaces are preferable to the filled patches created by `contourfm`. Surfaces are rendered more quickly and take less time to project and reproject. The use of surfaces also allows surface lighting to create shaded 3-D maps.

## See Also

`contourm`, `contour3m`, `clabelm`, `meshm`, `surfm`

**Purpose**

Project 2-D contour plot of map data

**Syntax**

```
contourm(Z, R)
contourm(lat, lon, Z)
contourm(Z, R, n)
contourm(Z, R, V) or contourm(lat, lon, Z, V)
contourm(..., linespec)
contourm(..., prop1, val1, prop2, val2,...)
C = contourm(...)
[C,h] = contourm(...)
```

**Description**

`contourm(Z, R)` creates a contour plot of the regular M-by-N data grid, Z. R is either a 1-by-3 vector containing elements:

```
[cells/degree northern_latitude_limit western_longitude_limit]
```

or a 3-by-2 referencing matrix that transforms raster row and column indices to or from geographic coordinates according to:

$$[\text{lon lat}] = [\text{row col 1}] * R$$

If R is a referencing matrix, it must define a (non-rotational, non-skewed) relationship in which each column of the data grid falls along a meridian and each row falls along a parallel. For more information about referencing vectors and matrices, see the section “Understanding Raster Geodata” in the User’s Guide.

If the current axis is a map axis, the coordinates of Z will be projected using the projection structure from the axis. The contours are drawn at their corresponding Z level.

`contourm(lat, lon, Z)` displays a contour plot of the geolocated M-by-N data grid, Z. `lat` and `lon` can be the size of Z or can specify the corresponding row and column dimensions for Z.

`contourm(Z, R, n)` or `contourm(lat,lon,Z,n)` where `n` is a scalar, draws `n` contour levels.

# contourm

---

`contourm(Z, R, V)` or `contourm(lat, lon, Z, V)` where `V` is a vector, draws contours at the levels specified by the input vector `v`. Use `V = [v v]` to compute a single contour at level `v`.

`contourm(..., linespec)` uses any valid `LineStyle` string to draw the contour lines.

`contourm(..., prop1, val1, prop2, val2, ...)` specifies property/value pairs that modify `contourgroup` graphics properties. Property names can be abbreviated and are case-insensitive.

`C = contourm(...)` returns a standard contour matrix, `C`, with the first row representing longitude data and the second row representing latitude data.

`[C,h] = contourm(...)` returns the contour matrix and the handle to the contour patches drawn onto the current axes. The handle is type `hggroup`.

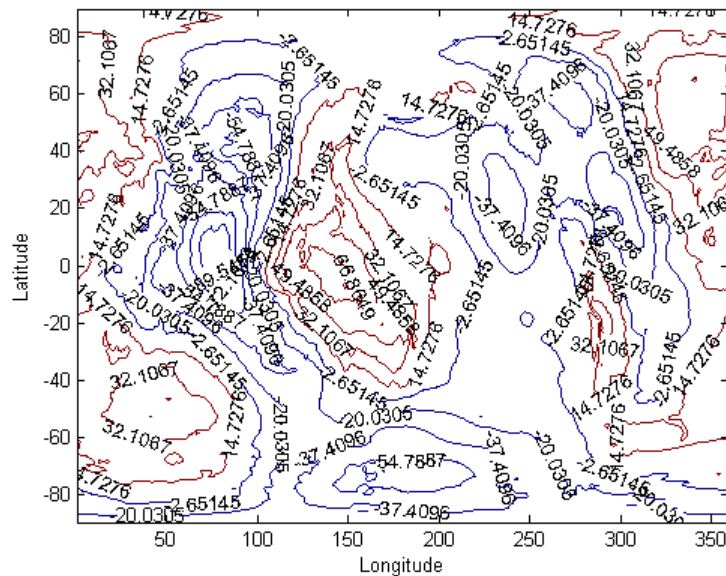
## Examples

### Example 1

Contour EGM96 geoid heights as dotted lines and with 10 levels and set the contour labels on.

```
load geoid
figure
contourm(geoid, geoidrefvec, 10, ':','ShowText','on');
xlabel('Longitude');
ylabel('Latitude');
```





## Example 2

Contour the Korean bathymetry and elevation data:

```
% Load the data.
load korea;
load geoid;

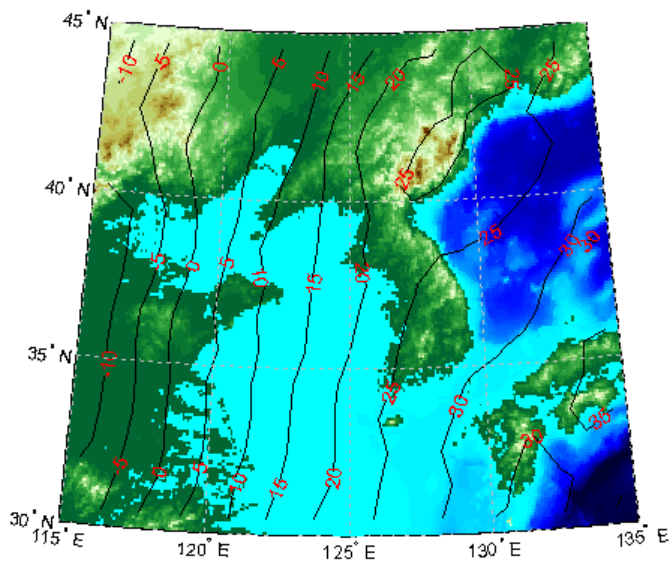
% Create a worldmap of Korea.
figure
worldmap(map, refvec);

% Display the digital elevation data and colormap.
geoshow(map, refvec, 'DisplayType', 'surface');
colormap(demcmap(map));
% Contour the geoid values from -100 to 100 in increments of 5.
[c,h] = contourm(geoid, geoidlegend, -100:5:100, 'k');
```

## contourm

---

```
% Add red labels to the contours.  
ht=clabel(c,h);  
set(ht,'Color','r');
```



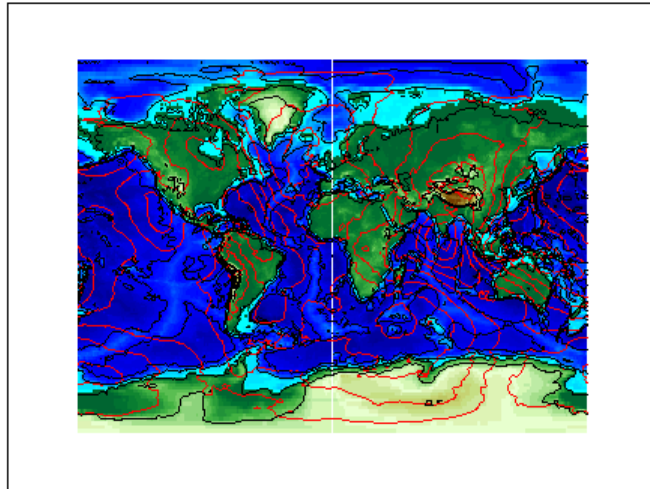
### Example 3

Contour the geoid and topography heights:

```
% Load the data.  
load topo  
load geoid  
  
% Create a Miller projection with geoid contours as red lines,  
% and topography contours as black lines.  
figure; axesm miller  
hold on  
contourm(geoid, geoidrefvec, 'r');  
contourm(topo, topolegend, 'k');
```

```
% Add the topography surface and color map.  
geoshow(topo, topolegend, 'DisplayType', 'surface')  
colormap(demcmap(topo))  
  
% Set the surface as the lowest value of topo  
% to keep the contour lines visible.  
zdatam(handlem('surface'), min(topo(:)))  
  
% Add a title  
title('Contour Plot of Topography and Geoid Heights');
```

Contour Plot of Topography and Geoid Heights

**See Also**

`clabelm`, `clegendm`, `contour`, `contourc`, `contour3`, `contour3m`,  
`geoshow`, `plot`

# convertlat

---

**Purpose** Convert between geodetic and auxiliary latitudes

**Syntax** `latout = convertlat(ellipsoid,latin,from,to,units)`

**Description** `latout = convertlat(ellipsoid,latin,from,to,units)` converts latitude values in `latin` from type FROM to type TO. `ellipsoid` is a 1-by-2 ellipsoid vector of the form [semimajoraxis eccentricity]. (The `almanac` function offers a set of built-in ellipsoids covering most widely available map data.)

`latin` is an array of input latitude values. `from` and `to` are each one of the latitude type strings listed below (or unambiguous abbreviations). `latin` has the angle units specified by `units`: either 'degrees', 'radians', or unambiguous abbreviations. The output array, `latout`, has the same size and units as `latin`.

Latitude Type	Description
geodetic	The geodetic latitude is the angle that a line perpendicular to the surface of the ellipsoid at the given point makes with the equatorial plane.
authalic	The authalic latitude maps an ellipsoid to a sphere while preserving surface area. Authalic latitudes are used in place of the geodetic latitudes when projecting the ellipsoid using an equal area projection.
conformal	The conformal latitude maps an ellipsoid conformally onto a sphere. Conformal latitudes are used in place of the geodetic latitudes when projecting the ellipsoid with a conformal projection.
geocentric	The geocentric latitude is the angle that a line connecting a point on the surface of the ellipsoid to its center makes with the equatorial plane.

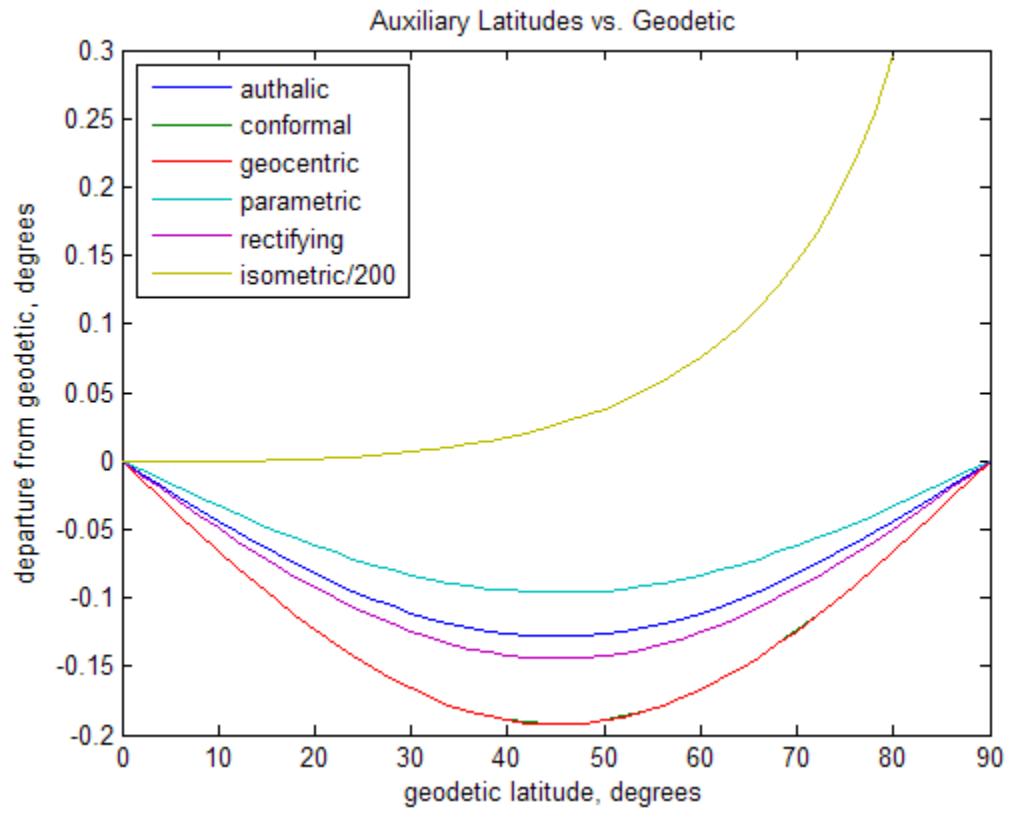
Latitude Type	Description
isometric	The isometric latitude is a nonlinear function of the geodetic latitude.
parametric	The parametric latitude of a point on the ellipsoid is the latitude on a sphere of radius $a$ , where $a$ is the semimajor axis of the ellipsoid, for which the parallel has the same radius as the parallel of geodetic latitude.
rectifying	The rectifying latitude is used to map an ellipsoid to a sphere in such a way that distance is preserved along meridians.

To properly project rectified latitudes, the radius must also be scaled to ensure the equal meridional distance property. This is accomplished by `rsphere`.

### Example

```
% Plot the difference between the auxiliary latitudes
% and geocentric latitude, from equator to pole,
% using the GRS 80 ellipsoid. Avoid the polar region with
% the isometric latitude, and scale down the difference
% by a factor of 200.
grs80 = almanac('earth','ellipsoid','m','grs80');
geodetic = 0:2:90;
authalic = ...
convertlat(grs80,geodetic,'geodetic','authalic','deg');
conformal = ...
convertlat(grs80,geodetic,'geodetic','conformal','deg');
geocentric = ...
convertlat(grs80,geodetic,'geodetic','geocentric','deg');
parametric = ...
convertlat(grs80,geodetic,'geodetic','parametric','deg');
rectifying = ...
convertlat(grs80,geodetic,'geodetic','rectifying','deg');
isometric = ...
convertlat(grs80,geodetic(1:end-5), ...
```

```
'geodetic','isometric','deg');
plot(geodetic, (authalic - geodetic),...
geodetic, (conformal - geodetic),...
geodetic, (geocentric - geodetic),...
geodetic, (parametric - geodetic),...
geodetic, (rectifying - geodetic),...
geodetic(1:end-5), (isometric - geodetic(1:end-5))/200);
title('Auxiliary Latitudes vs. Geodetic')
xlabel('geodetic latitude, degrees')
ylabel('departure from geodetic, degrees');
legend('authalic','conformal','geocentric', ...
'parametric','rectifying', 'isometric/200',...
'Location','NorthWest');
```



**See Also** [almanac](#), [rsphere](#)

# crossfix

---

## Purpose

Cross-fix positions from bearings and ranges

## Syntax

```
[newlat,newlon] = crossfix(lat,long,az)
[newlat,newlon] = crossfix(lat,long,az_range,case)
[newlat,newlon] = crossfix(lat,long,az_range,case,drlat,
    drlong)
[newlat,newlon] = crossfix(lat,long,az,units)
[newlat,newlon] = crossfix(lat,long,az_range,case,units)
[newlat,newlon] = crossfix(lat,long,az_range,drlat,drlong,
    units)
[newlat,newlon] = crossfix(lat,long,az_range,case,drlat,
    drlong,units)
mat = crossfix(...)
```

## Description

`[newlat,newlon] = crossfix(lat,long,az)` returns the intersection points of all pairs of great circles passing through the points given by the column vectors `lat` and `long` that have azimuths `az` at those points. The outputs are two-column matrices `newlat` and `newlon` in which each row represents the two intersections of a possible pairing of the input great circles. If there are  $n$  input objects, there will be  $n$  choose 2 pairings.

`[newlat,newlon] = crossfix(lat,long,az_range,case)` allows the input `az_range` to specify either azimuths or ranges. Where the vector `case` equals 1, the corresponding element of `az_range` is an azimuth; where `case` is 0, `az_range` is a range. The default value of `case` is a vector of ones (azimuths).

`[newlat,newlon] = crossfix(lat,long,az_range,case,drlat,drlong)` resolves the ambiguities when there is more than one intersection between two objects. The scalar-valued `drlat` and `drlong` provide the location of an estimated (dead reckoned) position. The outputs `newlat` and `newlon` are column vectors in this case, returning only the intersection closest to the estimated point. When this option is employed, if any pair of objects fails to intersect, no output is returned and the warning `No Fix` is displayed.



```
[newlat,newlon] =
crossfix(lat,long,az,units), [newlat,newlon] =
crossfix(lat,long,az_range,case,units), [newlat,newlon] =
crossfix(lat,long,az_range,drlat,drlong,units),
and [newlat,newlon] =
crossfix(lat,long,az_range,case,drlat,drlong,units) allow
the specification of the angle units to be used for all angles
and ranges, where units is any valid angle units string. The
default value of units is 'degrees'.
```

`mat = crossfix(...)` returns the output in a two- or four-column matrix `mat`.

This function calculates the points of intersection between a set of objects taken in pairs. Given great circle azimuths and/or ranges from input points, the locations of the possible intersections are returned. This is different from the navigational function `navfix` in that `crossfix` uses great circle measurement, while `navfix` uses rhumb line azimuths and nautical mile distances.

## Example

Where do the small circles defined as all points  $8^\circ$  in distance from the points  $(0^\circ,0^\circ)$ ,  $(5^\circ\text{N},5^\circ\text{E})$ , and  $(0^\circ,10^\circ\text{E})$  intersect?

```
figure('color','w');
ha = axesm('mapproj','mercator', ...
    'maplatlim',[-10 15], 'maplonlim',[-10 20],...
    'MLineLocation',2, 'PLineLocation',2);
axis off, gridm on, framem on;
mlabel on, plabel on;
latpts = [0;5;0];           % Define latitudes of three arbitrary points
lonpts = [0;5;10];          % Define longitudes of three arbitrary points
radii = [8;8;8];            % Define three radii, all 8 degrees

% Obtain intersections of imagined small circles around these points
[newlat,newlon] = crossfix(latpts,lonpts,radii,[0;0;0])

% Draw red circle markers at the given points
geoshow(latpts,lonpts,'DisplayType','point',...
```

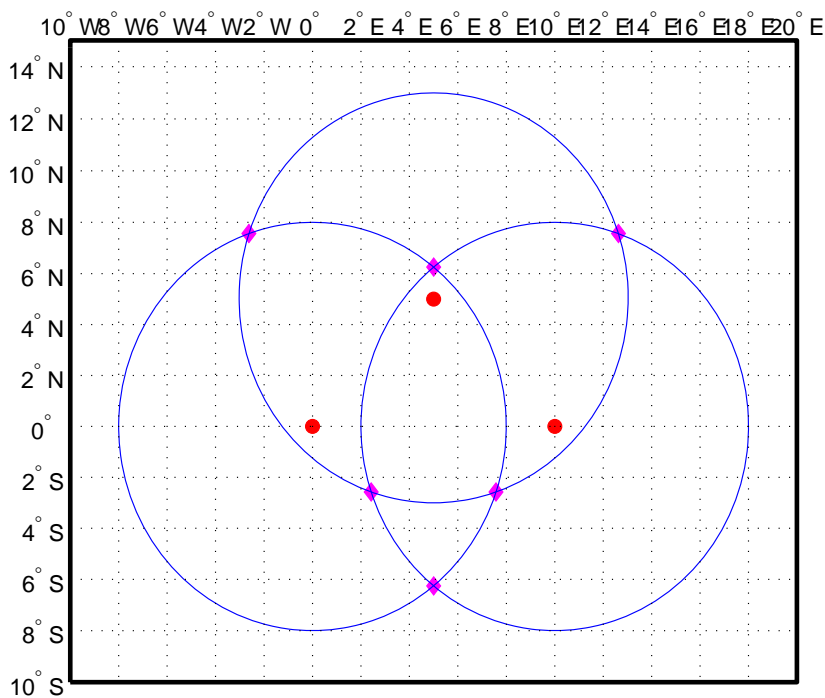
```
'markeredgecolor','r','markerfacecolor','r','marker','o')

% Draw magenta diamond markers at intersection points just found
geoshow(reshape(newlat,6,1),reshape(newlon,6,1),'DisplayType','point',...
        'markeredgecolor','m','markerfacecolor','m','marker','d')

% Generate a small circle 8 deg radius for each original point
[latc1,lonc1] = scircle1(latpts(1),lonpts(1),radii(1));
[latc2,lonc2] = scircle1(latpts(2),lonpts(2),radii(2));
[latc3,lonc3] = scircle1(latpts(3),lonpts(3),radii(3));

% Plot the small circles to show the intersections are as determined
geoshow(latc1,lonc1,'DisplayType','line',...
        'color','b','linestyle','-')
geoshow(latc2,lonc2,'DisplayType','line',...
        'color','b','linestyle','-')
geoshow(latc3,lonc3,'DisplayType','line',...
        'color','b','linestyle','-')
```

The diagram shows why there are six intersections:



If a dead reckoning position is provided, say (0°,5°E), then one from each pair is returned (the closest one):

```
[newlat,newlong] = crossfix([0 5 0]',[0 5 10]',...
                             [8 8 8]',[0 0 0]',0,5)
```

```
newlat =
    -2.5744
     6.2529
    -2.5744
```

```
newlong =
     7.5770
     5.0000
```

# crossfix

---

2.4230

## **See Also**

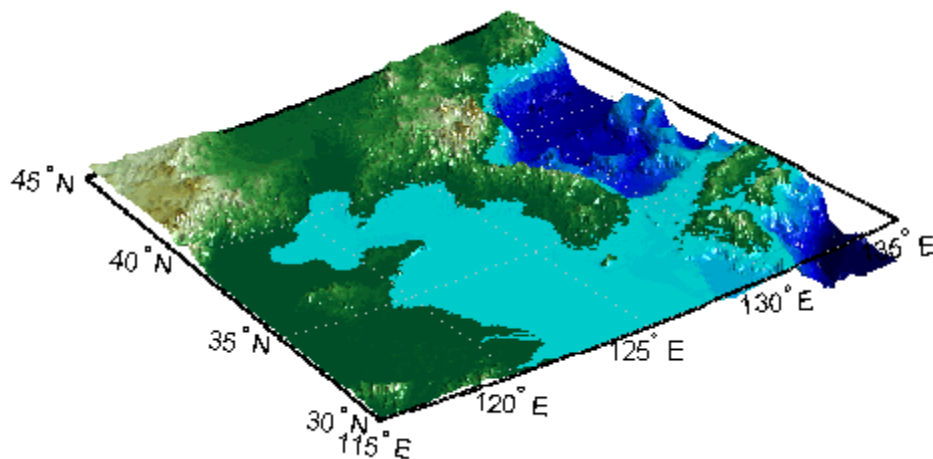
gcxgc, gcxsc, scxsc, rhxrh, polyxpoly, navfix

<b>Purpose</b>	Control vertical exaggeration in map display
<b>Syntax</b>	<pre>daspectm(<i>zunits</i>) daspectm(<i>zunits</i>,<i>vfac</i>) daspectm(<i>zunits</i>,<i>vfac</i>,<i>lat</i>,<i>long</i>) daspectm(<i>zunits</i>,<i>vfac</i>,<i>lat</i>,<i>long</i>,<i>az</i>) daspectm(<i>zunits</i>,<i>vfac</i>,<i>lat</i>,<i>long</i>,<i>az</i>,<i>gunits</i>) daspectm(<i>zunits</i>,<i>vfac</i>,<i>lat</i>,<i>long</i>,<i>az</i>,<i>gunits</i>,<i>radius</i>)</pre>
<b>Description</b>	<p><code>daspectm(<i>zunits</i>)</code> sets the figure 'DataAspectRatio' property so that the <i>z</i>-axis is in proportion to the <i>x</i>- and <i>y</i>-projected coordinates. This permits elevation data to be displayed without vertical distortion. The string <i>zunits</i> specifies the units of the elevation data, and can be any string recognized by <code>unitsratio</code>.</p> <p><code>daspectm(<i>zunits</i>,<i>vfac</i>)</code> sets the 'DataAspectRatio' property so that the <i>z</i>-axis is vertically exaggerated by the factor <i>vfac</i>. If omitted, the default is no vertical exaggeration.</p> <p><code>daspectm(<i>zunits</i>,<i>vfac</i>,<i>lat</i>,<i>long</i>)</code> sets the aspect ratio based on the local map scale at the specified geographic location. If omitted, the default is the center of the map limits.</p> <p><code>daspectm(<i>zunits</i>,<i>vfac</i>,<i>lat</i>,<i>long</i>,<i>az</i>)</code> also specifies the direction along which the scale is computed. If omitted, 90 degrees (west) is assumed.</p> <p><code>daspectm(<i>zunits</i>,<i>vfac</i>,<i>lat</i>,<i>long</i>,<i>az</i>,<i>gunits</i>)</code> also specifies the units in which the geographic position and direction are given. If omitted, 'degrees' is assumed.</p> <p><code>daspectm(<i>zunits</i>,<i>vfac</i>,<i>lat</i>,<i>long</i>,<i>az</i>,<i>gunits</i>,<i>radius</i>)</code> uses the last input to determine the radius of the sphere. If <i>radius</i> is a string, then it is evaluated as an almanac body to determine the spherical radius. If numerical, it is the radius of the desired sphere in <i>zunits</i>. If omitted, the default radius of the Earth is used.</p>
<b>Example</b>	Show the elevation map of the Korean peninsula with a vertical exaggeration factor of 30:

# daspectm

---

```
load korea
[latlim,lonlim] = limitm(map,refvec);
worldmap(latlim,lonlim)
meshm(map,refvec,size(map),map)
demcmap(map)
view(3)
daspectm('m',30)
tightmap
camlight
```



## Limitations

The relationship between the vertical and horizontal coordinates holds only as long as the `geoid` or `scale factor` properties of the map axes remain unchanged. If you change the scaling between geographic coordinates and projected axes coordinates, execute `daspectm` again.

## See Also

`daspect`, `paperscale`

**Purpose**

Read selected DCW worldwide basemap data

**Syntax**

```
struct = dcwdata(library,latlim,lonlim,theme,topolevel1)
struct = dcwdata(devicename,library,...)
[struct1, struct2,...] =
dcwdata(...,{topolevel1,topolevel2,
...})
```

**Description**

`struct = dcwdata(library,latlim,lonlim,theme,topolevel1)` reads data for the specified theme and topology level directly from the DCW CD-ROM. There are four CDs, one for each of the libraries: 'NOAMER' (North America), 'SASAUS' (Southern Asia and Australia), 'EURNASIA' (Europe and Northern Asia), and 'SOAMAFR' (South America and Africa). The desired theme is specified by a two-letter code string. A list of valid codes is displayed when an invalid code, such as '?', is entered. The region of interest can be given as a point latitude and longitude or as a region with two-element vectors of latitude and longitude limits. The units of latitude and longitude are degrees. The data covering the requested region is returned, but will include data extending to the edges of the 5-by-5 degree tiles. The result is returned as a Version 1 Mapping Toolbox display structure.

`struct = dcwdata(devicename,library,...)` specifies the logical device name of the CD-ROM for computers that do not automatically name the mounted disk.

`[struct1, struct2,...] = dcwdata(...,{topolevel1,topolevel2,...})` reads several topology levels. The levels must be specified as a cell array with the entries 'patch', 'line', 'point', or 'text'. Entering {'all'} for the topology level argument is equivalent to {'patch', 'line', 'point', 'text'}. Upon output, the data structures are returned in the output arguments by topology level in the same order as they were requested.

**Background**

The Digital Chart of the World (DCW) is a detailed and comprehensive source of publicly available global vector data. It was digitized from the Operational Navigation Charts (scale 1:1,000,000) and Jet Navigation

Charts (1:2,000,000), compiled by the U.S. Defense Mapping Agency (DMA) along with mapping agencies in Australia, Canada, and the United Kingdom. The digitized data was published on four CD-ROMS by the DMA and is distributed by the U.S. Geological Survey (USGS).

The DCW is out of print and has been succeeded by the Vector Map Level 0 (VMAPO).

The DCW organizes data into 17 different themes, such as political/oceans (PO), drainage (DN), roads (RD), or populated places (PP). The data is further tiled into 5-by-5 degree tiles and separated by topology level (patches, lines, points, and text).

## Remarks

Latitudes and longitudes use WGS84 as a horizontal datum. Elevations are in feet above mean sea level. The data set does not contain bathymetric data.

Some DCW themes do not contain all topology levels. In those cases, empty matrices are returned.

The data is tagged with strings describing the objects. Some data is provided with alternate tags in `tag2` and `tag3` fields. These alternate tags contain information that supplements the standard tag, such as the names of political entities or values of elevation. The `tag2` field generally has the actual values or codes associated with the data. If the information in the `tag2` field expands to more verbose descriptions, these are provided in the `tag3` field.

Point data for which there are descriptions of both the type and the individual names of objects is returned twice within the structure. The first set is a collection of points of the same type with appropriate tag. The second is a set of individual points with the tag 'Individual Points' and the name of the object in the `tag2` field.

Patches are broken at the tile boundaries. Setting the `EdgeColor` to 'none' and plotting the lines gives the map a normal appearance.

The DCW was published in 1992 based on data compiled some years earlier. The political boundaries do not reflect recent changes such as the dissolution of the Soviet Union, Czechoslovakia, and Yugoslavia.



In some cases, the boundaries of the successor nations are present as lower level political units. A new version, called VMAP0.

For information about the format of display structures, see “Version 1 Display Structures” on page 3-144 in the reference page for displaym.

## Examples

On a Macintosh® computer,

```
s = dcwdata('NOAMER',41,-69,'?','patch');

??? Error using ==> dcwdata
Theme not present in library NOAMER
Valid two-letter theme identifiers are:
PO: Political/Oceans
PP: Populated Places
LC: Land Cover
VG: Vegetation
RD: Roads
RR: Railroads
UT: Utilities
AE: Aeronautical
DQ: Data Quality
DN: Drainage
DS: Supplemental Drainage
HY: Hypsography
HS: Supplemental Hypsography
CL: Cultural Landmarks
OF: Ocean Features
PH: Physiography
TS: Transportation Structure
POpatch = dcwdata('NOAMER',[41 44],[-72 -69],'PO','patch')
POpatch =
1x234 struct array with fields:
    type
    otherproperty
    tag
    altitude
```

```
lat
long
tag2
tag3
```

On an MS-DOS based operating system with the CD-ROM as the 'd:' drive,

```
[RDtext,RDline] = dcwdata('d:', 'SASAU', [-48 -34], [164 180], ...
    'RD', {'text', 'line'});
```

On a UNIX® operating system with the CD-ROM mounted as '\cdrom',

```
[POpatch,POline,POpoint,POtext] = dcwdata('\cdrom', ...
    'EURNASIA', -48 ,164, 'PO', {'all'});
```

## References

The format and the history of the DCW are described in reference [1] of the “Bibliography” at the end of this chapter.

## See Also

dcwgaz, dcwread, dcwrhead, displaym, extractm, mlayers, updategeostruct, vmap0data

<b>Purpose</b>	Search DCW worldwide basemap gazette file
<b>Syntax</b>	<pre>dcwgaz(<i>library</i>,<i>object</i>) dcwgaz(<i>devicename</i>,<i>library</i>,<i>object</i>) mtextstruc = dcwgaz(...) [mtextstruc,mpointstruc] = dcwgaz(...)</pre>
<b>Description</b>	<p><code>dcwgaz(<i>library</i>,<i>object</i>)</code> searches the DCW library for items beginning with the <i>object</i> string. There are four CDs, one for each of the libraries: 'NOAMER' (North America), 'SASAUS' (Southern Asia and Australia), 'EURNASIA' (Europe and Northern Asia), and 'SOAMAFR' (South America and Africa). Items that exactly match or begin with the <i>object</i> string are displayed on screen.</p> <p><code>dcwgaz(<i>devicename</i>,<i>library</i>,<i>object</i>)</code> specifies the logical device name of the CD-ROM for computers that do not automatically name the mounted disk.</p> <p><code>mtextstruc = dcwgaz(...)</code> displays the matched items on screen and returns a Mapping Toolbox display structure with the matches as text entries.</p> <p><code>[mtextstruc,mpointstruc] = dcwgaz(...)</code> returns the matches in structures formatted both as text and as points.</p>
<b>Background</b>	<p>In addition to the geographic data, the Digital Chart of the World (DCW) also includes an extensive gazette feature. The gazette is a collection of the names of geographic items mentioned in the various themes of a DCW disk. One DCW disk can contain about 10,000 to 15,000 names. This function allows you to search the gazette for names beginning with a particular string.</p>
<b>Remarks</b>	<p>The search is not case sensitive. Items that match are those that begin with the <i>object</i> string. Spaces are significant.</p>
<b>Examples</b>	<p>On a Macintosh computer,</p> <pre>s = dcwgaz('EURNASIA','apatin')</pre>

```
APATIN
s =
    type: 'text'
  otherproperty: {1x2 cell}
    tag: 'Built up area'
  string: 'APATIN'
  altitude: []
    lat: 45.6660
    long: 18.9830
```

On a UNIX operating system with the CD-ROM mounted as '`\cdrom`',

```
[mtextstruc,mpointstruc] = ...
    dcwgaz('\cdrom','SOAMAFR', 'cape good')
```

```
Cape Goodenough
Cape Goodenough
Cape Goodenough
mtextstruc =
1x3 struct array with fields:
    type
  otherproperty
    tag
  string
  altitude
    lat
    long
mpointstruc =
1x3 struct array with fields:
    type
  otherproperty
    tag
  string
  altitude
    lat
    long
```

**See Also**

dcwdata, dcwread, dcwrhead, mlayers, updategeostruct

# dcwread

---

**Purpose** Read DCW worldwide basemap file

**Syntax**

```
dcwread(filepath,filename)
dcwread(filepath,filename,recordIDs)
dcwread(filepath,filename,recordIDs,field,varlen)
struc = dcwread(...)
[struc,field] = dcwread(...)
[struc,field,varlen] = dcwread(...)
[struc,field,varlen,description] = dcwread(...)
[struc,field,varlen,description,
  narrativefield] = dcwread(...)
```

**Description** `dcwread` reads a DCW file. The user selects the file interactively.

`dcwread(filepath,filename)` reads the specified file. The combination [*filepath filename*] must form a valid complete filename.

`dcwread(filepath,filename,recordIDs)` reads selected records or fields from the file. If `recordIDs` is a scalar or a vector of integers, the function returns the selected records. If `recordIDs` is a cell array of integers, all records of the associated fields are returned.

`dcwread(filepath,filename,recordIDs,field,varlen)` uses previously read field and variable-length record information to skip parsing the file header (see below).

`struc = dcwread(...)` returns the file contents in a structure.

`[struc,field] = dcwread(...)` returns the file contents and a structure describing the format of the file.

`[struc,field,varlen] = dcwread(...)` also returns a vector describing the fields that have variable-length records.

`[struc,field,varlen,description] = dcwread(...)` also returns a string describing the contents of the file.

`[struc,field,varlen,description,narrativefield] = dcwread(...)` also returns the name of the narrative file for the current file.

## Background

The Digital Chart of the World (DCW) uses binary files in a variety of formats. This function determines the format of the file and returns the contents in a structure. The field names of this structure are the same as the field names in the DCW file.

## Remarks

This function reads all DCW files except index files (files with names ending in 'X'), thematic index files (files with names ending in 'TI'), and spatial index files (files with names ending in 'SI').

File separators are platform dependent. The *filepath* input must use appropriate file separators, which you can determine using the MATLAB `filesep` function.

## Examples

The following examples use the Macintosh directory system and file separators for the pathname:

```
s = dcwread('NOAMER:DCW:NOAMER:', 'GRT')
s =
    ID: 1
    DATA_TYPE: 'GEO'
    UNITS: '014'
    ELLIPSOID: 'WGS 84'
    ELLIPSOID_DETAIL: 'A=6378137,B=6356752 Meters'
    VERT_DATUM_REF: 'MEAN SEA LEVEL'
    VERT_DATUM_CODE: '015'
    SOUND_DATUM: 'MEAN SEA LEVEL'
    SOUND_DATUM_CODE: '015'
    GEO_DATUM_NAME: 'WGS 84'
    GEO_DATUM_CODE: 'WGE'
    PROJECTION_NAME: 'DECIMAL DEGREES'

s = dcwread('NOAMER:DCW:NOAMER:AE:', 'INT.VDT')
s =
5x1 struct array with fields:
    ID
    TABLE
    ATTRIBUTE
```

```
VALUE
DESCRIPTION
for i = 1:length(s); disp(s(i)); end
    ID: 1
        TABLE: 'AEPOINT.PFT'
        ATTRIBUTE: 'AEPTTYPE'
        VALUE: 1
        DESCRIPTION: 'Active civil'

        ID: 2
        TABLE: 'AEPOINT.PFT'
        ATTRIBUTE: 'AEPTTYPE'
        VALUE: 2
        DESCRIPTION: 'Active civil and military'
ID: 3
    TABLE: 'AEPOINT.PFT'
    ATTRIBUTE: 'AEPTTYPE'
    VALUE: 3
    DESCRIPTION: 'Active military'

    ID: 4
    TABLE: 'AEPOINT.PFT'
    ATTRIBUTE: 'AEPTTYPE'
    VALUE: 4
    DESCRIPTION: 'Other'

    ID: 5
    TABLE: 'AEPOINT.PFT'
    ATTRIBUTE: 'AEPTTYPE'
    VALUE: 5
    DESCRIPTION: 'Added from ONC when not available from DAFIF'
s = dcwread('NOAMER:DCW:NOAMER:AE:', 'AEPOINT.PFT', 1)
s =
    ID: 1
    AEPTTYPE: 4
    AEPTNAME: 'THULE AIR BASE'
    AEPTVAL: 251
```



```
AEPTDATE: '19900502000000000000'  
AEPTICA0: '1261'  
AEPTDKEY: 'BR17652'  
TILE_ID: 94  
END_ID: 1
```

```
s = dcwread('NOAMER:DCW:NOAMER:AE:', 'AEPOINT.PFT', {1,2})
```

```
s =
```

```
4678x1 struct array with fields:
```

```
    ID  
    AEPTTYPE
```

**See Also**

dcwdata, dcwgaz, dcwrhead

# dcwrhead

---

**Purpose** Read DCW worldwide basemap file headers

**Syntax**

```
dcwrhead
dcwrhead(filepath,filename)
dcwrhead(filepath,filename,fid)
dcwrhead(...)
str = dcwrhead(...)
```

**Description** dcwrhead allows the user to select the header file interactively.

dcwrhead(*filepath*,*filename*) reads from the specified file. The combination [*filepath filename*] must form a valid complete filename.

dcwrhead(*filepath*,*filename*,*fid*) reads from the already open file associated with *fid*.

dcwrhead(...) with no output arguments displays the formatted header information on the screen.

str = dcwrhead(...) returns a string containing the DCW header.

**Background** The Digital Chart of the World (DCW) uses header strings in most files to document the contents and format of that file. This function reads the header string, displays a formatted version in the command window, or returns it as a string.

**Remarks** This function reads all DCW files except index files (files with names ending in 'X'), thematic index files (files with names ending in 'TI'), and spatial index files (files with names ending in 'SI').

File separators are platform dependent. The *filepath* input must use appropriate file separators, which you can determine using the MATLAB filesep function.

**Examples** The following example uses the Macintosh file separators and pathname:

```
dcwrhead('NOAMER:DCW:NOAMER:AE:', 'AEPOINT.PFT')
Aeronautical Points
```

```

AEPOINT.DOC
ID=I, 1,P,Row Identifier,-,-,
AEPTTYPE=I, 1,N,Airport Type,INT.VDT,-,
AEPTNAME=T, 50,N,Airport Name,-,-,
AEPTVAL=I, 1,N,Airport Elevation Value,-,-,
AEPTDATE=D, 1,N,Aeronautical Information Date,-,-,
AEPTICAO=T, 4,N,International Civil Organization Number,-,-,
AEPTDKEY=T, 7,N,DAFIF Reference Number,-,-,
TILE_ID=S, 1,F,Tile Reference Identifier,-,AEPOINT.PTI,
END_ID=I 1,F,Entity Node Primitive Foreign Key,-,-,

```

```
s = dcwrhead('NOAMER:DCW:NOAMER:AE:', 'AEPOINT.PFT')
```

```
s =
```

```

;Aeronautical Points;AEPOINT.DOC;ID=I, 1,P,Row
Identifier,-,-:AEPTTYPE=I, 1,N,Airport
Type,INT.VDT,-,:AEPTNAME=T, 50,N,Airport Name,-,-:AEPTVAL=I,
1,N,Airport Elevation Value,-,-:AEPTDATE=D, 1,N,Aeronautical
Information Date,-,-:AEPTICAO=T, 4,N,International Civil
Organization Number,-,-:AEPTDKEY=T, 7,N,DAFIF Reference
Number,-,-:TILE_ID=S, 1,F,Tile Reference
Identifier,-,AEPOINT.PTI,:END_ID=I 1,F,Entity Node Primitive
Foreign Key,-,-,:;

```

## See Also

dcwdata, dcwgaz, dcwread

# defaultm

---

**Purpose** Initialize or reset map projection structure

**Syntax** `mstruct = defaultm(projection)`  
`mstruct = defaultm(mstruct)`

**Description** `mstruct = defaultm(projection)` initializes a map projection structure. *projection* is a string containing the name of a MATLAB file.

`mstruct = defaultm(mstruct)` checks an existing map projection structure, sets empty properties, and adjusts dependent properties. The `Origin`, `FFlatLimit`, `FLonLimit`, `MapLatLimit`, and `MapLonLimit` properties may be adjusted for compatibility with each other and with the `MapProjection` property and (in the case of UTM or UPS) the `Zone` property.

With `defaultm`, you can construct a map projection structure (`mstruct`) that contains all the information needed to project and unproject geographic coordinates using `mfwdtran`, `minvtran`, `vfwdtran`, or `vintran` without creating a map axes or making any use at all of MATLAB graphics. Relevant parameters in the `mstruct` include the projection name, angle units, zone (for UTM or UPS), origin, aspect, false easting, false northing, and (for conic projections) the standard parallel or parallels. In very rare cases you might also need to adjust the frame limit (`FFlatLimit` and `FLonLimit`) or map limit (`MapLatLimit` and `MapLonLimit`) properties.

You should make exactly two calls to `defaultm` to set up your `mstruct`, using the following sequence:

- 1 Construct a provisional version containing default values for the projection you've selected: `mstruct = defaultm(projection);`
- 2 Assign appropriate values to `mstruct.angleunits`, `mstruct.zone`, `mstruct.origin`, etc.

**3** Set empty properties and adjust interdependent properties as needed to finalize your map projection structure: `mstruct = defaultm(mstruct);`

If you've set field `prop1` of `mstruct` to `value1`, field `prop2` to `value2`, and so forth, then the following sequence

```
mstruct = defaultm(projection);
mstruct.prop1 = value1;
mstruct.prop2 = value2;
...
mstruct = defaultm(mstruct);
```

produces exactly the same result as the following:

```
f = figure;
ax = axesm(projection, prop1, value1, prop2, value2, ...);
mstruct = getm(ax);
close(f)
```

but it avoids the use of graphics and is more efficient.

---

**Note** Angle-valued properties are in degrees by default. If you want to work in radians instead, you can make the following assignment in between your two calls to `defaultm`:

```
mstruct.angleunits = 'radians';
```

You must also use values in radians when assigning any angle-valued properties (such as `mstruct.origin`, `mstruct.parallels`, `mstruct.maplatlimit`, `mstruct.maplonlimit`, etc.).

---

See the Mapping Toolbox User's Guide section on "Working in UTM Without a Map Axes" for information and an example showing the use of `defaultm` in combination with UTM.

## Examples

Create an empty map projection structure for a Mercator projection:

```
mstruct = defaultm('mercator')

mstruct =
    mapprojection: 'mercator'
           zone: []
    angleunits: 'degrees'
           aspect: 'normal'
    falseeasting: []
    falsenorthing: []
    fixedorient: []
           geoid: [1 0]
    maplatlimit: []
    maplonlimit: []
    mapparallels: 0
           nparallels: 1
           origin: []
    scalefactor: []
           trimlat: [-86 86]
           trimlon: [-180 180]
           frame: []
           ffill: 100
    fedgecolor: [0 0 0]
    ffacecolor: 'none'
    flatlimit: []
    flinewidth: 2
    flonlimit: []
           grid: []
           galtitude: Inf
           gcolor: [0 0 0]
    glinestyle: ':'
    glinewidth: 0.5000
    mlineexception: []
           mlinefill: 100
           mlinelimit: []
           mlinelocation: []
```

```
mlinevisible: 'on'
plineexception: []
  plinefill: 100
  plinelimit: []
  plinelocation: []
  plinevisible: 'on'
  fontangle: 'normal'
  fontcolor: [0 0 0]
  fontname: 'helvetica'
  fontsize: 9
  fontunits: 'points'
  fontweight: 'normal'
  labelformat: 'compass'
  labelrotation: 'off'
  labelunits: []
  meridianlabel: []
  mlabellocation: []
  mlabelparallel: []
  mlabelround: 0
  parallellabel: []
  plabellocation: []
  plabelmeridian: []
  plabelround: 0
```

Now change the map origin to [0 90 0], and fill in default projection parameters accordingly:

```
mstruct.origin = [0 90 0];
mstruct = defaultm(mstruct)

mstruct =
  mapprojection: 'mercator'
    zone: []
    angleunits: 'degrees'
    aspect: 'normal'
  falseeasting: 0
  falsenorthing: 0
```

## defaultm

---

```
fixedorient: []
  geoid: [1 0]
maplatlimit: [-86 86]
maplonlimit: [-90 270]
mapparallels: 0
  nparallels: 1
  origin: [0 90 0]
scalefactor: 1
  trimlat: [-86 86]
  trimlon: [-180 180]
  frame: 'off'
  ffill: 100
fedgecolor: [0 0 0]
ffacecolor: 'none'
flatlimit: [-86 86]
flinewidth: 2
flonlimit: [-180 180]
  grid: 'off'
galtitude: Inf
gcolor: [0 0 0]
glinestyle: ':'
glinewidth: 0.5
mlineexception: []
  mlinefill: 100
  mlinelimit: []
  mlinelocation: 30
  mlinevisible: 'on'
plineexception: []
  plinefill: 100
  plinelimit: []
  plinelocation: 15
  plinevisible: 'on'
  fontangle: 'normal'
  fontcolor: [0 0 0]
  fontname: 'Helvetica'
  fontsize: 10
  fontunits: 'points'
```



```
    fontweight: 'normal'  
    labelformat: 'compass'  
    labelrotation: 'off'  
    labelunits: 'degrees'  
    meridianlabel: 'off'  
mlabellocation: 30  
mlabelparallel: 86  
    mlabelround: 0  
    parallellabel: 'off'  
plabellocation: 15  
plabelmeridian: -90  
    plabelround: 0
```

**See Also**

axesm, gcm, mfwdtran, minvtran, setm

# deg2km, deg2nm, deg2sm

---

**Purpose** Convert distance from degrees to kilometers, nautical miles, or statute miles

**Syntax**

```
km = deg2km(deg)
nm = deg2nm(deg)
sm = deg2sm(deg)
km = deg2km(deg,radius)
nm = deg2nm(deg,radius)
sm = deg2sm(deg,radius)
km = deg2km(deg,sphere)
nm = deg2nm(deg,sphere)
sm = deg2sm(deg,sphere)
```

**Description** `km = deg2km(deg)` converts distances from degrees to kilometers as measured along a great circle on a sphere with a radius of 6371 km, the mean radius of the Earth.

`nm = deg2nm(deg)` and `sm = deg2sm(deg)` work identically, except that the output units are nautical miles and statute miles, respectively.

`km = deg2km(deg,radius)` converts distances from degrees to kilometers as measured along a great circle on a sphere having the specified radius. `radius` must be in units of kilometers.

For `nm = deg2nm(deg,radius)` and `sm = deg2sm(deg,radius)`, make sure your input radius is in the appropriate units.

`km = deg2km(deg,sphere)` converts distances from degrees to kilometers, as measured along a great circle on a sphere approximating an object in the Solar System. `sphere` may be one of the following strings: 'sun', 'moon', 'mercury', 'venus', 'earth', 'mars', 'jupiter', 'saturn', 'uranus', 'neptune', or 'pluto', and is case-insensitive.

`nm = deg2nm(deg,sphere)` and `sm = deg2sm(deg,sphere)` work identically, except that the output units are nautical miles and statute miles, respectively.

## Examples

A degree of arc length is about 60 nautical miles:

```
deg2nm(1)
```

```
ans =  
    60.0405
```

This is not true on Mercury, of course:

```
deg2nm(1, 'mercury')
```

```
ans =  
    22.9852
```

## See Also

deg2nm, degtorad, deg2sm, km2deg, sm2deg

# degrees2dm

---

**Purpose** Convert degrees to degrees-minutes

**Syntax** `DM = degrees2dm(angleInDegrees)`

**Description** `DM = degrees2dm(angleInDegrees)` converts angles from values in degrees which may include a fractional part (sometimes called “decimal degrees”) to degree-minutes representation. The input should be a real-valued column vector. Given N-by-1 input, DM will be N-by-2, with one row per input angle. The first column of DM contains the “degrees” element and is integer-valued. The second column contains the “minutes” element and may have a nonzero fractional part. In any given row of DM, the sign of the first nonzero element indicates the sign of the overall angle. A positive number indicates north latitude or east longitude; a negative number indicates south latitude or west longitude. Any remaining elements in that row will have nonnegative values.

**Example**

```
angleInDegrees = [ 30.8457722555556; ...
                  -82.0444189583333; ...
                  -0.504756513888889; ...
                   0.004116666666667];
dm = degrees2dm(angleInDegrees)

dm =
    30.00000000000000    50.746335333336106
   -82.00000000000000     2.665137499997741
     0 -30.285390833333338
     0  0.247000000000020
```

**See Also** `dm2degrees`, `degtorad` `degrees2dms`, `radtodeg`

**Purpose** Convert degrees to degrees-minutes-seconds

**Syntax** DMS = degrees2dms(angleInDegrees)

**Description** DMS = degrees2dms(angleInDegrees) converts angles from values in degrees which may include a fractional part (sometimes called “decimal degrees”) to degree-minutes-seconds representation. The input should be a real-valued column vector. Given N-by-1 input, DMS will be N-by-3, with one row per input angle. The first column of DMS contains the “degrees” element and is integer-valued. The second column contains the “minutes” element and is integer valued. The third column contains the “seconds” element, and can have a nonzero fractional part. In any given row of DMS, the sign of the first nonzero element indicates the sign of the overall angle. A positive number indicates north latitude or east longitude; a negative number indicates south latitude or west longitude. Any remaining elements in that row will have nonnegative values.

**Example** Convert four angles from values in degrees to degree-minutes-seconds representation.

```
format long g
angleInDegrees = [ 30.8457722555556; ...
                  -82.0444189583333; ...
                  -0.504756513888889; ...
                   0.004116666666667];
dms = degrees2dms(angleInDegrees)
```

The output appears as follows:

```
dms =
      30          50      44.7801200001663
     -82           2      39.9082499998644
        0        -30      17.1234500000003
        0           0      14.8200000000012
```

Convert angles to a string, with each angle on its own line.

## degrees2dms

---

```
nonnegative = all((dms >= 0),2);
hemisphere = repmat('N', size(nonnegative));
hemisphere(~nonnegative) = 'S';
absvalues = num2cell(abs(dms'));
values = [absvalues; num2cell(hemisphere')];
str = sprintf('%2.0fd%2.0fm%7.5fs%s\n', values{:})
```

The output appears as follows:

```
str =
    30d50m44.78012sN
    82d 2m39.90825sS
    0d30m17.12345sS
    0d 0m14.82000sN
```

Split the string into cells as delimited by the newline character, then return to the original values using `str2angle`.

```
newline = sprintf('\n');
C = textscan(str, '%s', -1, 'delimiter', newline);
a = deal(C{:});
for k = 1:numel(a)
    str2angle(a{k})
end
```

The output appears as follows:

```
ans =
    30.8457722555556

ans =
   -82.0444189583333

ans =
   -0.504756513888889

ans =
```

0.00411666666666667

**See Also**

dms2degrees, degtorad degrees2dm, radtodeg

# degtorad

---

**Purpose** Convert angles from degrees to radians

**Syntax** `angleInRadians = degtorad(angleInDegrees)`

**Description** `angleInRadians = degtorad(angleInDegrees)` converts angle units from degrees to radians. This is both an angle conversion function and a distance conversion function, since arc length can be a measure of distance in either radians or degrees, provided that the radius is known.

**Examples** Show that there are  $2\pi$  radians in a full circle:

```
2*pi - degtorad(360)
```

```
ans =  
    0
```

**See Also** `fromDegrees` | `fromRadians` | `toDegrees` | `toRadians` | `radtodeg`



**Purpose** Colormaps appropriate to terrain elevation data

**Syntax**

```
demcmap(Z)
demcmap(Z,ncolors)
demcmap(Z,ncolors,cmapsea,cmapland)
demcmap(color,Z,spec)
demcmap(color,Z,spec,cmapsea,cmapland)
```

**Description** `demcmap(Z)` creates and assigns a colormap for elevation data grid `Z`. The colormap has the number of land and sea colors in the same proportions as the maximum elevations and depths in the data grid. With no output arguments, the colormap is applied to the current figure and the color axis is set so that the interface between the land and sea is in the right place.

`demcmap(Z,ncolors)` makes a colormap with a length of `ncolors`. The default value is 64.

`demcmap(Z,ncolors,cmapsea,cmapland)` allows the default colors for sea and land to be replaced. The colors in the created colormap are interpolated from the RGB color matrix inputs, which can be of any length. You can retain default colors for either land or sea by providing an empty matrix in place of the color matrices. You can specify the current figure colormap by entering the string 'window' in place of either RGB matrix.

`demcmap(color,Z,spec)` uses the `color` string to define a colormap. If the string is set to 'size', `spec` is the length of the colormap. If it is set to 'inc', `spec` is the size of the altitude range assigned to each color. If omitted, `color` is 'size' by default.

`demcmap(color,Z,spec,cmapsea,cmapland)` allows for both coloring options along with specified colors.

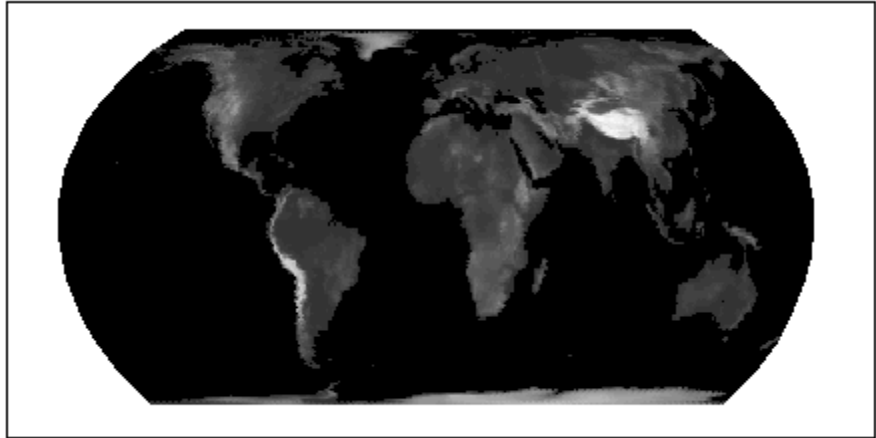
**Examples** Display the world topographical map using grayscale colors:

```
load topo
axesm hatano
meshm(topo,topolegend)
```

# demcmap

---

```
demcmap(topo,64,[0 0 0],[.2 .2 .2; 1 1 1])
```



## See Also

`caxis`, `colormap`, `meshlsrcm`, `meshm`, `surflsrcm`, `surfm`

<b>Purpose</b>	Departure of longitudes at specified latitudes
<b>Syntax</b>	<pre>dist = departure(long1,long2,lat) dist = departure(long1,long2,lat,geoid) dist = departure(long1,long2,lat,units) dist = departure(long1,long2,lat,geoid,units)</pre>
<b>Description</b>	<p><code>dist = departure(long1,long2,lat)</code> computes the departure distance from <code>long1</code> to <code>long2</code> at the input latitude <code>lat</code>. Departure is the distance along a specific parallel between two meridians. The output <code>dist</code> is returned in degrees of arc length on a sphere.</p> <p><code>dist = departure(long1,long2,lat,geoid)</code> computes the departure assuming that the input points lie on the ellipsoid defined by the input <code>geoid</code>. The <code>geoid</code> vector is of the form [semimajor axes, eccentricity].</p> <p><code>dist = departure(long1,long2,lat,units)</code> uses the input string <code>units</code> to define the angle units of the input and output data. In this form, the departure is returned as an arc length in the units specified by <code>units</code>. If <code>units</code> is omitted, 'degrees' is assumed.</p> <p><code>dist = departure(long1,long2,lat,geoid,units)</code> is a valid calling form. In this case, the departure is computed in the same units as the semimajor axes of the <code>geoid</code> vector.</p>
<b>Definitions</b>	<p><i>Departure</i> is the distance along a parallel between two points. Whereas a degree of latitude is always the same distance, a degree of longitude is different in length at different latitudes. In practice, this distance is usually given in nautical miles.</p>
<b>Examples</b>	<p>On a spherical Earth, the departure is proportional to the cosine of the latitude:</p> <pre>distance = departure(0, 10, 0)  distance =     10</pre>

# departure

---

```
distance = departure(0, 10, 60)
```

```
distance =  
    5
```

When an ellipsoid is used, the result is more complicated. The distance at 60° is not exactly twice the 0° value:

```
distance = departure(0, 10, 0, almanac('earth', 'ellipsoid', 'nm'))
```

```
distance =  
    601.0772
```

```
distance = departure(0, 10, 60, almanac('earth', 'ellipsoid', 'nm'))
```

```
distance =  
    299.7819
```

## See Also

[distance](#) | [stdm](#)

**Purpose**

Display geographic data from display structure

**Syntax**

```
displaym(displaystruct)
displaym(displaystruct,str)
displaym(displaystruct,strings)
displaym(displaystruct,strings,searchmethod)
h = displaym(displaystruct)
```

**Description**

`displaym(displaystruct)` projects the data contained in the input `displaystruct`, a Version 1 Mapping Toolbox display structure, in the current axes. The current axes must be a map axes with a valid map definition. See the remarks about “Version 1 Display Structures” on page 3-144 below for details on the contents of display structures.

`displaym(displaystruct,str)` displays the vector data elements of `displaystruct` whose 'tag' fields contains strings beginning with the string `str`. Vector data elements are those whose 'type' field is either 'line' or 'patch'. The string match is case-insensitive.

`displaym(displaystruct,strings)` displays the vector data elements of `displaystruct` whose 'tag' field matches begins with one of the elements (or rows) of `strings`. `strings` is a cell array of strings (or a 2-D character array). In the case of character array, trailing blanks are stripped from each row before matching.

`displaym(displaystruct,strings,searchmethod)` controls the method used to match the values of the tag field in `displaystruct`, as follows:

- 'strmatch' — Search for matches at the beginning of the tag (similar to the MATLAB `strmatch` function)
- 'findstr' — Search within the tag (similar to the MATLAB `findstr` function)
- 'exact' — Search for exact matches

Note that when `searchmethod` is specified the search is case-sensitive.

`h = displaym(displaystruct)` returns handles to the graphic objects created by `displaym`.

---

**Note** The type of *display structure* accepted by `displaym` is not the same as a *geographic data structure* (geostructs and mapstructs), introduced in Mapping Toolbox Version 2. Use `geoshow` or `mapshow` instead of `displaym` to display geostructs or mapstructs—created using `shaperead` and `gshhs`, for example. For more information, see “Mapping Toolbox Geographic Data Structures”.

---

## Remarks

The following section documents the contents of display structures.

### Version 1 Display Structures

A display structure is a MATLAB structure array with a specific set of fields:

- A `tag` field names an individual feature or object
- A `type` field specifies a MATLAB graphics object type ('line', 'patch', 'surface', 'text', or 'light') or has the value 'regular', specifying a regular data grid
- `lat` and `long` fields contain coordinate vectors of latitudes and longitudes, respectively
- An `altitude` field contains a vector of vertical coordinate values
- A `string` property contains text to be displayed if `type` is 'text'
- MATLAB graphics properties are specified explicitly, on a per-feature basis, in an `otherproperty` field

The choice of options for the `type` field reveals that a display structure can contain

- Vector geodata (type is 'line' or 'patch')
- Raster geodata (type is 'surface' or 'regular')

- Graphic objects (type is 'text' or 'light')

The following table indicates which fields are used in the six types of display structures:

Field Name	Type 'light'	Type 'line'	Type 'patch'	Type 'regular'	Type 'surface'	Type 'text'
type	•	•	•	•	•	•
tag	•	•	•	•	•	•
lat	•	•	•		•	•
long	•	•	•		•	•
map				•	•	
maplegend				•		
meshgrat				•		
string						•
altitude	•	•	•	•	•	•
otherproperty	•	•	•	•	•	•

Some fields can contain empty entries, but each indicated field must exist for the objects in the struct array to be displayed correctly. For instance, the `altitude` field can be an empty matrix and the `otherproperty` field can be an empty cell array.

The `type` field must be one of the specified map object types: 'line', 'patch', 'regular', 'surface', 'text', or 'light'.

The `tag` field must be a string different from the `type` field usually containing the name or kind of map object. Its contents must not be equal to the name of the object type (i.e., line, surface, text, etc.).

The `lat`, `long`, and `altitude` fields can be scalar values, vectors, or matrices, as appropriate for the map object type.

The `map` field is a data grid. If `map` is a regular data grid, `maplegend` is its corresponding referencing vector, and `meshgrat` is a two-element vector

# displaym

---

specifying the graticule mesh size. If `map` is a geolocated data grid, `lat` and `long` are the matrices of latitude and longitude coordinates.

The `otherproperty` field is a cell array containing any additional display properties appropriate for the map object. Cell array entries can be a line specification string, such as `'r+'`, or property name/property value pairs, such as `'color', 'red'`. If the `otherproperty` field is left as an empty cell array, default colors are used in the display of lines and patches based on the `tag` field.

---

**Note** In some cases you can use the `geoshow` function as a direct alternative to `displaym`. It accepts display structures of type `line` and `patch`.

---

## See Also

`extractm`, `geoshow`, `mapshow`, `mLayers`, `updategeostruct`



**Purpose**

Format distance strings

**Syntax**

```
str = dist2str(distin)
str = dist2str(dist,format)
str = dist2str(dist,format,units)
str = dist2str(dist,format,digits)
str = dist2str(dist,format,units,digits)
```

**Description**

`str = dist2str(distin)` converts a numerical vector of distances in kilometers, `distin`, to a string matrix. The output string matrix is useful for the display of distances.

`str = dist2str(dist,format)` uses the `format` string to specify the notation to be used for the string matrix. If blank or 'none', the result is a simple numerical representation (no indicator for positive distances, minus signs for negative distances). The only other format is 'pm' (for *plus-minus*) prefixes a + for positive distances.

`str = dist2str(dist,format,units)` defines the units in which the input distances are supplied, and which are encoded in the string matrix. Units must be one of the following: 'feet', 'kilometers', 'meters', 'nauticalmiles', 'statutemiles', 'degrees', or 'radians'. Note that statute miles are encoded as 'mi' in the string matrix, whereas in most Mapping Toolbox functions, 'mi' indicates international miles. If omitted or blank, 'kilometers' is assumed.

`str = dist2str(dist,format,digits)` or `str = dist2str(dist,format,units,digits)` uses the input `digits` to determine the number of decimal digits in the output matrix. `digits = -2` uses accuracy in the hundredths position, `digits = 0` uses accuracy in the units position. Default is `digits = -2`. For further discussion of specifying digits, see `roundn`.

The purpose of this function is to make distance-valued variables into strings suitable for map display.

**Examples**

Create a vector of values and convert to strings:

```
d = [-3.7 2.95 87];
```

## dist2str

---

```
str = dist2str(d, 'none', 'km')
```

```
str =  
-3.70 km  
 2.95 km  
87.00 km
```

Now change the units to nautical miles, add plus signs to positive values, and truncate to the tenths ( $10^{-1}$ ) slot:

```
str = dist2str(d, 'pm', 'nm', -1)
```

```
str =  
-3.7 nm  
+3.0 nm  
+87.0 nm
```

### See Also

angl2str, roundn

**Purpose**

Distance between points on sphere or ellipsoid

**Syntax**

```
[dist,az] = distance(lat1,lon1,lat2,lon2)
[dist,az] = distance(lat1,lon1,lat2,lon2,ellipsoid)
[dist,az] = distance(lat1,lon1,lat2,lon2,units)
[dist,az] = distance(lat1,lon1,lat2,lon2,ellipsoid,units)
[dist,az] = distance(pt1,pt2)
[dist,az] = distance(pt1,pt2,ellipsoid)
[dist,az] = distance(pt1,pt2,units)
[dist,az] = distance(pt1,pt2,ellipsoid,units)
[dist,az] = distance(track,...)
```

**Description**

`[dist,az] = distance(lat1,lon1,lat2,lon2)` computes the great circle distance(s) and azimuth(s) between pairs of points on the surface of a sphere. The input latitudes and longitudes, `lat1`, `lon1`, `lat2`, and `lon2`, are in degrees and can be scalars or arrays of equal size. The distance `dist` is expressed in degrees of arc length and will have the same size as the input arrays. Azimuth `az` is clockwise from north, from the first point to the second point. When given a combination of scalar and array inputs, the scalar inputs are automatically expanded to match the size of the arrays.

`[dist,az] = distance(lat1,lon1,lat2,lon2,ellipsoid)` computes the geodesic distance and azimuth assuming that the points lie on the reference ellipsoid defined by the input `ellipsoid`. The ellipsoid vector is of the form `[semimajor axis,eccentricity]`. The output `dist` is expressed in the same distance units as the semimajor axis of the ellipsoid vector.

`[dist,az] = distance(lat1,lon1,lat2,lon2,units)` uses the string `units` to define the angle units of the input latitudes and longitudes and the outputs `dist` and `az`. The `units` string may equal 'degrees' (the default value) or 'radians'.

`[dist,az] = distance(lat1,lon1,lat2,lon2,ellipsoid,units)` uses the `units` string to specify the units of the latitude-longitude coordinates, but the output range has the same units as the semimajor axis of the ellipsoid vector.

# distance

---

`[dist,az] = distance(pt1,pt2)` accepts N-by-2 coordinate arrays `pt1` and `pt2` such that `pt1 = [lat1 lon1]` and `pt2 = [lat2 lon2]` where `lat1`, `lon1`, `lat2`, and `lon2` are column vectors. It is equivalent to `dist = distance(pt1(:,1),pt1(:,2),pt2(:,1),pt2(:,2))`.

`[dist,az] = distance(pt1,pt2,ellipsoid)`,

`[dist,az] = distance(pt1,pt2,units)`, and

`[dist,az] = distance(pt1,pt2,ellipsoid,units)` are all valid calling forms.

`[dist,az] = distance(track,...)` specifies whether great circle distances or rhumb line distances are desired. Great circle distances, the default, are indicated with the standard *track* string 'gc'. Rhumb line distances are indicated with the standard *track* string 'rh'.

## Examples

Using `pt1,pt2` notation, find the distance from Norfolk, Virginia (37°N, 76°W), to Cape St. Vincent, Portugal (37°N, 9°W), just outside the Straits of Gibraltar. The distance between these two points depends upon the *track* string selected.

```
dist = distance('gc',[37,-76],[37,-9])
```

```
dist =  
    52.3094
```

```
dist = distance('rh',[37,-76],[37,-9])
```

```
dist =  
    53.5086
```

The difference between these two tracks is 1.1992 degrees, or about 72 nautical miles. This represents about 2% of the total trip distance. The trade-off is that at the cost of those 72 miles, the entire trip can be made on a rhumb line with a fixed course of 90°, due east, while in order to follow the shorter great circle path, the course must be changed continuously.

On a meridian and on the Equator, great circles and rhumb lines coincide, so the distances are the same. For example,

```
% great circle distance
dist = distance(37, -76, 67, -76)
dist =
    30.0000

% rhumb line distance
dist = distance('rh', 37, -76, 67, -76)

dist =
    30.0000
```

The distances are the same,  $30^\circ$ , or about 1800 nautical miles (there are about 60 nautical miles in a degree of arc length).

## Algorithm

Distance calculations for geodesics degrade slowly with increasing distance and may break down for points that are nearly antipodal, as well as when both points are very close to the Equator. In addition, for calculations on an ellipsoid, there is a small but finite input space, consisting of pairs of locations in which both the points are nearly antipodal *and* both points fall close to (but not precisely on) the Equator. In this case, a warning is issued and both `dist` and `az` are set to NaN for the “problem pairs.”

## Alternatives

Distance between two points can be calculated in two ways. For great circles (on the sphere) and geodesics (on the ellipsoid), the distance is the shortest surface distance between two points. For rhumb lines, the distance is measured along the rhumb line passing through the two points, which is not, in general, the shortest surface distance between them.

When you need to compute both distance and azimuth for the same point pair(s), it is more efficient to do so with a single call to `distance`. That is, use

```
[dist az] = distance(...);
```

# distance

---

rather than the slower

```
dist = distance(...)  
az = azimuth(...)
```

To express the output `dist` as an arc length in either degrees or radians, omit the `ellipsoid` argument. This is possible only on a sphere. If `ellipsoid` is supplied, `dist` is a distance expressed in the same units as the semimajor axis of the ellipsoid. Specify `ellipsoid` as `[R 0]` to compute `dist` as a distance on a sphere of radius `R`, with `dist` having the same units as `R`.

## See Also

`almanac` | `azimuth` | `elevation` | `reckon` | `track` | `track1` | `track2` | `trackg`

## How To

- “Great Circles, Rhumb Lines, and Small Circles”

## Purpose

Distortion parameters for map projections

## Syntax

```
areascale = distortcalc(lat, long)
areascale = distortcalc(mstruct, lat, long)
[areascale, angdef, maxscale, minscale, merscale,
 parscale] = distortcalc(...)
```

## Description

`areascale = distortcalc(lat, long)` computes the area distortion for the current map projection at the specified geographic location. An area scale of 1 indicates no scale distortion. Latitude and longitude can be scalars, vectors, or matrices in the angle units of the defined map projection.

`areascale = distortcalc(mstruct, lat, long)` uses the projection defined in the map structure `mstruct`.

`[areascale, angdef, maxscale, minscale, merscale, parscale] = distortcalc(...)` computes the area scale, maximum angular deformation of right angles (in the angle units of the defined projection), the particular maximum and minimum scale distortions in any direction, and the particular scale along the meridian and parallel. You can also call `distortcalc` with fewer output arguments, in the order shown.

## Background

Map projections inevitably introduce distortions in the shapes and sizes of objects as they are transformed from three-dimensional spherical coordinates to two-dimensional Cartesian coordinates. The amount and type of distortion vary between projections, over the projection, and with the selection of projection parameters such as standard parallels. This function allows a quantitative evaluation of distortion parameters.

## Examples

At the equator, the Mercator projection is free of both area and angular distortion:

```
axesm mercator
[areascale, angdef] = distortcalc(0,0)
```

# distortcalc

---

```
areascale =  
    1.0000  
angdef =  
    8.5377e-007
```

At 60 degrees north, objects are shown at 400% of their true area. The projection is conformal, so angular distortion is still zero.

```
[areascale,angdef] = distortcalc(60,0)  
  
areascale =  
    4.0000  
angdef =  
    4.9720e-004
```

## Remarks

This function uses a finite difference technique. The geographic coordinates are perturbed slightly in different directions and projected. A small amount of error is introduced by numerical computation of derivatives and the variation of map distortion parameters.

## See Also

`mdistort`, `tissot`



**Purpose**

Convert length units

**Syntax**

```
distOut = distdim(distIn,from,to)
distOut = distdim(distIn,from,to,radius)
distOut = distdim(distIn,from,to,sphere)
```

---

**Note** `distdim` has been replaced by `unitsratio`, but will be maintained for backward compatibility. See “Replacing `distdim`” on page 3-157 for details.

---

**Description**

`distOut = distdim(distIn,from,to)` converts `distIn` from the units specified by the string `from` to the units specified by the string `to`. `from` and `to` are case-insensitive, and may equal any of the following:

```
'meters' or 'm'
'feet' or 'ft'           U.S. survey feet
'kilometers' or 'km'
'nauticalmiles' or 'nm'
'miles', 'statutemiles', 'mi', or 'sm'  Statute miles
'degrees' or 'deg'
'radians' or 'rad'
```

If either `from` or `to` indicates angular units ('degrees' or 'radians'), the conversion to or from linear distance is made along a great circle arc on a sphere with a radius of 6371 km, the mean radius of the Earth.

`distOut = distdim(distIn,from,to,radius)`, where one of the unit strings, either `from` or `to`, indicates angular units and the other unit string indicates length units, uses a great circle arc on a sphere of the given radius. The specified length units must apply to `radius` as well as to the input distance (when `from` indicates length) or output distance (when `to` indicates length). If neither `from` nor `to` indicates angular units, or if both do, then the value of `radius` is ignored.

`distOut = distdim(distIn, from, to, sphere)`, where either *from* or *to* indicates angular units, uses a great circle arc on a sphere approximating a body in the Solar System. *sphere* may be one of the following strings: 'sun', 'moon', 'mercury', 'venus', 'earth', 'mars', 'jupiter', 'saturn', 'uranus', 'neptune', or 'pluto', and is case-insensitive. If neither *to* nor *from* is angular, *sphere* is ignored.

## Remarks

### Arc Lengths of Angles Not Constant

Distance is expressed in one of two general forms: as a linear measure in some unit (kilometers, miles, etc.) or as angular arc length (degrees or radians). While the use of linear units is generally understood, angular arc length is not always as clear. The conversion from angular units to linear units for the arc along any circle is the angle in radians multiplied by the radius of the circle. On the sphere, this means that radians of latitude are directly translatable to kilometers, say, by multiplying by the radius of the Earth in kilometers (about 6,371 km). However, the linear distance associated with radians of longitude changes with latitude; the radius in question is then not the radius of the Earth, but the (chord) radius of the small circle defining that parallel. The angle in radians or degrees associated with any distance is the arc length of a great circle passing through the points of interest. Therefore, the radius in question always refers to the radius of the relevant sphere, consistent with the distance function.

### Exercise Caution with 'feet' and 'miles'

*Exercise caution with 'feet' and 'miles'.* `distdim` interprets 'feet' and 'ft' as U.S. survey feet, and does not support international feet at all. In contrast, `unitsratio` follows the opposite, and more standard approach, interpreting both 'feet' and 'ft' as international feet. `unitsratio` provides separate options, including 'surveyfeet' and 'sf', to indicate survey feet. By definition, one international foot is exactly 0.3048 meters and one U.S. survey foot is exactly 1200/3937 meters. For many applications, the difference is significant. Most projected coordinate systems use either the meter or the survey foot as a standard unit. International feet are less likely to be used, but do occur sometimes. Likewise, `distdim` interprets 'miles' and 'mi' as

statute miles (also known as U.S. survey miles), and does not support international miles at all. By definition, one international mile is 5,280 international feet and one statute mile is 5,280 survey feet. You can evaluate:

```
unitsratio('millimeter','statute mile') - ...
unitsratio('millimeter','mile')
```

to see that the difference between a statute mile and an international mile is just over three millimeters. This may seem like a very small amount over the length of a single mile, but mixing up these units could result in a significant error over a sufficiently long baseline. Originally, the behavior of `distdim` with respect to `'miles'` and `'mi'` was documented only indirectly, via the now-obsolete `unitstr` function. As with feet, `unitsratio` takes a more standard approach. `unitsratio` interprets `'miles'` and `'mi'` as international miles, and `'statute miles'` and `'sm'` as statute miles. (`unitsratio` accepts several other strings for each of these units; see the `unitsratio` help for further information.)

### Replacing `distdim`

If both *from* and *to* are known at the time of coding, then you may be able to replace `distdim` with a direct conversion utility, as in the following examples:

<code>distdim(dist, 'nm', 'km')</code>	<code>=&gt; nm2km(dist)</code>
<code>distdim(dist, 'sm', 'deg')</code>	<code>=&gt; sm2deg(dist)</code>
<code>distdim(dist, 'rad', 'km', 'moon')</code>	<code>=&gt; rad2km(dist, 'moon')</code>

If there is no appropriate direct conversion utility, or you won't know the value of *from* and/or *to* until run time, you can generally replace

```
distdim(dist, FROM, TO)
```

with

```
unitsratio(TO, FROM) * dist
```

If you are using units of feet or miles, see the cautionary note above about how they are interpreted. For example, with `distIn` in meters and `distOut` in survey feet, `distOut = distdim(distIn, 'meters', 'feet')` should be replaced with `distOut = unitsratio('survey feet', 'meters') * distIn`. Saving a multiplicative factor computed with `unitsratio` and using it to convert in a separate step can make code cleaner and more efficient than using `distdim`. For example, replace

```
dist1_meters = distdim(dist1_nm, 'nm', 'meters');  
dist2_meters = distdim(dist2_nm, 'nm', 'meters');
```

with

```
metersPerNM = unitsratio('meters', 'nm');  
dist1_meters = metersPerNM * dist1_nm;  
dist2_meters = metersPerNM * dist2_nm;
```

`unitsratio` does not perform great-circle conversion between units of length and angle, but it can be easily combined with other functions to do so. For example, to convert degrees to meters along a great-circle arc on a sphere approximating the planet Mars, you could replace

```
distdim(dist, 'degrees', 'meters', 'mars')
```

with

```
unitsratio('meters', 'km') * deg2km(dist, 'mars')
```

## Examples

Convert 100 kilometers to nautical miles:

```
distkm = 100
```

```
distkm =
```

```
100
```

```
distnm = distdim(distkm, 'kilometers', 'nauticalmiles')
```

```
distnm =  
53.9957
```

A degree of arc length is about 60 nautical miles:

```
distnm = distdim(1, 'deg', 'nm')
```

```
distnm =  
60.0405
```

This is not accidental. It is the original definition of the nautical mile. Naturally, this assumption does not hold on other planets:

```
distnm = distdim(1, 'deg', 'nm', 'mars')
```

```
distnm =  
31.9474
```

## See Also

deg2km, deg2nm, deg2sm, km2deg, km2nm, km2rad, km2sm, nm2deg, nm2km, nm2rad, nm2sm, rad2km, rad2nm, rad2sm, sm2deg, sm2km, sm2nm, sm2rad, unitsratio

# dm2degrees

---

**Purpose** Convert degrees-minutes to degrees

**Syntax** `angleInDegrees = dm2degrees(DM)`

**Description** `angleInDegrees = dm2degrees(DM)` converts angles from degree-minutes representation to values in degrees which may include a fractional part (sometimes called “decimal degrees”). `DM` should be `N`-by-2 and real-valued, with one row per angle. The output will be an `N`-by-1 column vector whose  $k^{\text{th}}$  element corresponds to the  $k^{\text{th}}$  row of `DM`. The first column of `DM` contains the “degrees” element and should be integer-valued. The second column contains the “minutes” element and may have a fractional part. For an angle that is positive (north latitude or east longitude) or equal to zero, all elements in the row need to be nonnegative. For a negative angle (south latitude or west longitude), the first nonzero element in the row should be negative and the remaining value, if any, should be nonzero. Thus, for an input row with value `[D M]`, with integer-valued `D` and real `M`, the output value will be

$$\text{SGN} * (\text{abs}(D) + \text{abs}(M) / 60)$$

where `SGN` is 1 if `D` and `M` are both nonnegative and -1 if the first nonzero element of `[D M]` is negative (an error results if a nonzero `D` is followed by a negative `M`). Any fractional parts in the first (degrees) columns of `DM` are ignored. An error results unless the absolute values of all elements in the second (minutes) column are less than 60.

## Example

```
dm = [ ...
      30 44.78012; ...
      -82 39.90825; ...
      0 -17.12345; ...
      0 14.82000];
format long g
angleInDegrees = dm2degrees(dm)

angleInDegrees =
    30.7463353333333
   -82.6651375
```

-0.2853908333333333  
0.247

**See Also**      degrees2dm, degtorad, dms2degrees, str2angle

# dms2degrees

---

**Purpose** Convert degrees-minutes-seconds to degrees

**Syntax** `angleInDegrees = dms2degrees(DMS)`

**Description** `angleInDegrees = dms2degrees(DMS)` converts angles from degree-minutes-seconds representation to values in degrees which may include a fractional part (sometimes called “decimal degrees”). `DMS` should be `N`-by-3 and real-valued, with one row per angle. The output will be an `N`-by-1 column vector whose  $k^{\text{th}}$  element corresponds to the  $k^{\text{th}}$  row of `DMS`. The first column of `DMS` contains the “degrees” element and should be integer-valued. The second column contains the “minutes” element and should be integer-valued. The third column contains the “seconds” element and may have a fractional part. For an angle that is positive (north latitude or east longitude) or equal to zero, all elements in the row need to be nonnegative. For a negative angle (south latitude or west longitude), the first nonzero element in the row should be negative and the remaining values should be positive. Thus, for an input row with value `[D M S]`, with integer-valued `D` and `M`, and real `D`, `M`, and `S`, the output value will be

$$\text{SGN} * (\text{abs}(D) + \text{abs}(M)/60 + \text{abs}(S)/3600)$$

where `SGN` is 1 if `D`, `M`, and `S` are all nonnegative and -1 if the first nonzero element of `[D M S]` is negative (an error results if a nonzero element is followed by a negative element). Any fractional parts in the first (degrees) and second (minutes) columns of `DMS` are ignored. An error results unless the absolute values of all elements in the second (minutes) and third (seconds) columns are less than 60.

## Example

```
dms = [ ...
        30  50 44.78012; ...
       -82   2 39.90825; ...
         0 -30 17.12345; ...
         0   0 14.82000];
format long g
angleInDegrees = dms2degrees(dms)
```



```
angleInDegrees =  
    30.8457722555556  
    -82.0444189583333  
    -0.504756513888889  
    0.00411666666666667
```

## See Also

degrees2dm, degtorad, dm2degrees, str2angle

# dreckon

---

## Purpose

Dead reckoning positions for track

## Syntax

```
[drlat,drlong,drttime] = dreckon(waypoints,time,speed)
[drlat,drlong,drttime] = dreckon (waypoints,time,speed,
    spdtimes)
```

## Description

[drlat,drlong,drttime] = dreckon(waypoints,time,speed) returns the positions and times of required dead reckoning (DR) points for the input track that starts at the input time. The track should be in navigational track format (two columns, latitude then longitude, in order of traversal). These waypoints are the starting and ending points of each leg of the track. There is one fewer track leg than waypoints, as the last point included is the end of the track. In navigation, the first waypoint would be a navigational fix, taken at time. The speed input can be a scalar, in which case a constant speed is used throughout, or it can be a vector in which one speed is given for each track leg (that is, speed changes coincide with course changes).

[drlat,drlong,drttime] = dreckon (waypoints,time,speed,spdtimes) allows speed changes to occur independent of course changes. The elements of the speed vector must have a one-to-one correspondence with the elements of the spdtimes vector. This latter variable consists of the time interval after time at which each speed order *ends*. For example, if time is 6.75, and the first element of spdtimes is 1.35, then the first speed element is in effect from 6.75 to 8.1 hours. When this syntax is used, the last output DR is the *earlier* of the final spdtimes time or the final waypoints point.

## Background

This is a navigational function. It assumes that all latitudes and longitudes are in degrees, all distances are in nautical miles, all times are in hours, and all speeds are in knots, that is, nautical miles per hour.

Dead reckoning is an estimation of position at various times based on courses, speeds, and times elapsed from the last certain position, or fix. In navigational practice, a dead reckoning position, or DR, must be plotted at every course change, every speed change, and at every hour,

on the hour. Navigators also DR at other times that are not relevant to this function.

Often in practice, when two events occur that require DRs within a very short time, only one DR is generated. This function mimics that practice by setting a tolerance of 3 minutes (0.05 hours). No two DRs will fall closer than that.

Refer to “Navigation” in the *Mapping Toolbox Guide* for further information.

## Examples

Assume that a navigator gets a fix at noon, 1200Z, which is (10.3°N, 34.67°W). He’s in a hurry to make a 1330Z rendezvous with another ship at (9.9°N, 34.5°W), so he plans on a speed of 25 knots. After the rendezvous, both ships head for (0°, 37°W). The engineer wants to take an engine off line for maintenance at 1430Z, so at that time, speed must be reduced to 15 knots. At 1530Z, the maintenance will be done. Determine the DR points up to the end of the maintenance.

```

waypoints = [10.1 -34.6; 9.9 -34.5; 0 -37]

waypoints =
    10.1000  -34.6000    % Fix at noon
     9.9000  -34.5000    % Rendezvous point
     0      -37.0000    % Ultimate destination

speed = [25; 15];
spdtimes = [2.5; 3.5];    % Elapsed times after fix
noon = 12;
[drlat,drlong,dertime] = dreckon(waypoints,noon,speed,spdtimes);
[drlat,drlong,dertime]

ans =
    9.8999  -34.4999   12.5354    % Course change at waypoint
    9.7121  -34.5478   13.0000    % On the hour
    9.3080  -34.6508   14.0000    % On the hour
    9.1060  -34.7022   14.5000    % Speed change to 15 kts
    8.9847  -34.7330   15.0000    % On the hour

```

# dreckon

---

```
8.8635 -34.7639 15.5000 % Stop at final spdtime, last  
% waypoint has not been reached
```

**See Also**      legs, navfix, track

**Purpose**

Heading to correct for wind or current drift

**Syntax**

```
heading = driftcorr(course,airspeed,windfrom,windspeed)
[heading,groundspeed,windcorrangle] = driftcorr(...)
```

**Description**

heading = driftcorr(course,airspeed,windfrom,windspeed) computes the heading that corrects for drift due to wind (for aircraft) or current (for watercraft). course is the desired direction of movement (in degrees), airspeed is the speed of the vehicle relative to the moving air or water mass, windfrom is the direction facing into the wind or current (in degrees), and windspeed is the speed of the wind or current (in the same units as airspeed).

[heading,groundspeed,windcorrangle] = driftcorr(...) also returns the ground speed and wind correction angle. The wind correction angle is positive to the right, and negative to the left.

**Example**

An aircraft cruising at a speed of 160 knots plans to fly to an airport due north of its current position. If the wind is blowing from 310 degrees at 45 knots, what heading should the aircraft fly to remain on course?

```
course=0; airspeed=160;windfrom=310; windspeed = 45;
[heading,groundspeed,windcorrangle] =
driftcorr(course,airspeed,windfrom,windspeed)
```

```
heading =
```

```
347.56
```

```
groundspeed =
```

```
127.32
```

```
windcorrangle =
```

```
-12.442
```

## driftcorr

---

The required heading is 348 degrees, which amounts to a wind correction angle of 12 degrees to the left of course. The headwind component reduces the aircraft's ground speed to 127 knots.

### **See Also**

driftvel

---

<b>Purpose</b>	Wind or current from heading, course, and speeds
<b>Syntax</b>	<code>[windfrom,windspeed] = driftvel (course,groundspeed,heading,airspeed)</code>
<b>Description</b>	<code>[windfrom,windspeed] = driftvel (course,groundspeed,heading,airspeed)</code> computes the wind (for aircraft) or current (for watercraft) from course, heading, and speeds. <code>course</code> and <code>groundspeed</code> are the direction and speed of movement relative to the ground (in degrees), <code>heading</code> is the direction in which the vehicle is steered, and <code>airspeed</code> is the speed of the vehicle relative to the air mass or water. The output <code>windfrom</code> is the direction facing into the wind or current (in degrees), and <code>windspeed</code> is the speed of the wind or current (in the same units as <code>airspeed</code> and <code>groundspeed</code> ).
<b>Example</b>	<p>An aircraft is cruising at a true air speed of 160 knots and a heading of 10 degrees. From the Global Positioning System (GPS) receiver, the pilot determines that the aircraft is progressing over the ground at 155 knots in a northerly direction. What is the wind aloft?</p> <pre>course = 0; groundspeed = 155; heading = 10; airspeed = 160; [windfrom,windspeed] = driftvel(course,groundspeed,heading,airspeed)  windfrom =     84.717  windspeed =     27.902</pre> <p>The wind is blowing from the right, 085 degrees at 28 knots.</p>
<b>See Also</b>	<code>driftcorr</code>

**Purpose** Read U.S. Department of Defense Digital Terrain Elevation Data (DTED)

**Syntax**

```
[Z, refvec] = dted  
[Z, refvec] = dted(filename)  
[Z, refvec] = dted(filename, samplefactor)  
[Z, refvec] = dted(filename, samplefactor, latlim, lonlim)  
[Z, refvec] = dted(dirname, samplefactor, latlim, lonlim)  
[Z, refvec, UHL, DSI, ACC] = dted(...)
```

**Description** [Z, refvec] = dted returns all of the elevation data in a DTED file as a regular data grid, Z, with elevations in meters. The file is selected interactively. This function reads the DTED elevation files, which generally have filenames ending in .dtN, where N is 0,1,2,3,... refvec is the associated three-element referencing vector that geolocates Z.

[Z, refvec] = dted(filename) returns all of the elevation data in the specified DTED file. The file must be found on the MATLAB path. If not found, the file may be selected interactively.

[Z, refvec] = dted(filename, samplefactor) subsamples data from the specified DTED file. samplefactor is a scalar integer. When samplefactor is 1 (the default), DTED reads the data at its full resolution. When samplefactor is an integer n greater than one, every nth point is read.

[Z, refvec] = dted(filename, samplefactor, latlim, lonlim) reads the data for the part of the DTED file within the latitude and longitude limits. The limits must be two-element vectors in units of degrees.

[Z, refvec] = dted(dirname, samplefactor, latlim, lonlim) reads and concatenates data from multiple files within a DTED CD-ROM or directory structure. The dirname input is a string with the name of a directory containing the DTED directory. Within the DTED directory are subdirectories for each degree of longitude, each of which contain files for each degree of latitude. For DTED CD-ROMs, dirname is the device name of the CD-ROM drive.



[Z, refvec, UHL, DSI, ACC] = dted(...) returns structures containing the DTED User Header Label (UHL), Data Set Identification (DSI) and ACCuracy metadata records.

## Background

The U. S. Department of Defense, through the National Geospatial Intelligence Agency, produces several kinds of digital cartographic data. One is digital elevation data, in a series called DTED, for Defense Digital Terrain Elevation Data. The data is available as 1-by-1 degree quadrangles at horizontal resolutions ranging from about 1 kilometer to 1 meter. The lowest resolution data is available to the public. Certain higher resolution data is restricted to the U.S. Department of Defense and its contractors.

DTED Level 0 files have 121-by-121 points. DTED Level 1 files have 1201-by-1201. The edges of adjacent tiles have redundant records. Maps extend a half a cell outside the requested map limits. The 1 kilometer data and some higher-resolution data is available online, as are product specifications and documentation. DTED files are binary. No line ending conversion or byte-swapping is required when downloading a DTED file.

## Remarks

### Latitude-Dependent Sampling

In DTED files north of 50° North and south of 50° South, where the meridians have converged significantly relative to the equator, the longitude sampling interval is reduced to half of the latitude sampling interval. In order to retain square output cells, this function reduces the latitude sampling to match the longitude sampling. For example, it will return a 121-by-121 elevation grid for a DTED file covering from 49 to 50 degrees north, but a 61-by-61 grid for a file covering from 50 to 51 degrees north. When you supply a directory name instead of a file name, and `latlim` spans either 50° North or 50° South, an error results.

### Snapping Latitude and Longitude Limits

If you call `dted` specifying arbitrary latitude-longitude limits for a region of interest, the grid and referencing vector returned will not exactly honor the limits you specified unless they fall precisely on grid cell boundaries. Because grid cells are discrete and cannot be arbitrarily

divided, the data grid returned will include all areas between your latitude-longitude limits and the next row or column of cells, potentially in all four directions.

## Data Sources and Information

DTED files contain digital elevation maps covering 1-by-1-degree quadrangles at horizontal resolutions ranging from about 1 kilometer to 1 meter. For details on locating DTED for download over the Internet, see the following documentation at the MathWorks Web site:

<http://www.mathworks.com/support/tech-notes/2100/2101.html>

## Null Data Values

Some DTED Level 1 and higher data tiles contain null data cells, coded with value -32767. When encountered, these null data values are converted to NaN.

## Nonconforming Data Encoding

DTED files from some sources may depart from the specification by using two's complement encoding for binary elevation files instead of "sign-bit" encoding. This difference affects the decoding of negative values, and incorrect decoding usually leads to nonsensical elevations.

Thus, if the DTED function determines that all the (nonnull) negative values in a file would otherwise be less than -12,000 meters, it issues a warning and assumes two's complement encoding.

## Examples

```
[Z,refvec] = dted('n38.dt0');  
[Z,refvec,UHL,DSI,ACC] = dted('n38.dt0',1,[38.5 38.8],...  
    [-76.8 -76.6]);  
[Z,refvec,UHL,DSI,ACC] = dted('f:',1,[38.5 38.8],...  
    [-76.8 -76.6]);
```

## See Also

usgsdem, gtopo30, tbase, etopo

---

<b>Purpose</b>	DTED filenames for latitude-longitude quadrangle
<b>Syntax</b>	<pre>fname = dteds(latlim,lonlim) fname = dteds(latlim,lonlim,level)</pre>
<b>Description</b>	<p>fname = dteds(latlim,lonlim) returns Level 0 DTED file names (directory and name) required to cover the geographic region specified by latlim and lonlim.</p> <p>fname = dteds(latlim,lonlim,level) controls the level for which the file names are generated. Valid inputs for the level of the DTED files include 0, 1, or 2.</p>
<b>Background</b>	<p>The U. S. Department of Defense produces several kinds of digital cartographic data. One is digital elevation data, in a series called DTED, for Defense Digital Terrain Elevation Data. The data is available as 1-by-1 degree quadrangles at horizontal resolutions ranging from about 1 kilometer to 1 meter. The lowest resolution data is available to the public. Higher resolution data is restricted to the U.S. Department of Defense and its contractors.</p> <p>Determining the files needed to cover a particular region requires knowledge of the DTED database naming conventions. This function constructs the file names for a given geographic region based on these conventions.</p>
<b>Examples</b>	<p>Which files are needed for Cape Cod?</p> <pre>latlim = [ 41.15 42.22]; lonlim = [-70.94 -69.68]; dteds(latlim,lonlim,1)  ans =     '\DTED\W071\N41.dt1'     '\DTED\W070\N41.dt1'     '\DTED\W071\N42.dt1'     '\DTED\W070\N42.dt1'</pre>
<b>See Also</b>	dted

# eastof

---

## Purpose

Wrap longitudes to values east of specified meridian

---

**Note** The `eastof` function is obsolete and will be removed in a future release of Mapping Toolbox software. Replace it with the following calls, which are also more efficient:

```
eastof(lon,meridian,'degrees') ==> meridian+mod(lon-meridian,360)
```

```
eastof(lon,meridian,'radians') ==> meridian+mod(lon-meridian,2*pi)
```

---

## Syntax

```
lonWrapped = eastof(lon,meridian)
```

```
lonWrapped = eastof(lon,meridian,angleunits)
```

## Description

`lonWrapped = eastof(lon,meridian)` wraps angles in `lon` to values in the interval `[meridian meridian+360)`. `lon` is a scalar longitude or vector of longitude values. All inputs and outputs are in degrees.

`lonWrapped = eastof(lon,meridian,angleunits)` specifies the input and output units with the string *angleunits*. *angleunits* can be either 'degrees' or 'radians'. It may be abbreviated and is case-insensitive. If *angleunits* is 'radians', the input is wrapped to the interval `[meridian meridian+2*pi)`.

**Purpose**                    Flattening of ellipse with given eccentricity

**Syntax**                    `flattening = ecc2flat(eccentricity)`

**Description**                `flattening = ecc2flat(eccentricity)` returns the equivalent flattening for the input eccentricities. If the input, `eccentricity`, is a two-column vector, only the second column is used. This allows the standard two-element ellipsoid vectors to be used as rows of the input, because the second element of these vectors is the eccentricity. In all other cases, all columns of the input are used.

Flattening and eccentricity are two methods of defining an ellipsoid.

**Example**                    `flattening = ecc2flat(almanac('earth','ellipsoid'))`  
  
`flattening =`  
`0.0034`

**See Also**                    `almanac`, `ecc2n`, `majaxis`, `flat2ecc`

**Purpose** n-value of ellipse with given eccentricity

**Syntax** `n = ecc2n(eccentricity)`

**Description** `n = ecc2n(eccentricity)` returns the equivalent  $n$  for the input eccentricities. If the input, `eccentricity`, is a two-column vector, only the second column is used. This allows the standard two-element ellipsoid vectors to be used as rows of the input, because the second element of these vectors is the eccentricity. In all other cases, all columns of the input are used.

Eccentricity and the parameter  $n$  are two methods of defining an ellipsoid. The definition of  $n$  is

$$\frac{(\text{semimajor axis} - \text{semiminor axis})}{(\text{semimajor axis} + \text{semiminor axis})}$$

**Example**

```
n = ecc2n(almanac('earth','ellipsoid'))
n =
    0.00167922039463
```

**See Also** `almanac`, `ecc2flat`, `majaxis`, `n2ecc`

<b>Purpose</b>	Convert geocentric (ECEF) to geodetic coordinates
<b>Syntax</b>	<code>[phi,lambda,h] = ecef2geodetic(x,y,z,ellipsoid)</code>
<b>Description</b>	<code>[phi,lambda,h] = ecef2geodetic(x,y,z,ellipsoid)</code> converts geocentric Cartesian coordinates, stored in the coordinate arrays <code>x</code> , <code>y</code> , <code>z</code> , to geodetic coordinates <code>phi</code> (geodetic latitude in radians), <code>lambda</code> (geodetic longitude in radians), and <code>h</code> (height above the ellipsoid). The geodetic coordinates refer to the reference ellipsoid specified by <code>ellipsoid</code> (a row vector with the form <code>[semimajor axis, eccentricity]</code> ). Arrays <code>x</code> , <code>y</code> , <code>z</code> , and <code>h</code> must use the same units as the semimajor axis. <code>x</code> , <code>y</code> , <code>z</code> , <code>phi</code> , <code>lambda</code> , and <code>h</code> must have the same shape.
<b>Definitions</b>	For a definition of the geocentric system, also known as Earth-Centered, Earth-Fixed (ECEF), see the help for <code>geodetic2ecef</code> .
<b>See Also</b>	<code>ecef2lv</code>   <code>geodetic2ecef</code>   <code>lv2ecef</code>

**Purpose**

Convert geocentric (ECEF) to local vertical coordinates

**Syntax**

```
[x1,y1,z1] = ecef2lv(x,y,z,phi0,lambda0,h0,ellipsoid)
```

**Description**

```
[x1,y1,z1] = ecef2lv(x,y,z,phi0,lambda0,h0,ellipsoid)
```

converts geocentric point locations specified by the coordinate arrays  $x$ ,  $y$ , and  $z$  to the local vertical coordinate system, with its origin at geodetic latitude  $\phi_0$ , longitude  $\lambda_0$ , and ellipsoidal height  $h_0$ . The arrays  $x$ ,  $y$ , and  $z$  may be of any shape, as long as they all match in size.  $\phi_0$ ,  $\lambda_0$ , and  $h_0$  must be scalars. `ellipsoid` is a row vector with the form `[semimajor axis,eccentricity]`.  $x$ ,  $y$ ,  $z$ , and  $h_0$  must have the same length units as the semimajor axis.  $\phi_0$  and  $\lambda_0$  must be in radians. The output coordinate arrays,  $x_1$ ,  $y_1$ , and  $z_1$  are the local vertical coordinates of the input points. They have the same size as  $x$ ,  $y$ , and  $z$  and have the same length units as the semimajor axis.

In the local vertical Cartesian system defined by  $\phi_0$ ,  $\lambda_0$ ,  $h_0$ , and `ellipsoid`, the  $x_1$  axis is parallel to the plane tangent to the ellipsoid at  $(\phi_0,\lambda_0)$  and points due east. The  $y_1$  axis is parallel to the same plane and points due north. The  $z_1$  axis is normal to the ellipsoid at  $(\phi_0,\lambda_0)$  and points outward into space. The local vertical system is sometimes referred to as east-north-up or ENU.

**Definitions**

For a definition of the *geocentric system*, also known as Earth-Centered, Earth-Fixed (ECEF), see the help for `geodetic2ecef`.

**See Also**

`ecef2geodetic` | `elevation` | `geodetic2ecef` | `lv2ecef`



**Purpose**

Read 15-minute gridded geoid heights from EGM96

**Syntax**

```
[N, refvec] = egm96geoid(samplefactor)
[N, refvec] = egm96geoid(samplefactor, latlim, lonlim)
```

**Description**

[N, refvec] = egm96geoid(samplefactor) imports global geoid height in meters from the EGM96 geoid model. The data set is gridded at 15-minute intervals, but may be down-sampled as specified by the positive integer samplefactor. The result is returned in the regular data grid N along with referencing vector refvec. At full resolution (a samplefactor of 1), N will be 721-by-1441.

The gridded EGM96 data set must be on your path in a file named 'WW15MGH.GRD'.

[N, refvec] = egm96geoid(samplefactor, latlim, lonlim) imports data for the part of the world within the specified latitude and longitude limits. The limits must be two-element vectors in units of degrees. Longitude limits can be defined in the range [-180 180] or [0 360]. For example, lonlim = [170 190] returns data centered on the dateline, while lonlim = [-10 10] returns data centered on the prime meridian.

**Background**

Although the Earth is round, it is not exactly a sphere. The shape of the Earth is usually defined by the geoid, which is defined as a gravitational equipotential surface, but can be conceptualized as the shape the ocean surface would take in the absence of waves, weather, and land. For cartographic purposes it is generally sufficient to treat the Earth as a sphere or ellipsoid of revolution. For other applications, a more detailed model of the geoid such as EGM 96 may be required. EGM 96 is a spherical harmonic model of the geoid complete to degree and order 360. This function reads from a file of gridded geoid heights derived from the EGM 96 harmonic coefficients.

**Examples**

Read the EGM 96 geoid grid for the world, taking every 10th point.

```
[N, refvec] = egm96geoid(10);
```

# egm96geoid

---

Read a subset of the geoid grid at full resolution and interpolate to find the geoid height at a point between grid points.

```
[N,refvec] = egm96geoid(1,[-10 -12],[129 132]);  
n = ltln2val(N,refvec,-11.1,130.22,'bicubic')  
  
n =  
    52.7151
```

## Remarks

This function reads the 15-minute EGM96 grid file WW15MGH.GRD. The grid is available as either a DOS self-extracting compressed file or a UNIX compressed file. Do not modify the file once it has been extracted.

---

**Note** For details on locating map data for download over the Internet, see the following documentation at the MathWorks Web site: <http://www.mathworks.com/support/tech-notes/2100/2101.html>

---

Maps will extend a half a cell outside the requested map limits.

There are 721 rows and 1441 columns of values in the grid at full resolution. The low resolution data in GEOID.MAT is derived from the EGM 96 grid.

## See Also

ltln2val

**Purpose**

Local vertical elevation angle, range, and azimuth

**Syntax**

```
[elevationangle, slantrange, azimuthangle] = ...
    elevation(lat1, lon1, alt1, lat2, lon2, alt2)
[...] = elevation(lat1, lon1, alt1, lat2, lon2, alt2, ...
    angleunits)
[...] = elevation(lat1, lon1, alt1, lat2, lon2, alt2, ...
    angleunits, distanceunits)
[...] = elevation(lat1, lon1, alt1, lat2, lon2, alt2, ...
    angleunits, ellipsoid)
```

**Description**

```
[elevationangle, slantrange, azimuthangle] = ...
    elevation(lat1, lon1, alt1, lat2, lon2, alt2)
```

computes the elevation angle, slant range, and azimuth angle of point 2 (with geodetic coordinates `lat2`, `lon2`, and `alt2`) as viewed from point 1 (with geodetic coordinates `lat1`, `lon1`, and `alt1`). The coordinates `alt1` and `alt2` are ellipsoidal heights. The elevation angle is the angle of the line of sight above the local horizontal at point 1. The slant range is the three-dimensional Cartesian distance between point 1 and point 2. The azimuth is the angle from north to the projection of the line of sight on the local horizontal. Angles are in units of degrees; altitudes and distances are in meters. The figure of the earth is the default ellipsoid (GRS 80) as defined by `almanac`.

Inputs can be vectors of points, or arrays of any shape, but must match in size, with the following exception: Elevation, range, and azimuth from a single point to a set of points can be computed very efficiently by providing scalar coordinate inputs for point 1 and vectors or arrays for point 2.

```
[...] = elevation(lat1, lon1, alt1, lat2, lon2, alt2, ...
    angleunits)
```

uses the string `angleunits` to specify the units of the input and output angles. If the string `angleunits` is omitted, 'degrees' is assumed.

```
[...] = elevation(lat1, lon1, alt1, lat2, lon2, alt2, ...
    angleunits, distanceunits)
```

uses the string `distanceunits` to specify the altitude and slant-range units. If the string `distanceunits`

# elevation

---

is omitted, 'meters' is assumed. Any units string recognized by `unitsratio` may be used.

```
[...] = elevation(lat1,lon1,alt1,lat2,lon2,alt2,...  
    angleunits,ellipsoid)
```

uses the vector `ellipsoid`, with form `[semimajor axis, eccentricity]`, to specify the ellipsoid. If `ellipsoid` is supplied, the altitudes must be in the same units as the semimajor axis, and the slant range will be returned in these units. If `ellipsoid` is omitted, the default earth ellipsoid defined by `azimuth` is used, and distances are in meters unless otherwise specified.

---

**Note** The line-of-sight azimuth angles returned by `elevation` will generally differ slightly from the corresponding outputs of `azimuth` and `distance`, except for great circle azimuths on a spherical earth.

---

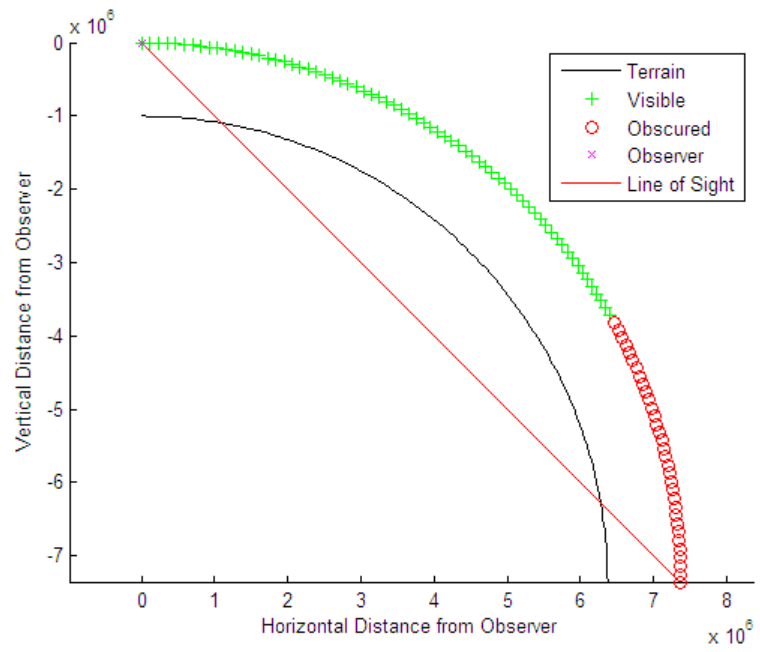
## Examples

Find the elevation angle of a point 90 degrees from an observer assuming that the observer and the target are both 1000 km above the Earth.

```
lat1 = 0; lon1 = 0; alt1 = 1000*1000;  
lat2 = 0; lon2 = 90; alt2 = 1000*1000;  
elevang = elevation(lat1,lon1,alt1,lat2,lon2,alt2)  
  
elevang =  
    -45
```

Visually check the result using the `los2` line of sight function. Construct a data grid of zeros to represent the Earth's surface. The `los2` function with no output arguments creates a figure displaying the geometry.

```
Z = zeros(180,360);  
refvec = [1 90 -180];  
los2(Z,refvec,lat1,lon1,lat2,lon2,alt1,alt1);
```



**See Also**

almanac | azimuth | distance

# ellipse1

---

## Purpose

Geographic ellipse from center, semimajor axes, eccentricity, and azimuth

## Syntax

```
[lat,lon] = ellipse1(lat0,lon0,ellipse)
[lat,lon] = ellipse1(lat0,lon0,ellipse,offset)
[lat,lon] = ellipse1(lat0,lon0,ellipse,offset,az)
[lat,lon] = ellipse1(lat0,lon0,ellipse,offset,az,ellipsoid)
[lat,lon] = ellipse1(lat0,lon0,ellipse,offset,units)

[lat,lon] = ellipse1(lat0,lon0,ellipse,offset,az,
                    ellipse,offset,az,ellipsoid,
                    units,npts)
[lat,lon] = ellipse1(track,...)
mat = ellipse1(...)
```

## Description

`[lat,lon] = ellipse1(lat0,lon0,ellipse)` computes ellipse(s) with center(s) at `lat0,lon0`. The ellipse is defined by the third input, which is of the form `[semimajor axis, eccentricity]`, where the eccentricity input can be a two-element row vector or a two-column matrix. The ellipse input must have the same number of rows as the input scalar or column vectors `lat0` and `lon0`. The input semimajor axis is in degrees of arc length on a sphere. All ellipses are oriented so that their major axes run north-south.

`[lat,lon] = ellipse1(lat0,lon0,ellipse,offset)` computes the ellipse(s) where the major axis is rotated from due north by an azimuth `offset`. The `offset` angle is measured clockwise from due north. If `offset = []`, then no `offset` is assumed.

`[lat,lon] = ellipse1(lat0,lon0,ellipse,offset,az)` uses the input `az` to define the ellipse arcs computed. The arc azimuths are measured clockwise from due north. If `az` is a column vector, then the arc length is computed from due north. If `az` is a two-column matrix, then the ellipse arcs are computed starting at the azimuth in the first column and ending at the azimuth in the second column. If `az = []`, then a complete ellipse is computed.

`[lat,lon] = ellipse1(lat0,lon0,ellipse,offset,az,ellipsoid)` computes the ellipse on the ellipsoid defined by the input `ellipsoid` vector, of the form `[semimajor axis,eccentricity]`. If omitted, the unit sphere, `ellipsoid = [1 0]`, is assumed. When an ellipsoid is supplied, the input semimajor axis must be in the same units as the ellipsoid semimajor axes. In this calling form, the units of the ellipse semimajor axis are not assumed to be in degrees.

`[lat,lon] = ellipse1(lat0,lon0,ellipse,offset,units)`,  
`[lat,lon] = ellipse1(lat0,lon0,ellipse,offset,az,units)`, and  
`[lat,lon] = ellipse1(lat0,lon0,ellipse,offset,az,ellipsoid,units)` are all valid calling forms, which use the input `units` to define the angle units of the inputs and outputs. If the `units` string is omitted, 'degrees' is assumed.

`[lat,lon] = ellipse1(lat0,lon0,ellipse,offset,az,ellipsoid,units,npts)` uses the scalar `npts` to determine the number of points per ellipse computed. If `npts` is omitted, 100 points are used.

`[lat,lon] = ellipse1(track,...)` uses the `track` string to define either great circle or rhumb line distances from the ellipse center. If `track = 'gc'`, then great circle distances are computed (the default). If `track = 'rh'`, then rhumb line distances are computed.

`mat = ellipse1(...)` returns a single output argument where `mat = [lat lon]`. This is useful if only one ellipse is computed.

You can define multiple ellipses with a common center by providing scalar `lat0` and `lon0` inputs and a two-column ellipse matrix.

## Examples

Create and plot the small ellipse centered at  $(0^\circ,0^\circ)$ , with a semimajor axis of  $10^\circ$  and a semiminor axis of  $5^\circ$ .

```
axesm mercator
ecc = axes2ecc(10,5);
plotm(0,0,'r+')
[elat,elon] = ellipse1(0,0,[10 ecc],45);
```

# ellipse1

---

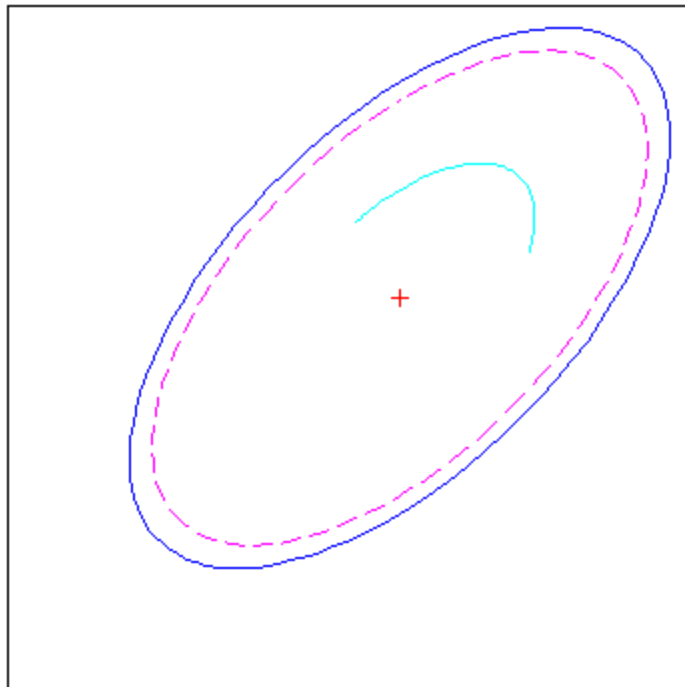
```
plotm(elat,elon)
```

If the desired radius is known in some nonangular distance unit, use the radius returned by the `almanac` function as the ellipsoid input to set the range units. (Use an empty azimuth entry to specify a full ellipse.)

```
earthradius = almanac('earth','radius','nm');  
[elat,elon] = ellipse1(0,0,[550 ecc],45,[],earthradius);  
plotm(elat,elon,'m--')
```

For just an arc of the ellipse, enter an azimuth range:

```
[elat,elon] = ellipse1(0,0,[5 ecc],45,[-30 70]);  
plotm(elat,elon,'c-')
```





**See Also**      `axes2ecc` | `scircle1` | `track1`

# encodem

---

**Purpose** Fill in regular data grid from seed values and locations

**Syntax**  
`newgrid = encodem(Z,seedmat)`  
`newgrid = encodem(Z,seedmat,stopvals)`

**Description** `newgrid = encodem(Z,seedmat)` fills in regions of the input data grid, `Z`, with desired new values. The boundary consists of the edges of the matrix and any entries with the value 1. The *seeds*, or starting points, and the values associated with them, are specified by the three-column matrix `seedmat`, the rows of which have the form [row column value].

`newgrid = encodem(Z,seedmat,stopvals)` allows you to specify a vector, `stopvals`, of stopping values. Any value that is an element of `stopvals` will act as a boundary.

This function *fills in* regions of data grids with desired values. If a *boundary* exists, the new value replaces all entries in all four directions until the boundary is reached. The boundary is made up of selected stopping values and the edges of the matrix. The new value tries to flood the region exhaustively, stopping only when no new spaces can be reached by moving up, down, left, or right without hitting a stopping value.

**Examples** For this imaginary map, fill in the upper right region with 7s and the lower left region with 3s:

```
Z = eye(4)

Z =
    1    0    0    0
    0    1    0    0
    0    0    1    0
    0    0    0    1

newgrid = encodem(Z,[4,1,3; 1,4,7])

newgrid =
    1    7    7    7
```

3	1	7	7
3	3	1	7
3	3	3	1

## See Also

`getseeds`, `imbedm`

# epsm

---

**Purpose** Accuracy in angle units for certain map computations

**Syntax** epsm  
epsm(*units*)

**Description** epsm is the limit of map angular precision. It is useful in avoiding trigonometric singularities, among other things.  
epsm(*units*) returns the same angle in units corresponding to any valid angle units string. The default is 'degrees'.

**Examples** The value of epsm is  $10^{-6}$  degrees. To put this in perspective, in terms of an angular arc length, the distance is

```
epsmkm = deg2km(epsm)

epsmkm =
    1.1119e-04    % kilometers
```

This is about 11 centimeters, a very small distance on a global scale.

**See Also** roundn

**Purpose** Convert from equal area to Greenwich coordinates

**Syntax**

```
[lat,lon] = eqa2grn(x,y)
[lat,lon] = eqa2grn(x,y,origin)
[lat,lon] = eqa2grn(x,y,origin,ellipsoid)
[lat,lon] = eqa2grn(x,y,origin,units)
mat = eqa2grn(x,y,origin...)
```

**Description**

`[lat,lon] = eqa2grn(x,y)` converts the equal-area coordinate points `x` and `y` to the Greenwich (standard geographic) coordinates `lat` and `lon`.

`[lat,lon] = eqa2grn(x,y,origin)` specifies the location in the Greenwich system of the `x-y` origin (0,0). The two-element vector `origin` must be of the form `[latitude longitude]`. The default places the origin at the Greenwich coordinates (0°,0°).

`[lat,lon] = eqa2grn(x,y,origin,ellipsoid)` specifies the two-element ellipsoid vector describing the ellipsoidal model of the figure of the Earth. The `ellipsoid` is spherical by default.

`[lat,lon] = eqa2grn(x,y,origin,units)` specifies the units for the outputs, where `units` is any valid angle units string. The default value is 'degrees'.

`mat = eqa2grn(x,y,origin...)` packs the outputs into a single variable.

This function converts data from equal-area `x-y` coordinates to geographic (latitude-longitude) coordinates. The opposite conversion can be performed with `grn2eqa`.

**Examples**

```
[lat,lon] = eqa2grn(.5,.5)

lat =
    30.0000
lon =
    28.6479
```

## eqa2grn

---

### **See Also**

grn2eqa, hista

**Purpose**

Read gridded global relief data (ETOPO products)

**Syntax**

```
[Z, refvec] = etopo
[Z, refvec] = etopo(samplefactor)
[Z, refvec] = etopo(samplefactor, latlim, lonlim)
[Z, refvec] = etopo(directory, ...)
[Z, refvec] = etopo(filename, ...)
[Z, refvec] = etopo({'etopo5.northern.bat',
                    'etopo5.southern.bat'}, ...)
```

**Description**

[Z, refvec] = etopo reads the ETOPO data for the entire world from the ETOPO data in the current directory. The etopo function searches the current directory first for ETOPO1c binary data, then ETOPO2V2c binary data, then ETOPO2 (2001) binary data, then ETOPO5 binary data, and finally ETOPO5 ASCII data. Once the function finds a case-insensitive file name match, it reads the data. See the table Supported ETOPO Data File Names on page 3-194 for a list of possible file names. The etopo function returns the data grid, Z, as an array of elevations. Data values, in whole meters, represent the elevation of the center of each cell. refvec, the associated three-element referencing vector, geolocates Z.

[Z, refvec] = etopo(samplefactor) reads the data for the entire world, downsampling the data by samplefactor. The scalar integer samplefactor when equal to 1 gives the data at its full resolution (10800 by 21600 values for ETOPO1 data, 5400 by 10800 values for ETOPO2 data, and 2160 by 4320 values for ETOPO5 data). When samplefactor is an integer  $n$  greater than one, the etopo function returns every  $n^{\text{th}}$  point. If you omit samplefactor or leave it empty, it defaults to 1. (If the etopo function reads an older, ASCII ETOPO5 data set, then samplefactor must divide evenly into the number of rows and columns of the data file.)

[Z, refvec] = etopo(samplefactor, latlim, lonlim) reads the data for the part of the world within the specified latitude and longitude limits. Specify the limits of the desired data as two-element vectors of latitude, latlim, and longitude, lonlim, in degrees. Specify the elements of latlim and lonlim in ascending order. Specify lonlim in

the range [0 360] for ETOPO5 data and [-180 180] for ETOPO2 and ETOPO1 data. If `latlim` is empty, the latitude limits are [-90 90]. If `lonlim` is empty, the file type determines the longitude limits.

`[Z, refvec] = etopo(directory, ...)` allows you to use the variable `directory` to specify the path for the ETOPO data file. Otherwise, the `etopo` function searches the current directory for the data.

`[Z, refvec] = etopo(filename, ...)` reads the ETOPO data from `filename`. The variable `filename`, a case-insensitive string, specifies the name of the ETOPO file, as referenced in the ETOPO data file names table. Include the directory name in `filename` or place the file in the current directory or in a directory on the MATLAB path.

`[Z, refvec] = etopo({'etopo5.northern.bat', 'etopo5.southern.bat'}, ...)` reads the ETOPO data from the specified case-insensitive ETOPO5 ASCII data files. Place the files in the current directory or in a directory on the MATLAB path.

## Tips

### Supported ETOPO Data File Names

Format	Filenames
ETOPO1c (cell)	<ul style="list-style-type: none"><li>• <code>etopo1_ice_c.flt</code></li><li>• <code>etopo1_bed_c.flt</code></li></ul>
ETOPO2V2c (cell)	<ul style="list-style-type: none"><li>• <code>ETOP02V2c_i2_MSB.bin</code></li><li>• <code>ETOP02V2c_i2_LSB.bin</code></li><li>• <code>ETOP02V2c_f4_MSB.flt</code></li><li>• <code>ETOP02V2c_f4_LSB.flt</code></li><li>• <code>ETOP02V2c.hdf</code></li></ul>
ETOPO2 (2001)	<ul style="list-style-type: none"><li>• <code>ETOP02.dos.bin</code></li><li>• <code>ETOP02.raw.bin</code></li></ul>



### Supported ETOPO Data File Names (Continued)

Format	Filenames
ETOPO5 (binary)	<ul style="list-style-type: none"> <li>• ETOPO5.DOS</li> <li>• ETOPO5.DAT</li> </ul>
ETOPO5 (ASCII)	<ul style="list-style-type: none"> <li>• etopo5.northern.bat</li> <li>• etopo5.southern.bat</li> </ul>

- For details on locating ETOPO data for download over the Internet, see the following documentation at the MathWorks™ Web site:  
<http://www.mathworks.com/support/tech-notes/2100/2101.html>.

## Definitions

According to the National Geophysical Data Center (NGDC) Web site, ETOPO models combine regional and global land topography and ocean bathymetry data from many data sources. ETOPO1, the most recent model, has an Ice Surface version showing the top of the Antarctic and Greenland ice sheets and a Bedrock version showing the bedrock below the ice sheets. For detailed information about the data sources used to create the ETOPO1 model, see the NGDC Web site. NGDC lists the ETOPO2 and ETOPO5 models as deprecated but still available.

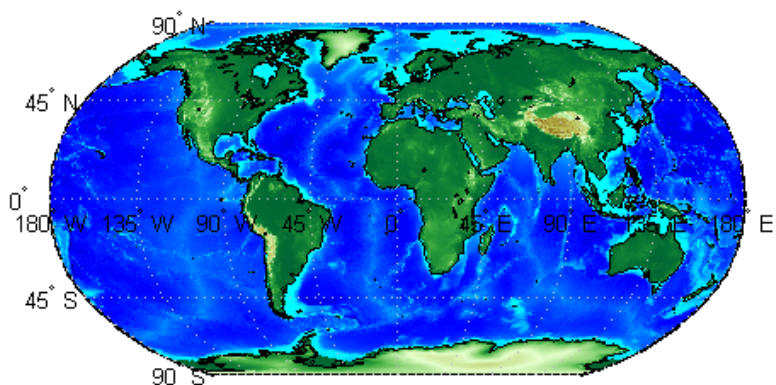
Model	Cell Size	Date Available
ETOPO1	1-arc-minute	March 2009
ETOPO2v2	2-minute	2006
ETOPO2	2-minute	2001
ETOPO5	5-minute	1988

## Examples

Read and display ETOPO2V2c data from the file 'ETOPO2V2c\_i2\_LSB.bin' downsampled to half-degree cell size and display the boundary of the land areas.

```
samplefactor = 15;
```

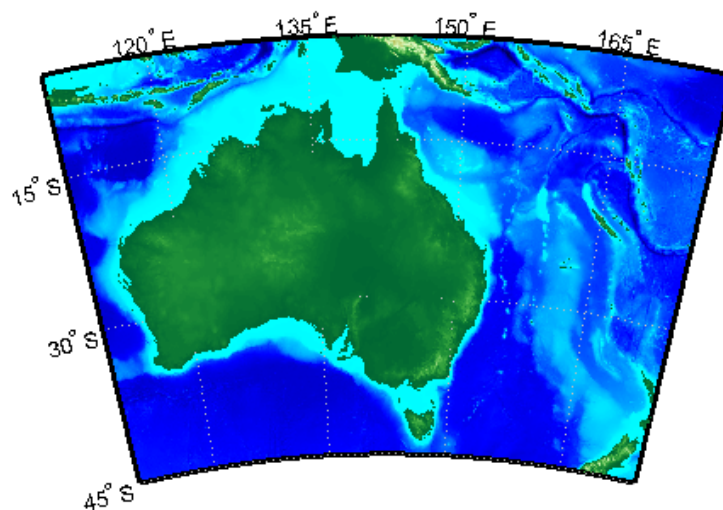
```
[Z, refvec] = etopo('ETOPO2V2c_i2_LSB.bin', samplefactor);  
figure  
worldmap world  
geoshow(Z, refvec, 'DisplayType', 'texturemap');  
demcmap(Z, 256);  
geoshow('landareas.shp', 'FaceColor', 'none', ...  
        'EdgeColor', 'black');
```



---

Read and display ETOPO1 data for a region around Australia.

```
figure  
worldmap australia  
mstruct = gcm;  
latlim = mstruct.maplatlimit;  
lonlim = mstruct.maplonlimit;  
[Z, refvec] = etopo('etopo1_ice_c.flt', 1, latlim, lonlim);  
geoshow(Z, refvec, 'DisplayType', 'surface');  
demcmap(Z, 256);
```



## References

- [1] “2-minute Gridded Global Relief Data (ETOPO2v2),” U.S. Department of Commerce, National Oceanic and Atmospheric Administration, National Geophysical Data Center, 2006.
- [2] Amante, C. and B. W. Eakins, “ETOPO1 1 Arc-Minute Global Relief Model: Procedures, Data Sources and Analysis,” *NOAA Technical Memorandum NESDIS NGDC-24*, March 2009.
- [3] “Digital Relief of the Surface of the Earth,” *Data Announcement 88-MGG-02*, NOAA, National Geophysical Data Center, Boulder, Colorado, 1988.
- [4] “ETOPO2v2 Global Gridded 2-minute Database,” National Geophysical Data Center, National Oceanic and Atmospheric Administration, U.S. Dept. of Commerce.

## See Also

gtopo30 | tbase | usgsdem

## Purpose

Read global 5-min digital terrain data

## Syntax

---

**Note** etopo5 will be removed in a future version; use etopo instead.

---

```
[Z, refvec] = etopo5
[Z, refvec] = etopo5(samplefactor)
[[Z, refvec] = etopo5(samplefactor, latlim, lonlim)
[Z, refvec] = etopo5(directory, ...)
[Z, refvec] = etopo5(file, ...)
```

## Description

[Z, refvec] = etopo5 reads the topography data for the entire world for the data in the current directory. The current directory is searched first for ETOPO2 binary data, followed by ETOPO5 binary data, followed by ETOPO5 ASCII data from the file names etopo5.northern.bat and etopo5.southern.bat. Once a match is found the data is read. The data grid, Z, is returned as an array of elevations. Data values are in whole meters, representing the elevation of the center of each cell. refvec is the associated three-element referencing vector that geolocates Z.

[Z, refvec] = etopo5(samplefactor) reads the data for the entire world, downsampling the data by samplefactor. samplefactor is a scalar integer, which when equal to 1 gives the data at its full resolution (1080 by 4320 values). When samplefactor is an integer n greater than one, every n<sup>th</sup> point is returned. samplefactor must divide evenly into the number of rows and columns of the data file. If samplefactor is omitted or empty, it defaults to 1.

[[Z, refvec] = etopo5(samplefactor, latlim, lonlim) reads the data for the part of the world within the specified latitude and longitude limits. The limits of the desired data are specified as two-element vectors of latitude, latlim, and longitude, lonlim, in degrees. The elements of latlim and lonlim must be in ascending order. If latlim is empty the latitude limits are [-90 90]. lonlim must be specified in the range [0 360]. If lonlim is empty, the longitude limits are [0 360].

`[Z, refvec] = etopo5(directory, ...)` allows the path for the data file to be specified by `directory` rather than the current directory.

`[Z, refvec] = etopo5(file, ...)` reads the data from `file`, where `file` is a string or a cell array of strings containing the name or names of the data files.

ETOPO5 is being superseded by ETOPO2 and the TerrainBase digital terrain model. See the `tbase` external interface function for more information.

---

**Note** For details on locating map data for download over the Internet, see the following documentation at the MathWorks Web Site:  
<http://www.mathworks.com/support/tech-notes/2100/2101.html>

---

## Examples

### Example 1

Read every tenth point in the data set:

```
% Read and display the ETOPO5 data from the directory 'etopo5'
% downsampled by a factor of 10.
[Z, refvec] = etopo5('etopo5',10);
axesm merc
geoshow(Z, refvec, 'DisplayType', 'surface');
colormap(demcmap(Z));
```

### Example 2

Read in data for Korea and Japan at the full resolution:

```
samplefactor = 1; latlim = [30 45]; lonlim = [115 145];
[Z,refvec] = etopo5(samplefactor,latlim,lonlim);
whos Z
```

Name	Size	Bytes	Class
Z	180x360	518400	double array

## See Also

`etopo`, `gtopo30`, `tbase`, `usgsdem`

# extractfield

---

**Purpose** Field values from structure array

**Syntax** `a = extractfield(s, name)`

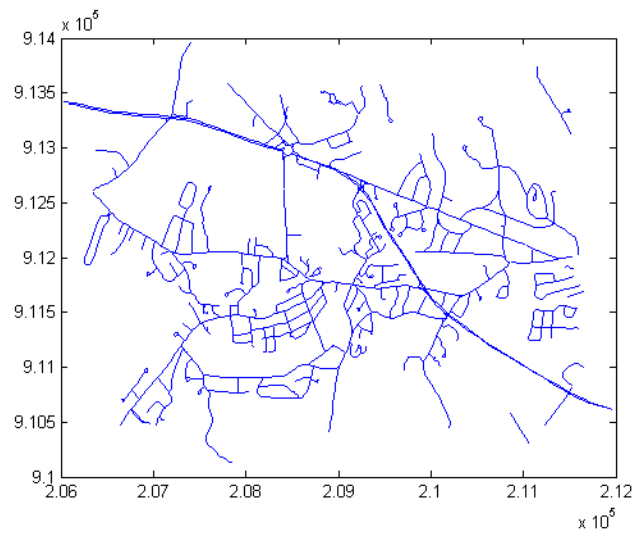
**Description** `a = extractfield(s, name)` returns the field values specified by the field named `name` into the 1-by-`n` output array `a`. `n` is the total number of elements in the field name of structure `s`, that is, `n = numel([s(:).(name)])`. `name` is a case-sensitive string defining the field name of the structure `s`. `a` is a cell array if any field values in the field name contain a string or if the field values are not uniform in type; otherwise `a` is the same type as the field values. The shape of the input field is not preserved in `a`.

**Examples**

```
% Plot the X, Y coordinates of the road's shape
roads = shaperead('concord_roads.shp');
plot(extractfield(roads,'X'),extractfield(roads,'Y'));

% Extract the names of the roads
roads = shaperead('concord_roads.shp');
names = extractfield(roads,'STREETNAME');

% Extract a mix-type field into a cell array
S(1).Type = 0;
S(2).Type = logical(0);
mixedType = extractfield(S,'Type');
```



**See Also** `struct`, `shaperead`

# extractm

---

**Purpose** Coordinate data from line or patch display structure

**Syntax**

```
[lat,lon] = extractm(display_struct,object_str)
[lat,lon] = extractm(display_struct,object_strings)
[lat,lon] = extractm(display_struct,object_strings,
    searchmethod)
[lat,lon] = extractm(display_struct)
[lat,lon,indx] = extractm(...)
mat = extractm(...)
```

**Description** [lat,lon] = extractm(display\_struct,object\_str) extracts latitude and longitude coordinates from those elements of display\_struct having 'tag' fields that begin with the string specified by object\_str. display\_struct is a Mapping Toolbox display structure in which the 'type' field has a value of either 'line' or 'patch'. The output lat and lon vectors include NaNs to separate the individual map features. The comparison of 'tag' values is not case-sensitive.

[lat,lon] = extractm(display\_struct,object\_strings), where object\_strings is a character array or a cell array of strings, selects features with 'tag' fields matching any of several different strings. Character array objects will have trailing spaces stripped before matching.

[lat,lon] = extractm(display\_struct,object\_strings,searchmethod) controls the method used to match the values of the 'tag' field in display\_struct. searchmethod can be one of three strings:



```
'strmatch'    Search for matches at the beginning of the tag  
              (similar to the strmatch function)  
  
'findstr'    Search within the tag (similar to the findstr  
              function)  
  
'exact'      Search for exact matches. Note that when  
              searchmethod is specified the search is  
              case-sensitive.
```

`[lat,lon] = extractm(display_struct)` extracts all vector data from the input map structure.

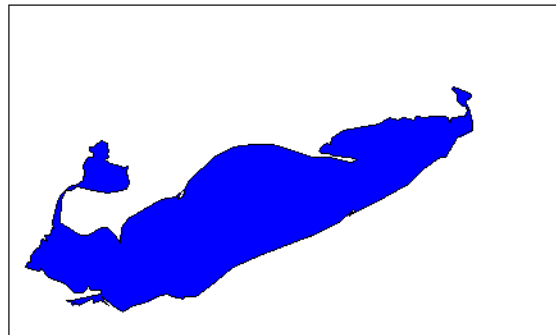
`[lat,lon,indx] = extractm(...)` also returns the vector `indx` identifying which elements of `display_struct` met the selection criteria.

`mat = extractm(...)` returns the vector data in a single matrix, where `mat = [lat lon]`.

## Example

Extract the District of Columbia from the low-resolution U.S. vector data:

```
load greatlakes  
[lat, lon] = extractm(greatlakes, 'Erie');  
axesm mercator  
geoshow(lat,lon, 'DisplayType','polygon', 'FaceColor','blue')
```



### Remarks

A Version 1 display structure is a MATLAB structure that can contain line, patch, text, regular data grid, geolocated data grid, and certain other objects and fixed attributes. In Mapping Toolbox Version 2, a new data structure for vector geodata was introduced (called a *mapstruct* or a *geostruct*, depending on whether coordinates it contains are projected or unprojected). Geostructs and mapstructs have few required fields and can include any number of user-defined fields, giving them much greater flexibility to represent vector geodata. For information about the contents and format of display structures, see “Version 1 Display Structures” on page 3-144 in the reference page for `displaym`. For information about converting display structures to geographic data structures, see the reference page for `updategeostruct`, which performs such conversions.

### See Also

`displaym`, `extractfield`, `geoshow`, `mapshow`, `updategeostruct`, `mlayers`

**Purpose** Project filled 3-D patch objects on map axes

**Syntax**

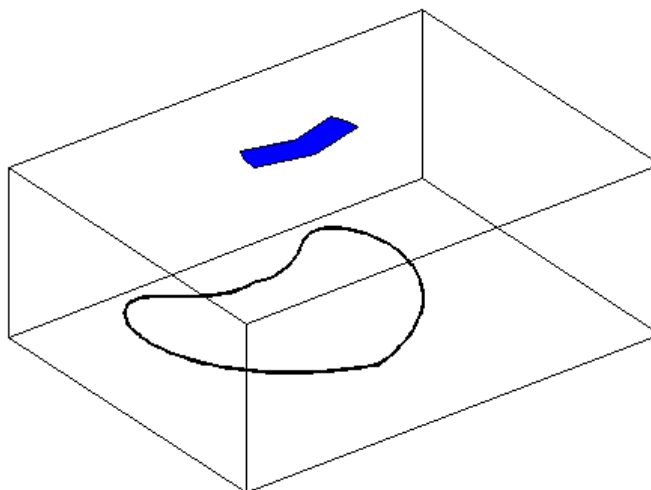
```
h = fill3m(lat,lon,z,cdata)
h = fill3m(lat,lon,z,PropertyName,PropertyValue,...)
```

**Description** `h = fill3m(lat,lon,z,cdata)` projects and displays any patch object with vertices defined by vectors `lat` and `lon` to the current map axes. The scalar `z` indicates the altitude plane at which the patch is displayed. The input `cdata` defines the patch face color. The patch handle or handles, `h`, can be returned.

`h = fill3m(lat,lon,z,PropertyName,PropertyValue,...)` allows any property name/property value pair supported by `patch` to be assigned to the `fill3m` object.

### Examples

```
lat = [30 15 0 0 0 15 30 30]';
lon = [-60 -60 -60 0 60 60 60 0]';
axesm bonne; framem
view(3)
fill3m(lat,lon,2,'b')
```



## fill3m

---

### **See Also**

fillm, patchesm, patchm

**Purpose**

Project filled 2-D patch objects on map axes

**Syntax**

```
h = fillm(lat,lon,cdata)
h = fillm(lat,lon,'PropertyName',PropertyValue,...)
```

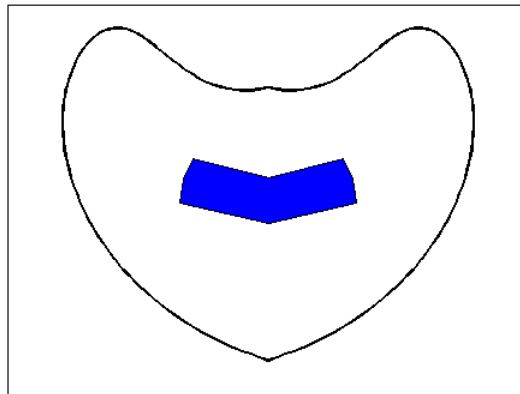
**Description**

`h = fillm(lat,lon,cdata)` projects and displays any patch object with vertices defined by the vectors `lat` and `lon` to the current map axes. The input `cdata` defines the patch face color. The patch handle or handles, `h`, can be returned.

`h = fillm(lat,lon,'PropertyName',PropertyValue,...)` allows any property name/property value pair supported by `patch` to be assigned to the `fillm` object.

**Examples**

```
lat = [30 15 0 0 0 15 30 30]';
lon = [-60 -60 -60 0 60 60 60 0]';
axesm bonne; framem
fillm(lat,lon,'b')
```

**See Also**

`fill3m`, `patchesm`, `patchm`

# filterm

---

**Purpose** Filter latitudes and longitudes based on underlying data grid

**Syntax**  
`[latout,lonout] = filterm(lat,lon,Z,R,allowed)`  
`[latout,lonout,indx] = filterm(lat,lon,Z,R,allowed)`

**Description** `[latout,lonout] = filterm(lat,lon,Z,R,allowed)` filters a set of latitudes and longitudes to include only those data points which have a corresponding value in Z equal to allowed. R is either a 1-by-3 vector containing elements:

```
[cells/degree northern_latitude_limit western_longitude_limit]
```

or a 3-by-2 referencing matrix that transforms raster row and column indices to/from geographic coordinates according to:

```
[lon lat] = [row col 1] * R
```

If R is a referencing matrix, it must define a (non-rotational, non-skewed) relationship in which each column of the data grid falls along a meridian and each row falls along a parallel.

`[latout,lonout,indx] = filterm(lat,lon,Z,R,allowed)` also returns the indices of the included points.

**Examples** Filter a random set of 100 geographic points. Use the topo map for starters:

```
load topo
```

Then generate 100 random points:

```
lat = -90+180*rand(100,1);  
long = -180+360*rand(100,1);
```

Make a land map, which is 1 where topo>0 elevation:

```
land = topo>0;  
[newlat,newlong] = filterm(lat,long,land,topolegend,1);  
size(newlat)
```

```
ans =  
    15     1
```

15 of the 100 random points fall on *land*.

**See Also**

imbedm, hista, histr

# findm

---

**Purpose** Latitudes and longitudes of nonzero data grid elements

**Syntax**

```
[lat,lon] = findm(Z,R)
[lat,lon] = findm(latz,lonz,Z)
[lat,lon,val] = findm(...)
mat = findm(...)
```

**Description** [lat,lon] = findm(Z,R) computes the latitudes and longitudes of the nonzero elements of a regular data grid, Z. R is either a 1-by-3 vector containing elements:

```
[cells/degree northern_latitude_limit western_longitude_limit]
```

or a 3-by-2 referencing matrix that transforms raster row and column indices to/from geographic coordinates according to:

```
[lon lat] = [row col 1] * R
```

If R is a referencing matrix, it must define a (non-rotational, non-skewed) relationship in which each column of the data grid falls along a meridian and each row falls along a parallel. All input and output angles are in units of degrees.

[lat,lon] = findm(latz,lonz,Z) returns the latitudes and longitudes of the nonzero elements of a geolocated data grid Z, which is an M-by-N logical or numeric array. Typically latz and lonz are M-by-N latitude-longitude arrays, but latz may be a latitude vector of length M and lonz may be a longitude vector of length N.

[lat,lon,val] = findm(...) returns the values of the nonzero elements of Z, in addition to their locations.

mat = findm(...) returns a single output, where mat = [lat lon].

This function works in two modes: with a regular data grid and with a geolocated data grid.

**Example** The data grid can be the result of a logical operation. For instance, you can find all locations with elevations greater than 5500 meters.



```
load topo
[lat, lon] = findm((topo>5500),topolegend);
[lat lon]

ans =
    34.5000    79.5000
    34.5000    80.5000
    30.5000    84.5000
    28.5000    86.5000
```

These points are in the Himalayas. Find the grid values at these locations with `setpostn`:

```
heights = topo(setpostn(topo,topolegend,lat,lon))

heights =
    5559
    5515
    5523
    5731
```

Use a regular data grid to retrieve the elevations from `setpostn`.

## See Also

`find` (MATLAB function)

# fipsname

---

**Purpose** Read Federal Information Processing Standard (FIPS) name file used with TIGER thinned boundary files

**Syntax**  
`struc = fipsname`  
`struc = fipsname(filename)`

**Description**  
`struc = fipsname` opens a file selection window to pick the file, reads the FIPS codes, and returns them in a structure.  
`struc = fipsname(filename)` reads the specified file.

**Background**  
The TIGER thinned boundary files provided by the U.S. Census use FIPS codes to identify geographic entities. This function reads the FIPS files as provided with the TIGER files. These files generally have names of the format *\_name.dat*.

**Remarks**  
The FIPS name files, along with TIGER thinned boundary files, are available over the Internet.

---

**Note** For details on locating map data for download over the Internet, see the following documentation at the MathWorks Web site: <http://www.mathworks.com/support/tech-notes/2100/2101.html>.

---

**Example**

```
struc = fipsname('st_name.dat')

struc =
1x57 struct array with fields:
    name
    id

s(1)

ans =
    name: 'Alabama'
    id: 1
```

**Purpose** Eccentricity of ellipse with given flattening

**Syntax** `eccentricity = flat2ecc(flattening)`

**Description** `eccentricity = flat2ecc(flattening)` returns the equivalent eccentricity for the input `flattening`. If the input, `flattening`, is a two-column vector, only the second column is used. This allows two-element vectors to be used as rows of the input, since the form `[semimajor-axis, flattening]` is a complete representation of an ellipsoid (but is not the standard form for ellipsoid vectors in the toolbox). In all other cases, all columns of the input are used.

Flattening and eccentricity are two methods of defining an ellipsoid.

**Example**

```
e = flat2ecc(0.003353)

e =
    0.08182149712026
```

This eccentricity is the default value for the Earth.

**See Also** `almanac`, `ecc2flat`, `ecc2n`, `majaxis`

# flatearthpoly

---

**Purpose** Insert points along date line to pole

**Syntax**  
`[latf,lonf] = flatearthpoly(lat,lon)`  
`[latf,lonf] = flatearthpoly(lat,lon,longitudeOrigin)`

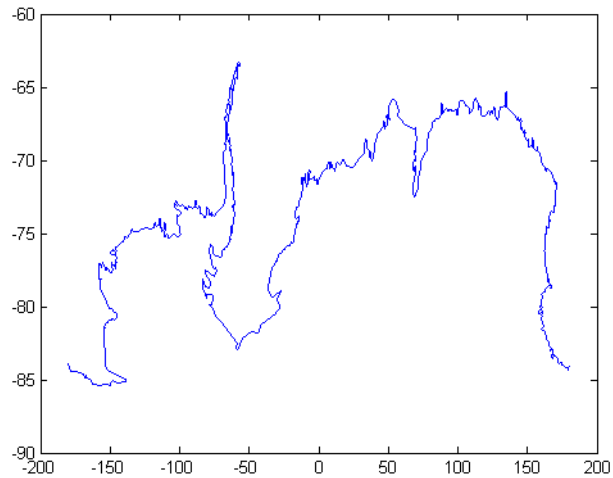
**Description** `[latf,lonf] = flatearthpoly(lat,lon)` trims NaN-separated polygons specified by the latitude and longitude vectors `lat` and `lon` to the limits `[-180 180]` in longitude and `[-90 90]` in latitude, inserting straight segments along the `+/- 180-degree` meridians and at the poles. Inputs and outputs are in degrees.

`[latf,lonf] = flatearthpoly(lat,lon,longitudeOrigin)` centers the longitude limits on the longitude specified by the scalar `longitudeOrigin`.

**Remarks** The polygon topology for the input vectors must be valid. This means that vertices for outer rings (main polygon or “island” polygons) must be in clockwise order, and any inner rings (“lakes”) must run in counterclockwise order for the function to work properly. You can use the `ispolycw` function to check whether or not your `lat`, `lon` vectors meet this criterion, and the `poly2cw` and `poly2ccw` functions to correct any that run in the wrong direction.

**Example** Vector data for geographic objects that encompass a pole will inevitably encounter or cross the date line. While the toolbox properly displays such polygons, they can cause problems for functions like the polygon intersection and Boolean operations that work with Cartesian coordinates. When these polygons are treated as Cartesian coordinates, the date line crossing results in a spurious line segment, and the polygon displayed as a patch does not have the interior filled correctly.

```
antarctica = shaperead('landareas', 'UseGeoCoords', true,...  
    'Selector', {@(name) strcmp(name,'Antarctica'), 'Name'});  
figure; plot(antarctica.Lon, antarctica.Lat); ylim([-100 -60])
```

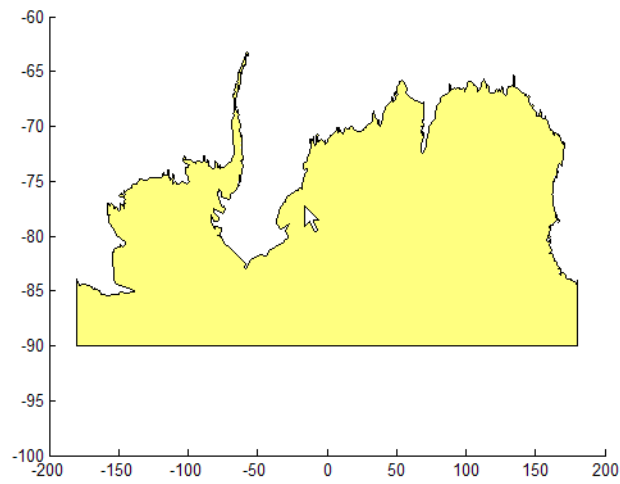


The polygons can be reformatted more appropriately for Cartesian coordinates using the `flatearthpoly` function. The result resembles a map display on a cylindrical projection. The polygon meets the date line, drops down to the pole, sweeps across the longitudes at the pole, and follows the date line up to the other side of the date line crossing.

```
[latf, lonf] = flatearthpoly(antarctica.Lat', antarctica.Lon');  
figure; mapshow(lonf, latf, 'DisplayType', 'polygon')  
ylim([-100 -60])
```

# flatearthpoly

---



## See Also

`ispolycw`, `maptrimp`, `poly2cw`, `poly2ccw`

---

<b>Purpose</b>	Toggle and control display of map frame
<b>Syntax</b>	<pre>framem framem('on') framem('off') framem('reset') framem(<i>linespec</i>) framem(<i>PropertyName,PropertyValue,...</i>)</pre>
<b>Description</b>	<p>framem toggles the visibility of the map frame by setting the map axes property Frame to 'on' or 'off'. The default setting for map axes is 'off'.</p> <p>framem('on') sets the map axes property Frame to 'on'.</p> <p>framem('off') sets the map axes property Frame to 'off'.</p> <p>When called with the string argument 'off', the map axes property Frame is set to 'off'.</p> <p>framem('reset') resets the entire frame using the current properties. This is essentially a <i>refresh</i> option.</p> <p>framem(<i>linespec</i>) sets the map axes FEdgeColor property to the color component of any <i>linespec</i> string recognized by the MATLAB line function.</p> <p>framem(<i>PropertyName,PropertyValue,...</i>) sets the appropriate map axes properties to the desired values. These property names and values are described on the axesm reference page.</p>
<b>Remarks</b>	You can also create or alter map frame properties using the axesm or setm functions.
<b>See Also</b>	axesm, setm

# fromDegrees

---

**Purpose** Convert angles from degrees

**Syntax** `[angle1, angle2, ...] = fromDegrees(toUnits,  
angle1InDegrees,  
angle2InDegrees, ...)`

**Description** `[angle1, angle2, ...] = fromDegrees(toUnits,  
angle1InDegrees, angle2InDegrees, ...)` converts  
`angle1InDegrees, angle2InDegrees, ...` from degrees to the  
specified output ("to") angle units. `toUnits` can be either 'degrees' or  
'radians' and may be abbreviated. The inputs `angle1InDegrees,`  
`angle2InDegrees, ...` and their corresponding outputs are  
numeric arrays of various sizes, with `size(angleN)` matching  
`size(angleNInDegrees)`.

**See Also** `degToRad, fromRadians, toDegrees, toRadians`



**Purpose** Convert angles from radians

**Syntax** `[angle1, angle2, ...] = fromRadians(toUnits,  
angle1InRadians,  
angle2InRadians, ...)`

**Description** `[angle1, angle2, ...] = fromRadians(toUnits,  
angle1InRadians, angle2InRadians, ...)` converts  
`angle1InRadians, angle2InRadians, ...` from radians to the  
specified output ("to") angle units. `toUnits` can be either 'degrees' or  
'radians' and may be abbreviated. The inputs `angle1InRadians,`  
`angle2InRadians, ...` and their corresponding outputs are  
numeric arrays of various sizes, with `size(angleN)` matching  
`size(angleNInRadians)`.

**See Also** `fromDegrees, radtodeg, toDegrees, toRadians`

**Purpose** Center and radius of great circle

**Syntax** `[centerlat,centerlong,radius] = gc2sc(lat,long,az)`  
`[centerlat,centerlong,radius] = gc2sc(lat,long,az,units)`  
`mat = gc2sc(...)`

**Description** `[centerlat,centerlong,radius] = gc2sc(lat,long,az)` converts a great circle (i.e., latitude, longitude, azimuth, where latitude/longitude is on the circle) to a small circle (i.e., latitude, longitude, range, where latitude/longitude is the center of the circle, and range is 90°). A great circle has two possible centers (or zeniths). One is given; its antipode is the other.

`[centerlat,centerlong,radius] = gc2sc(lat,long,az,units)` uses the input *units* to define the angle units of the inputs and outputs. The default is 'degrees'.

`mat = gc2sc(...)` returns a single output, where `mat = [lat long rng]`.

**Definitions** A *small circle* is the intersection of a plane with the surface of a sphere. A *great circle* is a small circle with a radius of 90°.

**Examples** Represent a great circle passing through (25°S,70°W) on an azimuth of 45° as a small circle:

```
[newlat,newlong,range] = gc2sc(-25,-70,45)

newlat =
    -39.8557
newlong =
     42.9098
range =
     90
```

A great circle always bisects the sphere. As a demonstration of this statement, consider the Equator, which passes through any point with

a latitude of  $0^\circ$  and proceeds on an azimuth of  $90^\circ$  or  $270^\circ$ . Represent the Equator as a small circle:

```
[newlat, newlong, range] = gc2sc(0, -70, 270)
newlat =
    90
newlong =
   -145.9638
range =
    90
```

Not surprisingly, the small circle is centered on the North Pole. As always at the poles, the longitude is arbitrary because of the convergence of the meridians.

Note that the center coordinates returned by this function always lead to one of two possibilities. Since the great circle bisects the sphere, the antipode of the returned point is also a center with a radius of  $90^\circ$ . In the above example, the South Pole would also be a suitable center for the Equator in a small circle.

## See Also

[antipode](#) | [crossfix](#) | [gcxgc](#) | [gcxsc](#) | [rhrhr](#)

**Purpose** Current map projection structure

**Syntax**  
mstruct = gcm  
mstruct = gcm(hndl)

**Description** mstruct = gcm returns the map axes *map structure*, which contains the settings for all the current map axes properties.

mstruct = gcm(hndl) specifies the map axes by axes handle.

**Examples** Establish a map axes with default values, then look at the structure:

```
axesm mercator
mstruct = gcm

mstruct =
    mapprojection: 'mercator'
           zone: []
           angleunits: 'degrees'
           aspect: 'normal'
falsenorthing: 0
falseeastng: 0
fixedorient: []
           geoid: [1 0]
maplatlimit: [-86 86]
maplonlimit: [-180 180]
mapparallels: 0
           nparallels: 1
           origin: [0 0 0]
scalefactor: 1
           trimlat: [-86 86]
           trimlon: [-180 180]
           frame: 'off'
           ffill: 100
fedgecolor: [0 0 0]
ffacecolor: 'none'
flatlimit: [-86 86]
```

```
flinewidth: 2
flonlimit: [-180 180]
  grid: 'off'
  galtitude: Inf
  gcolor: [0 0 0]
  glinestyle: ':'
  glinewidth: 0.5000
mlineexception: []
  mlinefill: 100
  mlinelimit: []
  mlinelocation: 30
  mlinevisible: 'on'
plineexception: []
  plinefill: 100
  plinelimit: []
  plinelocation: 15
  plinevisible: 'on'
  fontangle: 'normal'
  fontcolor: [0 0 0]
  fontname: 'Helvetica'
  fontsize: 10
  fontunits: 'points'
  fontweight: 'normal'
  labelformat: 'compass'
  labelrotation: 'off'
  labelunits: 'degrees'
meridianlabel: 'off'
mlabellocation: 30
mlabelparallel: 86
  mlabelround: 0
  parallellabel: 'off'
plabellocation: 15
plabelmeridian: -180
  plabelround: 0
```

**Remarks**

You create map structure properties with the `axesm` function. You can query them with the `getm` function and modify them with the `setm` function.

**See Also**

`axesm`, `getm`, `setm`

**Purpose**

Current mouse point from map axes

**Syntax**

```
pt = gcpmap
pt = gcpmap(hndl)
```

**Description**

`pt = gcpmap` returns the current point (the location of last button click) of the current map axes in the form [latitude longitude z-altitude].

`pt = gcpmap(hndl)` specifies the map axes in question by its handle.

**Remarks**

`gcpmap` works much like the standard MATLAB function `get(gca, 'CurrentPoint')`, except that the returned matrix is in [lat lon z], not [x y z].

The `CurrentPoint` property is updated whenever a button-click event occurs in a MATLAB figure window. The pointer does not have to be within the axes, or even the figure window; Coordinates with respect to the requested axes are returned regardless of the pointer location. Likewise, `gcpmap` will return values that may look reasonable whether the current point is within the graticule bounds or not, and thus must be used with care.

**Example**

Set up a map axes with a graticule and display a world map:

```
axesm robinson
gridm on
geoshow('landareas.shp')
```

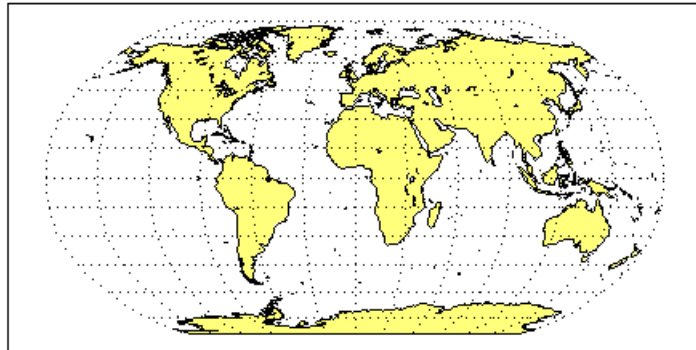
Click somewhere near Boston, Massachusetts to obtain a current point:

```
pt = gcpmap

pt =
    44.171    -69.967         2
    44.171    -69.967         0

whos
```

Name	Size	Bytes	Class	Attributes
pt	2x3	48	double array	



## See Also

`inputm`, `Axes Properties`



**Purpose**

Equally spaced waypoints along great circle

**Syntax**

```
[lat,lon] = gcwaypts(lat1,lon1,lat2,lon2)
[lat,lon] = gcwaypts(lat1,lon1,lat2,lon2,nlegs)
pts = gcwaypts(lat1,lon1,lat2,lon2...)
```

**Description**

[lat,lon] = gcwaypts(lat1,lon1,lat2,lon2) returns the coordinates of equally spaced points along a great circle path connecting two endpoints, (lat1,lon1) and (lat2,lon2).

[lat,lon] = gcwaypts(lat1,lon1,lat2,lon2,nlegs) specifies the number of equal-length track legs to calculate. nlegs+1 output points are returned, since a final endpoint is required. The default number of legs is 10.

pts = gcwaypts(lat1,lon1,lat2,lon2...) packs the outputs, which are otherwise two-column vectors, into a two-column matrix of the form [latitude longitude]. This format for successive waypoints along a navigational track is called *navigational track format* in this guide. See the [navigational track format reference page](#) in this section for more information.

**Background**

This is a navigational function. It assumes that all latitudes and longitudes are in degrees.

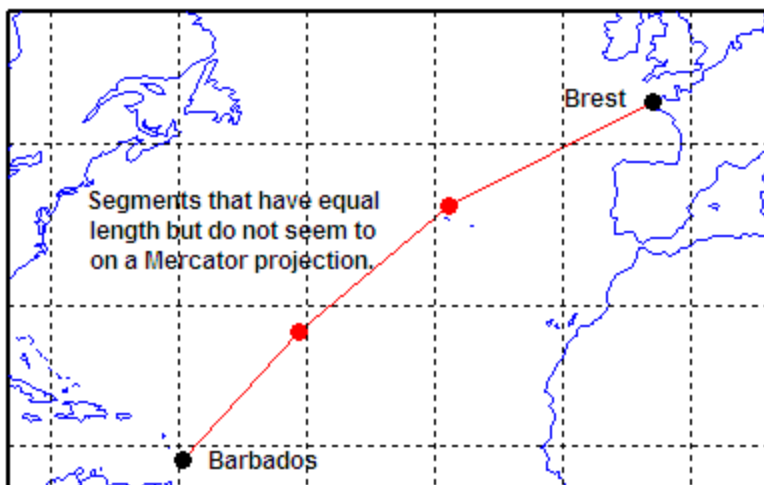
In navigational practice, great circle paths are often approximated by rhumb line segments. This is done to come reasonably close to the shortest distance between points without requiring course changes too frequently. The gcwaypts function provides an easy means of finding waypoints along a great circle path that can serve as endpoints for rhumb line segments (track legs).

**Examples**

Imagine you own a sailing yacht and are planning a voyage from North Point, Barbados (13.33° N,59.62°W), to Brest, France (48.36°N,4.49°W). To divide the track into three equal-length segments,

```
figure('color','w');
ha = axesm('mapproj','mercator',...
```

```
'maplatlim',[10 55],'maplonlim',[-80 10],...  
'MLineLocation',15,'PLineLocation',15);  
axis off, gridm on, framem on;  
load coast;  
hg = geoshow(lat,long,'displaytype','line','color','b');  
% Define point locations for Barbados and Brest  
barbados = [13.33 -59.62];  
brest = [48.36 -4.49];  
[l,g] = gcwaypts(barbados(1),barbados(2),brest(1),brest(2),3);  
geoshow(l,g,'displaytype','line','color','r',...  
'markeredgecolor','r','markerfacecolor','r','marker','o');  
geoshow(barbados(1),barbados(2),'DisplayType','point',...  
'markeredgecolor','k','markerfacecolor','k','marker','o')  
geoshow(brest(1),brest(2),'DisplayType','point',...  
'markeredgecolor','k','markerfacecolor','k','marker','o')
```



## See Also

dreckon, legs, navfix, track

**Purpose**

Intersection points for pairs of great circles

**Syntax**

```
[newlat,newlong] = gcxgc(lat1,long1,az1,lat2,long2,az2)
[newlat,newlong] =
gcxgc(lat1,long1,az1,lat2,long2,az2,units)
```

**Description**

[newlat,newlong] = gcxgc(lat1,long1,az1,lat2,long2,az2) returns the two intersection points of pairs of great circles input in *great circle notation*. When the two great circles are identical (which is not, in general, apparent by inspection), two NaNs are returned instead and a warning is displayed. For multiple pairings, the inputs must be column vectors.

```
[newlat,newlong] =
gcxgc(lat1,long1,az1,lat2,long2,az2,units) specifies the
standard angle unit string. The default value is 'degrees'.
```

For any pair of great circles, there are two possible intersection conditions: the circles are identical or they intersect exactly twice on the sphere.

*Great circle notation* consists of a point on the great circle and the azimuth at that point along which the great circle proceeds.

**Examples**

Given a great circle passing through (10°N,13°E) and proceeding on an azimuth of 10°, where does it intersect with a great circle passing through (0°, 20°E), on an azimuth of -23° (that is, 337°)?

```
[newlat,newlong] = gcxgc(10,13,10,0,20,-23)

newlat =
    14.3105   -14.3105
newlong =
    13.7838  -166.2162
```

Note that the two intersection points are always antipodes of each other. As a simple example, consider the intersection points of two meridians, which are just great circles with azimuths of 0° or 180°:

```
[newlat,newlong] = gcxgc(10,13,0,0,20,180)
```

```
newlat =  
    -90    90  
newlong =  
   -174.4504   12.5094
```

The two meridians intersect at the North and South Poles, which is exactly correct.

**See Also**

antipode, gc2sc, scxsc, gcxsc, rhxrh, crossfix, polyxpoly

**Purpose**

Intersection points for great and small circle pairs

**Syntax**

```
[newlat,newlong] = gcxsc(gclat,gclong,gcaz,sclat,sclong,
    scrange)
[newlat,newlong] = gcxsc(...,units)
```

**Description**

[newlat,newlong] = gcxsc(gclat,gclong,gcaz,sclat,sclong,scrange) returns the points of intersection of a great circle in *great circle notation* followed by a small circle in *small circle notation*. For multiple pairings, the inputs must be column vectors. The results are two-column matrices with the coordinates of the intersection points. If the circles do not intersect, or are identical, two NaNs are returned and a warning is displayed. If the two circles are tangent, the single intersection point is repeated twice.

[newlat,newlong] = gcxsc(...,units) specifies the standard angle unit string. The default value is 'degrees'.

For a pairing of a great circle with a small circle, there are four possible intersection conditions: the circles are identical (possible because great circles are a subset of small circles), they do not intersect, they are tangent to each other (the small circle interior to the great circle) and hence they intersect once, or they intersect twice.

*Great circle notation* consists of a point on the great circle and the azimuth at that point along which the great circle proceeds.

*Small circle notation* consists of a center point and a radius in units of angular arc length.

**Examples**

Given a great circle passing through (43°N,0°) and proceeding on an azimuth of 10°, where does it intersect with a small circle centered at (47°N,3°E) with an arc length radius of 12°?

```
[newlat,newlong] = gcxsc(43,0,10,47,3,12)
```

```
newlat =
    35.5068    58.9143
newlong =
```

-1.6159 5.4039

**See Also**

gc2sc, gcxgc, scxsc, rhxrh, crossfix, polyxpoly

**Purpose** Convert geocentric to geodetic latitude

**Syntax** `phiI = geocentric2geodeticlat(ecc, phi_g)`

**Description** `phiI = geocentric2geodeticlat(ecc, phi_g)` converts an array of geocentric latitude in radians, `phi_g`, to geodetic latitude in radians, `phiI`, on a reference ellipsoid with first eccentricity `ecc`.

For conversion to/from other types of auxiliary latitude and, optionally, to work in degrees, use Mapping Toolbox function `convertlat`. For conversion from 3-D geocentric coordinates, see `ecef2geodetic`.

**See Also** `convertlat`, `ecef2geodetic`, `geodetic2geocentricLat`

# geodetic2ecef

---

**Purpose** Convert geodetic to geocentric (ECEF) coordinates

**Syntax** `[x,y,z] = geodetic2ecef(phi,lambda,h,ellipsoid)`

**Description** `[x,y,z] = geodetic2ecef(phi,lambda,h,ellipsoid)` converts geodetic point locations specified by the coordinate arrays `phi` (geodetic latitude in radians), `lambda` (longitude in radians), and `h` (ellipsoidal height) to geocentric Cartesian coordinates `x`, `y`, and `z`. The geodetic coordinates refer to the reference ellipsoid specified by `ellipsoid` (a row vector with the form `[semimajor axis, eccentricity]`). `h` must use the same units as the semimajor axis; `x`, `y`, and `z` will be expressed in these units, also.

**Definitions** The geocentric Cartesian coordinate system is fixed with respect to the Earth, with its origin at the center of the ellipsoid and its `x`-, `y`-, and `z`-axes intersecting the surface at the locations listed in the table below.

Axis	Latitude where axis intersects surface	Longitude where axis intersects surface	Description
<code>x</code>	0	0	Equator/Prime Meridian
<code>y</code>	0	90° E	Equator/90° E meridian
<code>z</code>	90° N	NA	North Pole

A common synonym is Earth-Centered, Earth-Fixed coordinates, or ECEF.

**See Also** `ecef2geodetic` | `ecef2lv` | `geodetic2geocentricLat` | `lv2ecef`



**Purpose** Convert geodetic to geocentric latitude

**Syntax** `phi_g = geodetic2geocentriclat(ecc, phi)`

**Description** `phi_g = geodetic2geocentriclat(ecc, phi)` converts an array of geodetic latitude in radians, `phi`, to geocentric latitude in radians, `phi_g`, on a reference ellipsoid with first eccentricity `ecc`.

For conversion to/from other types of auxiliary latitude and, optionally, to work in degrees, use Mapping Toolbox function `convertlat`. For conversion to 3-D geocentric coordinates, see `geodetic2ecef`.

**See Also** `convertlat`, `geocentric2geodeticLat`, `geodetic2ecef`

# geoloc2grid

---

## Purpose

Convert geolocated data array to regular data grid

## Syntax

```
[Z, refvec] = geoloc2grid(lat, lon, A, cellsize)
```

## Description

`[Z, refvec] = geoloc2grid(lat, lon, A, cellsize)` converts the geolocated data array `A`, given geolocation points in `lat` and `lon`, to produce a regular data grid, `Z`, and the corresponding three-element referencing vector `refvec`. `cellsize` is a scalar that specifies the width and height of data cells in the regular data grid, using the same angular units as `lat` and `lon`. Data cells in `Z` falling outside the area covered by `A` are set to `NaN`.

## Remarks

`geoloc2grid` provides an easy-to-use alternative to gridding geolocated data arrays with `imbedm`. There is no need to preallocate the output map; there are no data gaps in the output (even if `cellsize` is chosen to be very small), and the output map is smoother.

## Example

```
% Load the geolocated data array 'map1'
% and grid it to 1/2-degree cells.
load mapmtx
cellsize = 0.5;
[Z, refvec] = geoloc2grid(lt1, lg1, map1, cellsize);

% Create a figure
f = figure;
[cmap, clim] = demcmap(map1);
set(f, 'Colormap', cmap, 'Color', 'w')

% Define map limits
latlim = [-35 70];
lonlim = [0 100];

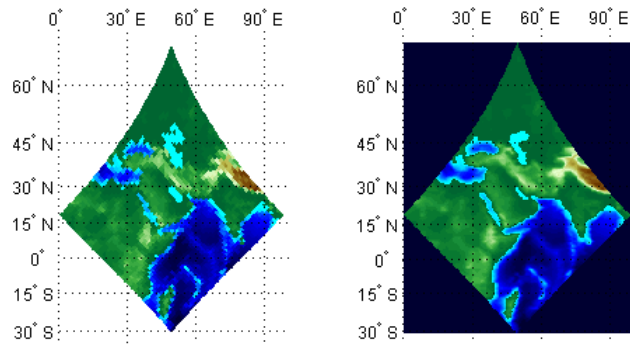
% Display 'map1' as a geolocated data array in subplot 1
subplot(1,2,1)
ax =
axesm('mercator', 'MapLatLimit', latlim, 'MapLonLimit', lonlim, ...
```

```

    'Grid','on','MeridianLabel','on','ParallelLabel','on');
    set(ax,'Visible','off')
    geoshow(lt1, lg1, map1, 'DisplayType', 'texturemap');

    % Display 'Z' as a regular data grid in subplot 2
    subplot(1,2,2)
    ax =
    axesm('mercator','MapLatLimit',latlim,'MapLonLimit',lonlim,...
        'Grid','on','MeridianLabel','on','ParallelLabel','on');
    set(ax,'Visible','off')
    geoshow(Z, refvec, 'DisplayType', 'texturemap');

```



## Purpose

Display map latitude and longitude data

## Syntax

```
geoshow(lat,lon)
geoshow(lat,lon, ..., 'DisplayType', displaytype, ...)
geoshow(lat,lon,Z, ..., 'DisplayType', displaytype, ...)
geoshow(Z,R, ..., 'DisplayType', displaytype,...),
geoshow(lat,lon,I),geoshow(lat,lon,BW),geoshow(lat,lon,X,
    cmap), geoshow(lat,lon,RGB),
geoshow(... 'DisplayType', ...)
geoshow(I,R),geoshow(BW,R),geoshow(RGB,R),geoshow(A,CMAP,R),
geoshow(... `DisplayType', ...)
geoshow(s)
geoshow(s, ..., `SymbolSpec', symspec)
geoshow(filename)
geoshow(ax, ...)
geoshow(..., 'Parent', ax, ...)
h = geoshow(...)
geoshow(..., param1, val1, param2, val2, ...)
```

## Description

`geoshow(lat,lon)` or `geoshow(lat,lon, ..., 'DisplayType', displaytype, ...)` project and display the latitude and longitude vectors, `lat` and `lon`, using the projection stored in the axes. If there is no projection, the latitudes and longitudes are projected using a default Plate Carree projection. `lat` and `lon` must be of equal length, and may contain embedded NaNs, delimiting individual lines or polygon parts. `DisplayType` can be 'point', 'line', or 'polygon', and defaults to 'line'.

`geoshow(lat,lon,Z, ..., 'DisplayType', displaytype, ...)`, projects and displays a geolocated data grid. `lat` and `lon` are M-by-N latitude-longitude arrays and `Z` is an M-by-N array of class double. `lat`, `lon`, and `Z` may contain NaN values. `DisplayType` must be set to 'surface', 'mesh', 'texturemap', or 'contour'.

`geoshow(Z,R, ..., 'DisplayType', displaytype,...)`, projects and displays a regular data grid. `Z` is a 2-D array of class double. `R` is either a 1-by-3 vector containing elements:

```
[cells/degree northern_latitude_limit western_longitude_limit]
```

or a 3-by-2 referencing matrix that transforms raster row and column indices to or from geographic coordinates according to:

$$[\text{lon lat}] = [\text{row col 1}] * R$$

If  $R$  is a referencing matrix, it must define a (non-rotational, non-skewed) relationship in which each column of the data grid falls along a meridian and each row falls along a parallel. For more information about referencing vectors and matrices, see the section “Understanding Raster Geodata” in the User’s Guide.

`DisplayType` must be set to 'surface', 'mesh', 'texturemap', or 'contour'. If `DisplayType` is 'texturemap', `geoshow` constructs a surface with `ZData` values set to 0.

`geoshow(lat,lon,I)`, `geoshow(lat,lon,BW)`, `geoshow(lat,lon,X,cmap)`, `geoshow(lat,lon,RGB)`, or `geoshow(... 'DisplayType', ...)` projects and display a geolocated image as a texturemap on a zero-elevation surface. `lat` and `lon` are latitude-longitude geolocation arrays and `I` is a grayscale image, `BW` is a logical image, `X` is an indexed image with colormap `cmap`, or `RGB` is a truecolor image. `lat`, `lon`, and the image array must match in size. If specified, `DisplayType` must be set to 'image'. Examples of geolocated images include a color composite from a satellite swath or an image originally referenced to a different coordinate system.

`geoshow(I,R)`, `geoshow(BW,R)`, `geoshow(RGB,R)`, `geoshow(A,CMAP,R)`, or `geoshow(... `DisplayType', ...)` project and display an image georeferenced to latitude-longitude through the referencing matrix  $R$ . The image is shown as a texturemap on a zero-elevation surface. If specified, `DisplayType` must be set to 'image'.

`geoshow(s)` or `geoshow(s, ..., `SymbolSpec', symspec)` display the vector geographic features stored in the geographic data structure `s` as points, multipoints, lines, or polygons according to the `Geometry` field of `s`. If `s` includes `Lat` and `Lon` fields, then the coordinate values are projected to map coordinates. If `s` includes `X` and `Y` fields they are

plotted as (preprojected) map coordinates and a warning is issued. `symspec` is a structure returned by `makesymbolspec` that specifies the symbolization rules to be used for displaying vector data.

`geoshow(filename)` projects and displays data from `filename` according to the type of file format. The `DisplayType` parameter is automatically set, according to the following table:

Format	DisplayType
Shape file	'point', 'line', or 'polygon'
GeoTIFF	'image'
TIFF/JPEG/PNG with a world file	'image'
ARC ASCII GRID	'surface' (can be overridden)
SDTS raster	'surface' (can be overridden)

`geoshow(ax, ...)` and `geoshow(..., 'Parent', ax, ...)` set the parent axes to `ax`.

`h = geoshow(...)` returns a handle to a MATLAB graphics object or, in the case of polygons, a modified patch object. If a `geostruct` or `shapefile` name is input, `geoshow` returns the handle to an `hgroup` object with one child per feature in the `geostruct` or `shapefile`, excluding any features that are completely trimmed away. In the case of a polygon `geostruct` or `shapefile`, each child is a modified patch object; otherwise it is a line object.

`geoshow(..., param1, val1, param2, val2, ...)` specifies parameter/value pairs that modify the type of display or set MATLAB graphics properties. Refer to the MATLAB Graphics documentation for `line`, `patch`, `image`, `surface`, `mesh`, and `contour` properties for full descriptions of these object properties and their values.

## Parameters

Parameter names can be abbreviated and are case insensitive. Parameters include

- **DisplayType:** The `DisplayType` parameter specifies the type of graphic display for the data. The value must be consistent with the type of data being displayed, as shown in the following table:

Data Type	Value(s)
Vector	'point', 'multipoint', 'line', or 'polygon'
Image	'image'
Grid	'surface', 'mesh', 'texturemap', or 'contour'

- **SymbolSpec:** The `SymbolSpec` parameter specifies the symbolization rules used for vector data through a structure returned by `makesymbolspec`. It is used only for vector data stored in geographic data structures.

In cases where both `SymbolSpec` and one or more graphics properties are specified, the graphics properties override any settings in the `symbolspec` structure.

To change the default symbolization rule for a property name/property value pair in the `symbolspec`, prefix the word 'Default' to the graphics property name (listed in the preceding table). See Example 2 below.

---

**Note** If you display a polygon, do not set 'EdgeColor' to either 'flat' or 'interp'. This combination may result in a warning.

---

## Graphics Properties

In addition to specifying a parent axes, you can set any appropriate property for a point, line, and polygon `DisplayType`, as follows:

DisplayType	Properties
'line'	Any MATLAB line property
'point'	Any MATLAB line marker property
'polygon'	Any MATLAB patch property

See the MATLAB Graphics Reference documentation for line, patch, image, and surface properties for complete descriptions of these properties and their values.

## Remarks

`geoshow` is often used to display vector geodata previously read from shapefiles using `shaperead`. When calling `shaperead` to read files that contain coordinates in latitude and longitude, be sure to specify the `shaperead` argument pair `'UseGeoCoords', true`; if you do not include this argument (or specify `'UseGeoCoords', false`), `shaperead` will create a `mapstruct`, with coordinate fields labelled `X` and `Y` instead of `Lon` and `Lat`, causing `geoshow` to assume that the `geostruct` is in fact a `mapstruct` containing projected coordinates. In such cases, `geoshow` warns and calls `mapshow` to display the `geostruct` data without projecting it.

When projecting data onto a map axes, `geoshow` uses the projection stored with the map axes. When displaying on a regular axes, it constructs a default Plate Carrée projection with a scale factor of  $180/\pi$ , enabling direct readout of coordinates in degrees.

---

**Note** When you display vector data in a map axes using `geoshow`, you should not subsequently change the map projection using `setm`. You can, however, change the projection with `setm` for raster data. For more information, see “Changing Map Projections when Using `geoshow`”.

---



`geoshow` adds graphics to the current map axes (it does not clear it first), enabling you to create multiple raster and vector map layers. If you do not want `geoshow` to draw on top of an existing map, create a new figure or subplot before calling it.

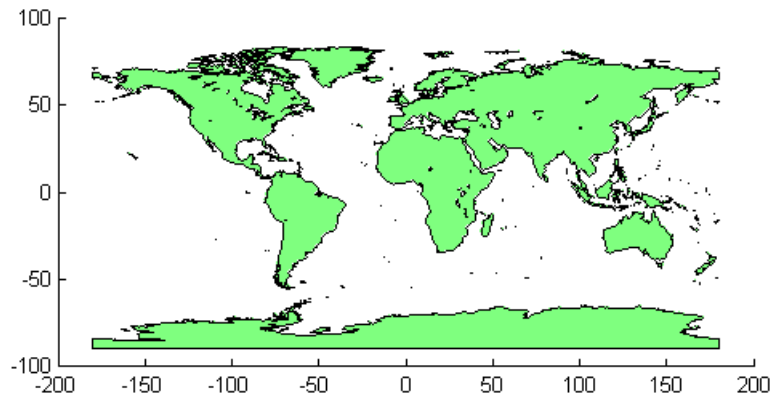
`geoshow` can generally be substituted for `display`. However, there are limitations where display of specific objects is concerned. See the remarks under `updategeostruct` for further information.

## Examples

### Example 1

Display world land areas using a default Plate Carree projection:

```
figure
geoshow('landareas.shp', 'FaceColor', [0.5 1.0 0.5]);
```



### Example 2

Override the `symbolspec` default rule:

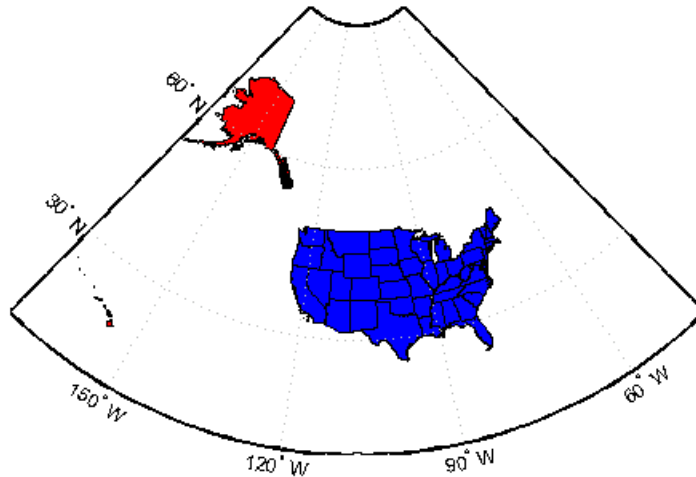
```
% Create a worldmap of North America
figure
worldmap('na');

% Read the USA high resolution data
```

```
states = shaperead('usastatehi', 'UseGeoCoords', true);

% Create a symbolspec to make Alaska and Hawaii polygons red.
symspec = makesymbolspec('Polygon', ...
    {'Name', 'Alaska', 'FaceColor', 'red'}, ...
    {'Name', 'Hawaii', 'FaceColor', 'red'});

% Display all the other states in blue.
geoshow(states, 'SymbolSpec', symspec, ...
    'DefaultFaceColor', 'blue', ...
    'DefaultEdgeColor', 'black');
```



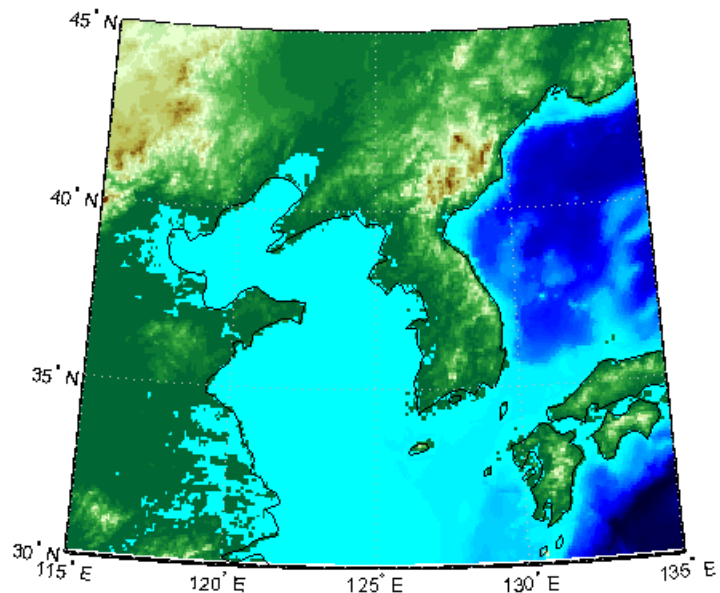
### Example 3

Create a worldmap of Korea and display the korea data grid as a texture map:

```
load korea
figure;
worldmap(map, refvec)
```

```
% Display the Korean data grid as a texture map.
geoshow(gca,map,refvec,'DisplayType','texturemap');
colormap(demcmap(map))
```

```
% Display the land area boundary as black lines.
S = shaperead('landareas','UseGeoCoords',true);
geoshow([S.Lat], [S.Lon],'Color','black');
```



#### Example 4

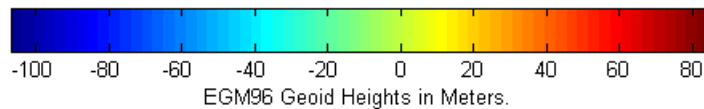
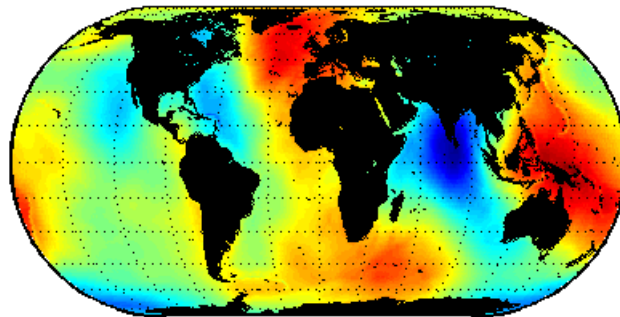
Display the EGM96 geoid heights, masking out land areas:

```
load geoid
% Create a figure with an Eckert projection.
figure
axesm eckert4;
framem; gridm;
axis off
```

```
% Display the geoid as a texture map.
geoshow(geoid, geoidrefvec, 'DisplayType', 'texturemap');

% Create a colorbar and title.
hcb = colorbar('horiz');
set(get(hcb,'Xlabel'),'String','EGM96 Geoid Heights in Meters.')

% Mask out all the land.
geoshow('landareas.shp', 'FaceColor', 'black');
```



## Example 5

Display the EGM96 geoid heights as a 3-D surface using the Eckert IV projection:

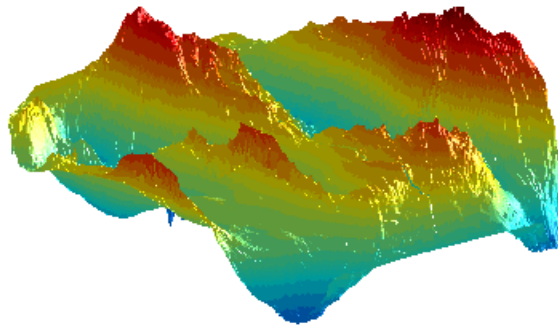
```
load geoid

% Create the figure with an Eckert projection.
figure
axesm eckert4;
axis off
```

```
% Display the geoid as a surface.
h=geoshow(geoid, geoidrefvec, 'DisplayType','surface');

% Add light and material.
light; material(0.6*[ 1 1 1]);

% View as a 3-D surface.
view(3)
axis normal
tightmap
```



### Example 6

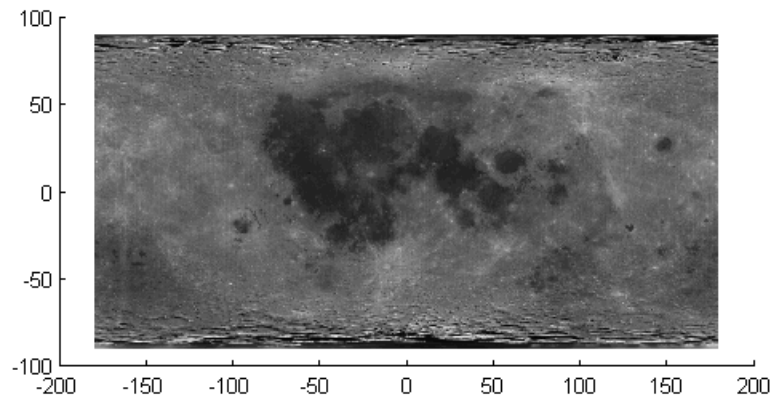
Display the moon albedo image projected using Plate Carree and in an orthographic projection.

```
load moonalb

% Projection not specified -- uses Plate Carree
figure
geoshow(moonalb,moonal Brefvec)
```

# geoshow

---



```
% Orthographic projection
figure
axesm ortho
geoshow(moonalb, moonalbrefvec, 'DisplayType', 'texturemap')
colormap(gray(256))
axis off
```



### Example 7

Read and display the San Francisco South 24K DEM data:

```
filenames = gunzip('sanfranciscos.dem.gz', tempdir);
demFilename = filenames{1};

% Read every point of the 1:24,000 DEM file.
[lat, lon,Z] = usgs24kdem(demFilename,2);

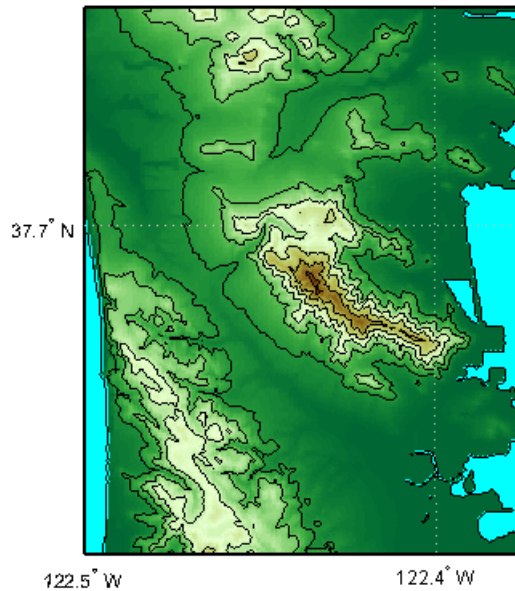
% Delete the temporary gunzipped file.
delete(demFilename);

% Move all points at sea level to -1 to color them blue.
Z(Z==0) = -1;

% Compute the latitude and longitude limits for the DEM.
latlim = [min(lat(:)) max(lat(:))];
```

```
lonlim = [min(lon(:)) max(lon(:))];

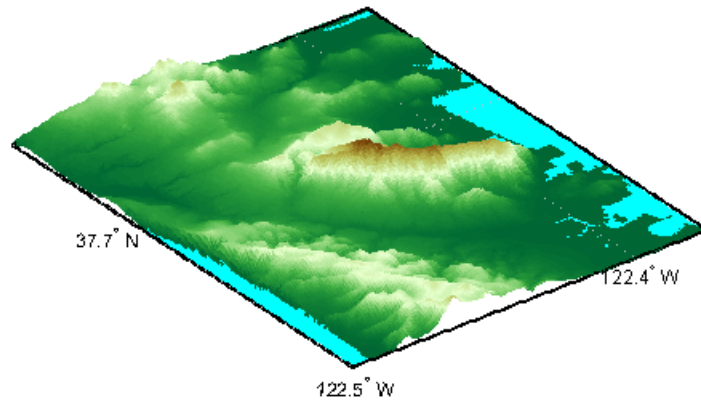
% Display the DEM values as a texture map.
figure
usamap(latlim, lonlim)
geoshow(lat, lon, Z, 'DisplayType','texturemap')
demcmap(Z)
daspectm('m',1)
% Overlay black contour lines onto the texturemap.
geoshow(lat, lon, Z, 'DisplayType', 'contour', ...
        'LineColor', 'black');
```



```
% View the DEM values in 3-D.
figure
usamap(latlim, lonlim)
geoshow(lat, lon, Z, 'DisplayType', 'surface')
demcmap(Z)
```



```
daspectm('m',1)  
view(3)
```

**See Also**

`axesm`, `makesymbolspec`, `mapshow`, `mapview`, `updategeostruct`

# geotiff2mstruct

---

**Purpose** Convert GeoTIFF information to map projection structure

**Syntax** `mstruct = geotiff2mstruct(proj)`

**Description** `mstruct = geotiff2mstruct(proj)` converts the GeoTIFF projection structure, `proj`, to the map projection structure, `mstruct`. The unit of length of the `mstruct` projection is meter.

**Example**

```
% Compare inverse transform of points using projinv and minvtran.
% Obtain the projection structure of 'boston.tif'.
proj = geotiffinfo('boston.tif');

% Convert the corner map coordinates to latitude and longitude.
x = proj.CornerCoords.X;
y = proj.CornerCoords.Y;
[latProj, lonProj] = projinv(proj, x, y);

% Obtain the mstruct from the GeoTIFF projection.
mstruct = geotiff2mstruct(proj);

% Convert the units of x and y to meter to match projection units.
x = unitsratio('meter','sf') * x;
y = unitsratio('meter','sf') * y;

% Convert the corner map coordinates to latitude and longitude.
[latMstruct, lonMstruct] = minvtran(mstruct, x, y);

% Verify the values are within a tolerance of each other.
abs(latProj - latMstruct) <= 1e-7
abs(lonProj - lonMstruct) <= 1e-7

ans =
     1     1     1     1

ans =
     1     1     1     1
```

**See Also** axesm, defaultm, geotiffinfo, projfwd, projinv, projlist

# geotiffinfo

---

**Purpose** Information about GeoTIFF file

**Syntax**  
`info = geotiffinfo(filename)`  
`info = geotiffinfo(url)`

**Description** `info = geotiffinfo(filename)` returns a structure whose fields contain image properties and cartographic information about a GeoTIFF file.

`filename` is a string that specifies the name of the GeoTIFF file. `filename` can include the directory name; otherwise, the file must be in the current directory or in a directory on the MATLAB path. If the named file includes the extension `.TIF` or `.TIFF` (either upper- or lowercase), the extension can be omitted from `filename`.

If `filename` is a file containing more than one GeoTIFF image, `info` is a structure array with one element for each image in the file. For example, `info(3)` would contain information about the third image in the file. If more than one image exists in the file, it is assumed that each image will have the same cartographic information and the same image width and height.

`info = geotiffinfo(url)` reads the GeoTIFF image from an Internet URL. The `url` must include the protocol type (e.g., “`http://`”).

## Field Description

The `info` structure contains the following fields:

<code>Filename</code>	String containing the name of the file
<code>FileModDate</code>	String containing the modification date of the file
<code>FileSize</code>	Integer indicating the size of the file in bytes
<code>Format</code>	String containing the file format, which should always be 'tiff'
<code>FormatVersion</code>	String or number specifying the file format version

Height	Integer indicating the height of the image in pixels
Width	Integer indicating the width of the image in pixels
BitDepth	Integer indicating the number of bits per pixel
ColorType	String indicating the type of image: 'truecolor' for a true-color (RGB) image, 'grayscale' for a grayscale image, or 'indexed' for an indexed image
ModelType	String indicating the type of coordinate system used to georeference the image: 'ModelTypeProjected', 'ModelTypeGeographic', or ''
PCS	String describing the projected coordinate system
Projection	String describing the EPSG identifier for the underlying projection method
MapSys	String indicating the map system, if applicable: 'STATE_PLANE_27', 'STATE_PLANE_83', 'UTM_NORTH', 'UTM_SOUTH', or ''
Zone	Double indicating the UTM or State Plane Zone number, empty ([]) if not applicable or unknown
CTProjection	String containing the GeoTIFF identifier for the underlying projection method
ProjParm	An N-by-1 double containing projection parameter values. The identity of each element is specified by the corresponding element of ProjParmId. Lengths are in meters, angles in decimal degrees.

ProjParmId	<p>An N-by-1 cell array listing the projection parameter identifier for each corresponding numerical element of ProjParm:</p> <ul style="list-style-type: none"><li>• 'ProjNatOriginLatGeoKey'</li><li>• 'ProjNatOriginLongGeoKey'</li><li>• 'ProjFalseEastingGeoKey'</li><li>• 'ProjFalseNorthingGeoKey'</li><li>• 'ProjFalseOriginLatGeoKey'</li><li>• 'ProjFalseOriginLongGeoKey'</li><li>• 'ProjCenterLatGeoKey'</li><li>• 'ProjCenterLongGeoKey'</li><li>• 'ProjAzimuthAngleGeoKey'</li><li>• 'ProjRectifiedGridAngleGeoKey'</li><li>• 'ProjScaleAtNatOriginGeoKey'</li><li>• 'ProjStdParallel1GeoKey'</li><li>• 'ProjStdParallel2GeoKey'</li></ul>
GCS	String indicating the geographic coordinate system
Datum	String indicating the projection datum type, such as 'North American Datum 1927' or 'North American Datum 1983'
Ellipsoid	String indicating the ellipsoid name as defined by the <code>ellipsoid.csv</code> EPSG file
SemiMajor	Double indicating the length of the semimajor axis of the ellipsoid, in meters
SemiMinor	Double indicating the length of the semiminor axis of the ellipsoid, in meters

---

PM	String indicating the prime meridian location, for example, 'Greenwich' or 'Paris'
PmLongToGreenwich	Double indicating the decimal degrees of longitude between this prime meridian and Greenwich. Prime meridians to the west of Greenwich are negative.
UOMLength	String indicating the units of length used in the projected coordinate system
UOMLengthInMeters	Double defining the UOMLength unit in meters
UOMAngle	String indicating the angular units used for geographic coordinates
UOMAngleInDegrees	Double defining the UOMAngle unit in degrees
TiePoints	Structure containing the image tiepoints. The structure contains these fields: <ul style="list-style-type: none"><li>• <b>ImagePoints</b> — A structure containing row and column coordinates of each image tiepoint. The <b>ImagePoints</b> structure contains these fields:<ul style="list-style-type: none"><li>▪ <b>Row</b> — A double array of size 1-by-N.</li><li>▪ <b>Col</b> — A double array of size 1-by-N.</li></ul></li><li>• <b>WorldPoints</b> — A structure containing the <i>x</i> and <i>y</i> world coordinates of the tiepoints. The <b>WorldPoints</b> structure contains these fields:<ul style="list-style-type: none"><li>▪ <b>X</b> — A double array of size 1-by-N</li><li>▪ <b>Y</b> — A double array of size 1-by-N</li></ul></li></ul>
PixelScale	3-by-1 double array that specifies the X, Y, Z pixel scale values

RefMatrix	3-by-2 double referencing matrix that must be unambiguously defined by the GeoTIFF file; otherwise it is returned empty ([ ]).
BoundingBox	2-by-2 double array that specifies the minimum (row 1) and maximum (row 2) values for each dimension of the image data in the GeoTIFF file
CornerCoords	<p>A structure with six fields that contains coordinates of the outer corners of the GeoTIFF image. Each field is a 1-by-4 double array, or empty ([ ]) if unknown. The arrays contain the coordinates of the outer corners of the corner pixels, starting from the (1,1) corner and proceeding clockwise:</p> <ul style="list-style-type: none"><li>• X — Horizontal coordinates in the projected coordinate system. X equals Lon (below) if <i>ModelType</i> is 'ModelTypeGeographic'.</li><li>• Y — Vertical coordinates in the projected coordinate system. Y equals Lat (below) if <i>ModelType</i> is 'ModelTypeGeographic'.</li><li>• Row — Row coordinates of the corner</li><li>• Col — Column coordinates of the corner</li><li>• Lat — Latitudes of the corner</li><li>• Lon — Longitudes of the corner</li></ul>



GeoTIFFCodes	<p>Structure containing raw numeric values for those GeoTIFF fields that are encoded numerically in the file. These raw values, converted to a string elsewhere in the INFO structure, are provided here for reference. The GeoTIFFCodes fields are:</p> <ul style="list-style-type: none"><li>• Model</li><li>• PCS</li><li>• GCS</li><li>• UOMLength</li><li>• UOMAngle</li><li>• Datum</li><li>• PM</li><li>• Ellipsoid</li><li>• ProjCode</li><li>• Projection</li><li>• CTProjection</li><li>• ProjParmId</li><li>• MapSys</li></ul> <p>Each is scalar, except for ProjParmId, which is a column vector.</p>
ImageDescription	<p>String describing the image; if no description is included in the file, the field is omitted.</p>

## Example

```
info = geotiffinfo('boston.tif')  
  
info =  
    Filename: [1x78 char]
```

```
FileModDate: '31-May-2007 03:25:30'  
  FileSize: 38729900  
    Format: 'tif'  
FormatVersion: []  
  Height: 2881  
  Width: 4481  
  BitDepth: 24  
  ColorType: 'truecolor'  
  ModelType: 'ModelTypeProjected'  
    PCS: 'NAD83 / Massachusetts Mainland'  
  Projection: 'SPCS83 Massachusetts Mainland zone (m)'  
    MapSys: 'STATE_PLANE_83'  
      Zone: 2001  
  CTProjection: 'CT_LambertConfConic_2SP'  
    ProjParm: [7x1 double]  
  ProjParmId: {7x1 cell}  
    GCS: 'NAD83'  
      Datum: 'North American Datum 1983'  
    Ellipsoid: 'GRS 1980'  
    SemiMajor: 6378137  
    SemiMinor: 6.3568e+006  
    PM: 'Greenwich'  
  PMLongToGreenwich: 0  
    UOMLength: 'US survey foot'  
  UOMLengthInMeters: 0.3048  
    UOMAngle: 'degree'  
  UOMAngleInDegrees: 1.0000  
    TiePoints: [1x1 struct]  
    PixelScale: [3x1 double]  
    RefMatrix: [3x2 double]  
    BoundingBox: [2x2 double]  
    CornerCoords: [1x1 struct]  
    GeoTIFFCodes: [1x1 struct]  
  ImageDescription: '"GeoEye"'
```

## See Also

`imfinfo`, `geotiffread`, `makerefmat`, `projfwd`, `projinv`, `projlist`

**Purpose** Read georeferenced image from GeoTIFF file

**Syntax**

```
A = geotiffread(filename)
[X, cmap] = geotiffread(filename)
[X, cmap, R, bbox] = geotiffread(filename)
[A, R, bbox] = geotiffread(filename)
[...] = geotiffread(filename, idx)
[...] = geotiffread(url, ...)
```

**Description** `A = geotiffread(filename)` reads the GeoTIFF image in `filename` into `A`. If the file contains a grayscale image, `A` is a two-dimensional array. If the file contains a true-color (RGB) image, `A` is a three-dimensional (M-by-N-by-3) array.

`filename` is a string that specifies the name of the GeoTIFF file. `filename` can include the directory name; otherwise, the file must be in the current directory or in a directory on the MATLAB path. If the named file includes the extension `.TIF` or `.TIFF` (either upper- or lowercase), the extension can be omitted from `filename`.

`[X, cmap] = geotiffread(filename)` reads the indexed image in `filename` into `X` and its associated colormap into `cmap`. Colormap values in the image file are automatically rescaled into the range `[0,1]`.

`[X, cmap, R, bbox] = geotiffread(filename)` reads the indexed image into `X`, the associated colormap into `cmap`, the referencing matrix into `R`, and the bounding box into `bbox`. The referencing matrix must be unambiguously defined by the GeoTIFF file; otherwise, it and the bounding box are returned empty (`[]`).

`[A, R, bbox] = geotiffread(filename)` reads the grayscale or RGB image into `A`, the referencing matrix into `R`, and the bounding box into `bbox`.

`[...] = geotiffread(filename, idx)` reads in one image from a multiimage GeoTIFF file. `idx` is an integer value that specifies the order that the image appears in the file. For example, if `idx` is 3, `geotiffread` reads the third image in the file. If you omit this argument, `geotiffread` reads the first image in the file.

[...] = geotiffread(url, ...) reads the GeoTIFF image from an Internet URL. The URL must include the protocol type (e.g., “http://”).

---

**Note** geotiffread imports pixel data using the TIFF-reading capabilities of the MATLAB function imread. Consequently, it shares the limitations of imread. Consult the imread documentation for details on the types of TIFF images that imread can import.

---

## Example

Read and display the Boston GeoTIFF image:

```
[boston, R, bbox] = geotiffread('boston.tif');  
figure  
mapshow(boston, R);  
axis image off
```



boston.tif copyright © GeoEye™, all rights reserved.

**See Also** `geotiffinfo`, `imread`, `mapview`, `mapshow`, `geoshow`

# getm

---

**Purpose** Map object properties

**Syntax**

```
mat = getm(h)
mat = getm(h,MapPropertyName)
getm('MapProjection')
getm('axes')
getm('units')
```

**Description**

`mat = getm(h)` returns the map structure of the map axes specified by its handle. If the handle of a child of the map axes is specified, only its properties are returned.

`mat = getm(h,MapPropertyName)` returns the specified property value.

`getm('MapProjection')` lists all available projections.

`getm('axes')` lists the map axes properties by property name.

`getm('units')` lists the available units.

**Examples** Create a default map axes and query a property value:

```
axesm('mercator','AngleUnits','degrees')
getm(gca,'MapParallels')

ans =
    0
```

**See Also** axesm, setm

**Purpose**

Interactively assign seeds for data grid encoding

**Syntax**

```
[row,col,val] = getseeds(map,R,nseeds)
[row,col,val] = getseeds(map,R,nseeds,seedval)
mat = getseeds(...)
```

**Description**

`[row,col,val] = getseeds(map,R,nseeds)` allows user to identify geographical objects while customizing a raster map. It prompts the user for mouse click positions of objects and assigns them a code value. The user is prompted for the value to seed at each location. The outputs are the row and column of the seed location and the value assigned at that location. `R` is either a 1-by-3 vector containing elements:

```
[cells/degree northern_latitude_limit western_longitude_limit]
```

or a 3-by-2 referencing matrix that transforms raster row and column indices to/from geographic coordinates according to:

```
[lon lat] = [row col 1] * R
```

If `R` is a referencing matrix, it must define a (non-rotational, non-skewed) relationship in which each column of the data grid falls along a meridian and each row falls along a parallel.

`[row,col,val] = getseeds(map,R,nseeds,seedval)` assigns the value `seedval` to each location supplied. If `seedval` is a scalar then the same value is assigned at each location. Otherwise, if `seedval` is a vector it must be `length(nseeds)` and each entry is assigned to the corresponding location. `getseeds` operates on the current axes (`gca`).

`mat = getseeds(...)` returns a single output matrix where `mat = [row col val]`.

**Examples**

Demonstrate this for yourself by typing the following and interactively selecting points:

```
load topo
axesm('gortho','grid','on')
```

# getseeds

---

```
seedmat = getseeds(topo,topolegend,3)
```

When you have selected three points, you are prompted for their values. The regular data grid need not be displayed to execute `getseeds` on it.

## See Also

`encodem`



**Purpose** Derive worldfile name from image filename

**Syntax** `worldfilename = getworldfilename(imagefilename)`

**Description** `worldfilename = getworldfilename(imagefilename)` returns the name of the corresponding worldfile derived from the name of an image file.

The worldfile and the image file have the same base name. If `imagefilename` follows the “.3” convention, then you create the worldfile extension by removing the middle letter and appending the letter 'w'.

If `imagefilename` has an extension that does not follow the “.3” convention, then a 'w' is appended to the full image name to construct the worldfile name.

If `imagefilename` has no extension, then '.wld' is appended to construct a worldfile name.

**Examples** Given the following image filenames, `worldfilename` would return these worldfile names:

Image File Name	Worldfile Name
<code>myimage.tif</code>	<code>myimage.tfw</code>
<code>myimage.jpeg</code>	<code>myimage.jpegw</code>
<code>myimage</code>	<code>myimage.wld</code>

**See Also** `mapshow`, `mapview`, `worldfileread`, `worldfilewrite`

# globedem

---

**Purpose** Read Global Land One-km Base Elevation (GLOBE) data

**Syntax**

```
[Z,refvec] = globedem(filename,scalefactor)
[Z,refvec] = globedem(filename,scalefactor,latlim,lonlim)
[Z,refvec] = globedem(dirname,scalefactor,latlim,lonlim)
```

**Description** `[Z,refvec] = globedem(filename,scalefactor)` reads the GLOBE DEM files and returns the result as a regular data grid. The filename is given as a string that does not include an extension. GLOBEDEM first reads the ESRI header file found in the subdirectory `'/esri/hdr/'` and then the binary data file filename. If the files are not found on the MATLAB path, they can be selected interactively. `scalefactor` is an integer that when equal to 1 gives the data at its full resolution. When `scalefactor` is an integer `n` larger than 1, every `n`th point is returned. The map data is returned as an array of elevations and associated three-element referencing vector. Elevations are given in meters above mean sea level, using WGS 84 as a horizontal datum.

`[Z,refvec] = globedem(filename,scalefactor,latlim,lonlim)` allows a subset of the map data to be read. The limits of the desired data are specified as vectors of latitude and longitude in degrees. The elements of `latlim` and `lonlim` must be in ascending order.

`[Z,refvec] = globedem(dirname,scalefactor,latlim,lonlim)` reads and concatenates data from multiple files within a GLOBE directory tree. The `dirname` input is a string with the name of the directory that contains both the uncompressed data files and the ESRI header files.

**Background** GLOBE, the Global Land One-km Base Elevation data, was compiled by the National Geophysical Data Center from more than 10 different sources of gridded elevation data. GLOBE can be considered a higher resolution successor to TerrainBase. The data set consists of 16 tiles, each covering 50 by 90 degrees. Tiles require as much as 60 MB of storage. Uncompressed tiles take between 100 and 130 MB.

## Remarks

The `globedem` function reads data from GLOBE Version 1.0. The data is for elevations only. Elevations are given in meters above mean sea level using WGS 84 as a horizontal datum. Areas with no data, such as the oceans, are coded with NaNs.

The data set and documentation are available over the Internet.

---

**Note** For details on locating map data for download over the Internet, see the following documentation at the MathWorks Web site: <http://www.mathworks.com/support/tech-notes/2100/2101.html>.

---

## Examples

Determine the file that contains the area around Cape Cod.

```
latlim = [41 42.5]; lonlim = [-73 -69.9];
globedems(latlim,lonlim)

ans =
    'f10g'
```

Extract every 20th point from the tile covering the northeastern United States and eastern Canada. Provide an empty file name, and select the file interactively.

```
[Z,refvec] = globedem([],20);
size(Z)

ans =
    300    540
```

Extract a subset of the data for Massachusetts at the full resolution.

```
latlim = [41 42.5]; lonlim = [-73 -69.9];
[Z,refvec] = globedem('f10g',1,latlim,lonlim);
size(Z)

ans =
```

181 373

Replace the NaNs in the ocean with -1 to color them blue.

```
Z(isnan(Z)) = -1;
```

Extract some data for southern Louisiana in an area that straddles two tiles. Provide the name of the directory containing the data files, and let `globedem` determine which files are required, read from the files, and concatenate the data into a single regular data grid.

```
latlim =[28.61 31.31]; lonlim = [-91.24 -88.62];
globedems(latlim,lonlim)

ans =
    'e10g'
    'f10g'

[Z,refvec] =
globedem('d:\externalData\globe\elev',1,latlim,lonlim);
size(Z)

ans =
    325.00    315.00
```

## References

See Web site for the National Oceanic and Atmospheric Administration, National Geophysical Data Center

## See Also

`demdataui`, `dted`, `gtopo30`, `satbath`, `tbase`, `usgsdem`

<b>Purpose</b>	GLOBE data filenames for latitude-longitude quadrangle
<b>Syntax</b>	<code>fname = globedems(latlim,lonlim)</code>
<b>Description</b>	<code>fname = globedems(latlim,lonlim)</code> returns a cell array of the filenames covering the geographic region for GLOBE DEM digital elevation maps. The region is specified by scalar latitude and longitude points, or two-element vectors of latitude and longitude limits in units of degrees.
<b>Background</b>	GLOBE, the Global Land One-km Base Elevation data, was compiled by the National Geophysical Data Center from more than 10 different sources of gridded elevation data. The data set consists of 16 tiles, each covering 50 by 90 degrees. Determining which files are needed to cover a particular region generally requires consulting an index map. This function takes the place of such a reference by returning the filenames for a given geographic region.
<b>Remarks</b>	The <code>globedems</code> function reads data from GLOBE Version 1.0. GLOBE DEM first reads the corresponding ESRI header file found in the subdirectory <code>'/esri/hdr/'</code> and then the binary data file (with no extension).
<b>Examples</b>	<p>Which files are needed for southern Louisiana?</p> <pre>latlim =[28.61 31.31]; lonlim = [-91.24 -88.62]; globedems(latlim,lonlim)  ans =     'e10g'     'f10g'</pre>
<b>References</b>	See Web site for the National Oceanic and Atmospheric Administration, National Geophysical Data Center
<b>See Also</b>	<code>globedem</code>

# gradientm

---

**Purpose** Calculate gradient, slope and aspect of data grid

**Syntax**

```
[ASPECT, SLOPE, gradN, gradE] = gradientm(Z, R)
[...] = gradientm(lat, lon, Z)
[...] = gradientm(..., ellipsoid)
[...] = gradientm(lat, lon, Z, ellipsoid, units)
```

**Description** [ASPECT, SLOPE, gradN, gradE] = gradientm(Z, R) computes the slope, aspect and north and east components of the gradient for a regular data grid Z with three-element referencing vector *refvec*. If the grid contains elevations in meters, the resulting aspect and slope are in units of degrees clockwise from north and up from the horizontal. The north and east gradient components are the change in the map variable per meter of distance in the north and east directions. The computation uses finite differences for the map variable on the default earth ellipsoid. R is either a 1-by-3 vector containing elements:

```
[cells/degree northern_latitude_limit western_longitude_limit]
```

or a 3-by-2 referencing matrix that transforms raster row and column indices to or from geographic coordinates according to:

```
[lon lat] = [row col 1] * R
```

If R is a referencing matrix, it must define a (non-rotational, non-skewed) relationship in which each column of the data grid falls along a meridian and each row falls along a parallel.

[...] = gradientm(lat, lon, Z) does the computation for a geolocated data grid. lat and lon, the latitudes and longitudes of the geolocation points, are in degrees.

[...] = gradientm(..., ellipsoid) uses the specified ellipsoid vector, *ellipsoid*, a 1-by-2 vector of the form [semimajor-axis, eccentricity]. If the map contains elevations in the same units as *ellipsoid(1)*, the slope and aspect are in units of degrees. This calling form is most useful for computations on bodies other than the earth.

[...] = gradientm(lat, lon, Z, ellipsoid, *units*) specifies the angle units of the latitude and longitude inputs. If omitted, 'degrees' are assumed. For elevation maps in the same units as ellipsoid(1), the resulting slope and aspect are in the specified units. The components of the gradient are the change in the map variable per unit of ellipsoid(1).

## Remarks

Coarse digital elevation models can considerably underestimate the local slope. For the preceding map, the elevation points are separated by about 10 kilometers. The terrain between two adjacent points is modeled as a linear variation, while actual terrain can vary much more abruptly over such a distance.

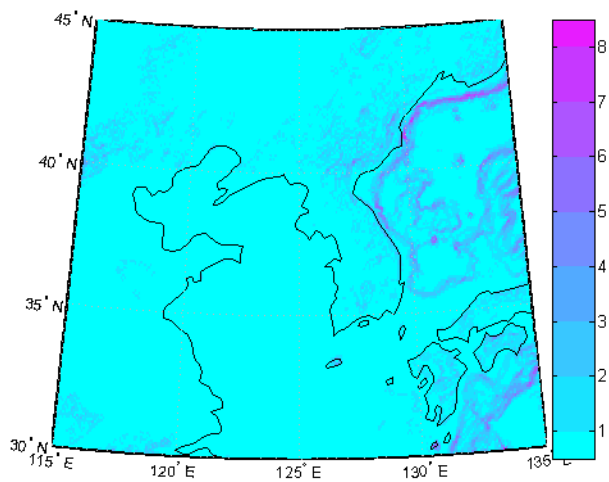
## Example

Compute and display the slope for the 30 arc-second (10 km) Korea elevation data. Slopes in the Sea of Japan are up to 8 degrees at this grid resolution.

```
load korea
[aspect, slope, gradN, gradE] = gradientm(map, refvec);
worldmap(slope, refvec)
geoshow(slope, refvec, 'DisplayType', 'texturemap')
cmap = cool(10);
demcmap('inc', slope, 1, [], cmap)
colorbar
latlim = getm(gca, 'maplatlimit');
lonlim = getm(gca, 'maplonlimit');
land = shaperead('landareas',...
    'UseGeoCoords', true, 'BoundingBox', [lonlim' latlim]);
geoshow(land, 'FaceColor', 'none')
set(gca, 'Visible', 'off')
```

# gradientm

---



## See Also

viewshed

## How To

- “Geolocated Data Grids”



## Purpose

Identify matching fields in fixed record length files

## Syntax

```
grepfields(filename,searchstring)
grepfields(filename,searchstring,casesens)
grepfields(filename,searchstring,casesens,startcol)
grepfields(filename,searchstring,casesens,startfield,fields)
grepfields(filename,searchstring,casesens,startfield,fields,
    machineformat)
indx = grepfields(...)
```

## Description

`grepfields(filename,searchstring)` displays lines in the file that begin with the search string. The file must have fixed-length records with line endings.

`grepfields(filename,searchstring,casesens)`, with `casesens` 'matchcase', specifies a case-sensitive search. If omitted or 'none', the search string matches regardless of the case.

`grepfields(filename,searchstring,casesens,startcol)` searches starting with the specified column. `startcol` is an integer between 1 and the bytes per record in the file. In this calling form, the file is regarded as a text file with line endings.

`grepfields(filename,searchstring,casesens,startfield,fields)` searches within the specified field. `startfield` is an integer between 1 and the number of fields per record. The format of the file is described by the `fields` structure. See `readfields` for recognized fields structure entries. In this calling form, the file can be binary and lack line endings. The search is within `startfield`, which must be a character field.

`grepfields(filename,searchstring,casesens,startfield,fields,machineformat)` opens the file with the specified machine format. `machineformat` must be recognized by `fopen`.

`indx = grepfields(...)` returns the record numbers of matched records instead of displaying them on screen.

## Example

Write a binary file and read it:

```
fid = fopen('testbin','wb');
for i = 1:3
    fwrite(fid,['character' num2str(i) ],'char');
    fwrite(fid,i,'int8');
    fwrite(fid,[i i],'int16');
    fwrite(fid,i,'integer*4');
    fwrite(fid,i,'real*8');
end
fclose(fid);

fs(1).length = 10;fs(1).type = 'char';fs(1).name = 'field 1';
fs(2).length = 1;fs(2).type = 'int8';fs(2).name = 'field 2';
fs(3).length = 2;fs(3).type = 'int16';fs(3).name = 'field 3';
fs(4).length = 1;fs(4).type = 'integer*4';fs(4).name = 'field 4';
fs(5).length = 1;fs(5).type = 'float64';fs(5).name = 'field 5';
```

Find the record matching the string 'character2'. The record contains binary data, which cannot be properly displayed.

```
grepfields('testbin','character2','none',1,fs)
character2? ? ?   ?@

indx = grepfields('testbin','character2','none',1,fs)
indx =
    2
```

Read the formatted file containing the following:

```
-----
character data 1  1  2  3 1e6 10D6

character data 2 11 22 33 2e6 20D6

character data 3111222333 3e6 30D6
-----
```

```
fs(1).length = 16;fs(1).type = 'char';fs(1).name = 'field 1';
fs(2).length = 3;fs(2).type = '%3d';fs(2).name = 'field 2';
fs(3).length = 1;fs(3).type = '%4g';fs(3).name = 'field 3';
fs(4).length = 1;fs(4).type = '%5D'; fs(4).name = 'field 4';
fs(5).length = 1;fs(5).type = 'char';fs(5).name = '';
```

Find the records that match at the beginning of the line.

```
grepfields('testfile1','character')
character data 1 1 2 3 1e6 10D6
character data 2 11 22 33 2e6 20D6
character data 3111222333 3e6 30D6

grepfields('testfile1','character data 2')
character data 2 11 22 33 2e6 20D6
```

Find the records that match, starting the search in column 11.

```
grepfields('testfile1','data 2','none',11)
character data 2 11 22 33 2e6 20D6
```

Search record number 1.

```
grepfields('testfile1','character data 2','none',1,fs)
character data 2 11 22 33 2e6 20D6
```

## Limitations

Searches are limited to fields containing character data.

## Remarks

See `readfields` for a complete discussion of the format and contents of the `fields` argument.

## See Also

`readfields`, `fopen`

# gridm

---

**Purpose** Toggle and control display of graticule lines

**Syntax**

```
gridm
gridm('on')
gridm('off')
gridm('reset')
gridm(linespec)
gridm(MapAxesPropertyName, PropertyValue,...)
h = gridm(...)
```

**Description** `gridm` toggles the display of a latitude-longitude graticule. The choice of meridians and parallels, as well as their graphics properties, depends on the property settings of the map axes.

`gridm('on')` creates the graticule, if it does not yet exist, and makes it visible.

`gridm('off')` makes the graticule invisible.

`gridm('reset')` redraws the graticule using the current map axes properties.

`gridm(linespec)` uses any valid *linespec* string to control the graphics properties of the lines in the graticule.

`gridm(MapAxesPropertyName, PropertyValue,...)` sets the appropriate graticule properties to the desired values. For a description of these property names and values, see the “Properties That Control the Grid” on page 3-46 section of the `axesm` reference page.

`h = gridm(...)` returns the handles of the graticule lines. If both parallels and meridians exist, then `h` is a two-element vector: `h(1)` is the handle to the line comprising the parallels, and `h(2)` is the handle to the line comprising the meridians.

**Remarks** You can also create or alter map grid properties using the `axesm` or `setm` functions.

**See Also** `axesm`, `setm`

**Purpose** Display regular data grid as image

**Syntax** `grid2image(Z,R)`  
`grid2image(Z,R,'PropertyName',PropertyValue,...)`  
`h = grid2image(...)`

**Description** `grid2image(Z,R)` displays a regular data grid as an image. `Z` can be a matrix of dimension M-by-N or M-by-N-by-3, and can contain double, `uint8`, or `uint16` data. `R` is a 1-by-3 referencing vector defined as [cells/angle units north-latitude west-longitude], or a 3-by-2 referencing matrix, defining a two-dimensional affine transformation from pixel coordinates to spatial coordinates. The displayed map is a Plate Carrée projection, treating longitude as X and latitude as Y. This projection produces significant distortion near the poles.

`grid2image(Z,R,'PropertyName',PropertyValue,...)` uses the specified image properties to display the map. See the `image` function reference page for a list of properties that can be changed.

`h = grid2image(...)` returns the handle of the image object displayed.

**See Also** `image`, `mapshow`, `mapview`, `meshm`, `surfacem`, `surfm`

# grn2eqa

---

**Purpose** Convert from Greenwich to equal area coordinates

**Syntax**

```
[x,y] = grn2eqa(lat,lon)
[x,y] = grn2eqa(lat,lon,origin)
[x,y] = grn2eqa(lat,lon,origin,ellipsoid)
[x,y] = grn2eqa(lat,lon,origin,units)
mat = grn2eqa(lat,lon,origin...)
```

**Description**

`[x,y] = grn2eqa(lat,lon)` converts the Greenwich coordinates `lat` and `lon` to the equal-area coordinate points `x` and `y`.

`[x,y] = grn2eqa(lat,lon,origin)` specifies the location in the Greenwich system of the  $x$ - $y$  origin (0,0). The two-element vector `origin` must be of the form `[latitude, longitude]`. The default places the origin at the Greenwich coordinates (0°,0°).

`[x,y] = grn2eqa(lat,lon,origin,ellipsoid)` specifies the two-element ellipsoid vector describing the ellipsoidal model of the figure of the Earth. The `ellipsoid` is spherical by default.

`[x,y] = grn2eqa(lat,lon,origin,units)` specifies the units for the inputs, where `units` is any valid angle units string. The default value is 'degrees'.

`mat = grn2eqa(lat,lon,origin...)` packs the outputs into a single variable.

The `grn2eqa` function converts data from Greenwich-based latitude-longitude coordinates to equal-area  $x$ - $y$  coordinates. The opposite conversion can be performed with `eqa2grn`.

**Examples**

```
lats = [56 34]; longs = [-140 23];
[x,y] = grn2eqa(lats,longs)

x =
    -2.4435    0.4014
y =
    0.8290    0.5592
```

**See Also**      eqa2grn, hista

**Purpose** Read Global Self-Consistent Hierarchical High-Resolution Shoreline

**Syntax**

```
S = gshhs(filename)
S = gshhs(filename, latlim, lonlim)
indexfilename = gshhs(filename, 'createindex')
```

**Description** `S = gshhs(filename)` reads GSHHS version 1.3 and earlier vector data for the entire world from `filename`. GSHHS files have names of the form `gshhs_X.b`, where `X` is one of the letters `c`, `l`, `i`, `h` and `f`, corresponding to increasing resolution (and file size). The result returned in `S` is a polygon geographic data structure array (`geostruct`).

`S = gshhs(filename, latlim, lonlim)` reads a subset of the vector data from `filename`. The limits of the desired data are specified as two-element vectors of latitude, `latlim`, and longitude, `lonlim`, in degrees. The elements of `latlim` and `lonlim` must be in ascending order. Longitude limits range from `[-180 195]`. If `latlim` is empty the latitude limits are `[-90 90]`. If `lonlim` is empty, the longitude limits are `[-180 195]`.

`indexfilename = gshhs(filename, 'createindex')` creates an index file for faster data access when requesting a subset of a larger dataset. The index file has the same name as the GSHHS data file, but with the extension `'i'`, instead of `'b'` and is written in the same directory as `filename`. The name of the index file is returned, but no coastline data are read. A call using this option should be followed by an additional call to `gshhs` to import actual data. On that and subsequent calls, `gshhs` detects the presence of the index file and uses it to access records by location much faster than it would without an index.



**Output Structure**

The geostruct output structure S contains the following fields; all latitude and longitude values are in degrees:

Field Name	Field Contents
Geometry	'Polygon'
BoundingBox	[minLon minLat; maxLon maxLat]
Lon	Coordinate vector
Lat	Coordinate vector
South	Southern latitude boundary
North	Northern latitude boundary
West	Western longitude boundary
East	Eastern longitude boundary
Area	Area of polygon in square kilometers
Level	Scalar value ranging from 1 to 4, indicates level in topological hierarchy
LevelString	'land' or 'lake', or 'island_in_lake', or 'pond_in_island_in_lake' or 'other'
NumPoints	Number of points in the polygon
FormatVersion	Format version of data: empty if unspecified
Source	Source of data: 'WDBII' or 'WVS'
CrossGreenwich	Scalar flag: true if the polygon crosses the prime meridian, false otherwise
GSHHS_ID	Unique polygon scalar id number, starting at 0

**Remarks**

If you are extracting data within specified geographic limits and using data other than coarse resolution, consider creating an index file first.

Also, to speed rendering when mapping very large amounts of data, you might want to plot the data as NaN-clipped lines rather than as patches.

Note that when you specify latitude-longitude limits, polygons that completely fall outside those limits are excluded, but no trimming of features that partially traverse the region is performed. If you want to eliminate data outside of a rectangular region of interest, you can use `maptrim` with the `Lat` and `Lon` fields of the `geostruct` returned by `gshhs` to clip the data to your region and still maintain polygon topology.

## Background

The Global Self-Consistent Hierarchical High-Resolution Shoreline was created by Paul Wessel of the University of Hawaii and Walter H.F. Smith of the NOAA Geosciences Lab. At the full resolution the data requires 85 MB uncompressed, but lower resolution versions are also provided. This database includes coastlines, major rivers, and lakes. The GSHHS data in various resolutions is available over the Internet from the National Oceanic and Atmospheric Administration, National Geophysical Data Center Web site.

Version 1.3 of the `gshhs_c.b` (coarse) data set ships with the toolbox in the `toolbox/map/mapdemos` directory. For details, type

```
type gshhs_c.txt
```

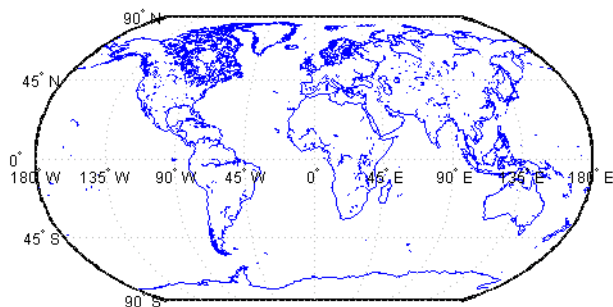
at the MATLAB command prompt.

## Examples

### Example 1

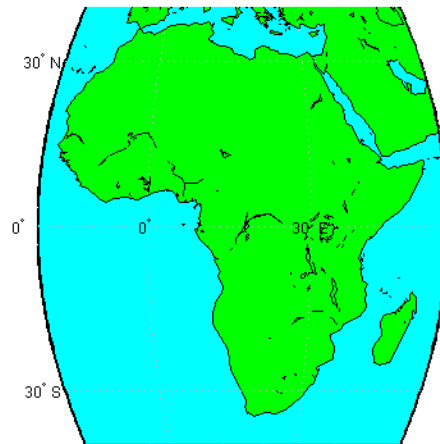
Read the entire coarse data set (located on the MATLAB path in `matlabroot/toolbox/map/mapdemos`) and display as a coastline:

```
filename = gunzip('gshhs_c.b.gz', tempdir);  
world = gshhs(filename{1});  
delete(filename{1})  
figure  
worldmap world  
geoshow([world.Lat], [world.Lon])
```



After creating an index file, read and display Africa as a green polygon; note that gshhs detects and uses the index file automatically:

```
filename = gunzip('gshhs_c.b.gz', tempdir);
indexname = gshhs(filename{1}, 'createindex');
figure
worldmap Africa
projection = gcm;
latlim = projection.maplatlimit;
lonlim = projection.maplonlimit;
africa = gshhs(filename{1}, latlim, lonlim);
delete(filename{1})
delete(indexname)
geoshow(africa, 'FaceColor', 'green')
setm(gca, 'FFaceColor', 'cyan')
```



---

**Note** The following examples use publicly available GSHHS data files that do not ship with the Mapping Toolbox software. For details on locating GSHHS data for download over the Internet, see the following documentation at the MathWorks Web site: <http://www.mathworks.com/support/tech-notes/2100/2101.html>.

---

## Example 2

Read all of the lowest resolution database:

```
s = gshhs('gshhs_c.b')
```

## Example 3

Read the intermediate resolution database for South America:

```
s = gshhs('gshhs_i.b', [-60 -15], [-90 -30])
```

## Example 4

Read the full-resolution file for East and West Falkland Islands (Islas Malvinas):

```
s = gshhs('gshhs_f.b', [-55 -50], [-65 -55])
```

**Example 5**

Create the index file for the high-resolution database:

```
gshhs('gshhs_h.b', 'createindex')
```

**See Also**

dcwdata, geoshow, maptrimp, shaperead, vmap0data, worldmap

# gtextm

---

**Purpose** Place text on map using mouse

**Syntax** `h = gtextm(string)`  
`h = gtextm(string,PropertyName,PropertyValue,...)`

**Description** `h = gtextm(string)` places the text object `string` at the position selected by mouse input. When this function is called, the current map axes are brought up and the cursor is activated for mouse-click position entry. The text object's handle is returned.

`h = gtextm(string,PropertyName,PropertyValue,...)` allows the specification of any properties supported by the MATLAB `text` function.

**Example** Create map axes:

```
axesm('sinusoid','FEdgeColor','red')
gtextm('hello world','FontWeight','bold')
```

Click inside the frame and the text appears.

**See Also** `axesm`, `textm`

**Purpose**

Read 30-arc-second global digital elevation data (GTOPO30)

**Syntax**

```
[Z,refvec] = gtopo30(tilename)
[Z,refvec] = gtopo30(tilename,samplefactor)
[Z,refvec] = gtopo30(tilename,samplefactor,latlim,lonlim)
[Z,refvec] = gtopo30(dirname,samplefactor,latlim,lonlim)
```

**Description**

`[Z,refvec] = gtopo30(tilename)` reads the GTOPO30 tile specified by `tilename` and returns the result as a regular data grid. `tilename` is a string which does not include an extension and indicates a GTOPO30 tile in the current directory or on the MATLAB path. If `tilename` is empty or omitted, a file browser will open for interactive selection of the GTOPO30 header file. The data is returned at full resolution with the latitude and longitude limits determined from the GTOPO30 tile. The data grid, `Z`, is returned as an array of elevations. Elevations are given in meters above mean sea level using WGS84 as a horizontal datum. `refvec` is the associated referencing vector.

`[Z,refvec] = gtopo30(tilename,samplefactor)` reads a subset of the elevation data from `tilename`. `samplefactor` is a scalar integer, which when equal to 1 reads the data at its full resolution. When `samplefactor` is an integer `n` greater than one, every `n`th point is read. If `samplefactor` is omitted or empty, it defaults to 1.

`[Z,refvec] = gtopo30(tilename,samplefactor,latlim,lonlim)` reads a subset of the elevation data from `tilename`. The limits of the desired data are specified as two-element vectors of latitude, `latlim`, and longitude, `lonlim`, in degrees. The elements of `latlim` and `lonlim` must be in ascending order. Longitude limits range from `[-180 180]`. If `latlim` and `lonlim` are omitted, the coordinate limits are determined from the file. The latitude and longitude limits are snapped outward to define the smallest possible rectangular grid of GTOPO30 cells that fully encloses the area defined by the input limits. Any cells in this grid that fall outside the extent of the tile are filled with NaN.

`[Z,refvec] = gtopo30(dirname,samplefactor,latlim,lonlim)` reads and concatenates data from multiple tiles within a GTOPO30 CD-ROM or directory structure. The `dirname` input is a string with the

name of the directory which contains the GTOPO30 tile directories or GTOPO30 tiles. Within the tile directories are the uncompressed data files. The `dirname` for CD-ROMs distributed by the USGS is the device name of the CD-ROM drive. As in the case with a single tile, any cells in the grid specified by `latlim` and `lonlim` are NaN filled if they are not covered by a tile within `dirname`.

`samplefactor` if omitted or empty defaults to 1. `latlim` if omitted or empty defaults to [-90 90]. `lonlim` if omitted or empty defaults to [-180 180].

When directory `dirname` contains no GTOPO30 data or `filename` identifies a file with a `.DEM` extension that is not a GTOPO30 file, the function returns a single NaN in `Z`, a canonical `refvec`, and issues a warning.

The data and documentation are available over the Internet via `http` and anonymous `ftp`, as well as for purchase on CD-ROM.

---

**Note** For details on locating map data for download over the Internet, see the following documentation at the MathWorks Web site: <http://www.mathworks.com/support/tech-notes/2100/2101.html>.

---

## Examples

### Example 1

Extract and display full resolution data for the state of Massachusetts:

```
% Read the stateline polygon boundary and calculate boundary limits.
Massachusetts = shaperead('usastatehi','UseGeoCoords',true, ...
    'Selector',{@(name) strcmpi(name,'Massachusetts'),'Name'});
latlim = [min(Massachusetts.Lat(:)) max(Massachusetts.Lat(:))];
lonlim = [min(Massachusetts.Lon(:)) max(Massachusetts.Lon(:))];

% Read the GTOPO30 data at full resolution.
[Z,refvec] = gtopo30('W100N90',1,latlim,lonlim);

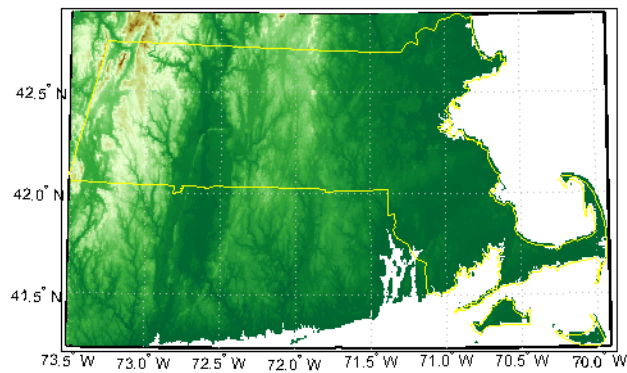
% Display the data grid and overlay the stateline boundary.
```



```

figure
usamap(Z,refvec);
geoshow(Z,refvec,'DisplayType','surface')
colormap(demcmap(Z))
geoshow(Massachusetts,'DisplayType','polygon',...
        'facecolor','none','edgecolor','y')

```



## Example 2

```

% Extract every 20th point from a tile.
% Provide an empty filename and select the file interactively.
[Z,refvec] = gtopo30([],20);

```

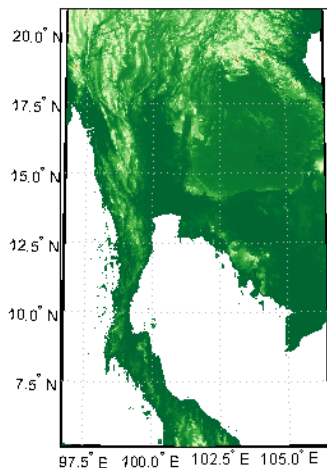
## Example 3

```

% Extract data for Thailand, an area which straddles two tiles.
% The data is on CD number 3 distributed by the USGS.
% The CD-device is 'F:\'
latlim = [5.22 20.90];
lonlim = [96.72 106.38];
gtopo30s(latlim,lonlim)
% Extract every fifth data point for Thailand.
% Specify actual directory or mapped drive if not "F:\'
[Z,refvec] = gtopo30('F:\',5,latlim,lonlim);
worldmap(Z,refvec);

```

```
geoshow(Z,refvec,'DisplayType','surface')  
colormap(demcmap(Z))
```



## Example 4

```
% Extract every 10th point from a column of data 5 degrees around  
% the prime meridian. The current directory contains GTOPO30 data.  
[Z,refvec] = gtopo30(pwd,10,[],[-5 5]);
```

## See Also

gtopo30s, globedem, dted, satbath, tbase, usgsdem

<b>Purpose</b>	GTOPO30 data filenames for latitude-longitude quadrangle
<b>Syntax</b>	<code>fname = gtopo30s(latlim,lonlim)</code>
<b>Description</b>	<code>fname = gtopo30s(latlim,lonlim)</code> returns a cell array of the filenames covering the geographic region for GTOPO30 digital elevation maps (also referred to as “30-arc second” DEMs). <code>latlim</code> and <code>lonlim</code> specify the region as scalar latitude and longitude points, or two-element vectors of latitude and longitude limits in units of degrees.
<b>Remarks</b>	The data and documentation are available over the Internet via <code>http</code> and anonymous <code>ftp</code> .
	<hr/> <b>Note</b> For details on locating map data for download over the Internet, see the following documentation at the MathWorks Web site: <a href="http://www.mathworks.com/support/tech-notes/2100/2101.html">http://www.mathworks.com/support/tech-notes/2100/2101.html</a> . <hr/>
<b>See Also</b>	<code>gtopo30</code>

# handlem

---

**Purpose** Handles of displayed map objects

**Syntax**

```
handlem or handlem('taglist')
h = handlem('prompt')
h = handlem(object)
handlem('object', axesh)
handlem('object', axesh, 'searchmethod')
h = handlem(handles)
```

**Description** `handlem` or `handlem('taglist')` displays a dialog box for selecting the objects for which you want handles.

`h = handlem('prompt')` displays another dialog box, which allows greater control of object selection.

`h = handlem(object)` returns the handles of those objects specified by the input string. The options for the *object* string are

'all'	All children of the current axes
'clabels'	Contour labels on the current map axes
'contour'	Contourgroup for contours on the current map axes
'contour3d'	3-D contour lines on the current map axes
'cpatches'	Filled contour patches on the current map axes
'frame'	Map frame
'grid'	Map grid lines
'hgroup'	All hgroup objects
'hidden'	Hidden objects on the current axes
'image'	Image objects on the current axes
'light'	Light objects on the current axes
'line'	Line objects on the current axes

'map'	All objects on the map, excluding the frame (default)
'meridian'	Longitude grid lines
'mlabel'	Longitude labels
'parallel'	Latitude grid lines
'patch'	Patch objects on the current axes
'plabel'	Latitude labels
'scaleruler'	Scaleruler objects
'surface'	Surface objects on the current axes
'text'	Text objects on the current axes
'tissot'	Tissot indicatrices on the current map axes
'visible'	Visible objects on the current axes

Or any user-defined object tag string.

A prefix of 'all' can be applied to strings defining a Handle Graphics® object type ('allimage', 'allline', 'allsurface', 'allpatch', 'alltext') to determine all object handles that meet the type criteria. Without the 'all' prefix, those objects named by the user with the `tagm` function are not included (e.g., a line with the tag 'route' would not be included for object string 'line', but would be for 'allline').

`handlem('object', axesh)` searches within the axes specified by the input handle `axesh`.

`handlem('object', axesh, 'searchmethod')` controls the method used to match the 'str' input. If omitted, 'exact' is assumed. Search method 'strmatch' searches for matches at the beginning of the tag, similar to the MATLAB `strmatch` function. Search method 'findstr' searches within the tag, similar to the MATLAB `findstr` function.

`h = handlem(handles)` returns those elements of an input vector of handles that are still valid.

# handlem

---

## **See Also**

clma, clmo, hidem, namem, showm, tagm

**Purpose** Hide specified graphic objects on map axes

**Syntax** `hidem`  
`hidem(handle)`  
`hidem(object)`

**Description** `hidem` brings up a dialog box for selecting the objects to hide (set their `Visible` property to 'off').

`hidem(handle)` hides the objects specified by a vector of handles.

`hidem(object)` hides those objects specified by the `object` string, which can be any string recognized by the `handlem` function.

**See Also** `clma`, `clmo`, `handlem`, `namem`, `showm`, `tagm`

# hista

---

**Purpose** Histogram for geographic points with equal-area bins

**Syntax**

```
[lat,lon,num] = hista(lats,lons)
[lat,lon,num] = hista(lats,lons,binarea)
[lat,lon,num] = hista(lats,lons,binarea,ellipsoid)
[lat,lon,num] = hista(lats,lons,binarea,units)
```

**Description** [lat,lon,num] = hista(lats,lons) returns the center coordinates of equal-area bins and the number of observations falling in each based on the geographically distributed input data.

[lat,lon,num] = hista(lats,lons,binarea) specifies the equal-area bin size, in square kilometers. It is 100 km<sup>2</sup> by default.

[lat,lon,num] = hista(lats,lons,binarea,ellipsoid) specifies the elliptical definition of the Earth to be used with the two-element ellipsoid vector. The default ellipsoid model is a spherical Earth, which is sufficient for most applications.

[lat,lon,num] = hista(lats,lons,binarea,units) specifies the standard angle unit string. The default value is 'degrees'.

## Examples

Create random data:

```
lats = rand(4)
```

```
lats =
```

```
0.4451    0.8462    0.8381    0.8318
0.9318    0.5252    0.0196    0.5028
0.4660    0.2026    0.6813    0.7095
0.4186    0.6721    0.3795    0.4289
```

```
longs = rand(4)
```

```
longs =
```

```
0.3046    0.3028    0.3784    0.4966
0.1897    0.5417    0.8600    0.8998
0.1934    0.1509    0.8537    0.8216
```



```
0.6822    0.6979    0.5936    0.6449
```

Bin the data in 50-by-50 km cells (2500 sq km):

```
[lat,lon,num] = hista(lats,longs,2500);  
[lat lon num]
```

```
ans =  
    0.2574    0.3757    4.0000  
    0.7070    0.3757    5.0000  
   -0.1923    0.8253    1.0000  
    0.2573    0.8253    2.0000  
    0.7070    0.8254    4.0000
```

## See Also

eqa2grn, grn2eqa, histr

**Purpose** Histogram for geographic points with equirectangular bins

**Syntax**

```
[lat,lon,num,wnum] = histr(lats,lons)
[lat,lon,num,wnum] = histr(lats,lons,units)
[lat,lon,num,wnum] = histr(lats,lons,bindensty)
```

**Description** `[lat,lon,num,wnum] = histr(lats,lons)` returns the center coordinates of equal-rectangular bins and the number of observations, `num`, falling in each based on the geographically distributed input data. Additionally, an area-weighted observation value, `wnum`, is returned. `wnum` is the bin's `num` divided by its normalized area. The largest bin has the same `num` and `wnum`; a smaller bin has a larger `wnum` than `num`.

`[lat,lon,num,wnum] = histr(lats,lons,units)` specifies the standard angle unit string. The default value is 'degrees'.

`[lat,lon,num,wnum] = histr(lats,lons,bindensty)` sets the number of bins per angular unit. For example, if `units` is 'degrees', a `bindensty` of 10 would be 10 bins per degree of latitude or longitude, resulting in 100 bins per *square* degree. The default is one cell per angular unit.

The `histr` function sorts geographic data into equirectangular bins for histogram purposes. Equirectangular in this context means that each bin has the same angular measurement on each side (e.g., 1°-by-1°). Consequently, the result is not an equal-area histogram. The `hista` function provides that capability. However, the results of `histr` can be weighted by their area bias to correct for this, in some sense.

**Examples** Create random data:

```
lats = rand(4)
```

```
lats =
    0.4451    0.8462    0.8381    0.8318
    0.9318    0.5252    0.0196    0.5028
    0.4660    0.2026    0.6813    0.7095
    0.4186    0.6721    0.3795    0.4289
```

```
longs = rand(4)

longs =
    0.3046    0.3028    0.3784    0.4966
    0.1897    0.5417    0.8600    0.8998
    0.1934    0.1509    0.8537    0.8216
    0.6822    0.6979    0.5936    0.6449
```

Bin the data in 0.5-by-0.5 degree cells (two bins per degree):

```
[lat,lon,num,wnum] = histr(lats,longs,2);
[lat,lon,num,wnum]
```

```
ans =
    0.2500    0.2500    3.0000    3.0000
    0.7500    0.2500    4.0000    4.0003
    0.2500    0.7500    4.0000    4.0000
    0.7500    0.7500    5.0000    5.0004
```

The bins centered at 0.75°N are slightly smaller in area than the others. wnum reflects the relative count per normalized unit area.

**See Also**

filterm, hista

# imbedm

---

**Purpose** Encode data points into regular data grid

**Syntax**

```
Z = imbedm(lat, lon, value, Z, R)
Z = imbedm(lat, lon, value, Z, R, units)
[Z, indxPointOutsideGrid] = imbedm(...)
```

**Description** `Z = imbedm(lat, lon, value, Z, R)` resets certain entries of a regular data grid, `Z`. `R` is either a 1-by-3 vector containing elements:

```
[cells/degree northern_latitude_limit western_longitude_limit]
```

or a 3-by-2 referencing matrix that transforms raster row and column indices to/from geographic coordinates according to:

```
[lon lat] = [row col 1] * R
```

If `R` is a referencing matrix, it must define a (non-rotational, non-skewed) relationship in which each column of the data grid falls along a meridian and each row falls along a parallel. The entries to be reset correspond to the locations defined by the latitude and longitude position vectors `lat` and `lon`. The entries are reset to the same number if `value` is a scalar, or to individually specified numbers if `value` is a vector the same size as `lat` and `lon`. If any points lie outside the input grid, a warning is issued. All input angles are in degrees.

`Z = imbedm(lat, lon, value, Z, R, units)` specifies the units of the vectors `lat` and `lon`, where *units* is any valid angle units string ('degrees' by default).

`[Z, indxPointOutsideGrid] = imbedm(...)` returns the indices of `lat` and `lon` corresponding to points outside the grid in the variable `indxPointOutsideGrid`.

**Examples** Create a simple grid map and embed new values in it:

```
Z = ones(3,6)
```

```
Z =
```

```
      1      1      1      1      1      1
      1      1      1      1      1      1
      1      1      1      1      1      1
refvec = [1/60 90 -180]

refvec =
      0.0167   90.0000 -180.0000

newgrid = imbedm([23 -23], [45 -45],[5 5],Z,refvec)

newgrid =
      1      1      1      1      1      1
      1      1      5      5      1      1
      1      1      1      1      1      1
```

**See Also** `1t1n2val`, `setpostn`

# ind2rgb8

---

**Purpose** Convert indexed image to uint8 RGB image

**Syntax** `RGB = ind2rgb8(X,cmap)`

**Description** `RGB = ind2rgb8(X,cmap)` creates an RGB image of class `uint8`. `X` must be `uint8`, `uint16`, or `double`, and `cmap` must be a valid MATLAB colormap.

**Example**

```
% Convert the 'concord_ortho_e.tif' image to RGB.
[X, cmap] = imread('concord_ortho_e.tif');
RGB = ind2rgb8(X, cmap);
R = worldfileread('concord_ortho_e.tfw');
mapshow(RGB, R);
```

**See Also** `ind2rgb`

**Purpose**

True for points inside or on lat-lon quadrangle

**Syntax**

`tf = ingeoquad(lat, lon, latlim, lonlim)`

**Description**

`tf = ingeoquad(lat, lon, latlim, lonlim)` returns an array `tf` that has the same size as `lat` and `lon`. `tf(k)` is true if and only if the point `lat(k)`, `lon(k)` falls within or on the edge of the geographic quadrangle defined by `latlim` and `lonlim`. `latlim` is a vector of the form `[southern-limit northern-limit]`, and `lonlim` is a vector of the form `[western-limit eastern-limit]`. All angles are in units of degrees.

**Example**

- 1 Load and display a digital elevation model (DEM) including the Korean Peninsula:

```
korea = load('korea');
[latlim, lonlim] = limitm(korea.map, korea.refvec);
figure('Color','white')
worldmap([20 50],[90 150])
geoshow(korea.map, korea.refvec, 'DisplayType', 'texturemap');
colormap(demcmap(korea.map))
```

- 2 Generate a track that crosses the DEM:

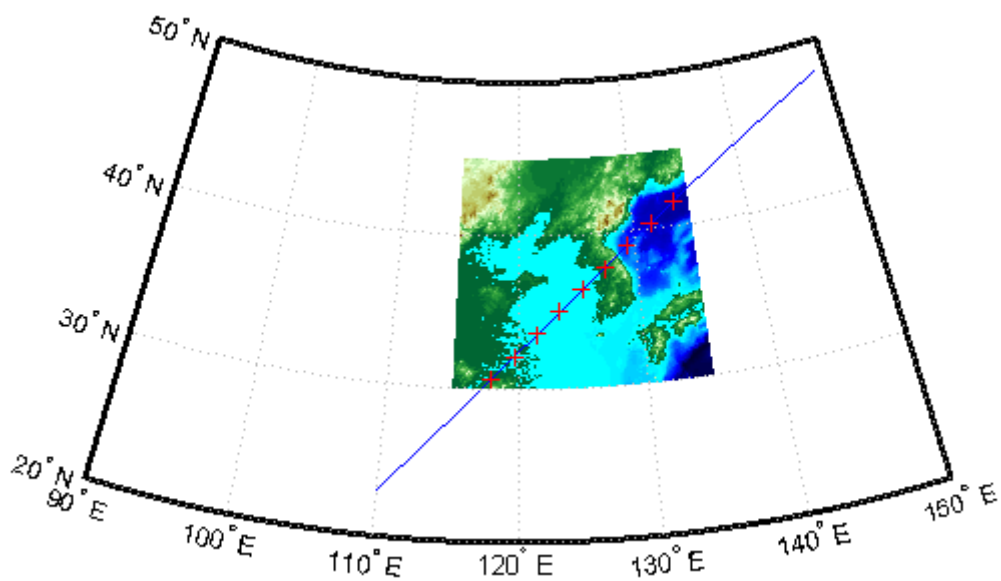
```
[lat, lon] = track2(23, 110, 48, 149, [1 0], 'degrees', 20);
geoshow(lat, lon, 'DisplayType', 'line')
```

- 3 Identify and mark points on the track that fall within the quadrangle outlining the DEM:

```
tf = ingeoquad(lat, lon, latlim, lonlim);
geoshow(lat(tf), lon(tf), 'DisplayType', 'point')
```

# ingeoquad

---



**See Also** `inpolygon`, `intersectgeoquad`



<b>Purpose</b>	Intersection of two latitude-longitude quadrangles
<b>Syntax</b>	<code>[latlim, lonlim] = intersectgeoquad(latlim1, lonlim1, latlim2, lonlim2)</code>
<b>Description</b>	<p><code>[latlim, lonlim] = intersectgeoquad(latlim1, lonlim1, latlim2, lonlim2)</code> computes the intersection of the quadrangle defined by the latitude and longitude limits <code>latlim1</code> and <code>lonlim1</code>, with the quadrangle defined by the latitude and longitude limits <code>latlim2</code> and <code>lonlim2</code>. <code>latlim1</code> and <code>latlim2</code> are two-element vectors of the form <code>[southern-limit northern-limit]</code>. Likewise, <code>lonlim1</code> and <code>lonlim2</code> are two-element vectors of the form <code>[western-limit eastern-limit]</code>. All input and output angles are in units of degrees. The intersection results are given in the output arrays <code>latlim</code> and <code>lonlim</code>. Given an arbitrary pair of input quadrangles, there are three possible results:</p> <ol style="list-style-type: none"> <li><b>1</b> <i>The quadrangles fail to intersect.</i> In this case, both <code>latlim</code> and <code>lonlim</code> are empty arrays.</li> <li><b>2</b> <i>The intersection consists of a single quadrangle.</i> In this case, <code>latlim</code> (like <code>latlim1</code> and <code>latlim2</code>) is a two-element vector that has the form <code>[southern-limit northern-limit]</code>, where <code>southern-limit</code> and <code>northern-limit</code> represent scalar values. <code>lonlim</code> (like <code>lonlim1</code> and <code>lonlim2</code>), is a two-element vector that has the form <code>[western-limit eastern-limit]</code>, with a pair of scalar limits.</li> <li><b>3</b> <i>The intersection consists of a pair of quadrangles.</i> This can happen when longitudes wrap around such that the eastern end of one quadrangle overlaps the western end of the other and vice versa. For example, if <code>lonlim1 = [-90 90]</code> and <code>lonlim2 = [45 -45]</code>, there are two intervals of overlap: <code>[-90 -45]</code> and <code>[45 90]</code>. These limits are returned in <code>lonlim</code> in separate rows, forming a 2-by-2 array. In our example (assuming that the latitude limits overlap), <code>lonlim</code> would equal <code>[-90 -45; 45 90]</code>. It still has the form <code>[western-limit eastern-limit]</code>, but <code>western-limit</code> and <code>eastern-limit</code> are 2-by-1 rather than scalar. The two output quadrangles have the same latitude limits, but these are replicated so that <code>latlim</code> is also 2-by-2.</li> </ol>

# intersectgeoquad

---

To continue the example, if `latlim1 = [0 30]` and `latlim2 = [20 50]`, `latlim` equals `[20 30; 20 30]`. The form is still `[southern-limit northern-limit]`, but in this case `southern-limit` and `northern-limit` are 2-by-1.

## Remarks

`latlim1` and `latlim2` should normally be given in order of increasing numerical value. No error will result if, for example, `latlim1(2) < latlim1(1)`, but the outputs will both be empty arrays.

No such restriction applies to `lonlim1` and `lonlim2`. The first element is always interpreted as the western limit, even if it exceeds the second element (the eastern limit). Furthermore, `intersectgeoquad` correctly handles whatever longitude-wrapping convention may have been applied to `lonlim1` and `lonlim2`.

In terms of output, `intersectgeoquad` wraps `lonlim` such that all elements fall in the closed interval `[-180 180]`. This means that if (one of) the output quadrangle(s) crosses the 180° meridian, its western limit exceeds its eastern limit. The result would be such that

$$\text{lonlim}(2) < \text{lonlim}(1)$$

if the intersection comprises a single quadrangle or

$$\text{lonlim}(k,2) < \text{lonlim}(k,1)$$

where `k` equals 1 or 2 if the intersection comprises a pair of quadrangles.

If `abs(diff(lonlim1))` or `abs(diff(lonlim2))` equals 360, its quadrangle is interpreted as a latitudinal zone that fully encircles the planet, bounded only by one parallel on the south and another parallel on the north. If two such quadrangles intersect, `lonlim` is set to `[-180 180]`.

If you want to display geographic quadrangles generated by this function or any other which are more than one or two degrees in extent, they may not follow curved meridians and parallels very well. The degree of departure depends on the extent of the quadrangle, the map projection, and the map scale. In such cases, you can interpolate

intermediate vertices along quadrangle edges with the `outlinegeoquad` function.

## Examples

### Example 1

Nonintersecting quadrangles:

```
[latlim, lonlim] = intersectgeoquad( ...
                                [-40 -60], [-180 180], [40 60], [-180 180])
latlim =
    []
lonlim =
    []
```

### Example 2

Intersection is a single quadrangle:

```
[latlim, lonlim] = intersectgeoquad( ...
                                [-40 60], [-120 45], [-60 40], [160 -75])
latlim =
    -40    40
lonlim =
    -120   -75
```

### Example 3

Intersection is a pair of quadrangles:

```
[latlim, lonlim] = intersectgeoquad( ...
                                [-30 90], [-10 -170], [-90 30], [170 10])
latlim =
    -30    30
    -30    30
```

# intersectgeoquad

---

```
lonlim =  
    -10    10  
    170  -170
```

## Example 4

Inputs and output fully encircle the planet:

```
[latlim, lonlim] = intersectgeoquad( ...  
    [-30 90],[-180 180],[-90 30],[0 360])  
  
latlim =  
    -30    30  
  
lonlim =  
   -180   180
```

## Example 5

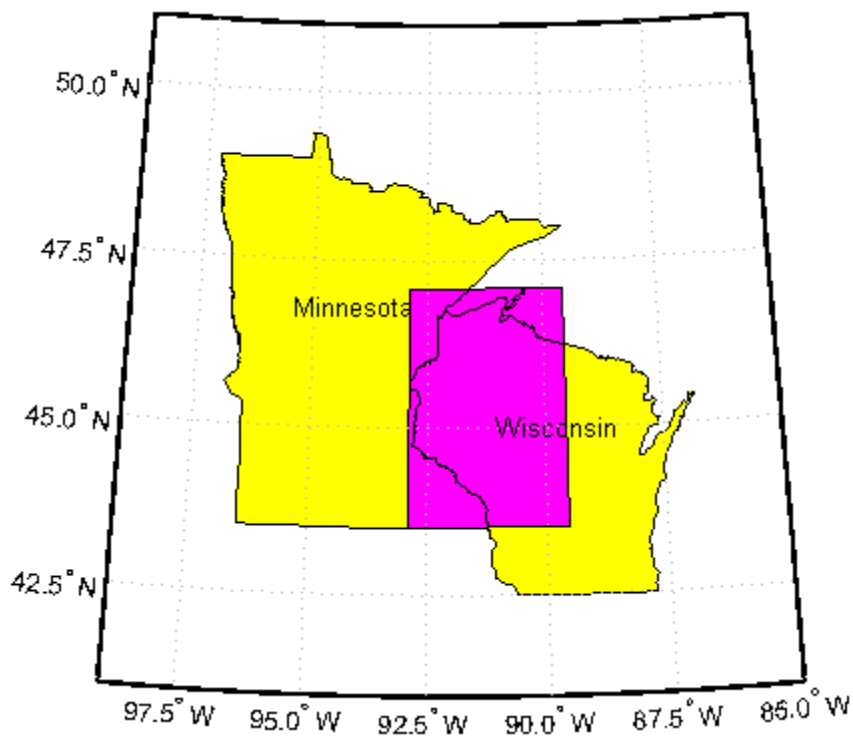
Find and map the intersection of the bounding boxes of adjoining U.S. states:

```
usamap({'Minnesota','Wisconsin'})  
S = shaperead('usastatehi','UseGeoCoords',true,'Selector',...  
    {@(name) any(strcmp(name,{'Minnesota','Wisconsin'})), 'Name'});  
geoshow(S, 'FaceColor', 'y')  
textm([S.LabelLat], [S.LabelLon], {S.Name},...  
    'HorizontalAlignment', 'center')  
latlimMN = S(1).BoundingBox(:,2)'  
  
latlimMN =  
    43.4995    49.3844  
  
lonlimMN = S(1).BoundingBox(:,1)'  
  
lonlimMN =  
   -97.2385  -89.5612
```

```
latlimWI = S(2).BoundingBox(:,2)'  
  
latlimWI =  
    42.4918    47.0773  
  
lonlimWI = S(2).BoundingBox(:,1)'  
  
lonlimWI =  
   -92.8892   -86.8059  
  
[latlim lonlim] = ...  
    intersectgeoquad(latlimMN, lonlimMN, latlimWI, lonlimWI)  
  
latlim =  
    43.4995    47.0773  
  
lonlim =  
   -92.8892   -89.5612  
  
geoshow(latlim([1 2 2 1 1]), lonlim([1 1 2 2 1]), ...  
    'DisplayType','polygon','FaceColor','m')
```

# intersectgeoquad

---



**See Also**      `ingeoquad`, `outlinegeoquad`

---

<b>Purpose</b>	Latitudes and longitudes of mouse-click locations
<b>Syntax</b>	<pre>[lat, lon] = inputm [lat, lon] = inputm(n) [lat, lon] = inputm(n,h) [lat, lon, button] = inputm(n) MAT = inputm(...)</pre>
<b>Description</b>	<p><code>[lat, lon] = inputm</code> returns the latitudes and longitudes in geographic coordinates of points selected by mouse clicks on a displayed grid. The point selection continues until the return key is pressed.</p> <p><code>[lat, lon] = inputm(n)</code> returns <i>n</i> points specified by mouse clicks.</p> <p><code>[lat, lon] = inputm(n,h)</code> prompts for points from the map axes specified by the handle <i>h</i>. If omitted, the current axes (<code>gca</code>) is assumed.</p> <p><code>[lat, lon, button] = inputm(n)</code> returns a third result, <code>button</code>, that contains a vector of integers specifying which mouse button was used (1,2,3 from left) or ASCII numbers if a key on the keyboard was used.</p> <p><code>MAT = inputm(...)</code> returns a single matrix, where <code>MAT = [lat lon]</code>.</p>
<b>Remarks</b>	<p><code>inputm</code> works much like the standard MATLAB <code>ginput</code>, except that the returned values are latitudes and longitudes extracted from the projection, rather than axes <i>x-y</i> coordinates. If you click outside of the projection bounds (beyond the map frame in the corners of a Robinson projection, for example), no coordinates are returned for that location.</p> <p><code>inputm</code> cannot be used with a 3-D display, including those created using <code>globe</code>.</p>
<b>See Also</b>	<code>gcpmap</code> , <code>ginput</code> (MATLAB function)

# interp

---

## Purpose

Densify latitude-longitude sampling in lines or polygons

## Syntax

```
[latout,lonout] = interp(lat,lon,maxdiff)
[latout,lonout] = interp(lat,lon,maxdiff,method)
[latout,lonout] = interp(lat,lon,maxdiff,method,units)
```

## Description

`[latout,lonout] = interp(lat,lon,maxdiff)` fills in any gaps in latitude (`lat`) or longitude (`lon`) data vectors that are greater than a defined tolerance `maxdiff` apart in either dimension. The angle units of the three inputs need not be specified, but they must be identical. `latout` and `lonout` are the new latitude and longitude data vectors, in which any gaps larger than `maxdiff` in the original vectors have been filled with additional points. The default method of interpolation used by `interp` is linear.

`[latout,lonout] = interp(lat,lon,maxdiff,method)` interpolates between vector data coordinate points using a specified interpolation method. Valid interpolation method strings are 'gc' for great circle, 'rh' for rhumb line, and 'lin' for linear interpolation.

`[latout,lonout] = interp(lat,lon,maxdiff,method,units)` specifies the units used, where *units* is any valid angle units string. The default is 'degrees'.

## Examples

```
lat = [1 2 4 5]; lon = [7 8 9 11];
[latout,lonout] = interp(lat,lon,1);
[latout lonout]
```

```
ans =
    1.0000    7.0000
    2.0000    8.0000
    3.0000    8.5000
    4.0000    9.0000
    4.5000   10.0000
    5.0000   11.0000
```

## See Also

`intrplat`, `intrplon`



**Purpose**

Interpolate latitude at given longitude

**Syntax**

```
newlat = intrplat(long,lat,newlong)
newlat = intrplat(long,lat,newlong,method)
newlat = intrplat(long,lat,newlong,method,units)
```

**Description**

`newlat = intrplat(long,lat,newlong)` returns an interpolated latitude, `newlat`, corresponding to a longitude `newlong`. `long` must be a monotonic vector of longitude values. The actual entries must be monotonic; that is, the longitude vector `[350 357 3 10]` is not allowed even though the geographic *direction* is unchanged (use `[350 357 363 370]` instead). `lat` is a vector of the latitude values paired with each entry in `long`.

`newlat = intrplat(long,lat,newlong,method)` specifies the method of interpolation employed. The default value of the `method` string is 'linear', which results in linear, or Cartesian, interpolation between the numerical values entered. This is really just a pass-through to the MATLAB `interp1` function. Similarly, 'spline' and 'cubic' perform cubic spline and cubic interpolation, respectively. The 'rh' method returns interpolated points that lie on rhumb lines between input data. Similarly, the 'gc' method returns interpolated points that lie on great circles between input data.

`newlat = intrplat(long,lat,newlong,method,units)` specifies the units used, where `units` is any valid angle units string. The default is 'degrees'.

The function `intrplat` is a geographic data analogy of the standard MATLAB function `interp1`.

**Examples**

Compare the results of the various methods:

```
lats = [25 45]; longs = [30 60];
newlat = intrplat(longs,lats,45,'linear')

newlat =
    35
```

# intrplat

---

```
newlat = intrplat(longs,lats,45,'rh')  
  
newlat =  
    35.6213  
  
newlat = intrplat(longs,lats,45,'gc')  
  
newlat =  
    37.1991
```

## Remarks

There are separate functions for interpolating latitudes and longitudes, for although the cases are identical when using those methods supported by `interp1`, when latitudes and longitudes are treated like the spherical angles they are (using `'rh'` or `'gc'`), the results are different. Compare the example above to the example under `intrplon`, which reverses the values of latitude and longitude.

## See Also

`interp1`, `intrplon`

**Purpose**

Interpolate longitude at given latitude

**Syntax**

```
newlon = intrplon(lat,lon,newlat)
newlon = intrplon(lat,lon,newlat,method)
newlon = intrplon(lat,lon,newlat,method,units)
```

**Description**

`newlon = intrplon(lat,lon,newlat)` returns an interpolated longitude, `newlon`, corresponding to a latitude `newlat`. `lat` must be a monotonic vector of longitude values. `lon` is a vector of the longitude values paired with each entry in `lat`.

`newlon = intrplon(lat,lon,newlat,method)` specifies the method of interpolation employed. The default value of the *method* string is 'linear', which results in linear, or Cartesian, interpolation between the numerical values entered. This is really just a pass-through to the MATLAB `interp1` function. Similarly, 'spline' and 'cubic' perform cubic spline and cubic interpolation, respectively. The 'rh' method returns interpolated points that lie on rhumb lines between input data. Similarly, the 'gc' method returns interpolated points that lie on great circles between input data.

`newlon = intrplon(lat,lon,newlat,method,units)` specifies the units used, where *units* is any valid angle units string. The default is 'degrees'.

The function `intrplon` is a geographic data analogy of the MATLAB function `interp1`.

**Examples**

Compare the results of the various methods:

```
long = [25 45]; lat = [30 60];
newlon = intrplon(lat,long,45,'linear')

newlon =
    35

newlon = intrplon(lat,long,45,'rh')
```

# intrplon

---

```
newlon =  
    33.6515  
  
newlon = intrplon(lat,long,45,'gc')  
  
newlon =  
    32.0526
```

## Remarks

There are separate functions for interpolating latitudes and longitudes, for although the cases are identical when using those methods supported by `interp1`, when latitudes and longitudes are treated like the spherical angles they are (using 'rh' or 'gc'), the results are different. Compare the previous example to the example under `intrplat`, which reverses the values of latitude and longitude.

## See Also

`interp`, `intrplat`

**Purpose** True for axes with map projection

**Syntax**  
`mflag = ismap`  
`mflag = ismap(hndl)`  
`[mflag,msg] = ismap(hndl)`

**Description** `mflag = ismap` returns a 1 if the current axes is a map axes, and 0 otherwise.

`mflag = ismap(hndl)` specifies the handle of the axes to be tested.

`[mflag,msg] = ismap(hndl)` returns a string message if the axes is not a map axes, specifying why not.

The `ismap` function tests an axes object to determine whether it is a map axes.

**See Also** `gcm`, `ismapped`

# ismapped

---

**Purpose** True, if object is projected on map axes

**Syntax**  
`mflag = ismapped`  
`mflag = ismapped(hndl)`  
`[mflag,msg] = ismapped(hndl)`

**Description** `mflag = ismapped` returns a 1 if the current object is projected on a map axes, and 0 otherwise.

`mflag = ismapped(hndl)` specifies the handle of the object to be tested.

`[mflag,msg] = ismapped(hndl)` returns a string message if the axes is not projected on a map axes, specifying why not.

The `ismapped` function tests an object to determine whether it is projected on map axes.

**See Also** `gcm`, `ismap`

<b>Purpose</b>	True if polygon vertices are in clockwise order
<b>Syntax</b>	<code>tf = ispolycw(x, y)</code>
<b>Description</b>	<p><code>tf = ispolycw(x, y)</code> returns true if the polygonal contour vertices represented by <code>x</code> and <code>y</code> are ordered in the clockwise direction. <code>x</code> and <code>y</code> are numeric vectors with the same number of elements.</p> <p>Alternatively, <code>x</code> and <code>y</code> can contain multiple contours, either in NaN-separated vector form or in cell array form. In that case, <code>ispolycw</code> returns a logical array containing one true or false value per contour.</p> <p><code>ispolycw</code> always returns true for polygonal contours containing two or fewer vertices.</p> <p>Vertex ordering is not well defined for self-intersecting polygonal contours. For such contours, <code>ispolycw</code> returns a result based on the order of vertices immediately before and after the left-most of the lowest vertices. In other words, of the vertices with the lowest <code>y</code> value, find the vertex with the lowest <code>x</code> value. For a few special cases of self-intersecting contours, the vertex ordering cannot be determined using only the left-most of the lowest vertices; for these cases, <code>ispolycw</code> uses a signed area test to determine the ordering.</p>
<b>Class Support</b>	<code>x</code> and <code>y</code> may be any numeric class.
<b>Example</b>	Orientation of a square: <pre>x = [0 1 1 0 0]; y = [0 0 1 1 0]; ispolycw(x, y) % Returns 0 ispolycw(fliplr(x), fliplr(y)) % Returns 1</pre>
<b>See Also</b>	<code>poly2cw</code> , <code>poly2ccw</code> , <code>polybool</code>

# isShapeMultipart

---

**Purpose** True, if polygon or line has multiple parts

**Syntax** `tf = isShapeMultipart(xdata, ydata)`

**Description** `tf = isShapeMultipart(xdata, ydata)` returns 1 (true) if the polygon or line shape specified by `xdata` and `ydata` consists of multiple NaN-separated parts (i.e. has inner or multiple polygon rings or multiple line segments). The coordinate arrays `xdata` and `ydata` must match in size and have identical NaN locations.

## Examples

```
isShapeMultipart([0 0 1],[0 1 0])
```

```
ans =  
    0
```

```
isShapeMultipart([0 0 1 NaN 2 2 3 3],[0 1 0 NaN 2 3 3 2])
```

```
ans =  
    1
```

```
load coast  
isShapeMultipart(lat, long)
```

```
ans =  
    1
```

```
S = shaperead('concord_hydro_area');  
isShapeMultipart( S(1).X, S(1).Y)
```

```
ans =  
    0
```

```
isShapeMultipart(S(14).X, S(14).Y)
```

```
ans =  
    1
```



**See Also**      `polysplit`

# km2deg, nm2deg, sm2deg

---

**Purpose** Convert from distance units to degrees

**Syntax**

```
deg = km2deg(km)
deg = nm2deg(nm)
deg = sm2deg(sm)
deg = km2deg(km, radius)
deg = nm2deg(nm, radius)
deg = sm2deg(sm, radius)
deg = km2deg(km, sphere)
deg = nm2deg(nm, sphere)
deg = sm2deg(sm, sphere)
```

**Description** `deg = km2deg(km)` converts distances from kilometers to degrees as measured along a great circle on a sphere with a radius of 6371 km, the mean radius of the Earth.

`deg = nm2deg(nm)` converts distances from nautical miles to degrees as measured along a great circle on a sphere with a radius of 6371 km (3440.065 nm), the mean radius of the Earth.

`deg = sm2deg(sm)` converts distances from statute miles to degrees as measured along a great circle on a sphere with a radius of 6371 km (3958.748 sm), the mean radius of the Earth.

`deg = km2deg(km, radius)` converts distances from kilometers to degrees as measured along a great circle on a sphere having the specified radius. `radius` must be in units of kilometers.

`deg = nm2deg(nm, radius)` and `deg = sm2deg(sm, radius)` work identically, except that both the input distance and radius must be in nautical miles and statute miles, respectively.

`deg = km2deg(km, sphere)` converts distances from kilometers to degrees, as measured along a great circle on a sphere approximating an object in the Solar System. `sphere` may be one of the following strings: 'sun', 'moon', 'mercury', 'venus', 'earth', 'mars', 'jupiter', 'saturn', 'uranus', 'neptune', or 'pluto', and is case-insensitive.

`deg = nm2deg(nm, sphere)` and `deg = sm2deg(sm, sphere)` work identically, except that the input units are nautical miles and statute miles, respectively.

## Examples

Two cities are 340 km apart. How many degrees of arc is that? How many degrees would it be if the cities were on Mars?

```
deg = km2deg(340)
```

```
deg =  
3.0577
```

```
deg = km2deg(340, 'mars')
```

```
deg =  
5.7465
```

## See Also

`degtorad`, `radtodeg`, `deg2km`, `km2rad`, `km2nm`, `km2sm`, `deg2nm`, `nm2deg`, `nm2km`, `nm2sm`, `deg2sm`, `sm2deg`, `sm2km`, `sm2nm`

# km2rad, nm2rad, sm2rad

---

**Purpose** Convert from distance units to radians

**Syntax**

```
rad = km2rad(km)
rad = nm2rad(nm)
rad = sm2rad(sm)
rad = km2rad(km, radius)
rad = nm2rad(nm, radius)
rad = sm2rad(sm, radius)
rad = km2rad(km, sphere)
rad = nm2rad(nm, sphere)
rad = sm2rad(sm, sphere)
```

**Description** `rad = km2rad(km)` converts distances from kilometers to radians as measured along a great circle on a sphere with a radius of 6371 km, the mean radius of the Earth.

`rad = nm2rad(nm)`, and `rad = sm2rad(sm)` work identically, except that the input units are nautical miles and statute miles, respectively.

`rad = km2rad(km, radius)` converts distances from kilometers to radians as measured along a great circle on a sphere having the specified radius. `radius` must be in units of kilometers.

`rad = nm2rad(nm, radius)` and `rad = sm2rad(sm, radius)` work identically, except that both the input distance and radius must be in nautical miles and statute miles, respectively.

`rad = km2rad(km, sphere)` converts distances from kilometers to radians, as measured along a great circle on a sphere approximating an object in the Solar System. `sphere` may be one of the following strings: 'sun', 'moon', 'mercury', 'venus', 'earth', 'mars', 'jupiter', 'saturn', 'uranus', 'neptune', or 'pluto', and is case-insensitive.

`rad = nm2rad(nm, sphere)` and `rad = sm2rad(sm, sphere)` work identically, except that the input units must be nautical miles and statute miles, respectively.

## Examples

How many radians does 1,000 km span on the Earth and on the Moon?

```
rad = km2rad(1000)
```

```
rad =  
0.1570
```

```
rad = km2rad(1000, 'moon')
```

```
rad =  
0.5754
```

## See Also

degto rad, radto deg, rad2km, km2deg, km2nm, km2sm, rad2nm, nm2deg, nm2km, nm2sm, rad2sm, sm2deg, sm2km, sm2nm

# km2nm, km2sm, nm2km, nm2sm, sm2km, sm2nm

---

**Purpose** Convert distance between kilometers and miles

**Syntax**

```
nm = km2nm(km)
sm = km2sm(km)
km = nm2km(nm)
sm = nm2sm(nm)
km = sm2km(sm)
nm = sm2nm(sm)
```

**Description**

nm = km2nm(km) converts distances from kilometers to nautical miles.

sm = km2sm(km) works identically, except that the output units are statute miles.

km = nm2km(nm) converts distances from nautical miles to kilometers.

sm = nm2sm(nm) works identically, except that the output units are statute miles.

km = sm2km(sm) converts distances from statute miles to kilometers.

nm = sm2nm(sm) works identically, except that the output units are nautical miles.

**Examples** How many statute miles is a *10k run*?

```
sm = km2sm(10)
```

```
sm =
  6.2137
```

How fast is 30 knots (nautical miles per hour) in kph?

```
km = nm2km(30)
```

```
km =
  55.5600
```

**See Also** deg2km, km2deg, km2rad, rad2km, deg2nm, nm2deg, nm2rad, rad2nm, deg2sm, sm2deg, deg2sm, sm2rad, rad2sm

**Purpose**

Write geographic data to KML file

**Syntax**

```
kmlwrite(filename, lat, lon)
kmlwrite(filename, S)
kmlwrite(filename, address)
kmlwrite(..., param1, val1, param2, val2, ...)
```

**Description**

`kmlwrite(filename, lat, lon)` writes the latitude and longitude points `lat` and `lon` to disk in KML format. KML stands for Keyhole Markup Language. It is an XML dialect used by the Google™ Earth and Google Maps mapping services and similar applications. `lat` and `lon` are numeric vectors, specified in degrees. `lat` must be in the range `[-90, 90]`. There is no range constraint on `lon`; all longitudes are automatically wrapped to the range `[-180, 180]`, to adhere to the KML specification. `filename` must be a character string specifying the output file name and location. If an extension is included, it must be `.kml`.

`kmlwrite(filename, S)` writes a point or multipoint geobject to disk in KML format. The `Geometry` field of `S` must be either `'Point'` or `'Multipoint'`. `S` must include `Lat` and `Lon` fields. (If `S` includes `X` and `Y` fields an error is issued). The attribute fields of `S` are presented as a table in the description tag of the placemark displayed for each element of `S`, in the same order as they appear in `S`.

`kmlwrite(filename, address)` specifies the location of a KML Placemark via an `address` string or cell array of strings. Each string represents an unstructured address with city, state, and/or postal code. If `address` is a cell array, each cell contains the address of a unique point.

`kmlwrite(..., param1, val1, param2, val2, ...)` specifies parameter-value pairs that set additional KML feature properties. Parameter names can be abbreviated and are case-insensitive.

The parameter-value pairs are listed below:

- **Name** — A string or cell array of strings that specifies a name displayed in the viewer as the label for the object. If the value is a

string, the name is applied to all objects. If the value is a cell array, it must match in size to `lat` and `lon`, `S`, or `address`.

- **Description** — A string, cell array of strings, or an attribute spec, that specifies the contents to be displayed in the feature's description tag(s). The description appears in the description balloon when the user clicks either the feature name in the Google Earth application Places panel or clicks the placemark icon in the viewer window. If the value is a string, the description is applied to all objects. If the value is a cell array, it must match the size of `lat` and `lon`, `S`, or `address`. Use a cell array to customize descriptive tags for different placemarks.

Description elements can be either plain text or marked up with HTML. When it is plain text, the Google Earth application applies basic formatting, replacing each newline with `<br>` and giving anchor tags to all valid URLs for the World Wide Web. The URL strings are converted to hyperlinks. This means that you do not need to surround a URL with `<A HREF>` tags in order to create a simple link. Examples of HTML tags recognized by the Google Earth application are provided on its Web site, <http://earth.google.com>.

- **Icon** — A string or cell array of strings that specifies a custom icon filename. If the value is a string, the value is applied to all objects. If the value is a cell array, it must have the same size as `lat` and `lon`, `S`, or `address`. If the icon filename is not in the current directory, or in a directory on the MATLAB path, specify a full or relative path name. The string can be an Internet URL. The URL must include the protocol prefix (e.g., `http://`).
- **IconScale** — A positive numeric scalar or array that specifies a scaling factor for the icon. If the value is a scalar, the value is applied to all objects. If the value is an array, it must have the same size as `lat` and `lon`, `S`, or `address`.

## Remarks

### Using an Attribute Spec to Control Formatting of Attributes

An attribute spec is a structure with field names of attributes that controls how the table is displayed in its description balloon. In



it, each field name you want to display has two fields, `Format` and `AttributeLabel`.

When you provide `geostruct, S`, to `kmlwrite`, then the `Description` parameter can be an attribute spec. In this case, the attribute fields of `S` are displayed as a table in the `description` tag of the placemark for each element of `S`. (If you specify an attribute spec with `lat` and `lon` input syntax, the attribute spec is ignored.) The attribute spec can control:

- Which attributes are included in the table
- The name for the attribute
- The order in which attributes appear
- The formatting of attributes

The easiest way to construct an attribute spec is to call `makeattribspec`, and then modify the output to remove attributes or change the `Format` field for one or more attributes. The `lat` and `lon` fields of `S` are never treated as attributes.

### Viewing the KML file with the Google Earth browser

A KML file may be displayed in a Google Earth browser. The Google Earth application must be installed on the system. On Microsoft® Windows platforms you can display the KML file with:

```
winopen(filename)
```

For Unix and MAC users, display the KML file with:

```
cmd = 'googleearth ';
fullfilename = fullfile(pwd, filename);
system([cmd fullfilename])
```

### Viewing the KML file with a Web Browser

You can view KML files using the Google Maps mapping service in addition to using an installed Google Earth application. To do so, the file must be located on a web server that is accessible from the Internet.

A private intranet server will not suffice, because the Google Maps server must be able to access the URL that you provide to it. Here is a template for viewing your KML in a browser window via the Google Maps mapping service:

```
GMAPS_URL = 'http://maps.google.com/maps?q=';
KML_URL = 'http://<your web server and path to your KML file>';
web([GMAPS KML_URL])
```

You can only display a limited number of placemarks on a Google Maps page, and all placemarks must be geolocated using latitude-longitude coordinates (address-based placemarks are not supported). Google Mobile has further restrictions. See the Google KML documentation for more information.

## Examples

### Example 1 – Write a single point to a KML file

Add a description containing HTML markup, a name, and provide the location of an icon to display. Specifying an icon as a URL from the Web (as opposed to specifying one from a local file) makes the icon accessible to users of Google Maps service as well as to Google Earth users.

```
% Write a single point to a KML file.
% Add a description containing HTML, a name and an icon.
lat = 42.299827;
lon = -71.350273;
description = sprintf('%s<br>%s</br><br>%s</br>', ...
    '3 Apple Hill Drive', 'Natick, MA. 01760', ...
    'http://www.mathworks.com');
name = 'The MathWorks, Inc.';
filename = 'The_MathWorks.kml';
kmlwrite(filename, lat, lon, ...
    'Description', description, 'Name', name, 'Icon', ...
    'http://www.mathworks.com/products/product_listing/images/ml_icon.gif');
```

### Example 2 – Write the locations of major European cities to a KML file

Include the names of the cities, and remove the default description table:

```
latlim = [ 30; 75];
lonlim = [-25; 45];
cities = shaperead('worldcities.shp','UseGeoCoords', true, ...
    'BoundingBox', [lonlim, latlim]);
filename = 'European_Cities.kml';
kmlwrite(filename, cities, 'Name', {cities.Name}, 'Description', {});
```

### Example 3 – Write the locations of several Australian cities to a KML file

List the addresses to be displayed in a cell array:

```
address = {'Perth, Australia', ...
    'Melbourne, Australia', ...
    'Sydney, Australia'};
filename = 'Australian_Cities.kml';
kmlwrite(filename, address, 'Name', address);
```

### Example 4 – Unproject locations of Boston landmarks and write to a KML file

The Boston placenames file contains points stored in projected coordinates of meters, but Earth browsers require geographic coordinates (latitudes and longitudes). Begin by converting coordinates from meters to survey feet, inverting the projection to latitudes and longitudes, and then adding the latitudes and longitudes to the geostruct. To unproject properly, use the projection information extracted from the GeoTIFF file `boston.tif`:

```
S = shaperead('boston_placenames');
proj = geotiffinfo('boston.tif');
surveyFeetPerMeter = unitsratio('sf','meter');
for k=1:numel(S)
    x = surveyFeetPerMeter * S(k).X;
```

# kmlwrite

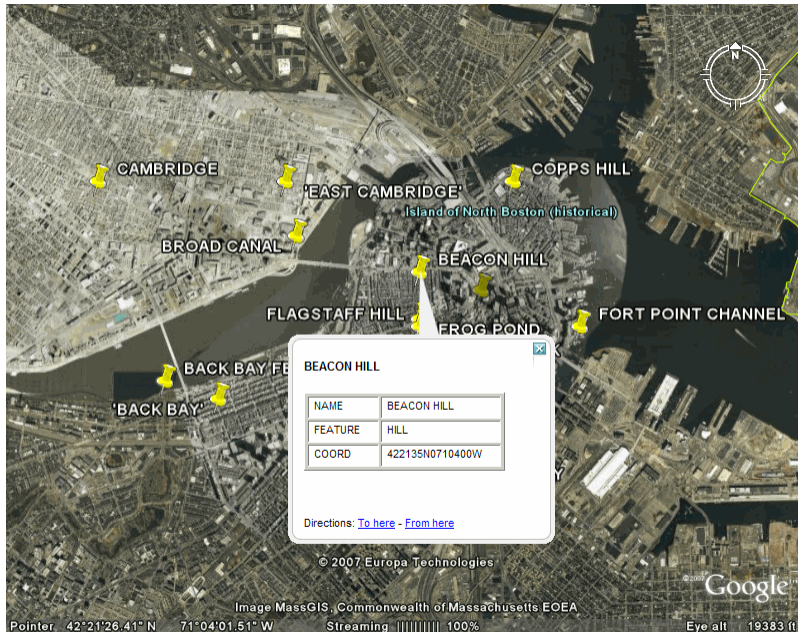
```
y = surveyFeetPerMeter * S(k).Y;  
[S(k).Lat, S(k).Lon] = projinv(proj, x, y);  
end  
filename = 'Boston_Placenames.kml';  
kmlwrite(filename, S, 'Name', {S.NAME});
```

If you have the Google Earth application installed, you can view the file on Microsoft Windows as follows:

```
winopen(filename)
```

On UNIX or MAC, use:

```
cmd = 'googleearth '  
fullfilename = fullfile(pwd, filename);  
system([cmd fullfilename])
```



For a different view of this location and placename data, see “Tour Boston with the Map Viewer”.

**See Also**

geoshow, makeattribspec, shaperead, shapewrite

# latlon2pix

---

**Purpose** Convert latitude-longitude coordinates to pixel coordinates

**Syntax** `[row, col ] = latlon2pix(R,lat,lon)`

**Description** `[row, col ] = latlon2pix(R,lat,lon)` calculates pixel coordinates `row`, `col` from latitude-longitude coordinates `lat`, `lon`. `R` is a 3-by-2 referencing matrix defining a two-dimensional affine transformation from pixel coordinates to spatial coordinates. `lat` and `lon` are vectors or arrays of matching size. The outputs `row` and `col` have the same size as `lat` and `lon`. `lat` and `lon` must be in degrees.

Longitude wrapping is handled in the following way: Results are invariant under the substitution `lon = lon +/- n * 360` where `n` is an integer. Any point on the Earth that is included in the image or gridded data set corresponding to `r` will yield row/column values between 0.5 and 0.5 + the image height/width, regardless of what longitude convention is used.

## Example

```
% Find the pixel coordinates of the upper left and lower right
% outer corners of a 2-by-2 degree gridded data set.
R = makerefmat(1, 89, 2, 2);
[UL_row, UL_col] = latlon2pix(R, 90, 0)    % Upper left
[LR_row, LR_col] = latlon2pix(R, -90, 360) % Lower right
[LL_row, LL_col] = latlon2pix(R, -90, 0)   % Lower left
% Note that in both the 2nd case and 3rd case we get a column
% value of 0.5, because the left and right edges are on the same
% meridian and (-90, 360) is the same point as (-90, 0).
```

**See Also** `makerefmat`, `pix2latlon`, `map2pix`

**Purpose** Colorbar with text labels

**Syntax** `lcolorbar(labels)`  
`lcolorbar(labels, 'property', value, ...)`  
`hcb = lcolorbar(...)`

**Description** `lcolorbar(labels)` appends a colorbar with text labels. The labels input is a cell array of label strings. The colorbar is constructed using the current colormap with the label strings applied at the centers of the color bands.

`lcolorbar(labels, 'property', value, ...)` controls the colorbar's properties. The location of the colorbar is controlled by the `Location` property. Valid entries for `Location` are 'vertical' (the default) or 'horizontal'. Properties `TitleString`, `XLabelString`, `YLabelString` and `ZLabelString` set the respective strings. Property `ColorAlignment` controls whether the colorbar labels are centered on the color bands or the color breaks. Valid values for `ColorAlignment` are 'center' and 'ends'.

Other valid property-value pairs are any properties and values that can be applied to the title and labels of the colorbar axes.

`hcb = lcolorbar(...)` returns a handle to the colorbar axes.

**Example**

```
figure; colormap(jet(5))
labels = {'apples', 'oranges', 'grapes', 'peachs', 'melons'};
lcolorbar(labels, 'fontweight', 'bold');
```

**See Also** `contourcmap`, `colormapeditor` (MATLAB function)

# legs

---

**Purpose** Courses and distances between navigational waypoints

**Syntax**

```
[course,dist] = legs(lat,lon)
[course,dist] = legs(lat,lon,method)
[course,dist] = legs(pts) and [course,dist] = legs(pts,
    method)
mat = legs(lat,...)
```

**Description**

`[course,dist] = legs(lat,lon)` returns the azimuths (*course*) and distances (*dist*) between navigational waypoints, which are specified by the column vectors *lat* and *lon*.

`[course,dist] = legs(lat,lon,method)` specifies the logic for the leg characteristics. If the string *method* is 'rh' (the default), *course* and *dist* are calculated in a rhumb line sense. If *method* is 'gc', great circle calculations are used.

`[course,dist] = legs(pts)` and `[course,dist] = legs(pts,method)` allow you to input the waypoints in a single two-column matrix, *pts*.

`mat = legs(lat,...)` packs up the outputs into a single two-column matrix, *mat*.

This is a navigation function. All angles are in degrees, and all distances are in nautical miles. Track legs are the courses and distances traveled between navigational waypoints.

**Examples**

Imagine an airplane taking off from Logan International Airport in Boston (42.3°N,71°W) and traveling to LAX in Los Angeles (34°N,118°W). The pilot wants to file a flight plan that takes the plane over O'Hare Airport in Chicago (42°N,88°W) for a navigational update, while maintaining a constant heading on each of the two legs of the trip.

What are those headings and how long are the legs?

```
lat = [42.3; 42; 34]; long = [-71; -88; -118];
[course,dist] = legs(lat,long,'rh')
```



```
course =
    268.6365
    251.2724
dist =
    1.0e+003 *
    0.7569
    1.4960
```

Upon takeoff, the plane should proceed on a heading of about 269° for 756 nautical miles, then alter course to 251° for another 1495 miles.

How much farther is it traveling by not following a great circle path between waypoints? Using rhumb lines, it is traveling

```
totalrh = sum(dist)

totalrh =
    2.2530e+003
```

For a great circle route,

```
[coursegc,distgc] = legs(lat,long,'gc'); totalgc = sum(distgc)

totalgc =
    2.2451e+003
```

The great circle path is less than one-half of one percent shorter.

## See Also

dreckon, gcwaypts, navfix, track

# lightm

---

**Purpose** Project light objects on map axes

**Syntax**

```
h = lightm(lat,lon)
h = lightm(lat,lon,PropertyName,PropertyValue,...)
h = lightm(lat,lon,alt)
```

**Description**

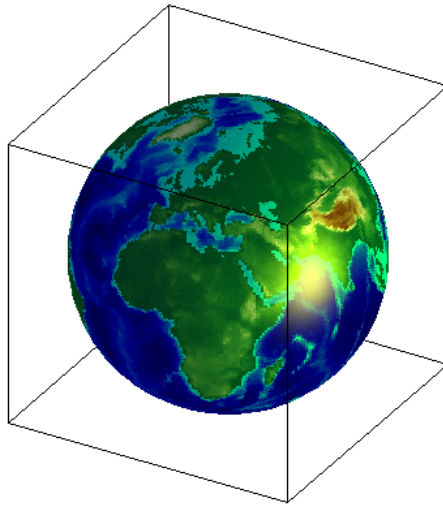
`h = lightm(lat,lon)` projects a light object at the coordinates `lat` and `lon`. The handle, `h`, of the object can be returned.

`h = lightm(lat,lon,PropertyName,PropertyValue,...)` allows the specification of any property name/property value pair supported by the standard MATLAB light function.

`h = lightm(lat,lon,alt)` allows the specification of an altitude, `alt`, for the light object. When omitted, the default is an infinite light source altitude.

**Examples**

```
load topo
axesm globe; view(120,30)
meshm(topo,topolegend); demcmap(topo)
lightm(0,90,'color','yellow')
material([.5 .5 1]); lighting phong
```



**See Also** `light` (MATLAB function), `lightm`

# limitm

---

**Purpose** Determine latitude and longitude limits of regular data grid

**Syntax**  
`[latlim, lonlim] = limitm(Z,R)`  
`latlonlim = limitm(Z,R)`

**Description** `[latlim, lonlim] = limitm(Z,R)` computes the latitude and longitude limits of the geographic quadrangle bounding the regular data grid `Z` with referencing vector or matrix `R`. `R` is either a 1-by-3 vector containing elements:

```
[cells/degree northern_latitude_limit western_longitude_limit]
```

or a 3-by-2 referencing matrix that transforms raster row and column indices to/from geographic coordinates according to:

```
[lon lat] = [row col 1] * R
```

If `R` is a referencing matrix, it must define a (non-rotational, non-skewed) relationship in which each column of the data grid falls along a meridian and each row falls along a parallel. The output `latlim` is a vector of the form `[southern_limit northern_limit]` and `lonlim` is a vector of the form `[western_limit eastern_limit]`. All angles are in units of degrees.

`latlonlim = limitm(Z,R)` concatenates `latlim` and `lonlim` into a 1-by-4 row vector of the form:

```
[southern_limit northern_limit western_limit eastern_limit]
```

**Examples** Using a familiar data grid,

```
load topo
[latlimits,lonlimits] = limitm(topo,topolegend)
latlimits =
    -90    90
lonlimits =
     0   360
```

Which is expected, because `topo` covers the whole globe.

**See Also**

makerefmat

# linecirc

---

<b>Purpose</b>	Intersections of circles and lines in Cartesian plane
<b>Syntax</b>	<code>[xout,yout] = linecirc(slope,intercpt,centerx,centery,radius)</code>
<b>Description</b>	<p><code>[xout,yout] = linecirc(slope,intercpt,centerx,centery,radius)</code> finds the points of intersection given a circle defined by a center and radius in <math>x</math>-<math>y</math> coordinates, and a line defined by slope and <math>y</math>-intercept, or a slope of “inf” and an <math>x</math>-intercept. Two points are returned. When the objects do not intersect, NaNs are returned.</p> <p>When the line is tangent to the circle, two identical points are returned. All inputs must be scalars.</p>
<b>See Also</b>	<code>circcirc</code>

**Purpose**

Project line object on map axes

**Syntax**

```
h = linem(lat,lon)
h = linem(lat,lon,linetype)
h = linem(lat,lon,PropertyName,PropertyValue,...)
h = linem(lat,lon,z)
```

**Description**

`h = linem(lat,lon)` displays projected line objects on the current map axes. `lat` and `lon` are the latitude and longitude coordinates, respectively, of the line object to be projected. Note that this ordering is conceptually reversed from the MATLAB `line` function, because the *vertical* ( $y$ ) coordinate comes first. However, the ordering latitude, then longitude, is standard geographic usage. `lat` and `lon` must be the same size and in the `AngleUnits` of the map axes. The object handle for the displayed line can be returned in `h`.

`h = linem(lat,lon,linetype)` allows the specification of the line style, where *linetype* is any string recognized by the MATLAB `line` function.

`h = linem(lat,lon,PropertyName,PropertyValue,...)` allows the specification of any number of property name/property value pairs for any properties recognized by the MATLAB `line` function except for `XData`, `YData`, and `ZData`.

`h = linem(lat,lon,z)` displays a line object in three dimensions, where `z` is the same size as `lat` and `lon` and contains the desired altitude data. `z` is independent of `AngleUnits`. If omitted, all points are assigned a `z`-value of 0 by default.

The units of `z` are arbitrary, except when using the `Globe` projection. In the case of `globe`, `z` should have the same units as the radius of the earth or semimajor axis specified in the `'geoid'` (reference ellipsoid) property of the map axes. This implies that for a reference ellipsoid vector of `[1 0]` (a unit sphere), the units of `z` are earth radii.

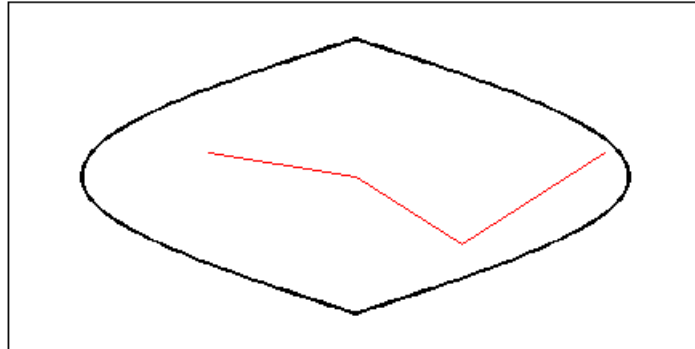
`linem` is the mapping equivalent of the MATLAB `line` function. It is a low-level graphics function for displaying line objects in map projections. Ordinarily, it is not used directly. Use `plotm` or `plot3m` instead.

# linem

---

## Examples

```
axesm sinusoid; framem  
linem([15; 0; -45; 15],[-100; 0; 100; 170],'r-')
```



## See Also

line, plot3m, plotm



**Purpose**

Line-of-sight visibility between two points in terrain

**Syntax**

```
vis = los2(Z,R,lat1,lon1,lat2,lon2)
vis = los2(Z,R,lat1,lon1,lat2,lon2,alt1)
vis = los2(Z,R,lat1,lon1,lat2,lon2,alt1,alt2)
vis = los2(Z,R,lat1,lon1,lat2,lon2,alt1,alt2,alt1opt)
vis = los2(Z,R,lat1,lon1,lat2,lon2,alt1,alt2,alt1opt,alt2opt)
vis = los2(Z,R,lat1,lon1,lat2,lon2,alt1,alt2,alt1opt, ...
    alt2opt,actualradius)
vis = los2(Z,R,lat1,lon1,lat2,lon2,alt1,alt2,alt1opt, ...
    alt2opt,actualradius,effectiveradius)
[vis,visprofile,dist,H,lattrk,lontrk] = los2(...)
los2(...)
```

**Description**

los2 computes the mutual visibility between two points on a displayed digital elevation map. los2 uses the current object if it is a regular data grid, or the first regular data grid found on the current axes. The grid's zdata is used for the profile. The color data is used in the absence of data in z. The two points are selected by clicking on the map. The result is displayed in a new figure. Markers indicate visible and obscured points along the profile. The profile is shown in a Cartesian coordinate system with the origin at the observer's location. The displayed z coordinate accounts for the elevation of the terrain and the curvature of the body.

vis = los2(Z,R,lat1,lon1,lat2,lon2) computes the mutual visibility between pairs of points on a digital elevation map. The elevations are provided as a regular data grid Z containing elevations in units of meters. The two points are provided as vectors of latitudes and longitudes in units of degrees. The resulting logical variable vis is equal to one when the two points are visible to each other, and zero when the line of sight is obscured by terrain. If any of the input arguments are empty, los2 attempts to gather the data from the current axes. With one or more output arguments, no figures are created and only the data is returned. R is either a 1-by-3 vector containing elements:

```
[cells/degree northern_latitude_limit western_longitude_limit]
```

or a 3-by-2 referencing matrix that transforms raster row and column indices to or from geographic coordinates according to:

$$[\text{lon lat}] = [\text{row col 1}] * R$$

If  $R$  is a referencing matrix, it must define a (non-rotational, non-skewed) relationship in which each column of the data grid falls along a meridian and each row falls along a parallel.

`vis = los2(Z,R,lat1,lon1,lat2,lon2,alt1)` places the first point at the specified altitude in meters above the surface (on a tower, for instance). This is equivalent to putting the point on a tower. If omitted, point 1 is assumed to be on the surface. `alt1` may be either a scalar or a vector with the same length as `lat1`, `lon1`, `lat2`, and `lon2`.

`vis = los2(Z,R,lat1,lon1,lat2,lon2,alt1,alt2)` places both points at a specified altitudes in meters above the surface. `alt2` may be either a scalar or a vector with the same length as `lat1`, `lon1`, `lat2`, and `lon2`. If `alt2` is omitted, point 2 is assumed to be on the surface.

`vis = los2(Z,R,lat1,lon1,lat2,lon2,alt1,alt2,alt1opt)` controls the interpretation of `alt1` as either a relative altitude (`alt1opt` equals 'AGL', the default) or an absolute altitude (`alt1opt` equals 'MSL'). If the altitude option is 'AGL', `alt1` is interpreted as the altitude of point 1 in meters above the terrain (“above ground level”). If `alt1opt` is 'MSL', `alt1` is interpreted as altitude above zero (“mean sea level”).

`vis = los2(Z,R,lat1,lon1,lat2,lon2,alt1,alt2,alt1opt,alt2opt)` controls the interpretation ALT2.

`vis = los2(Z,R,lat1,lon1,lat2,lon2,alt1,alt2,alt1opt, ... alt2opt,actualradius)` does the visibility calculation on a sphere with the specified radius. If omitted, the radius of the earth in meters is assumed. The altitudes, elevations and the radius should be in the same units. This calling form is most useful for computations on bodies other than the earth.

`vis = los2(Z,R,lat1,lon1,lat2,lon2,alt1,alt2,alt1opt, ... alt2opt,actualradius,effectiveradius)` assumes a larger radius for propagation of the line of sight. This can account for the curvature of the signal path due to refraction in the atmosphere. For example, radio propagation in the atmosphere is commonly treated as straight line propagation on a sphere with  $4/3$  the radius of the earth. In that case the last two arguments would be `R_e` and `4/3*R_e`, where `R_e` is the radius of the earth. Use `Inf` as the effective radius for flat earth visibility calculations. The altitudes, elevations and radii should be in the same units.

`[vis,visprofile,dist,H,lattrk,lontrk] = los2(...)`, for scalar inputs (`lat1`, `lon1`, etc.), returns vectors of points along the path between the two points. `visprofile` is a logical vector containing true (`logical(1)`) where the intermediate points are visible and false (`logical(0)`) otherwise. `dist` is the distance along the path (in meters or the units of the radius). `H` contains the terrain profile relative to the vertical datum along the path. `lattrk` and `lontrk` are the latitudes and longitudes of the points along the path. For vector inputs `los2` returns `visprofile`, `dist`, `H`, `lattrk`, and `lontrk` as cell arrays, with one cell per element of `lat1`, `lon1`, etc.

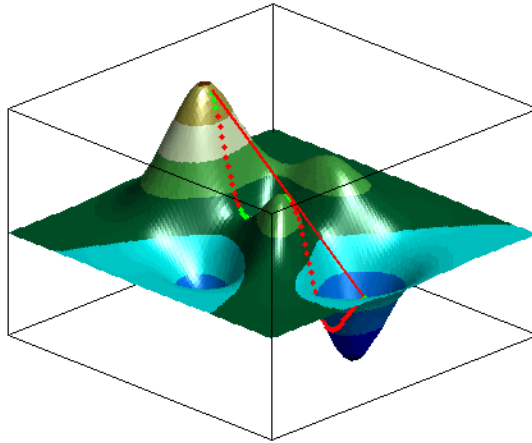
`los2(...)`, with no output arguments, displays the visibility profile between the two points in a new figure.

## Example

```
Z = 500*peaks(100);
refvec = [1000 0 0];
[lat1, lon1, lat2, lon2] = deal(-0.027, 0.05, -0.093, 0.042);
los2(Z,refvec,lat1,lon1,lat2,lon2,100);
figure;
axesm('globe','geoid',almanac('earth','sphere','meters'))
meshm(Z, refvec, size(Z), Z); axis tight
camposm(-10,-10,1e6); camupm(0,0)
demcmap('inc', Z, 1000); shading interp; camlight

[vis,visprofile,dist,h,lattrk,lontrk] = ...
los2(Z,refvec,lat1,lon1,lat2,lon2,100);
plot3m(lattrk([1;end]),lontrk([1; end]),...
```

```
h([1; end])+[100; 0], 'r', 'linewidth', 2)
plotm(latrk(~visprofile), lontrk(~visprofile), ...
h(~visprofile), 'r.', 'markersize', 10)
plotm(latrk(visprofile), lontrk(visprofile), ...
h(visprofile), 'g.', 'markersize', 10)
```



## See Also

viewshed, mapprofile

**Purpose**

Extract data grid values for specified locations

**Syntax**

```
val = ltln2val(Z, R, lat, lon)
val = ltln2val(Z, R, lat, lon, method)
```

**Description**

`val = ltln2val(Z, R, lat, lon)` interpolates a regular data grid `Z` with referencing vector `R` at the points specified by vectors of latitude and longitude, `lat` and `lon`. `R` is either a 1-by-3 vector containing elements:

```
[cells/degree northern_latitude_limit western_longitude_limit]
```

or a 3-by-2 referencing matrix that transforms raster row and column indices to/from geographic coordinates according to:

$$[\text{lon } \text{lat}] = [\text{row } \text{col } 1] * R$$

If `R` is a referencing matrix, it must define a (non-rotational, non-skewed) relationship in which each column of the data grid falls along a meridian and each row falls along a parallel. Nearest-neighbor interpolation is used by default. NaN is returned for points outside the grid limits or for which `lat` or `lon` contain NaN. All angles are in units of degrees.

`val = ltln2val(Z, R, lat, lon, method)` accepts a `method` string to specify the type of interpolation: 'bilinear' for linear interpolation, 'bicubic' for cubic interpolation, or 'nearest' for nearest neighbor interpolation.

**Examples**

Find the elevations in `topo` associated with three European cities—Milan, Bern, and Prague (topo elevations are in meters):

```
load topo
% The city locations, [Milan Bern Prague]
lats = [45.45; 46.95; 50.1];
longs = [9.2; 7.4; 14.45];
elevations = ltln2val(topo,topolegend,lats,longs)
```

# ltn2val

---

```
elevations =  
  313  
 1660  
  297
```

## See Also

findm, imbedm

---

<b>Purpose</b>	Convert local vertical to geocentric (ECEF) coordinates
<b>Syntax</b>	<code>[x,y,z] = lv2ecef(x1,y1,z1,phi0,lambda0,h0,ellipsoid)</code>
<b>Description</b>	<code>[x,y,z] = lv2ecef(x1,y1,z1,phi0,lambda0,h0,ellipsoid)</code> converts arrays <code>x1</code> , <code>y1</code> , and <code>z1</code> in the local vertical coordinate system to arrays <code>x</code> , <code>y</code> , and <code>z</code> in the geocentric coordinate system. The origin of the local vertical system is at geodetic latitude <code>phi0</code> , geodetic longitude <code>lambda0</code> , and ellipsoidal height <code>h0</code> . The arrays <code>x1</code> , <code>y1</code> , and <code>z1</code> may have any shape, as long as they are all the same size. They are measured in the same length units as the semimajor axis. <code>phi0</code> and <code>lambda0</code> are scalars measured in radians; <code>h0</code> is a scalar with the same length units as the semimajor axis; and <code>ellipsoid</code> is a row vector with the form <code>[semimajor axis, eccentricity]</code> . The coordinates <code>x</code> , <code>y</code> , and <code>z</code> also have the same units as the semimajor axis.
<b>Definitions</b>	For a definition of the local vertical system, also known as East-North-Up (ENU), see the help for <code>ecef2lv</code> . For a definition of the geocentric system, also known as Earth-Centered, Earth-Fixed (ECEF), see the help for <code>geodetic2ecef</code> .
<b>See Also</b>	<code>ecef2geodetic</code>   <code>ecef2lv</code>   <code>elevation</code>   <code>geodetic2ecef</code>

# majaxis

---

**Purpose** Semimajor axis of ellipse given semiminor axis and eccentricity

**Syntax**  
`semimajor = majaxis(semiminor, eccentricity)`  
`semimajor = majaxis([semiminor eccentricity])`

**Description** `semimajor = majaxis(semiminor, eccentricity)` returns the semimajor axis length corresponding to the input semiminor axis and eccentricity.  
`semimajor = majaxis([semiminor eccentricity])` allows the inputs to be packed into a single two-column input of the form `[semiminor eccentricity]`.  
The semimajor axis, the first element of a standard Mapping Toolbox ellipsoid vector, can be determined given both the semiminor axis and the eccentricity.

**Examples** Using the default values for the Earth,

```
semimajor = majaxis(6356.7523, 0.0818192)
semimajor =
    6.3781e+03
```

This is the default semimajor axis.

## See Also

`almanac`, `axes2ecc`, `minaxis`



**Purpose**

Attribute specification from geographic data structure

**Syntax**

```
attribspec = makeattribspec(S)
```

**Description**

`attribspec = makeattribspec(S)` analyzes a geographic data structure `S` and constructs an attribute specification suitable for use with `kmlwrite`. `kmlwrite`, given `geostruct` input, constructs an HTML table that consists of a label for the attribute in the first column and the string value of the attribute in the second column. You can modify `attribspec`, and then pass it to `kmlwrite` to exert control over which `geostruct` attribute fields are written to the HTML table and the format of the string conversion.

`attribspec` is a scalar MATLAB structure with two levels. The top level consists of a field for each attribute in `S`. Each of these fields, on the next level, contains a scalar structure with a fixed pair of fields:

AttributeLabel	A string that corresponds to the name of the attribute field in the geographic data structure. With <code>kmlwrite</code> , the string is used to label the attribute in the first column of the HTML table. The string may be modified prior to calling <code>kmlwrite</code> . You might modify an attribute label, for example, because you want to use spaces in your HTML table, but the attribute field names in <code>S</code> must be valid MATLAB variable names and cannot have spaces themselves.
Format	The <code>printf</code> format character string that converts the attribute value to a string.

**Example**

- 1 Import a shapefile representing *tsunami* (tidal wave) events reported between 1950 and 2006 and tagged geographically by source location, and construct a default attribute specification (which includes all the shapefile attributes):

```
s = shaperead('tsunamis', 'UseGeoCoords', true);
```

# makeattribspec

---

```
attribspec = makeattribspec(s)
attribspec =

    Year: [1x1 struct]
    Month: [1x1 struct]
    Day: [1x1 struct]
    Hour: [1x1 struct]
    Minute: [1x1 struct]
    Second: [1x1 struct]
    Val_Code: [1x1 struct]
    Validity: [1x1 struct]
    Cause_Code: [1x1 struct]
    Cause: [1x1 struct]
    Eq_Mag: [1x1 struct]
    Country: [1x1 struct]
    Location: [1x1 struct]
    Max_Height: [1x1 struct]
    Iida_Mag: [1x1 struct]
    Intensity: [1x1 struct]
    Num_Deaths: [1x1 struct]
    Desc_Deaths: [1x1 struct]
```

## 2 Modify the attribute specification to

- Display just the attributes Max\_Height, Cause, Year, Location, and Country
- Rename the Max\_Height field to Maximum Height
- Display each attribute's label in bold type
- Set to zero the number of decimal places used to display Year
- Add “Meters” to the Height format, given independent knowledge of these units

```
desiredAttributes = ...
    {'Max_Height', 'Cause', 'Year', 'Location', 'Country'};
allAttributes = fieldnames(attribspec);
attributes = setdiff(allAttributes, desiredAttributes);
```

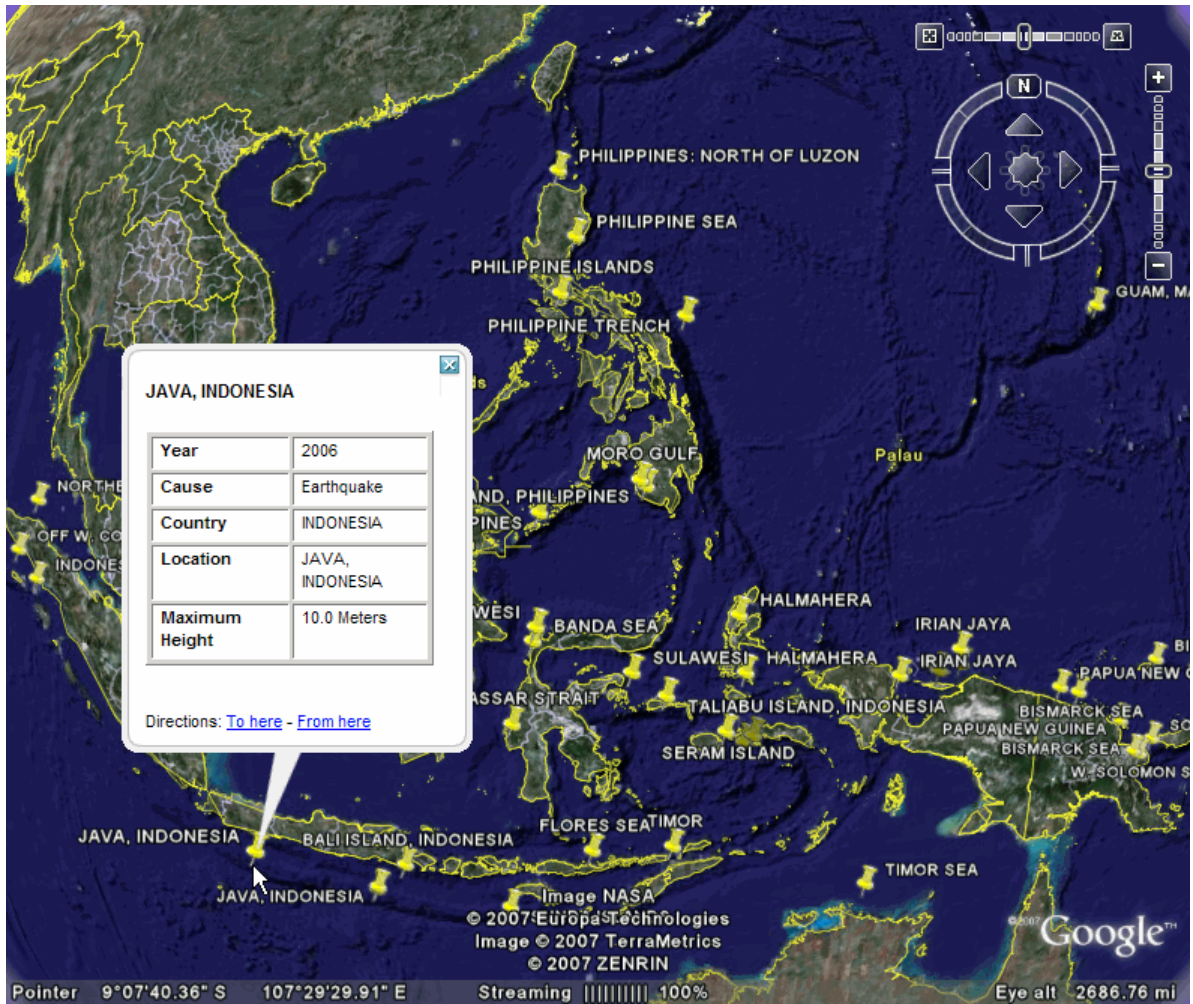
```
attribspec = rmfield(attribspec, attributes);
attribspec.Max_Height.AttributeLabel = '<b>Maximum Height</b>';
attribspec.Max_Height.Format = '%.1f Meters';
attribspec.Cause.AttributeLabel = '<b>Cause</b>';
attribspec.Year.AttributeLabel = '<b>Year</b>';
attribspec.Year.Format = '%.0f';
attribspec.Location.AttributeLabel = '<b>Location</b>';
attribspec.Country.AttributeLabel = '<b>Country</b>';
```

- 3 Use the attribute specification to export the selected attributes and source locations to a KML file as a Description:

```
filename = 'tsunami.kml';
kmlwrite(filename, s, 'Description', attribspec, ...
         'Name', {s.Location})
```

A view of Southeast Asia produced by the Google Earth application shows the selected, formatted attributes displayed for a 2006 tsunami in Indonesia.

# makeattribspec



**See also** kmlwrite, makedbfspec, shapewrite

**Purpose** DBF specification from geographic data structure

**Syntax** `dbfspec = makedbfspec(S)`

**Description** `dbfspec = makedbfspec(S)` analyzes a geographic data structure, `S`, and constructs a DBF specification suitable for use with `shapewrite`. You can modify `dbfspec`, then pass it to `shapewrite` to exert control over which geostruct attribute fields are written to the DBF component of the shapefile, the field-widths, and the precision used for numerical values.

`dbfspec` is a scalar MATLAB structure with two levels. The top level consists of a field for each attribute in `S`. Each of these fields, in turn, contains a scalar structure with a fixed set of four fields:

dbfspec field	Contents
FieldName	The field name to be used within the DBF file. This will be identical to the name of the corresponding attribute, but may be modified prior to calling <code>shapewrite</code> . This might be necessary, for example, because you want to use spaces in your DBF field names, but the attribute fieldnames in <code>S</code> must be valid MATLAB variable names and cannot have spaces themselves.
<i>FieldType</i>	The field type to be used in the file, either 'N' (numeric) or 'C' (character).
FieldLength	The number of bytes that each instance of the field will occupy in the file.
FieldDecimalCount	The number of digits to the right of the decimal place that are kept in a numeric field. Zero for integer-valued fields and character fields. The default value for noninteger numeric fields is 6.

**Example** Import a shapefile representing a small network of road segments, and construct a DBF specification.

# makedbfspec

---

```
s = shaperead('concord_roads')

s =
609x1 struct array with fields:
    Geometry
    BoundingBox
    X
    Y
    STREETNAME
    RT_NUMBER
    CLASS
    ADMIN_TYPE
    LENGTH

dbfspec = makedbfspec(s)

dbfspec =
    STREETNAME: [1x1 struct]
    RT_NUMBER: [1x1 struct]
    CLASS: [1x1 struct]
    ADMIN_TYPE: [1x1 struct]
    LENGTH: [1x1 struct]
```

Modify the DBF spec to (a) eliminate the 'ADMIN\_TYPE' attribute, (b) rename the 'STREETNAME' field to 'Street Name', and (c) reduce the number of decimal places used to store road lengths.

```
dbfspec = rmfield(dbfspec, 'ADMIN_TYPE')

dbfspec =
    STREETNAME: [1x1 struct]
    RT_NUMBER: [1x1 struct]
    CLASS: [1x1 struct]
    LENGTH: [1x1 struct]

dbfspec.STREETNAME.FieldName = 'Street Name';
dbfspec.LENGTH.FieldDecimalCount = 1;
```

Export the road network back to a modified shapefile. (Actually, only the DBF component will be different.)

```
shapewrite(s, 'concord_roads_modified', 'DbfSpec', dbfspec)
```

Verify the changes you made. Notice the appearance of 'Street Name' in the field names reported by shapeinfo, the absence of the 'ADMIN\_TYPE' field, and the reduction in the precision of the road lengths.

```
info = shapeinfo('concord_roads_modified')
info =
    Filename: [3x28 char]
    ShapeType: 'PolyLine'
    BoundingBox: [2x2 double]
    NumFeatures: 609
    Attributes: [4x1 struct]

{info.Attributes.Name}

ans =
    'Street Name'    'RT_NUMBER'    'CLASS'    'LENGTH'

r = shaperead('concord_roads_modified')

r =
609x1 struct array with fields:
    Geometry
    BoundingBox
    X
    Y
    StreetName
    RT_NUMBER
    CLASS
    LENGTH

s(33).LENGTH
```

# makedbfspec

---

```
ans =  
    3.492817400000000e+002
```

```
r(33).LENGTH
```

```
ans =  
    3.493000000000000e+002
```

**See also**      `shapeinfo`, `shapewrite`



**Purpose** Convert ordinary graphics object to mapped object

**Syntax** `makemapped(h)`

**Description** `makemapped(h)` modifies the graphic object(s) associated with `h` such that upon subsequent modification of map axes properties, they are automatically reprojected appropriately. The object's coordinates are not changed by `makemapped`, but will change should you modify the map projection. `h` can be a handle, vector of handles, or any name string recognized by `handlem`. The objects are then considered to be geographic data. You should first trim objects extending outside the map frame to the map frame using `trimcart`.

**Example**

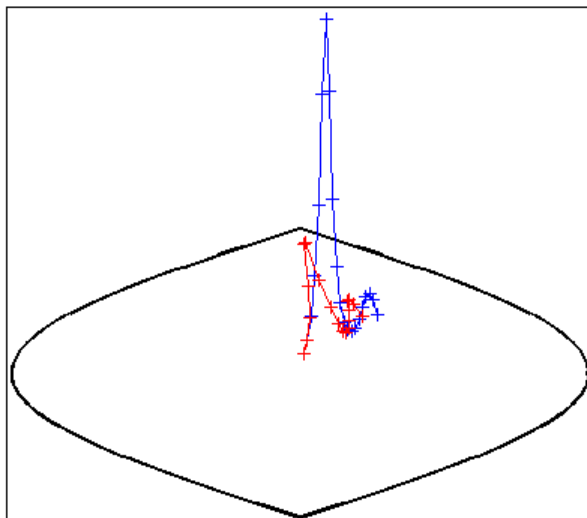
```
axesm('miller','geoid',[25 0])
framem
plot(humps,'b+-')

h = plot(humps,'r+-');
trimcart(h)
makemapped(h)

setm(gca,'MapProjection','sinusoid')
```

# makemapped

---



## Remarks

Objects should first be trimmed to the map frame using `trimcart`. This avoids problems in taking inverse map projections with out-of-range data.

## See Also

`trimcart`, `handlem`, `cart2grn`

**Purpose**

Construct affine spatial-referencing matrix

**Syntax**

```
R = makereformat(x11, y11, dx, dy)
R = makereformat(lon11, lat11, dlon, dlat)
R = makereformat(param1, val1, param2, val2, ...)
```

**Description**

`R = makereformat(x11, y11, dx, dy)`, with scalars `dx` and `dy`, constructs a referencing matrix that aligns image or data grid rows to map  $x$  and columns to map  $y$ . Scalars `x11` and `y11` specify the map location of the center of the first (1,1) pixel in the image or the first element of the data grid, so that

$$[x11 \ y11] = \text{pix2map}(R, 1, 1)$$

`dx` is the difference in  $x$  (or longitude) between pixels in successive columns, and `dy` is the difference in  $y$  (or latitude) between pixels in successive rows. More abstractly, `R` is defined such that

$$[x11 + (col-1) * dx, y11 + (row-1) * dy] = \text{pix2map}(R, row, col)$$

Pixels cover squares on the map when  $\text{abs}(dx) = \text{abs}(dy)$ . To achieve the most typical kind of alignment, where  $x$  increases from column to column and  $y$  decreases from row to row, make `dx` positive and `dy` negative. In order to specify such an alignment along with square pixels, make `dx` positive and make `dy` equal to `-dx`:

$$R = \text{makereformat}(x11, y11, dx, -dx)$$

`R = makereformat(x11, y11, dx, dy)`, with two-element vectors `dx` and `dy`, constructs the most general possible kind of referencing matrix, for which

$$[x11 + ([row \ col]-1) * dx(:), y11 + ([row \ col]-1) * dy(:)] \dots \\ = \text{pix2map}(R, row, col)$$

In this general case, each pixel can become a parallelogram on the map, with neither edge necessarily aligned to map  $x$  or  $y$ . The vector

`[dx(1) dy(1)]` is the difference in map location between a pixel in one row and its neighbor in the preceding row. Likewise, `[dx(2) dy(2)]` is the difference in map location between a pixel in one column and its neighbor in the preceding column.

To specify pixels that are rectangular or square (but possibly rotated), choose `dx` and `dy` such that `prod(dx) + prod(dy) = 0`. To specify square (but possibly rotated) pixels, choose `dx` and `dy` such that the 2-by-2 matrix `[dx(:) dy(:)]` is a scalar multiple of an orthogonal matrix (that is, its two eigenvalues are real, nonzero, and equal in absolute value). This amounts to either rotation, a mirror image, or a combination of both. Note that for scalars `dx` and `dy`,

```
R = makereformat(x11, y11, [0 dx], [dy 0])
```

is equivalent to

```
R = makereformat(x11, y11, dx, dy)
```

`R = makereformat(lon11, lat11, dlon, dlat)`, with longitude preceding latitude, constructs a referencing matrix for use with geographic coordinates. In this case,

```
[lat11,lon11] = pix2latlon(R,1,1),  
[lat11+(row-1)*dlat,lon11+(col-1)*dlon] = pix2latlon(R,row,col)
```

for scalar `dlat` and `dlon`, and

```
[lat11+[row col]-1)*dlat,lon11+([row col]-1)*dlon] = ...  
pix2latlon(R, row,col)
```

for vector `dlat` and `dlon`. Images or data grids aligned with latitude and longitude might already have referencing vectors. In this case you can use function `refvec2mat` to convert to a referencing matrix.

`R = makereformat(param1, val1, param2, val2, ...)` uses parameter name-value pairs to construct a referencing matrix for an image or raster grid that is referenced to and aligned with a geographic coordinate system. There can be no rotation or skew: each column must

fall along a meridian, and each row must fall along a parallel. Each parameter name must be specified exactly as shown, including case.

Parameter Name	Data Type	Value
RasterSize	Two-element size vector [M N]	<p>The number of rows (M) and columns (N) of the raster or image to be used with the referencing matrix.</p> <p>With 'RasterSize', you may also provide a size vector having more than two elements. This enables usage such as:</p> <pre>R = makereformat('RasterSize', ...                  size(RGB), ...)</pre> <p>where RGB is M-by-N-by-3. However, in cases like this, only the first two elements of the size vector will actually be used. The higher (non-spatial) dimensions will be ignored. The default value is [1 1].</p>
Latlim	Two-element row vector of the form: [southern_limit, northern_limit], in units of degrees.	The limits in latitude of the geographic quadrangle bounding the georeferenced raster. The default value is [0 1].
Lonlim	Two-element row vector of the form: [western_limit, eastern_limit], in units of degrees.	The limits in longitude of the geographic quadrangle bounding the georeferenced raster. The elements of the 'Lonlim' vector must be ascending in value. In other words, the limits must be unwrapped. The default value is [0 1].

Parameter Name	Data Type	Value
ColumnsStartFrom	String	Indicates the column direction of the raster (south-to-north vs. north-to-south) in terms of the edge from which row indexing starts. The input string can have the value 'south' or 'north', can be shortened, and is case-insensitive. In a typical terrain grid, row indexing starts at southern edge. In images, row indexing starts at northern edge. The default value is 'south'.
RowsStartFrom	String	Indicates the row direction of the raster (west-to-east vs. east-to-west) in terms of the edge from which column indexing starts. The input string can have the value 'west' or 'east', can be shortened, and is case-insensitive. Rows almost always run from west to east. The default value is 'west'.

## Definition

### Spatial Referencing Matrix

A spatial referencing matrix  $R$  ties the row and column subscripts of an image or regular data grid to 2-D map coordinates or to geographic coordinates (longitude and geodetic latitude).  $R$  is a 3-by-2 affine transformation matrix.  $R$  either transforms pixel subscripts (row, column) to/from map coordinates (x,y) according to

$$[x \ y] = [row \ col \ 1] * R$$

or transforms pixel subscripts to/from geographic coordinates according to

$$[lon \ lat] = [row \ col \ 1] * R$$

To construct a referencing matrix for use with geographic coordinates, use longitude in place of X and latitude in place of Y, as shown in the `R = makereformat(X11, Y11, dx, dy)` syntax. This is one of the few places where longitude precedes latitude in a function call.

## Examples

Create a referencing matrix for an image with square, four-meter pixels and with its upper left corner (in a map coordinate system) at  $x = 207000$  meters,  $y = 913000$  meters. The image follows the typical orientation:  $x$  increasing from column to column and  $y$  decreasing from row to row.

```
x11 = 207002; % Two meters east of the upper left corner
y11 = 912998; % Two meters south of the upper left corner
dx = 4;
dy = -4;
R = makereformat(x11, y11, dx, dy)
```

Create a referencing matrix for a global geoid grid.

```
% Add array 'geoid' to the workspace:
load geoid

%'geoid' contains a model of the Earth's geoid sampled in
% one-degree-by-one-degree cells. Each column of 'geoid'
% contains geoid heights in meters for 180 cells starting
% at latitude -90 degrees and extending to +90 degrees, for
% a given longitude. Each row contains geoid heights for 360
% cells starting at longitude 0 and extending 360 degrees.
geoidR = makereformat('RasterSize', size(geoid), ...
    'Latlim', [-90 90], 'Lonlim', [0 360])

% At its most extreme, the geoid reaches a minimum of slightly
% less than -100 meters. This minimum occurs in the Indian Ocean
% at approximately 4.5 degrees latitude, 78.5 degrees longitude.
% Check the geoid height at its most extreme by using latlon2pix
% with the referencing matrix.
[row, col] = latlon2pix(geoidR, 4.5, 78.5)
```

# makerefmat

---

```
geoid(round(row),round(col))
```

## See Also

[latlon2pix](#) | [map2pix](#) | [pix2latlon](#) | [pix2map](#) | [refvec2mat](#) | [worldfileread](#) | [worldfilewrite](#)

## Tutorials

- [Creating a Half-Resolution Georeferenced Image](#)

## How To

- [“Understanding Raster Geodata”](#)



**Purpose** Construct vector layer symbolization specification

**Syntax** `symbolspec = makesymbolspec(geometry,rule1,rule2,...ruleN)`

**Description** `symbolspec = makesymbolspec(geometry,rule1,rule2,...ruleN)` constructs a symbol specification structure (`symbolspec`) for symbolizing a (vector) shape layer in the Map Viewer or when using `mapshow`. `geometry` is one of 'Point', 'Line', 'PolyLine', 'Polygon', or 'Patch'. Rules, defined in detail below, specify the graphics properties for each feature of the layer. A rule can be a default rule that is applied to all features in the layer or it may limit the symbolization to only those features that have a particular value for a specified attribute. Features that do not match any rules are displayed using the default graphics properties.

To create a rule that applies to all features, a default rule, use the following syntax:

```
{'Default',Property1,Value1,Property2,Value2,...
    PropertyN,ValueN}
```

To create a rule that applies only to features that have a particular value or range of values for a specified attribute, use the following syntax:

```
{AttributeName,AttributeValue,
    Property1,Value1,Property2,Value2,...,PropertyN,ValueN}
```

`AttributeValue` and `ValueN` can each be a two-element vector, [`low high`], specifying a range. If `AttributeValue` is a range, `ValueN` might or might not be a range.

The following is a list of allowable values for `PropertyN`.

- Points or Multipoints: 'Marker', 'Color', 'MarkerEdgeColor', 'MarkerFaceColor', 'MarkerSize', and 'Visible'
- Lines or PolyLines: 'Color', 'LineStyle', 'LineWidth', and 'Visible'

# makesymbolspec

---

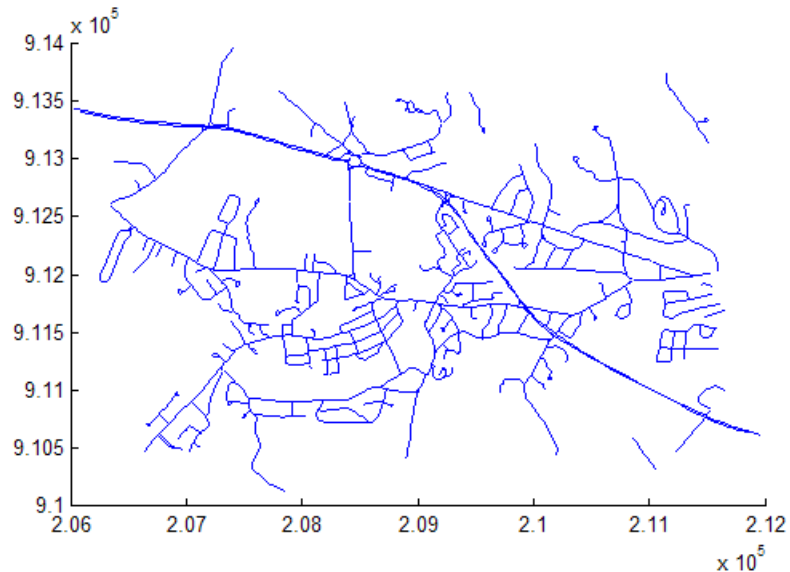
- Polygons: 'FaceColor', 'FaceAlpha', 'LineStyle', 'LineWidth', 'EdgeColor', 'EdgeAlpha', and 'Visible'

## Examples

The following examples import a shapefile containing road data and symbolize it in several ways using symbol specifications.

### Example 1 – Default Color

```
roads = shaperead('concord_roads.shp');
blueRoads = makesymbolspec('Line',{ 'Default','Color',[0 0 1]});
mapshow(roads, 'SymbolSpec',blueRoads);
```



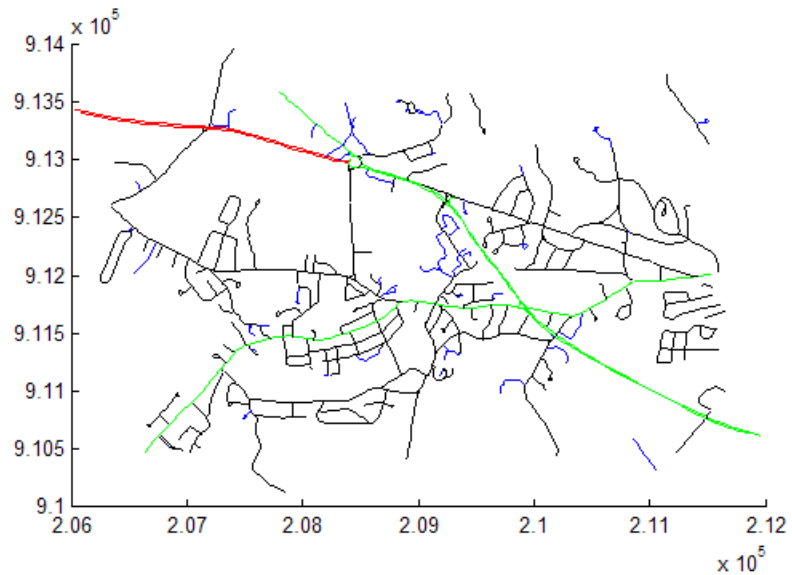
### Example 2 – Discrete Attribute Based

```
roads = shaperead('concord_roads.shp');
roadColors = ...
makesymbolspec('Line',{ 'CLASS',2,'Color','r'},...
               {'CLASS',3,'Color','g'},...
               {'CLASS',6,'Color','b'},...)
```

```

        {'Default','Color','k'});
mapshow(roads,'SymbolSpec',roadColors);

```

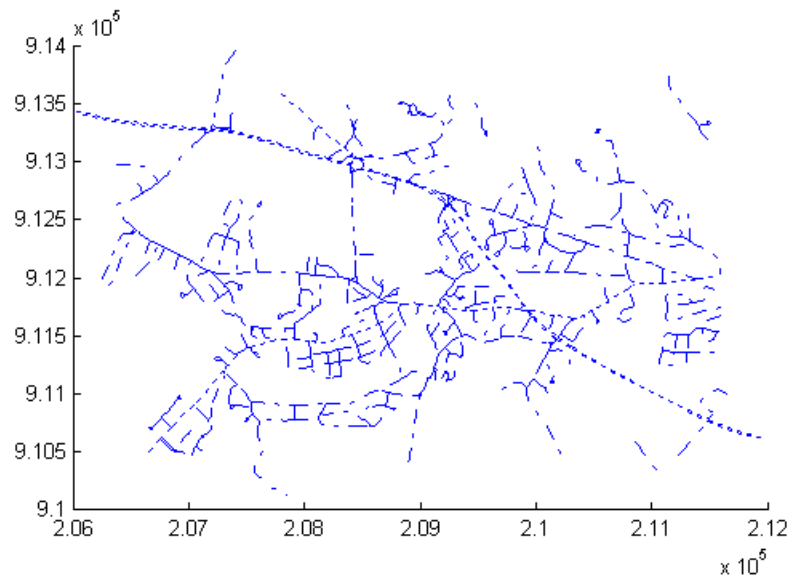


### Example 3 – Using a Range of Attribute Values

```

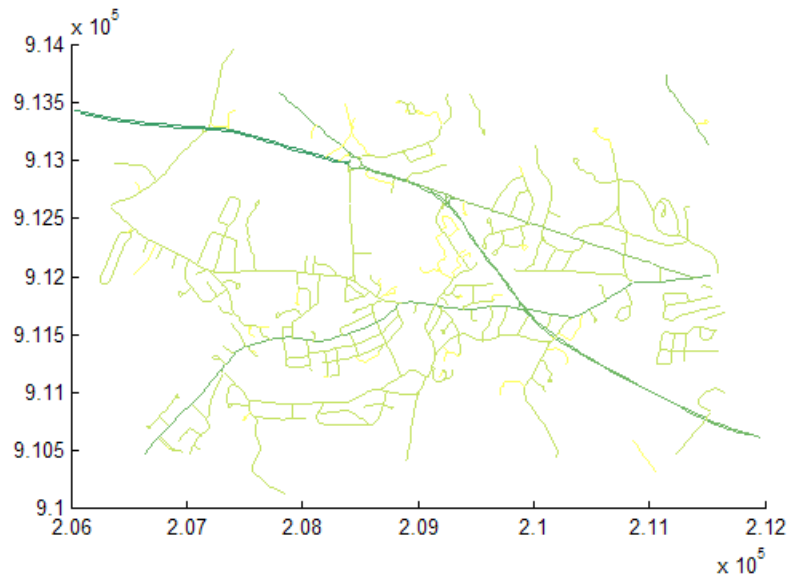
roads = shaperead('concord_roads.shp');
lineStyle = makesymbolspec('Line',...
    {'CLASS',[1 3], 'LineStyle',':'},...
    {'CLASS',[4 6], 'LineStyle','-.'});
mapshow(roads,'SymbolSpec',lineStyle);

```



## Example 4 – Using a Range of Attribute Values and a Range of Property Values

```
roads = shaperead('concord_roads.shp');
colorRange = makesymbolspec('Line',...
    {'CLASS',[1 6],'Color',summer(10)});
mapshow(roads,'SymbolSpec',colorRange);
```



**See Also**

mapshow, geoshow, mapview

# map2pix

---

**Purpose** Convert map coordinates to pixel coordinates

**Syntax**

```
[row,col] = map2pix(R,x,y)
p = map2pix(R,x,y)
[...] = map2pix(R,s)
```

**Description** `[row,col] = map2pix(R,x,y)` calculates pixel coordinates `row`, `col` from map coordinates `x,y`. `R` is a 3-by-2 referencing matrix defining a two-dimensional affine transformation from pixel coordinates to map coordinates. `x` and `y` are vectors or arrays of matching size. The outputs `row` and `col` have the same size as `x` and `y`.

`p = map2pix(R,x,y)` combines `row` and `col` into a single array `p`. If `x` and `y` are column vectors of length `n`, then `p` is an `n`-by-2 matrix and each `p(k,:)` specifies the pixel coordinates of a single point. Otherwise, `p` has size `[size(row) 2]`, and `p(k1,k2,...,kn,:)` contains the pixel coordinates of a single point.

`[...] = map2pix(R,s)` combines `x` and `y` into a single array `s`. If `x` and `y` are column vectors of length `n`, the `s` should be an `n`-by-2 matrix such that each row (`s(k,:)`) specifies the map coordinates of a single point. Otherwise, `s` should have size `[size(X) 2]`, and `s(k1,k2,...,kn,:)` should contain the map coordinates of a single point.

**Example**

```
% Find the pixel coordinates for the spatial coordinates
% (207050, 912900)
R = worldfileread('concord_ortho_w.tif');
[r,c] = map2pix(R, 207050, 912900);
```

**See Also** `latlon2pix`, `makerefmat`, `pix2map`, `worldfileread`

---

<b>Purpose</b>	Compute bounding box of georeferenced image or data grid						
<b>Syntax</b>	<pre>bbox = mapbbox(R, height, width) bbox = mapbbox(R, sizea) BBOX = mapbbox(info)</pre>						
<b>Description</b>	<p><code>bbox = mapbbox(R, height, width)</code> computes the 2-by-2 bounding box of a georeferenced image or regular gridded data set. <code>R</code> is a 3-by-2 affine referencing matrix. <code>height</code> and <code>width</code> are the image dimensions. <code>bbox</code> bounds the outer edges of the image in map coordinates:</p> <pre>[minX minY maxX maxY]</pre> <p><code>bbox = mapbbox(R, sizea)</code> accepts <code>sizea = [height, width, ...]</code> instead of <code>height</code> and <code>width</code>.</p> <p><code>BBOX = mapbbox(info)</code> accepts a scalar struct array with the fields</p> <table><tr><td>'RefMatrix'</td><td>3-by-2 referencing matrix</td></tr><tr><td>'Height'</td><td>Scalar number</td></tr><tr><td>'Width'</td><td>Scalar number</td></tr></table>	'RefMatrix'	3-by-2 referencing matrix	'Height'	Scalar number	'Width'	Scalar number
'RefMatrix'	3-by-2 referencing matrix						
'Height'	Scalar number						
'Width'	Scalar number						
<b>See Also</b>	<code>geotiffinfo</code> , <code>makerefmat</code> , <code>mapoutline</code> , <code>pixcenters</code> , <code>pix2map</code>						

# maplist

---

**Purpose** Available Mapping Toolbox map projections

**Syntax** `list = maplist`  
`[list,defproj] = maplist`

**Description** `list = maplist` returns a structure that lists all the available Mapping Toolbox map projections. The list structure is `list.Name`, `list.IdString`, `list.Classification`, `list.ClassCode`. This list structure is used by the functions `maps` and `axesmui` when processing map projection identifiers during operation of the toolbox functions.

`[list,defproj] = maplist` also returns the default projection's `IdString`.

`list.Name` defines the full name of the projection. This entry is used in the command-line table display and in the Projection Control Box.

`list.IdString` provides the name of the MATLAB function that computes the projection.

`list.Classification` defines the projection classification that is used in the command-line table display.

`list.ClassCode` defines the character string that is used to label the classes of projections in the Projection Control Box. The eight class codes are

- `Azim` — Azimuthal
- `Coni` — Conic
- `Cyln` — Cylindrical
- `Mazi` — Modified azimuthal
- `Pazi` — Pseudoazimuthal
- `Pcon` — Pseudoconic
- `Pcy` — Pseudocylindrical
- `Poly` — Polyconic



When map projections are added to the toolbox, the list structure needs to be extended. For example, if a new projection is added to the default list, then a new entry in the list structure would be

```
list.Name(61)           = 'My Projection'  
list.IdString(61)      = 'newprojection';  
list.Classification(61) = 'New Projection Type';  
list.ClassCode(61)     = 'Code';
```

**See Also**      maps, axesmui

# mapoutline

---

**Purpose** Compute outline of georeferenced image or data grid

**Syntax**

```
[x,y] = mapoutline(R, height, width)
[x,y] = mapoutline(R, sizea)
[x,y] = mapoutline(info)
[x,y] = mapoutline(...,'close')
[lon,lat] = mapoutline(R,...)
outline = mapoutline(...)
```

**Description** `[x,y] = mapoutline(R, height, width)` computes the outline of a georeferenced image or regular gridded data set in map coordinates. `R` is a 3-by-2 affine referencing matrix. `height` and `width` are the image dimensions. `x` and `y` are 4-by-1 column vectors containing the map coordinates of the outer corners of the corner pixels, in the following order:

```
(1,1), (height,1), (height, width), (1, width).
```

`[x,y] = mapoutline(R, sizea)` accepts `SIZEA = [height, width, ...]` instead of `height` and `width`.

`[x,y] = mapoutline(info)` accepts a scalar struct array with the fields

'RefMatrix'	3-by-2 referencing matrix
'Height'	Scalar number
'Width'	Scalar number

`[x,y] = mapoutline(...,'close')` returns `x` and `y` as 5-by-1 vectors, appending the coordinates of the first of the four corners to the end.

`[lon,lat] = mapoutline(R,...)`, where `R` georeferences pixels to longitude and latitude rather than map coordinates, returns the outline in geographic coordinates. Longitude must precede latitude in the output argument list.

`outline = mapoutline(...)` returns the corner coordinates in a 4-by-2 or 5-by-2 array.

**Example**

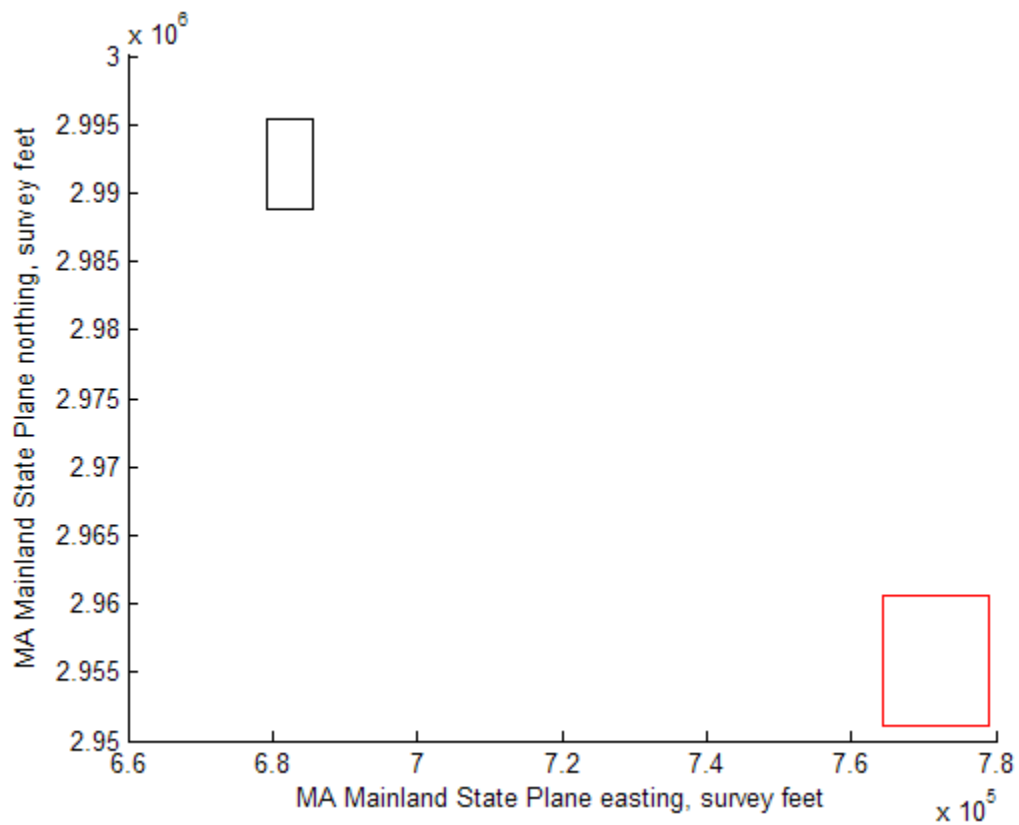
Draw a red outline delineating the Boston GeoTIFF image, which is referenced to the Massachusetts Mainland State Plane coordinate system with units of survey feet.

```
figure
info = geotiffinfo('boston.tif');
[x,y] = mapoutline(info, 'close');
hold on
plot(x,y,'r')
xlabel('MA Mainland State Plane easting, survey feet')
ylabel('MA Mainland State Plane northing, survey feet')
```

Draw a black outline delineating a TIFF image of Concord, Massachusetts, while lies roughly 25 km north west of Boston. Convert world file units to survey feet from meters to be consistent with the Boston image.

```
info = imfinfo('concord_ortho_w.tif');
R = worldfileread('concord_ortho_w.tfw');
R = R * unitsratio('sf','meter');
[x,y] = mapoutline(R, info.Height, info.Width, 'close');
plot(x,y,'k')
```

# mapoutline



## See Also

`makereformat`, `mapbbox`, `pixcenters`, `pix2map`

## Purpose

Interpolate heights between waypoints on regular data grid

## Syntax

```
[zi,rng,lat,lon] = mapprofile
[zi,rng,lat,lon] = mapprofile(Z,R,lat,lon)
[zi,rng,lat,lon] = mapprofile(Z,R,lat,lon,rngunits)
[zi,rng,lat,lon] = mapprofile(Z,R,lat,lon,ellipsoid)
[zi,rng,lat,lon] = ... mapprofile(Z,R,lat,lon,rngunits,
    trackmethod,interpmethod)
[zi,rng,lat,lon] = ... mapprofile(Z,R,lat,lon,ellipsoid,
    trackmethod,interpmethod)
```

## Description

mapprofile plots a profile of values between waypoints on a displayed regular data grid. mapprofile uses the current object if it is a regular data grid, or the first regular data grid found on the current axes. The grid's Zdata is used for the profile. The color data is used in the absence of Zdata. The result is displayed in a new figure.

[zi,rng,lat,lon] = mapprofile returns the values of the profile without displaying them. The output zi contains interpolated values from map along great circles between the waypoints. rng is a vector of associated distances from the first waypoint in units of degrees of arc along the surface. lat and lon are the corresponding latitudes and longitudes.

[zi,rng,lat,lon] = mapprofile(Z,R,lat,lon) accepts as input a regular data grid and waypoint vectors. No displayed grid is required. Sets of waypoints may be separated by NaNs into line sequences. The output ranges are measured from the first waypoint within a sequence. R is either a 1-by-3 vector containing elements:

```
[cells/degree northern_latitude_limit western_longitude_limit]
```

or a 3-by-2 referencing matrix that transforms raster row and column indices to/from geographic coordinates according to:

```
[lon lat] = [row col 1] * R
```

If `R` is a referencing matrix, it must define a (non-rotational, non-skewed) relationship in which each column of the data grid falls along a meridian and each row falls along a parallel.

`[zi,rng,lat,lon] = mapprofile(Z,R,lat,lon,rngunits)` specifies the units of the output ranges along the profile. Valid range units inputs are any distance string recognized by `unitsratio`. Surface distances are computed using the default radius of the grid. If omitted, 'degrees' is assumed.

`[zi,rng,lat,lon] = mapprofile(Z,R,lat,lon,ellipsoid)` uses the provided ellipsoid definition in computing the range along the profile. The ellipsoid vector is of the form `[semimajor axes, eccentricity]`. The output range is reported in the same distance units as the semimajor axes of the ellipsoid vector. If omitted, the range vector is for a sphere.

`[zi,rng,lat,lon] = ...`  
`mapprofile(Z,R,lat,lon,rngunits,trackmethod,interpmethod)`  
and `[zi,rng,lat,lon] = ...`  
`mapprofile(Z,R,lat,lon,ellipsoid,trackmethod,interpmethod)`  
control the interpolation methods used. Valid trackmethods are 'gc' for great circle tracks between waypoints, and 'rh' for rhumb lines. Valid interpmethods for interpolation within the data grid are 'bilinear' for linear interpolation, 'bicubic' for cubic interpolation, and 'nearest' for nearest neighbor interpolation. If omitted, 'gc' and 'bilinear' are assumed.

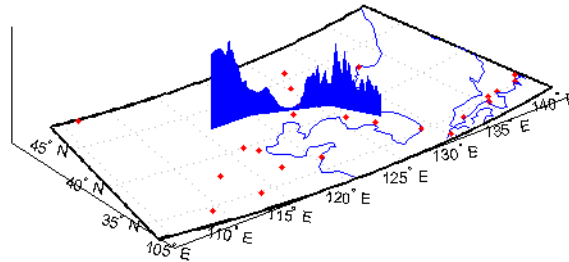
## Examples

### Example 1

Create a map axes for the Korean peninsula. Specify an elevation profile across the sample Korean digital elevation data and plot it, combined with a coastline and city markers:

```
load korea
h = worldmap(map, refvec); % The figure has no map content
plat = [ 43  43  41  38];
plon = [116 120 126 128];
mapprofile(map, refvec, plat, plon)
```

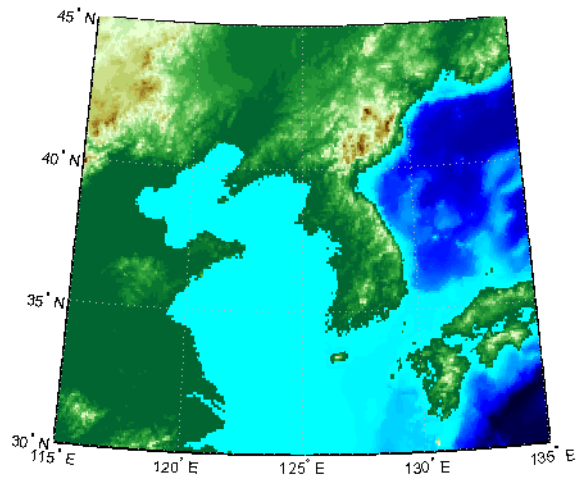
```
load coast
plotm(lat, long)
geoshow('worldcities.shp', 'Marker', '.', 'Color', 'red')
```



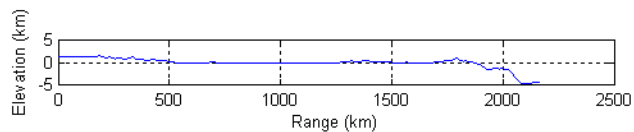
When you select more than two waypoints, the automatically generated figure displays the result in three dimensions. The following example shows the relative sizes of the mountains in northern China compared to the depths of the Sea of Japan. The call to `mapprofile` without input arguments requires you to interactively pick waypoints on the figure using the mouse, and press **Enter** after you select the final point:

```
axes(h);
meshm(map, refvec, size(map))
demcmap(map)
[z,rng,lat,lon] = mapprofile;
```

Adding output arguments suppresses the display of the results in a new figure. You can then use the results in further calculations or display the results yourself. Here the profile from the upper left to lower right is computed from waypoints interactively picked on the map (your profile will not be identical to what is shown below). The example converts ranges and elevations to kilometers and displays them in a new figure, setting the vertical exaggeration factor to 20. With no vertical exaggeration, the changes in elevation would be almost too small to see.



```
figure
plot(deg2km(rng),z/1000)
daspect([ 1 1/20 1 ]);
xlabel 'Range (km)'
ylabel 'Elevation (km)'
```



Naturally, the profile you get depends on the transect locations you pick.

## Example 2

You can compute values along a path without reference to an existing figure by providing a regular data grid and vectors of waypoint coordinates. Optional arguments allow control over the units of the range output and interpolation methods between waypoints and data grid elements.

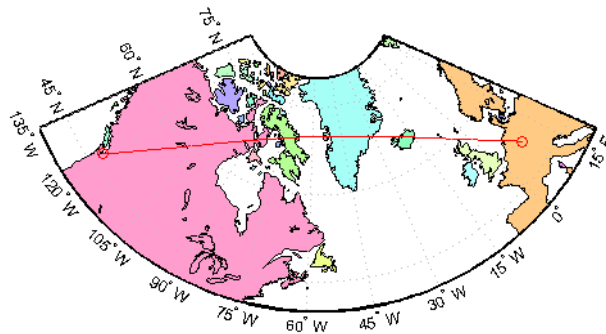


Show what land and ocean areas lie under a great circle track from Frankfurt to Seattle:

```

cities = shaperead('worldcities.shp', 'UseGeoCoords', true);
Seattle = strmatch('Seattle', {cities(:).Name});
Frankfurt = strmatch('Frankfurt', {cities(:).Name});
lat = [cities(Seattle).Lat cities(Frankfurt).Lat]
lon = [cities(Seattle).Lon cities(Frankfurt).Lon]
load topo
[valp, rngp, latp, lonp] = ...
    mapprofile(double(topo), topolegend, ...
        lat, lon, 'km', 'gc', 'nearest');
figure
worldmap([40 80], [-135 20])
land = shaperead('landareas.shp', 'UseGeoCoords', true);
faceColors = makesymbolspec('Polygon', ...
    {'INDEX', [1 numel(land)], 'FaceColor', ...
    polcmap(numel(land))});
geoshow(land, 'SymbolSpec', faceColors)
plotm(latp, lonp, 'r')
plotm(lat, lon, 'ro')
axis off

```



## See Also

1t1n2val, los2

# maps

---

**Purpose** List available map projections and verify names

**Syntax**

```
strmat = maps('namelist')
strmat = maps('idlist')
stdstr = maps(id_string)
```

**Description** `maps` displays in the Command Window a table describing all projections available for use.

`strmat = maps('namelist')` returns the English names for the available projections as a matrix of strings.

`strmat = maps('idlist')` returns the standard projection identification strings for the available projections as a matrix of strings.

`stdstr = maps(id_string)` returns the specific standard projection identification string associated with a unique truncation abbreviation.

**Examples** To show the first five entries of the projections name list,

```
str1 = maps('namelist');
str1(1:5,:)
ans =
Balthasart Cylindrical
Behrmann Cylindrical
Bolshoi Sovietskii Atlas Mira
Braun Perspective Cylindrical
Cassini Cylindrical
```

The corresponding shorthand names are

```
str2 = maps('idlist');
str2(1:5,:)
ans =
balhsrt
behrmann
bsam
braun
cassini
```

These are the strings used, for example, when setting the `axesm` property `MapProjection`.

The functions `setm` and `axesm` recognize unique abbreviations (truncations) of these strings. The `maps` function can be used to convert such an abbreviation to the standard ID string:

```
stdstr = maps('merc')
stdstr =
mercator
```

When the function name alone is used,

```
maps

MapTools Projections
CLASS          NAME                                     ID STRING
Cylindrical    Balthasart Cylindrical                            balthsrt
Cylindrical    Behrmann Cylindrical                              behrmann
Cylindrical    Bolshoi Sovietskii Atlas Mira*                    bsam
Cylindrical    Braun Perspective Cylindrical*                    braun
Cylindrical    Cassini Cylindrical                               cassini
Cylindrical    Central Cylindrical*                              ccylin
Cylindrical    Equal Area Cylindrical                            eqacylin
Cylindrical    Equidistant Cylindrical                          eqdcylin
Cylindrical    Gall Isographic                                   giso...
```

The actual result contains all defined projections.

## See Also

`axesm`, `setm`

# mapshow

---

**Purpose** Display map data without projection

**Syntax**

```
mapshow(x,y)
mapshow(x,y, ..., 'DisplayType', displaytype, ...)
mapshow(x,y,z, ..., 'DisplayType', displaytype, ...)
mapshow(Z,R, ..., 'DisplayType', displaytype,...)
mapshow(x,y,I)
mapshow(x,y,BW)
mapshow(x,y,A,cmap)
mapshow(x,y,RGB)
mapshow(I,R)
mapshow(BW,R)
mapshow(RGB,R)
mapshow(A,cmap,R)
mapshow(s)
mapshow(s,...,'SymbolSpec',symspec, ...)
mapshow(filename)
mapshow(..., param1, val1, param2, val2, ...)
mapshow(ax, ...)
mapshow(..., 'Parent', ax, ...)
h = mapshow(...)
```

**Description**

`mapshow(x,y)` or `mapshow(x,y, ..., 'DisplayType', displaytype, ...)` displays the coordinate vectors `x` and `y`. `x` and `y` can contain embedded NaNs, delimiting individual lines or polygon parts. `displaytype` can be 'point', 'line', or 'polygon' and defaults to 'line'.

`mapshow(x,y,z, ..., 'DisplayType', displaytype, ...)` displays a geolocated data grid. `x` and `y` are M-by-N coordinate arrays, `z` is an M-by-N array of class double, and `displaytype` is 'surface', 'mesh', 'texturemap', or 'contour'. `z` can contain NaN values.

`mapshow(Z,R, ..., 'DisplayType', displaytype,...)` displays a regular data grid, `Z`. `Z` is class double and `displaytype` can be 'surface', 'mesh', 'texturemap', or 'contour'. `R` is a referencing matrix that relates the subscripts of `Z` to map coordinates. If

`DisplayType` is `'texturemap'`, `mapshow` constructs a surface with `ZData` values set to 0.

`mapshow(x,y,I)`, `mapshow(x,y,BW)`, `mapshow(x,y,A,cmap)`, and `mapshow(x,y,RGB)` display a geolocated image as a texturemap on a zero-elevation surface. `x` and `y` are geolocation arrays in map coordinates; `I` is a grayscale image, `BW` is a logical image, `A` is an indexed image with colormap `cmap`, or `rgb` is a truecolor image. `x`, `y`, and the image array must match in size. If specified, `DisplayType` must be set to `'image'`. Examples of geolocated images include a color composite from a satellite swath or an image originally referenced to a different coordinate system.

`mapshow(I,R)`, `mapshow(BW,R)`, `mapshow(RGB,R)`, and `mapshow(A,cmap,R)` display an image georeferenced to map coordinates through the referencing matrix `R`. It constructs an image object if the display geometry permits; otherwise, the image is shown as a texturemap on a zero-elevation surface. If specified, `'DisplayType'` must be set to `'image'`.

`mapshow(s)` or `mapshow(s,...,'SymbolSpec',symspec,...)` display the vector geographic features stored in the geographic data structure `s` as points, multipoints, lines, or polygons according to the `Geometry` field of `s`. If `s` includes `X` and `Y` fields, then they are used directly to plot features in map coordinates. If `Lat` and `Lon` fields are present in `s` instead, the coordinates are projected using the Plate Carree projection and a warning is issued. `symspec` specifies the symbolization rules used for the vector data through a structure returned by `makesymbolspec`.

If `s` is a `geostruct` (has `Lat` and `Lon` fields), it may be more appropriate to use `geoshow` to display them. You can project latitude and longitude coordinate values to map coordinates by displaying with `geoshow` on a map axes.

`mapshow(filename)` displays data from `filename`, according to the type of file format. The `DisplayType` parameter is automatically set according to the following table:

Format	DisplayType
Shapefile	'point', 'line', or 'polygon'
GeoTIFF	'image'
TIFF/JPEG/PNG with a world file	'image'
ARC ASCII GRID	'surface' (can be overridden)
SDTS raster	'surface' (can be overridden)

`mapshow(..., param1, val1, param2, val2, ...)` specifies parameter/value pairs that modify the type of display or set MATLAB graphics properties. Parameter names can be abbreviated and are not case-sensitive. Refer to the MATLAB Graphics documentation on `line`, `patch`, `image`, `surface`, `mesh`, and `contour` Handle Graphics object properties for a complete description of these properties and their values.

`mapshow(ax, ...)` and `mapshow(..., 'Parent', ax, ...)` set the axes parent to `ax`.

`h = mapshow(...)` returns a handle to a MATLAB graphics object or, in the case of polygons, a modified patch object. If a mapstruct or shapefile name is input, `mapshow` returns the handle to an `hgroup` object with one child per feature in the mapstruct or shapefile. In the case of a polygon mapstruct or shapefile, each child is a modified patch object; otherwise it is a line object.

## Parameters

Parameters for `mapshow` include

- **DisplayType:** The `DisplayType` parameter specifies the type of graphic display for the data. The value must be consistent with the type of data being displayed, as shown in the following table:

---

Data Type	Value
vector	'point', 'line', or 'polygon'
image	'image'
grid	'surface', 'mesh', 'texturemap', or 'contour'

- **SymbolSpec:** The `SymbolSpec` parameter specifies the symbolization rules used for vector data through a structure returned by `makesymbolspec`. It is used only for vector data.

When both `SymbolSpec` and one or more graphics properties are specified, the graphics properties will override any settings in the `symbolspec` structure.

To change the default symbolization rule for a property name/property value pair in the `symbolspec`, prefix the word `'Default'` to the graphics property name (listed in the preceding table).

If `PropertyN` is `'SymbolSpec'`, then `ValueN` must be `symspec`. `symspec` should conform to the structure returned by `makesymbolspec`.

When you use `'SymbolSpec'/symspec` and other property name/property value pairs together, the property name/property value pairs override any settings in `symspec`.

---

**Note** If you display a polygon, do not set `'EdgeColor'` to either `'flat'` or `'interp'`. This combination may result in a warning.

---

## Graphics Properties

In addition to specifying a parent axes, you can set any appropriate property for a point, line, and polygon `DisplayType`, as follows:

<b>DisplayType</b>	<b>Properties</b>
'line'	Any MATLAB line property
'point'	Any MATLAB line marker property
'polygon'	Any MATLAB patch property

See the MATLAB Graphics documentation for line, patch, image, and surface properties for complete descriptions of these properties and their values.

## Remarks

You can use `mapshow` to display vector data in an `axesm` figure. However, you should not subsequently change the map projection using `setm`.

`mapshow` adds graphics to the current axes (it does not clear it first), enabling you to create multiple raster and vector map layers. If you do not want `mapshow` to draw on top of an existing map, create a new figure or subplot before calling it.

## Examples

### Example 1

Overlay Boston roads on an orthophoto. You need to convert Boston road vectors to units of survey feet before overlaying them on the image. Note that `mapshow` draws a new layer in the axes rather than replacing its contents:

```
figure
mapshow boston.tif
axis image off

% The orthophoto is in survey feet, the roads are in meters;
% convert the road units to feet before overlaying them.
S = shaperead('boston_roads.shp');
surveyFeetPerMeter = unitsratio('sf','meter');
x = surveyFeetPerMeter * [S.X];
y = surveyFeetPerMeter * [S.Y];
```



```
mapshow(x,y)
```

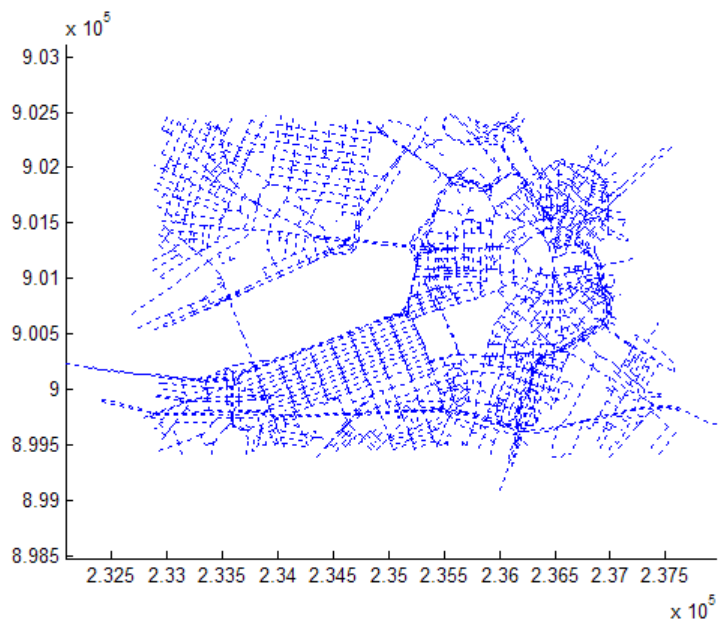


boston.tif image copyright © GeoEye, all rights reserved.

## Example 2

Display Boston roads and change the line style:

```
roads = shaperead('boston_roads.shp');  
figure  
mapshow(roads, 'LineStyle', ':');
```

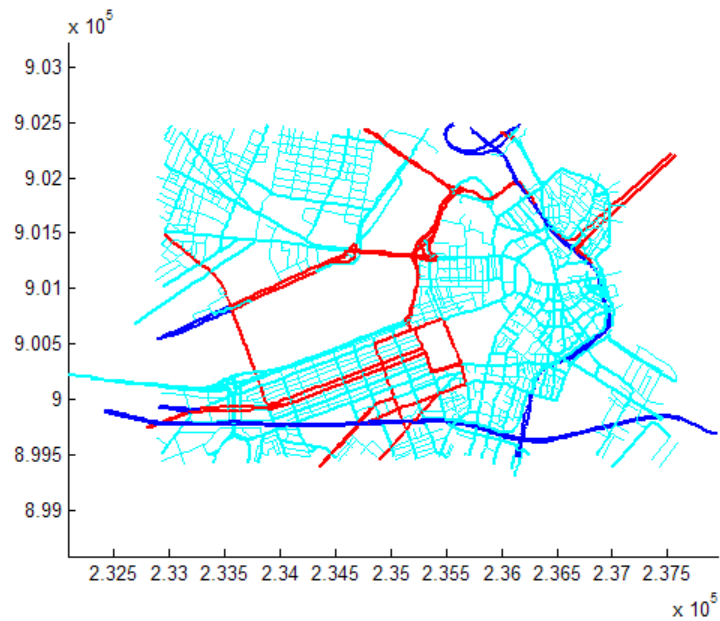


### Example 3

Display the Boston roads shapes using a symbolspec:

```
% Create a SymbolSpec to color local roads:
% (ADMIN_TYPE=0) cyan, state roads (ADMIN_TYPE=3) red.
% Hide very minor roads (CLASS=6).
% Make all roads that are major or larger (CLASS=1-4)
% have a LineWidth of 2.
roadspec = makesymbolspec('Line',...
    {'ADMIN_TYPE',0,'Color','cyan'}, ...
    {'ADMIN_TYPE',3,'Color','red'},...
    {'CLASS',6,'Visible','off'},...
    {'CLASS',[1 4],'LineWidth',2});

figure
mapshow('boston_roads.shp','SymbolSpec',roadspec);
```



#### Example 4

Override default properties in combination with a symbolspec.

```
roadspec = makesymbolspec('Line',...
    {'Default', 'Color', 'yellow'}, ...
    {'ADMIN_TYPE',0,'Color','c'}, ...
    {'ADMIN_TYPE',3,'Color','r'},...
    {'CLASS',6,'Visible','off'},...
    {'CLASS',[1 4],'LineWidth',2});

figure
mapshow('boston_roads.shp', 'Color', 'black', ...
'SymbolSpec', roadspec);
```

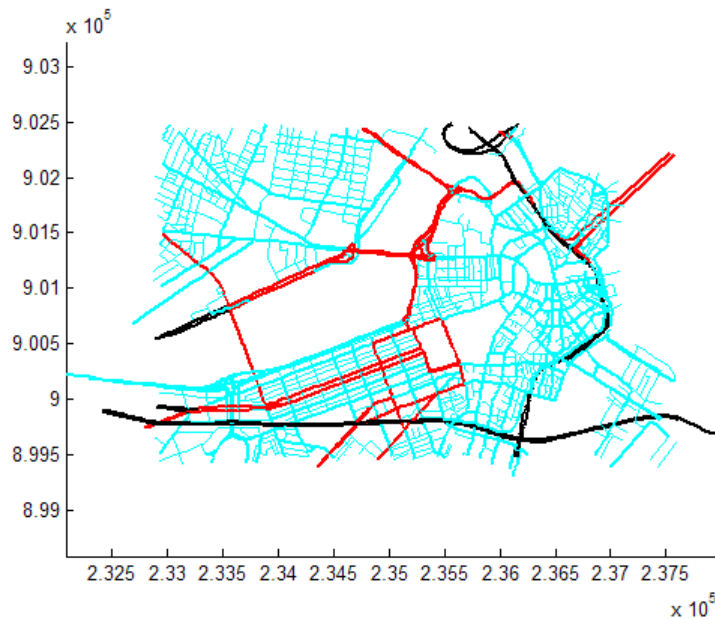


## Example 5

Override default properties of the line with a symbolspec:

```
roadspec = makesymbolspec('Line',...
    {'Default', 'Color', 'black'}, ...
    {'ADMIN_TYPE',0,'Color','c'}, ...
    {'ADMIN_TYPE',3,'Color','r'},...
    {'CLASS',6,'Visible','off'},...
    {'CLASS',[1 4],'LineWidth',2});

figure
mapshow('boston_roads.shp','SymbolSpec',roadspec);
```



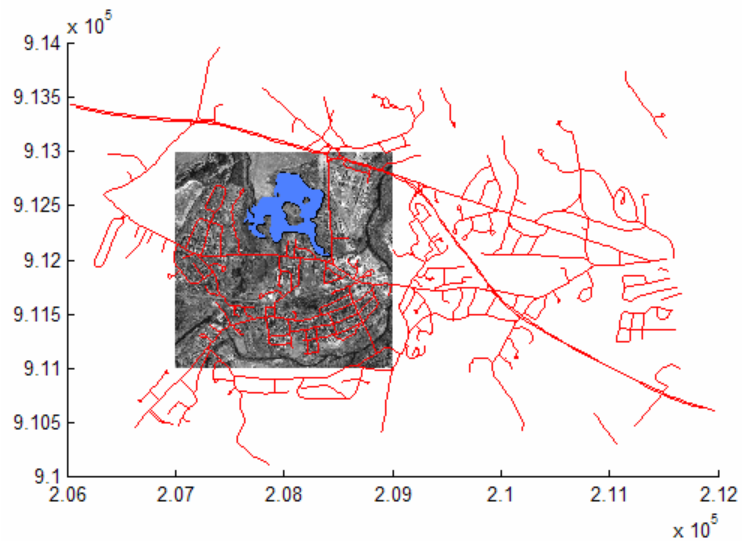
### Example 6

Display an orthophoto of Concord, MA, including a pond with three large islands:

```
[ortho, cmap] = imread('concord_ortho_w.tif');
R = worldfileread('concord_ortho_w.tfw');
figure
mapshow(ortho, cmap, R)

% Overlay a polygon representing the same pond
% (feature 14 in the concord_hydro_area shapefile).
% Note that the islands are visible in the orthophoto
% through three "holes" in the pond polygon.
pond = shaperead('concord_hydro_area.shp', 'RecordNumbers', 14);
mapshow(pond, 'FaceColor', [0.3 0.5 1], 'EdgeColor', 'black')
% Overlay roads in the same figure.
```

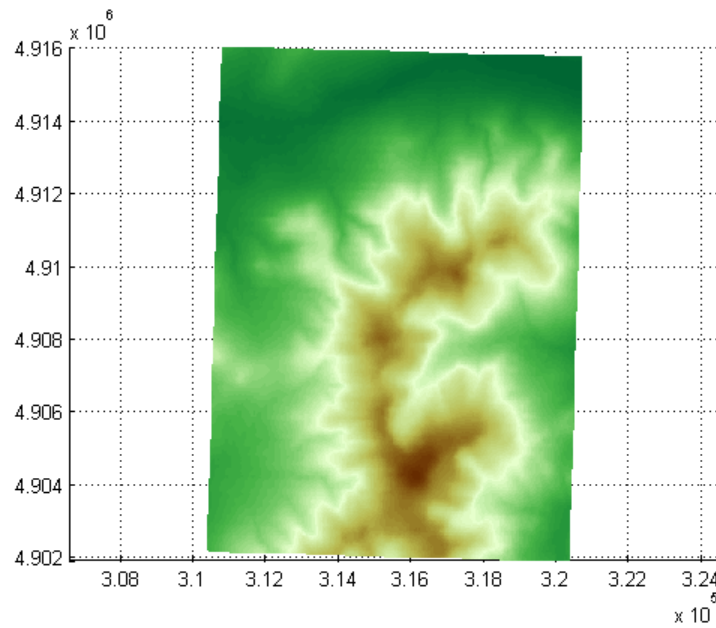
```
mapshow('concord_roads.shp', 'Color', 'red', 'LineWidth', 1);
```



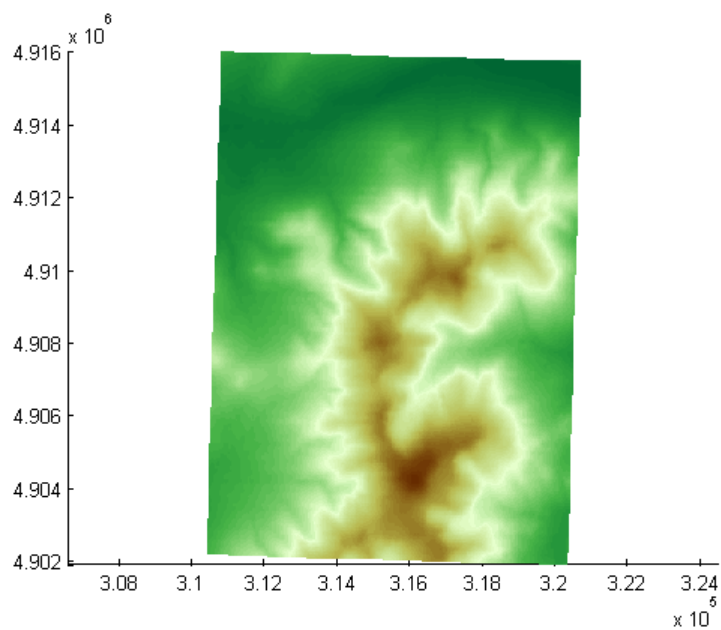
## Example 7

Read and view the Mount Washington SDTS DEM terrain data three different ways:

```
[Z, R] = sdtsemread('9129CATD.DDF');  
  
% View the Mount Washington terrain data as a mesh.  
figure  
mapshow(Z, R, 'DisplayType', 'mesh');  
colormap(demcmap(Z))
```

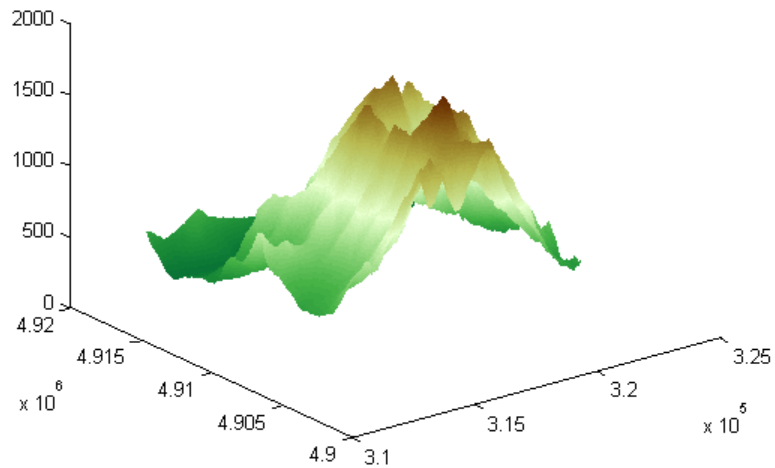


```
% View the Mount Washington terrain data as a surface.  
figure  
mapshow(Z, R, 'DisplayType', 'surface');  
colormap(demcmap(Z))
```



```
% View as a 3-D surface.  
view(3);  
axis normal
```



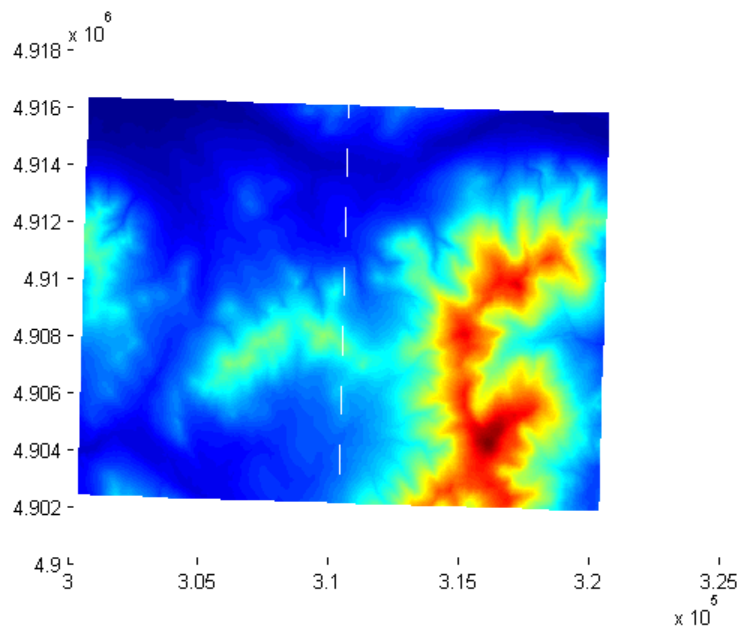


### Example 8

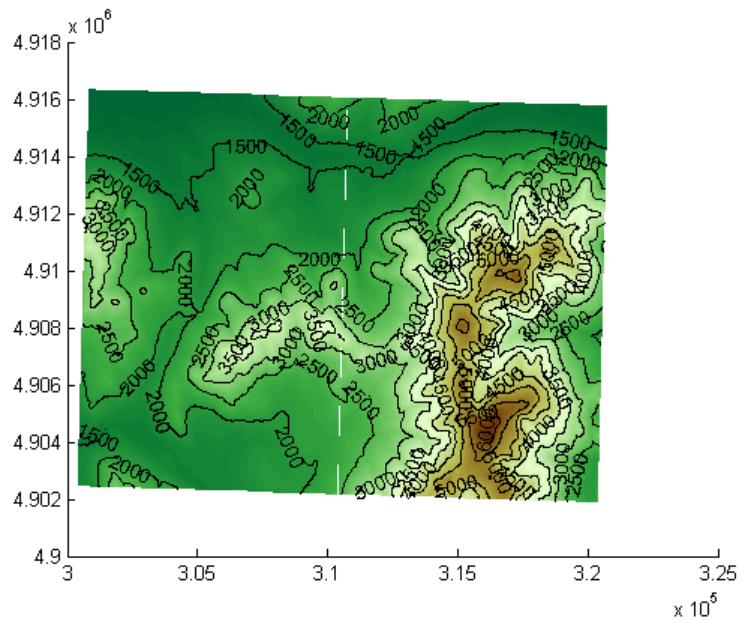
Display the grid and contour lines of Mount Washington and Mount Dartmouth.

```
% Read the terrain data files.
[Z_W, R_W] = arcgridread('MtWashington-ft.grd');
[Z_D, R_D] = arcgridread('MountDartmouth-ft.grd');

% Display the terrain data as a texture map.
figure
hold on
h1 = mapshow(Z_W, R_W, 'DisplayType', 'texturemap');
h2 = mapshow(Z_D, R_D, 'DisplayType', 'texturemap');
set([h1, h2], 'FaceColor', 'flat');
```



```
% Overlay black contour lines with labels onto the texturemap.  
mapshow(Z_W, R_W, 'DisplayType', 'contour', ...  
        'LineColor','black', 'ShowText', 'on');  
mapshow(Z_D, R_D, 'DisplayType', 'contour', ...  
        'LineColor','black', 'ShowText', 'on');  
  
% Set the colormap appropriate to terrain elevation.  
colormap(demcmap(Z_W))
```

**See Also**

geoshow, makesymbolspec, mapview, shaperead

# maptriml

---

**Purpose** Trim lines to latitude-longitude quadrangle

**Syntax** `[lat,lon] = maptriml(lat0,lon0,latlim,lonlim)`

**Description** `[lat,lon] = maptriml(lat0,lon0,latlim,lonlim)` returns *filtered* NaN-delimited vector map data sets from which all points lying outside the desired latitude and longitude limits have been discarded. These limits are specified by the two-element vectors `latlim` and `lonlim`, which have the form `[south-limit north-limit]` and `[west-limit east-limit]`, respectively.

**Examples** Following is a simple example:

```
lat0 = [1:10,9:-1:0]; lon0 = -30:-11;
[lat,lon] = maptriml(lat0,lon0,[3 7],[-29 -12]);
[lat lon]
```

```
ans =
     NaN     NaN
      3    -28
      4    -27
      5    -26
      6    -25
      7    -24
     NaN     NaN
      7    -18
      6    -17
      5    -16
      4    -15
      3    -14
     NaN     NaN
```

Notice that trimmed line segment ends have NaNs inserted at trim points.

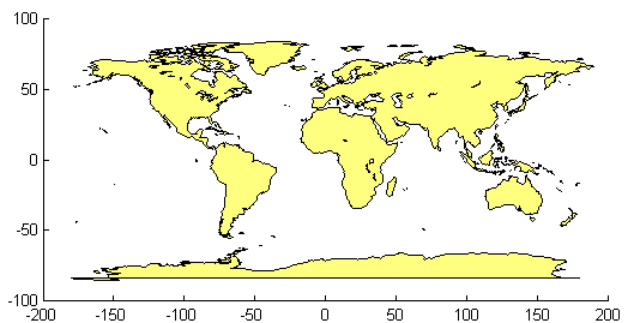
**See Also** `maptrimp`, `maptrims`

---

<b>Purpose</b>	Trim polygons to latitude-longitude quadrangle
<b>Syntax</b>	<code>[latTrimmed,lonTrimmed] = maptrimp(lat,lon,latlim,lonlim)</code>
<b>Description</b>	<code>[latTrimmed,lonTrimmed] = maptrimp(lat,lon,latlim,lonlim)</code> trims the polygons in <code>lat</code> and <code>lon</code> to the quadrangle specified by <code>latlim</code> and <code>lonlim</code> . <code>latlim</code> and <code>lonlim</code> are two-element vectors, defining the latitude and longitude limits respectively. <code>lat</code> and <code>lon</code> must be vectors that represent valid polygons.
<b>Remarks</b>	<p><code>maptrimp</code> conditions the longitude limits such that:</p> <ul style="list-style-type: none"><li>• <code>lonlim(2)</code> always exceeds <code>lonlim(1)</code></li><li>• <code>lonlim(2)</code> never exceeds <code>lonlim(1)</code> by more than 360</li><li>• <code>lonlim(1) &lt; 180</code> or <code>lonlim(2) &gt; -180</code></li><li>• Should the quadrangle span the Greenwich meridian, then that meridian appears at longitude = 0.</li></ul>
<b>Example</b>	<p>Display a world map of coastline data, trim the dataset to a specific geographic area, and display a map of this trimmed data.</p> <pre>coast = load('coast.mat'); figure mapshow(coast.long, coast.lat, 'DisplayType', 'polygon');</pre>

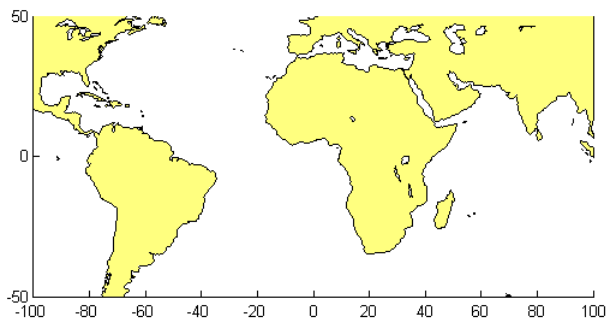
# maptrimp

---



## Original Map

```
latlim = [-50 50];  
lonlim = [-100 50];  
[latTrimmed, lonTrimmed] = maptrimp(coast.lat, coast.long, ...  
    latlim, lonlim);  
figure  
mapshow(lonTrimmed, latTrimmed, 'DisplayType', 'polygon');
```



## Map with Trimmed Data

### See Also

maptrim1, maptrims

**Purpose**

Trim regular data grid to latitude-longitude quadrangle

**Syntax**

```
[Z_trimmed] = maptrims(Z,R,latlim,lonlim)
[Z_trimmed] = maptrims(Z,R,latlim,lonlim,cellDensity)
[Z_trimmed, R_trimmed] = maptrims(...)
```

**Description**

`[Z_trimmed] = maptrims(Z,R,latlim,lonlim)` trims a regular data grid `Z` to the region specified by `latlim` and `lonlim`. `R` is either a 1-by-3 vector containing elements:

```
[cells/degree northern_latitude_limit western_longitude_limit]
```

or a 3-by-2 referencing matrix that transforms raster row and column indices to/from geographic coordinates according to:

```
[lon lat] = [row col 1] * R
```

If `R` is a referencing matrix, it must define a (non-rotational, non-skewed) relationship in which each column of the data grid falls along a meridian and each row falls along a parallel. `latlim` and `lonlim` are two-element vectors, defining the latitude and longitude limits, respectively. The `latlim` vector has the form:

```
[southern_limit northern_limit]
```

Likewise, the `lonlim` vector has the form:

```
[western_limit eastern_limit]
```

The output grid `Z_trimmed` has the same sample size as the input.

`[Z_trimmed] = maptrims(Z,R,latlim,lonlim,cellDensity)` uses `cellDensity` to reduce the size of the output. If `R` is a referencing vector, then `R(1)` must be evenly divisible by `cellDensity`. If `R` is a referencing matrix, then the inverse of each element in the first two rows (containing "deltaLat" and "deltaLon") must be evenly divisible by `cellDensity`.

`[Z_trimmed, R_trimmed] = maptrims(...)` returns a referencing vector or matrix for the trimmed data grid. If `R` is a referencing vector,

# maptrims

---

then `R_trimmed` is a referencing vector. Likewise, if `R` is a referencing matrix, then `R_trimmed` is a referencing matrix.

## Examples

```
load topo
[subgrid,subrefvec] = maptrims(topo,topolegend,...
                               [80.25 85.3],[165.2 170.7])

subgrid =
    -2826    -2810    -2802    -2793
    -2915    -2913    -2905    -2884
    -3192    -3186    -3165    -3122
    -3399    -3324    -3273    -3214

subrefvec =
     1     85    166
```

The upper left corner of the grid might differ slightly from that of the requested region. `maptrims` uses the corner coordinates of the first cell inside the limits.

## See Also

`maptrim1`, `maptrimp`, `resizem`



---

<b>Purpose</b>	Interactive map viewer
<b>Syntax</b>	mapview
<b>Description</b>	<p>Use the Map Viewer to work with vector, image, and raster data grids in a map coordinate system: load data, pan and zoom on the map, control the map scale of your screen display, control the order, visibility, and symbolization of map layers, annotate your map, and click to learn more about individual vector features. <code>mapview</code> complements <code>mapshow</code> and <code>geoshow</code>, which are for constructing maps in ordinary figure windows in a less interactive, script-oriented way.</p> <p><code>mapview</code> (with no arguments) starts a new Map Viewer in an empty state. The Map Viewer is a self-contained GUI for viewing geospatial data in map (<math>x</math>-<math>y</math>) coordinates. For usage information, see the following sections. You can also work through the Map Viewer tutorial, “Tour Boston with the Map Viewer”.</p>
<b>Importing Data</b>	<p>The Map Viewer opens with no data loaded and an empty map display window. The first step is to import a data set. Use the options in the <b>File</b> menu to select data from a file or from the MATLAB workspace:</p> <p><b>Import From File</b></p> <p>Use the file browsing dialog to open a file in one of the following formats: Shapefile, GeoTIFF, SDTS DEM, Arc ASCII Grid, TIFF, JPEG, or PNG with world file. This option imports the data into the viewer but does not add it to your workspace.</p> <p>To view standard-format geodata files provided with the toolbox, set your working directory or navigate the Map Viewer Open dialog to</p> <pre><i>matlabroot/toolbox/map/mapdemos</i></pre>

## Import From Workspace

**Images.** Use the **Raster Data > Image** import dialog to select a **referencing matrix and data name** for the image from the list of workspace variables. If the image type is truecolor (RGB), specify which band represents the red, green, and blue intensities.

**Data grids.** Use the **Raster Data > Grid** import dialog to select X and Y geolocation and data grid array names from the list of workspace variables.

**Vector data.** Use the **Vector Data > Map coordinates** import dialog to select X and Y variables for map coordinates from the list of workspace variables and identify the type of geometry to be displayed (**Point**, **Line**, or **Polygon**). The X and Y variables can specify multiple line segments or multiple polygons if they contain NaNs at matching locations in the coordinate vectors.

**Vector geographic data structure.** Use the **Vector Data > Geographic data structure** import dialog to select the struct that contains vector map data from the list of workspace variables.

Once you import your first data set, the Map Viewer automatically sets the limits of its map display window to the spatial extent of the imported data.

## Working in Map Coordinates

As you move any of the Map Viewer cursors across the map display area, the coordinate readout in the lower left corners shows you the cursor position in map X and Y coordinates.

The Map Viewer requires that all currently viewed data sets possess the same coordinate system and length units. This is likely to be the case for data sets that originated from a common source. If it is not the case, you will need to adjust coordinates before importing data into the Map Viewer.

If some or all of your data is in geographic coordinates, use `projfw` or `mfwdtran` to project latitudes and longitudes to your desired map

coordinate system before you import it. When starting from a different projection, you must first unproject to latitude and longitude using `projinv` or `minvtran`, then reproject with `projfwd` or `mfwdtran`. You might also need to adjust the horizontal datum of your data using, for example, the free GEOTRANS (Geographic Translator) application from the Geospatial Sciences Division of the U.S. National Geospatial-Intelligence Agency (NGA). If you simply need a change of units, multiply by the appropriate conversion factor obtained from `unitsratio`.

mapview can also display data in unprojected geographic coordinates, if you consistently substitute longitude for map X and latitude for map Y. Geographic coordinates must be consistently expressed in either degrees or radians (not both at once). When using geographic coordinates, do not specify the viewer's map units (see below); you can only use the Map Viewer's map scale display when working in linear units of length.

## Setting Map Units and Scale

If you tell the Map Viewer which length unit you are using, it can calculate an approximate map scale for your onscreen display. Set the map units with either the drop-down menu at the bottom of the display or the **Set Map Units** item in the **Tools** menu.

The scale computed by the Map Viewer is displayed in the window just above the map units drop-down. To change your display scale while keeping the center of the map display fixed, simply edit this text box.

Make sure to format your text in the standard way ( $1:N$ , where  $N$  is a positive number such that a distance on the ground is  $N$  times the same distance on your screen, e.g.,  $1:24000$ ).

The scale is approximate because it depends on the MATLAB estimate of the size of your screen pixels. It is also approximate if your projection introduces significant distortion. If your data falls in a fairly small area and you use a conformal projection (e.g., UTM with all data in a single zone), the scale will be very consistent across your entire map.

## Navigating Your Map

By default, the Map Viewer sets the limits of your map window to match the extent of the first data set that you load. You will probably want to adjust this to see some areas in greater detail.

The Map Viewer provides several tools to control the limits of your map window and the map scale of the data display. Some are familiar from standard MATLAB figure windows.

- **Zoom in:** Drag a box to zoom in on a specific area or click a point to zoom in with that point centered in the map display.
- **Zoom out:** Click a point to zoom out with that point centered in the map display.
- **Pan tool:** Click, hold, and drag to reposition the selected point in the display window, while holding the map scale fixed. Release when you are satisfied with new display limits.
- **Fit to window:** Set the map display to enclose all currently loaded data layers. This is equivalent to selecting **Fit to Window** in the **View** menu.
- **Back to previous view:** Click this button once to return the map scale and display center to their values prior to the most recent zoom, pan, or scale change. Click repeatedly to undo earlier changes. This is equivalent to selecting **Previous View** in the **View** menu.

Another way to zoom in or out while keeping the center of the view fixed at the same map coordinates is to directly edit the map scale box at the bottom of the screen.

## Managing Map Layers

Each time you import a set of vectors, an image, or a data grid into the Map Viewer, the new data is stored in a new map layer. The layers form an ordered stack. Each layer is listed as an item in the **Layers** menu, with its position in the menu indicating its position in the stack.

When you import a new layer, the Map Viewer automatically places it at the top of the layer stack. To reposition a layer in the stack, select it in the **Layers** menu, slide right, and select **To Top**, **To Bottom**, **Move Up**, or **Move Down** from the pop-up submenu.

The vector features or raster in a given layer obscure coincident elements of any underlying layers. To control layers that are obscuring one another, you can also toggle layer visibility on and off. Use the item

**Visible** in the slide-right menu. Or, simply remove a layer from the Map Viewer via the **Remove** item in the slide-right menu. Remember that even if a layer's visibility is *on*, the layer does not appear if its contents are located completely outside the current display limits or are obscured by another layer.

## Symbolizing Vector Features

When point, line, and polygon layers are loaded, the Map Viewer initializes their graphics properties as follows:

Geometry	Properties
Point (line objects)	LineStyle = 'none' Marker = 'x' MarkerEdgeColor = <randomly generated value> MarkerFaceColor = 'none'
Line (line objects)	Color = <randomly generated value> LineStyle = '-' Marker = 'none'
Polygon (patch objects)	EdgeColor = [0 0 0] FaceColor = <randomly generated value>

To override symbolism defaults for a vector layer, use `makesymbolspec` to create a symbol specification in the workspace. A `symbolspec` contains a set of rules for setting vector graphics properties based on the values of feature attributes. For instance, if you have a line layer representing roads of various classes (e.g., major highway, secondary road, etc.), you can create a `symbolspec` to use a different color, line width, or line style for each road class. See the `makesymbolspec` help for examples and to learn how to construct a `symbolspec`. If you regularly work with data sets sharing a common set of feature attributes, you might want to save one or more `symbolspec`s in a MAT-file (or save calls to `makesymbolspec` in a MATLAB program file).

Once you have a `symbolspec` in your workspace, select your vector layer in the **Layers** menu, then slide right and click **Set Symbol Spec**,

which opens a dialog box. Use the dialog box to select the symbolspec from your workspace.

## Getting Information About Vector Features

The **Datatip** tool and the **Info** tool provide different ways to check the attributes of vector features that you select graphically. Before using either tool you must designate one of your vector layers as *active*. (The default active layer is the first one that you imported.) Either use the **Active Layer** drop-down menu at the bottom of your screen or select the layer in the **Layers** menu, slide right, and select **Active**. Having a designated active layer ensures that when you click a feature you don't inadvertently select an overlapping feature from a different layer.

- **Datatip tool:** The **Datatip** tool displays a feature attribute in a text label each time you click a vector feature. By default the attribute is the first one in the layer's attribute list. To change which attribute is used, select the layer in the **Layers** menu, slide right, and click **Set Layer Attribute**. In the dialog that follows, select a different attribute, or **Index**. If you choose **Index**, the Map Viewer displays the one-based index value corresponding to a given feature—based on its position in the input file or workspace array. To remove a text label, right-click it and choose **Delete datatip** from the context menu. Or choose **Delete all datatips** from the context menu or the **Tools** menu.
- **Info tool:** The **Info** tool opens a separate text window each time you click a vector feature. The window displays all the attribute names and values for that feature, in contrast to the **Datatip** tool, which displays only the value of a single attribute. If you need to compare two or more features, simply click each one and view the info windows together. Use its close button to close an info window when you're done with it, or choose **Close All Info Windows** from the **Tools** menu.

## Annotating Your Map

Use the **text**, **line**, or **arrow** annotation tools to mark and highlight points of interest on your map, or select the corresponding items in the **Insert** menu. Note that to insert an additional object of the same type, you must reselect the appropriate tool. In addition, the **Insert** menu

allows you to insert axis labels and a title. Use the **Select annotations** tool and **Edit** menu to modify or remove your annotations. The Map Viewer manages annotations separately from data layers; annotations always stay on top. Note that annotations cannot be saved as graphic objects, although you can export maps containing annotations to an image format as described below.

## Creating and Using Additional Views

Use **New View** on the **File** menu to create an additional Map Viewer window linked to an existing window. Consider using an additional window when you want to see your map at different scales at the same time (e.g., a detailed view plus an overview), or when you want to simultaneously see different areas of the map at large scale. You can create as many additional windows as you need, and close them when you want. Your `mapview` session ends when you close the last window.

Options for creating a new viewer window include: **Duplicate Current View**, **Full Extent**, **Full Extent of Active Layer**, and **Selected Area**. Click and drag with the **Select area** tool to define a selected area.

A new viewer window differs from existing windows mainly in terms of the visible map extent and scale (it also omits annotations and any labels you added with the `datatip` tool). You will see the same layers in the same order with the same settings (including the active layer). Updates to layers (insertion/removal, order, visibility, label attribute, and symbolization) in one viewer window are propagated automatically to all the windows with which it is linked. Updates to annotations and `datatip` labels are not propagated between viewers. If you need two different layer configurations in different windows, launch a second `mapview` from the command line instead of creating an additional window. The views it contains will not be linked to previous ones.

## Exporting Your Map

The Map Viewer allows you to export all or part of your map for use in a publication or on a Web page. Use **File > Save As Raster Map** to export an image of either the current display extent or an area outlined with the **Select area** tool. Select a format (PNG, TIFF, JPEG) from the drop-down menu in the export dialog. For maps including vector layers, PNG (Portable Network Graphics) is often the best choice. This format provides excellent quality, good compression, and is well supported

by modern Web browsers. The export process automatically creates a world file (ending with suffix `tfw`, `jgw`, or `pgw`) as well; the pair of files constitute a georeferenced image that itself can be displayed with `mapview`, `mapshow`, and many external GIS packages.

## **See Also**

`arcgridread`, `geoshow`, `geotiffread`, `makesymbolspec`, `mapshow`,  
`sdtsemread`, `shaperead`, `updategeostruct`, `worldfileread`



**Purpose** Display contours of constant map distortion

**Syntax**

```
mdistort
mdistort off
mdistort(parameter)
mdistort parameter
mdistort(parameter,levels)
mdistort(parameter,levels,gsize)
h = mdistort(...)
```

**Description** `mdistort`, with no input arguments, toggles the display of contours of projection-induced distortion on the current map axes. The magnitude of the distortion is reported in percent.

`mdistort off` removes the contours.

`mdistort(parameter)` or `mdistort parameter` displays contours of distortion for the specified parameter. Recognized *parameter* strings are 'area', 'angles' for the maximum angular distortion of right angles, 'scale' or 'maxscale' for the maximum scale, 'minscale' for the minimum scale, 'parscale' for scale along the parallels, 'merscale' for scale along the meridians, and 'scaleratio' for the ratio of maximum and minimum scale. If omitted, the 'maxscale' parameter is displayed. All parameters are displayed as percent distortion except angles, which are displayed in degrees.

`mdistort(parameter,levels)` specifies the levels for which the contours are drawn. *levels* is a vector of values as used by `contour`. If empty, the default levels are used.

`mdistort(parameter,levels,gsize)` controls the size of the underlying graticule matrix used to compute the contours. *gsize* is a two-element vector containing the number of rows and columns. If omitted, the default Mapping Toolbox graticule size of [50 100] is assumed.

`h = mdistort(...)` returns a handle to the `contourgroup` object containing the contours and text.

## Background

Map projections inevitably introduce distortions in the shape and size of objects as they are transformed from three-dimensional spherical coordinates to two-dimensional Cartesian coordinates. The amount and type of distortion vary between projections, over the projection, and with the selection of projection parameters such as standard parallels. This function provides a quantitative graphical display of distortion parameters.

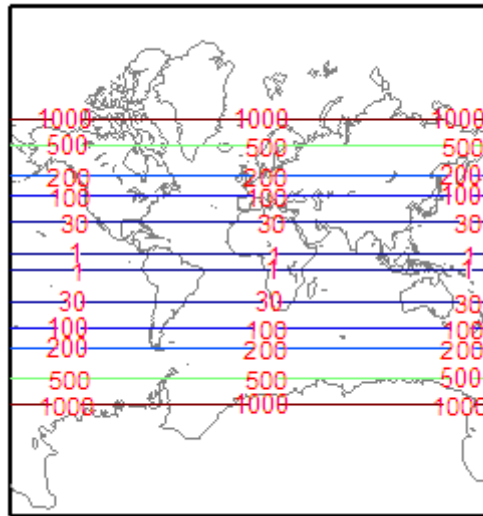
`mdistort` is not intended for use with UTM. Distortion is minimal within a given UTM zone. `mdistort` issues a warning if a UTM projection is encountered.

## Examples

### Example 1

Note the extreme area distortion of the Mercator projection. This makes it ill-suited for global displays.

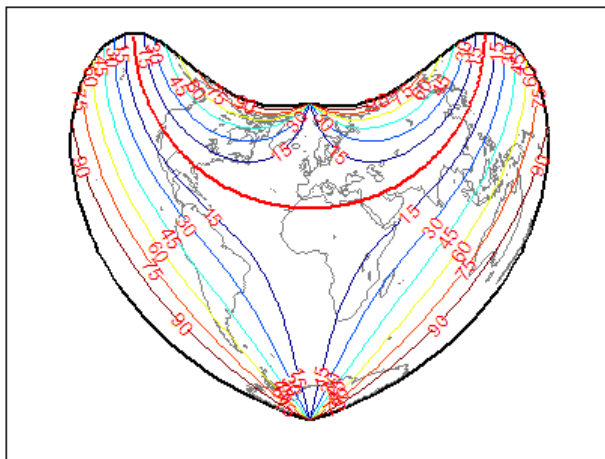
```
figure
axesm mercator
load coast
framem;
plotm(lat, long, 'color', .5*[1 1 1])
mdistort('area', [1 30 100 200 500 1000])
```



## Example 2

The lines of zero distortion for the Bonne projection follow the central meridian and the standard parallel.

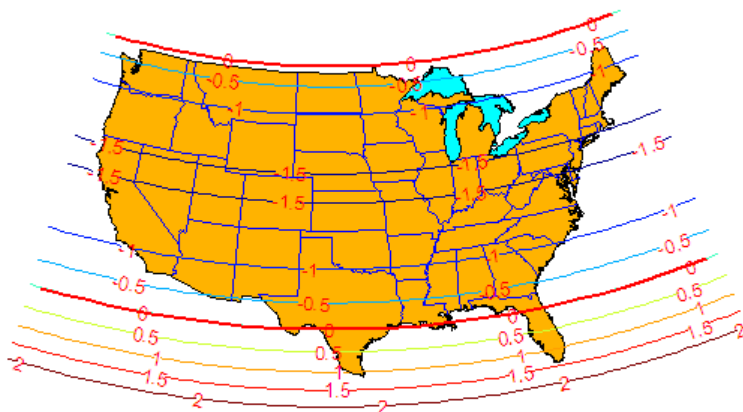
```
figure
axesm bonne
load coast
framem;plotm(lat, long,'color',.5*[1 1 1])
mdistort('angles', 0:15:90)
parallelui
```



### Example 3

An equidistant conic projection with properly chosen parallels can map the conterminous United States with less than 1.5% distortion.

```
figure
usamap conus
load conus
patchm(uslat, uslon, [1 0.7 0])
plotm(statelat, statelon)
patchm(gtlakelat, gtlakelon, 'cyan')
framem off; gridm off; mlabel off; plabel off
mdistort('parscale', -2:.5:2)
parallelui
```



**Remarks**

mdistort can help in the placement of standard parallels for projections. Standard parallels are generally placed to minimize distortion over the region of interest. The default parallel locations might not be appropriate for maps of smaller regions. By using mdistort and parallelui, you can immediately see how the movement of parallels reduces distortion.

**See Also**

tissot, distortcalc, vfwdtran

# meanm

---

**Purpose** Mean location of geographic coordinates

**Syntax**

```
[latmean,lonmean] = meanm(lat,lon)
[latmean,lonmean] = meanm(lat,lon,units)
[latmean,lonmean] = meanm(lat,lon,ellipsoid)
```

**Description**

[latmean,lonmean] = meanm(lat,lon) returns row vectors of the geographic mean positions of the columns of the input latitude and longitude points.

[latmean,lonmean] = meanm(lat,lon,units) indicates the angular units of the data. When the standard angle string *units* is omitted, 'degrees' is assumed.

[latmean,lonmean] = meanm(lat,lon,ellipsoid) specifies the elliptical definition of the Earth to be used with the two-element ellipsoid vector. The default ellipsoid model is a spherical Earth, which is sufficient for most applications.

If a single output argument is used, then `geomeans = [latmean,longmean]`. This is particularly useful if the original `lat` and `lon` inputs are column vectors.

**Background** Finding the mean position of geographic points is more complicated than simply averaging the latitudes and longitudes. `meanm` determines mean position through three-dimensional vector addition. See “Geographic Statistics” in the *Mapping Toolbox User’s Guide*.

**Examples** Create random latitude and longitude matrices:

```
lat = rand(3)

lat =
    0.9501    0.4860    0.4565
    0.2311    0.8913    0.0185
    0.6068    0.7621    0.8214

lon = rand(3)
```

```
lon =
  0.4447    0.9218    0.4057
  0.6154    0.7382    0.9355
  0.7919    0.1763    0.9169

[latmean,lonmean] = meanm(lat,lon,'radians')

latmean =
  0.6004    0.7395    0.4448
lonmean =
  0.6347    0.6324    0.7478
```

**See Also**

filterm, hista, histr, stdist, stdm

# meridianarc

---

**Purpose** Ellipsoidal distance along meridian

**Syntax** `s = meridianarc(phi1,phi2,ellipsoid)`

**Description** `s = meridianarc(phi1,phi2,ellipsoid)` calculates the (signed) distance `s` between latitudes `phi1` and `phi2` along a meridian on the ellipsoid defined by the 1-by-2 vector `ellipsoid`. Latitudes `phi1` and `phi2` are in radians. The distance `s` has the same units as the semimajor axis of the ellipsoid. If `phi2` is less than `phi1`, `s` is negative.

**See Also** `meridianfwd`



**Purpose** Reckon position along meridian

**Syntax** `phi2 = meridianfwd(phi1,s,ellipsoid)`

**Description** `phi2 = meridianfwd(phi1,s,ellipsoid)` determines the geodetic latitude `phi2` reached by starting at geodetic latitude `phi1` and traveling distance `s` north (positive `s`) or south (negative `s`) along a meridian on the specified `ellipsoid`. Latitudes `phi1` and `phi2` are in radians, and `s` has the same units as the semimajor axis of the ellipsoid.

**See Also** `meridianarc`

# meshgrat

---

**Purpose** Construct map graticule for surface object display

**Syntax**

```
[lat, lon] = meshgrat(Z, R)
[lat, lon] = meshgrat(Z, R, gratsize)
[lat,lon] = meshgrat(lat,lon)
[lat,lon] = meshgrat(latlim,lonlim,gratsize)
[lat,lon] = meshgrat(lat,lon,angleunits)
[lat,lon] = meshgrat(latlim,lonlim,angleunits)
[lat,lon] = meshgrat(latlim,lonlim,gratsize,angleunits)
```

**Description** [lat, lon] = meshgrat(Z, R) constructs a graticule for use in displaying a regular data grid, Z. In typical usage, a latitude-longitude graticule is projected, and the grid is warped to the graticule using MATLAB graphics functions. In this two-argument calling form, the graticule size is equal to the size Z. R is either a 1-by-3 vector containing elements:

```
[cells/degree northern_latitude_limit western_longitude_limit]
```

or a 3-by-2 referencing matrix that transforms raster row and column indices to/from geographic coordinates according to:

```
[lon lat] = [row col 1] * R
```

If R is a referencing matrix, it must define a (non-rotational, non-skewed) relationship in which each column of the data grid falls along a meridian and each row falls along a parallel.

[lat, lon] = meshgrat(Z, R, gratsize) produces a graticule of size gratsize. gratsize is a two-element vector of the form [number\_of\_parallels number\_of\_meridians]. If gratsize = [], then the graticule returned has the default size 50-by-100. (But if gratsize is omitted, a graticule of the same size as Z is returned.) A finer graticule uses larger arrays and takes more memory and time but produces a higher fidelity map.

`[lat,lon] = meshgrat(lat,lon)` takes the vectors `lat` and `lon` and returns graticule arrays of size `numel(lat)`-by-`numel(lon)`. In this form, `meshgrat` is similar to the MATLAB function `meshgrid`.

`[lat,lon] = meshgrat(latlim,lonlim,gratsize)` returns a graticule mesh of size `gratsize` that covers the geographic limits defined by the two-element vectors `latlim` and `lonlim`.

`[lat,lon] = meshgrat(lat,lon,angleunits)`,  
`[lat,lon] = meshgrat(latlim,lonlim,angleunits)`, and  
`[lat,lon] = meshgrat(latlim,lonlim,gratsize,angleunits)` use the string `angleunits` to specify the angle units of the inputs and outputs. The string `angleunits` can be either `'degrees'` (the default) or `'radians'`.

The graticule mesh is a grid of points that are projected on a map axes and to which surface map objects are warped. The fineness, or resolution, of this grid determines the quality of the projection and the speed of plotting. There is no hard and fast rule for sufficient graticule resolution, but in general, cylindrical projections need very few graticules in the longitudinal direction, while complex curve-generating projections require more.

## Examples

Make a (coarse) graticule for the entire world:

```
latlim = [-90 90];
lonlim = [-180 180];
[lat,lon] = meshgrat(latlim,lonlim,[3 6])

lat =
  -90.0000  -90.0000  -90.0000  -90.0000  -90.0000  -90.0000
         0         0         0         0         0         0
   90.0000   90.0000   90.0000   90.0000   90.0000   90.0000
lon =
 -180.0000 -108.0000 -36.0000   36.0000  108.0000  180.0000
 -180.0000 -108.0000 -36.0000   36.0000  108.0000  180.0000
 -180.0000 -108.0000 -36.0000   36.0000  108.0000  180.0000
```

# meshgrat

---

These paired coordinates are the graticule vertices, which are projected according to the requirements of the desired map projection. Then a surface object like the topo map can be warped to the grid.

## See Also

meshgrid, meshm, surfacem, surfm

**Purpose** 3-D lighted shaded relief of regular data grid

**Syntax**

```
meshlstrm(Z,R)
meshlstrm(Z,R,[azim elev])
meshlstrm(Z,R,[azim elev],cmap)
meshlstrm(Z,R,[azim elev],cmap,clim)
h = meshlstrm(...)
```

**Description** `meshlstrm(Z,R)` displays the regular data grid `Z` colored according to elevation and surface slopes. By default, shading is based on a light to the east (90°) at an elevation of 45 degrees. Also by default, the colormap is constructed from 16 colors and 16 grays. Lighting is applied before the data is projected. The current axes must have a valid map projection definition. `R` is either a 1-by-3 vector containing elements:

```
[cells/degree northern_latitude_limit western_longitude_limit]
```

or a 3-by-2 referencing matrix that transforms raster row and column indices to/from geographic coordinates according to:

```
[lon lat] = [row col 1] * R
```

If `R` is a referencing matrix, it must define a (non-rotational, non-skewed) relationship in which each column of the data grid falls along a meridian and each row falls along a parallel.

`meshlstrm(Z,R,[azim elev])` displays the regular data grid `Z` with the light coming from the specified azimuth and elevation. Angles are specified in degrees, with the azimuth measured clockwise from North, and elevation up from the zero plane of the surface.

`meshlstrm(Z,R,[azim elev],cmap)` displays the regular data grid `Z` using the specified colormap. The number of grayscales is chosen to keep the size of the shaded colormap below 256. If the vector of azimuth and elevation is empty, the default locations are used. Color axis limits are computed from the data.

`meshlstrm(Z,R,[azim elev],cmap,clim)` uses the provided color axis limits, which by default are computed from the data.

# meshlsrcm

---

`h = meshlsrcm(...)` returns the handle to the surface drawn.

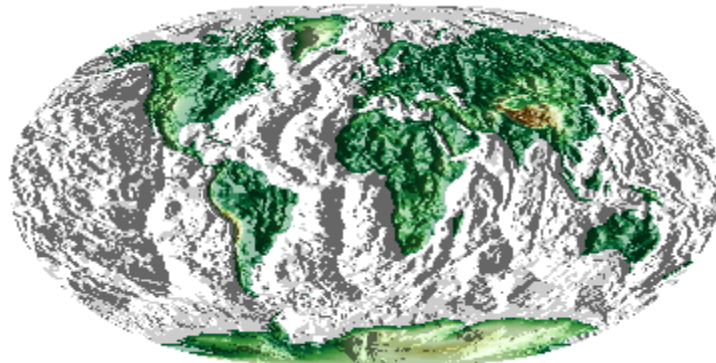
## Remarks

This function effectively multiplies two colormaps, one with color based on elevation, the other with a grayscale based on the slope of the surface, to create a new colormap. This produces an effect similar to using a light on a surface, but with all of the visible colors actually in the colormap. Lighting calculations are performed on the unprojected data.

## Examples

Create a new colormap using `demcmap`, with white colors for the sea and default colors for land. Use this colormap for a lighted shaded relief map of the world.

```
load topo
[cmap,clim] = demcmap(topo,[],[1 1 1],[]);
axesm loximuth
meshlsrcm(topo,topolegend,[],cmap,clim)
```



## See Also

`meshgrat`, `meshm`, `pcolorm`, `surfacem`, `surflm`, `surflsrcm`

**Purpose**

Project regular data grid on map axes

**Syntax**

```
meshm(Z, R)
meshm(Z, R, gratsize)
meshm(Z, R, gratsize, alt)
meshm(..., param1, val1, param2, val2, ...)
H = meshm(...)
```

**Description**

`meshm(Z, R)` will display the regular data grid `Z` warped to the default projection graticule. `R` is either a 1-by-3 vector containing elements:

```
[cells/degree northern_latitude_limit western_longitude_limit]
```

or a 3-by-2 referencing matrix that transforms raster row and column indices to/from geographic coordinates according to:

$$[\text{lon lat}] = [\text{row col 1}] * R$$

If `R` is a referencing matrix, it must define a (non-rotational, non-skewed) relationship in which each column of the data grid falls along a meridian and each row falls along a parallel. The current axes must have a valid map projection definition.

`meshm(Z, R, gratsize)` displays a regular data grid warped to a graticule mesh defined by the 1-by-2 vector `gratsize`. `gratsize(1)` indicates the number of lines of constant latitude (parallels) in the graticule, and `gratsize(2)` indicates the number of lines of constant longitude (meridians).

`meshm(Z, R, gratsize, alt)` displays the regular surface map at the altitude specified by `alt`. If `alt` is a scalar, then the grid is drawn in the  $z = \text{alt}$  plane. If `alt` is a matrix, then `size(alt)` must equal `gratsize`, and the graticule mesh is drawn at the altitudes specified by `alt`. If the default graticule is desired, set `gratsize = []`.

`meshm(..., param1, val1, param2, val2, ...)` uses optional parameter name-value pairs to control the properties of the surface object constructed by `meshm`. (If data is placed in the `UserData` property

# meshm

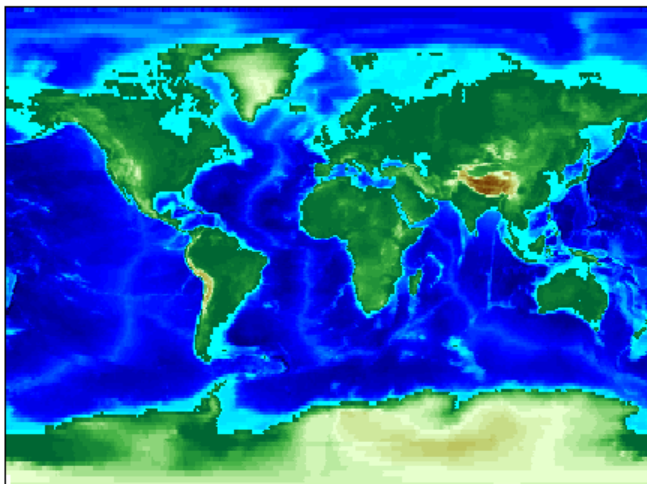
---

of the surface, then the projection of this object can not be altered once displayed.)

H = meshm(...) returns the handle to the surface drawn.

## Example

```
load topo
axesm miller
meshm(topo,topolegend,[90 180])
demcmap(topo)
tightmap
```



## See Also

geoshow, mapshow, meshgrat, pcolorm, surfacem, surfm



**Purpose**

Project geographic features to map coordinates

**Syntax**

```
[x,y] = mfwdtran(lat,lon)
[x,y,z] = mfwdtran(lat,lon,alt)
[...] = mfwdtran(mstruct,...)
```

**Description**

[x,y] = mfwdtran(lat,lon) applies the forward transformation defined by the map projection in the current map axes. You can use this function to convert point locations and line and polygon vertices given in latitudes and longitudes to a planar, projected map coordinate system.

[x,y,z] = mfwdtran(lat,lon,alt) applies the forward projection to 3-D input, resulting in 3-D output. If the input alt is empty or omitted, then alt = 0 is assumed.

[...] = mfwdtran(mstruct,...) requires a valid map projection structure as the first argument. In this case, no map axes is needed.

**Examples**

The following latitude and longitude data for the District of Columbia is obtained from the usastatelo demo shapefile:

```
dc = shaperead('usastatelo', 'UseGeoCoords', true,...
    'Selector',{@(name) strcmpi(name,'District of Columbia'),...
    'Name'});
lat = [dc.Lat]';
lon = [dc.Lon]';
[lat lon]

ans =
    38.9000 -77.0700
    38.9500 -77.1200
    39.0000 -77.0300
    38.9000 -76.9000
    38.7800 -77.0300
    38.8000 -77.0200
    38.8700 -77.0200
    38.9000 -77.0700
    38.9000 -77.0500
```

```
38.9000 -77.0700
      NaN      NaN
```

Before projecting the data, it is necessary to define projection parameters. You can do this with the `axesm` function or with the `defaultm` function:

```
mstruct = defaultm('mercator');
mstruct.origin = [38.89 -77.04 0];
mstruct = defaultm(mstruct);
```

Now that the projection parameters have been set, transform the District of Columbia data into map coordinates using the Mercator projection:

```
[x,y] = mfwdtran(mstruct,lat,lon);
[x y]
```

```
ans =
-0.0004    0.0002
-0.0011    0.0010
 0.0001    0.0019
 0.0019    0.0002
 0.0001   -0.0019
 0.0003   -0.0016
 0.0003   -0.0003
-0.0004    0.0002
-0.0001    0.0002
-0.0004    0.0002
      NaN      NaN
```

## See Also

`defaultm`, `gcm`, `minvtran`, `projfwd`, `projinv`, `vfwdtran`, `vinvtran`

**Purpose** Semiminor axis of ellipse given semimajor axis and eccentricity

**Syntax** `semiminor = minaxis(semimajor, eccentricity)`  
`semiminor = minaxis([semimajor, eccentricity])`

**Description** `semiminor = minaxis(semimajor, eccentricity)` returns the semiminor axis length corresponding to the input semimajor axis and eccentricity.

`semiminor = minaxis([semimajor, eccentricity])` allows the inputs to be packed into a single two-column input of the form `[semimajor, eccentricity]`.

The semiminor axis can be determined given both the semimajor axis and the eccentricity, the two elements of a standard Mapping Toolbox ellipsoid vector.

**Examples** Using the default values for the Earth,

```
semiminor = minaxis(almanac('earth', 'ellipsoid'))  
semiminor =  
    6.3568e+03
```

**See Also** `almanac`, `axes2ecc`, `majaxis`

# minvtran

---

**Purpose** Unproject features from map to geographic coordinates

**Syntax**

```
[lat,lon] = minvtran(x,y)
[lat,lon,alt] = minvtran(x,y,z)
[...] = minvtran(mstruct,...)
```

**Description** [lat,lon] = minvtran(x,y) applies the inverse transformation defined by the map projection in the current map axes. Using minvtran, you can convert point locations and line and polygon vertices in a planar, projected map coordinate system to latitudes and longitudes.

[lat,lon,alt] = minvtran(x,y,z) applies the inverse projection to 3-D input, resulting in 3-D output. If the input Z is empty or omitted, then Z = 0 is assumed.

[...] = minvtran(mstruct,...) takes a valid map projection structure as the first argument. In this case, no map axes is needed.

**Examples** Before using any transformation functions, it is necessary to create a map projection structure. You can do this with axesm or the defaultm function:

```
mstruct = defaultm('mercator');
mstruct.origin = [38.89 -77.04 0];
mstruct = defaultm(mstruct);
```

The following latitude and longitude data for the District of Columbia is obtained from the usastatelo shapefile:

```
dc = shaperead('usastatelo', 'UseGeoCoords', true,...
    'Selector',{@(name) strcmpi(name,'District of Columbia')},...
    'Name'});
lat = [dc.Lat]';
lon = [dc.Lon]';
[lat lon]

ans =
    38.9000  -77.0700
```

```

38.9500 -77.1200
39.0000 -77.0300
38.9000 -76.9000
38.7800 -77.0300
38.8000 -77.0200
38.8700 -77.0200
38.9000 -77.0700
38.9000 -77.0500
38.9000 -77.0700
      NaN      NaN

```

This data can be projected into Cartesian coordinates of the Mercator projection using the `mfwdtran` function:

```

[x,y] = mfwdtran(mstruct,lat,lon);
[x y]

```

```

ans =
-0.0004    0.0002
-0.0011    0.0010
 0.0001    0.0019
 0.0019    0.0002
 0.0001   -0.0019
 0.0003   -0.0016
 0.0003   -0.0003
-0.0004    0.0002
-0.0001    0.0002
-0.0004    0.0002
      NaN      NaN

```

To transform the projected  $x$ - $y$  data back into the unprojected geographic system, use the `minvtran` function:

```

[lat2,lon2] = minvtran(mstruct,x,y);
[lat2 lon2]

```

```

ans =
38.9000 -77.0700

```

# minvtran

---

```
38.9500 -77.1200
39.0000 -77.0300
38.9000 -76.9000
38.7800 -77.0300
38.8000 -77.0200
38.8700 -77.0200
38.9000 -77.0700
38.9000 -77.0500
38.9000 -77.0700
      NaN      NaN
```

## See Also

axesm, defaultm, gcm, mfwdtran, projfwd, projinv, vfwdtran,  
vinvtran

---

<b>Purpose</b>	Toggle and control display of meridian labels
<b>Syntax</b>	<pre>mlabel mlabel('on') mlabel('off') mlabel('reset') mlabel(parallel) mlabel(<i>MapAxesPropertyName</i>,<i>PropertyValue</i>,...)</pre>
<b>Description</b>	<p>mlabel toggles the visibility of meridian labeling on the current map axes.</p> <p>mlabel('on') sets the visibility of meridian labels to 'on'.</p> <p>mlabel('off') sets the visibility of meridian labels to 'off'.</p> <p>mlabel('reset') resets the displayed meridian labels using the currently defined meridian label properties.</p> <p>mlabel(parallel) sets the value of the MLabelParallel property of the map axes to the value of parallel. This determines the parallel upon which the labels are placed (see axesm). The options for parallel are a scalar latitude or the strings 'north', 'south', or 'equator'.</p> <p>mlabel(<i>MapAxesPropertyName</i>,<i>PropertyValue</i>,...) allows paired map axes' property names and property values to be passed in. For a complete description of map axes properties, see the axesm reference page in this guide.</p> <p>Meridian label handles can be returned in h if desired.</p>
<b>See Also</b>	axesm, mlabelzero22pi, plabel, setm

# mlabelzero22pi

---

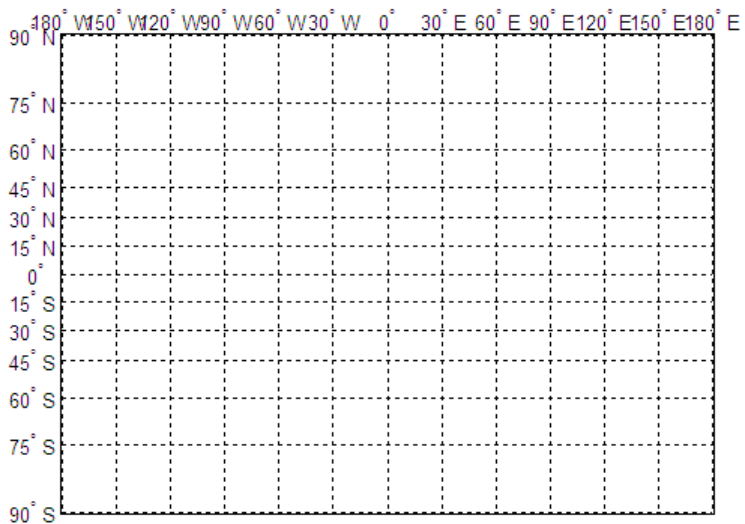
**Purpose** Convert meridian labels to 0-360 degree range

**Syntax** mlabelzero22pi

**Description** mlabelzero22pi displays longitude labels in the range of 0 to 360 degrees east of the prime meridian.

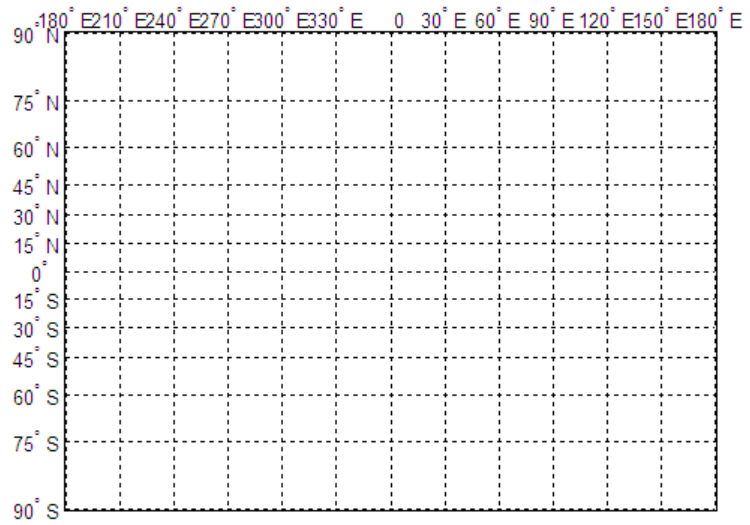
**Example**

```
% create a map
figure('color','w'); axesm('miller','grid','on'); tightmap;
mlabel on; plabel on
```



```
% Display longitude labels in the range of 0 to 360 degrees
mlabelzero22pi
```





## See Also

`mlabel`

**Purpose** Eccentricity of ellipse with given n-value

**Syntax** `eccentricity = n2ecc(n)`

**Description** `eccentricity = n2ecc(n)` returns the equivalent eccentricities for the input  $n$  parameters. If the input  $n$  is a two-column vector, only the second column is used. This allows two-element vectors to be used as rows of the input, because the form [semimajor-axis,  $n$ ] is a complete representation of an ellipsoid (but is not the standard form for Mapping Toolbox ellipsoid vectors). In all other cases, all columns of the input are used.

Eccentricity and the parameter  $n$  are two methods of defining an ellipsoid. The definition of  $n$  is

$$\frac{(\text{semimajor axis} - \text{semiminor axis})}{(\text{semimajor axis} + \text{semiminor axis})}$$

**Example** `ecc = n2ecc(0.00167922039463)`

```
ecc =  
    0.08181919104285
```

This eccentricity is the default value for the Earth.

**See Also** `almanac`, `ecc2flat`, `majaxis`, `ecc2n`

**Purpose** Determine names of valid graphics objects

**Syntax** `objects = namem`  
`objects = namem(handles)`

**Description** `objects = namem` returns the object names for all objects on the current axes. The object name is defined as its tag, if the object `Tag` property is supplied. Otherwise, it is the object `Type`. Duplicate object names are removed from the output string matrix.

`objects = namem(handles)` returns the object names for the objects specified by the input `handles`.

The names returned are either set at object creation or defined by the user with the `tagm` function.

**See Also** `clma`, `clmo`, `handlem`, `hidem`, `showm`, `tagm`

# nanclip

---

**Purpose** Clip vector data with NaNs at specified pen-down locations

**Syntax**  
`dataout = nanclip(datain)`  
`dataout = nanclip(datain,pendowncmd)`

**Description** `dataout = nanclip(datain)` and `dataout = nanclip(datain,pendowncmd)` return the pen-down delimited data in the matrix `datain` as NaN-delimited data in `dataout`. When the first column of `datain` equals `pendowncmd`, a segment is started and a NaN is inserted in all columns of `dataout`. The default `pendowncmd` is `-1`.

Pen-down delimited data is a matrix with a first column consisting of pen commands. At the beginning of each segment in the data, this first column has an entry corresponding to a pen-down command. Other entries indicate that the segment is continuing. NaN-delimited data consists of columns of data, each segment of which ends in a NaN in every data column. Since there is no pen command column, the NaN-delimited format can represent the same data in one fewer columns; the remaining columns have more entries, one for each NaN (that is, for each segment).

## Examples

```
datain = [-1 45 67; 0 23 54; 0 28 97; -1 47 89; 0 56 12]
```

```
datain =  
    -1    45    67           % Begin first segment  
     0    23    54  
     0    28    97  
    -1    47    89           % Begin second segment  
     0    56    12
```

```
dataout = nanclip(datain)
```

```
dataout =  
    45    67  
    23    54  
    28    97  
   NaN   NaN           % End first segment  
    47    89
```

```
56 12  
NaN NaN % End second segment
```

**See Also** `spread`

# nanm

---

**Purpose** Construct regular data grid of NaNs

**Syntax** `[Z,refvec] = nanm(latlim,lonlim,scale)`

**Description** `[Z,refvec] = nanm(latlim,lonlim,scale)` returns a regular data grid consisting entirely of NaNs and a three-element referencing vector for the returned Z. The two-element vectors `latlim` and `lonlim` define the latitude and longitude limits of the geographic region. They should be of the form `[south north]` and `[west east]`, respectively. The scalar `scale` specifies the number of rows and columns per degree of latitude and longitude.

**Example** `[Z,refvec] = nanm([46,51],[-79,-75],1)`

```
Z =
    NaN    NaN    NaN    NaN
    NaN    NaN    NaN    NaN
    NaN    NaN    NaN    NaN
    NaN    NaN    NaN    NaN
    NaN    NaN    NaN    NaN
refvec =
     1    51   -79
```

**See Also** `limitm`, `onem`, `sizem`, `spzerom`, `zerom`

**Purpose**

Mercator-based navigational fix

**Syntax**

```
[latfix,lonfix] = navfix(lat,long,az)
[latfix,lonfix] = navfix(lat,long,range,casetype)
[latfix,lonfix] = navfix(lat,long,az_range,casetype)
[latfix,lonfix] = navfix(lat,long,az_range,casetype,drlat,
    drlon)
```

**Description**

`[latfix,lonfix] = navfix(lat,long,az)` returns the intersection points of rhumb lines drawn parallel to the observed bearings, `az`, of the landmarks located at the points `lat` and `long` and passing through these points. One bearing is required for each landmark. Each possible pairing of the  $n$  landmarks generates one intersection, so the total number of resulting intersection points is the combinatorial  $n \text{ choose } 2$ . The calculation time therefore grows rapidly with  $n$ .

`[latfix,lonfix] = navfix(lat,long,range,casetype)` returns the intersection points of Mercator projection circles with radii defined by `range`, centered on the landmarks located at the points `lat` and `long`. One range value is required for each landmark. Each possible pairing of the  $n$  landmarks generates up to two intersections (circles can intersect twice), so the total number of resulting intersection points is the combinatorial  $2 \text{ times } (n \text{ choose } 2)$ . The calculation time therefore grows rapidly with  $n$ . In this case, the variable `casetype` is a vector of 0s the same size as the variable `range`.

`[latfix,lonfix] = navfix(lat,long,az_range,casetype)` combines ranges and bearings. For each element of `casetype` equal to 1, the corresponding element of `az_range` represents an azimuth to the associated landmark. Where `casetype` is a 0, `az_range` is a range.

`[latfix,lonfix] = navfix(lat,long,az_range,casetype,drlat,drlon)` returns for each possible pairing of landmarks only the intersection that lies closest to the dead reckoning position indicated by `drlat` and `drlon`. When this syntax is used, all included landmarks' bearing lines or range arcs must intersect. If any possible pairing fails, the warning `No Fix` is displayed.

## Background

This is a navigational function. It assumes that all latitudes and longitudes are in degrees and all distances are in nautical miles. In navigation, piloting is the practice of fixing one's position based on the observed bearing and ranges *to* fixed landmarks (points of land, lighthouses, smokestacks, etc.) *from* the navigator's vessel. In conformance with navigational practice, bearings are treated as rhumb lines and ranges are treated as the radii of circles on a Mercator projection.

In practice, at least three azimuths (bearings) and/or ranges are required for a usable fix. The resulting intersections are unlikely to coincide exactly. Refer to "Navigation" in the *Mapping Toolbox User's Guide* for a more complete description of the use of this function.

## Remarks

The outputs of this function are matrices providing the locations of the intersections for all possible pairings of the  $n$  entered lines of bearing and range arcs. These matrices therefore have  $n$ -choose-2 rows. In order to allow for two intersections per combination, these matrices have two columns. Whenever there are fewer than two intersections for that combination, one or two NaNs are returned in that row.

When a dead reckoning position is included, these matrices are column vectors.

## Examples

For a fully illustrated example of the application of this function, refer to the "Navigation" section in the *Mapping Toolbox User's Guide*.

Imagine you have two landmarks, at (15°N,30.4°W) and (14.8°N,30.1°W). You have a visual bearing to the first of 280° and to the second of 160°. Additionally, you have a range to the second of 12 nm. Find the intersection points:

```
[latfix,lonfix] = navfix([15 14.8 14.8],[-30.4 -30.1 -30.1],...  
                        [280 160 12],[1 1 0])
```

```
latfix =  
    14.9591      NaN  
    14.9680    14.9208
```

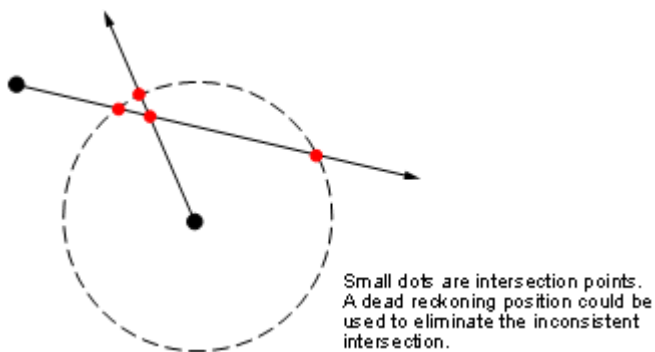


```

      14.9879      NaN
lonfix =
     -30.1599      NaN
     -30.2121  -29.9352
     -30.1708      NaN

```

Here is an illustration of the geometry:



## Limitations

Traditional plotting and the `navfix` function are limited to relatively short distances. Visual bearings are in fact great circle azimuths, not rhumb lines, and range arcs are actually arcs of small circles, not of the planar circles plotted on the chart. However, the mechanical ease of the process and the practical limits of visual bearing ranges and navigational radar ranges (~30 nm) make this limitation moot in practice. The error contributed because of these assumptions is minuscule at that scale.

## See Also

`crossfix`, `gcxgc`, `gcxsc`, `scxsc`, `rhxrh`, `polyxpoly`, `dreckon`, `gcwaypts`, `legs`, `track`

# neworig

---

**Purpose** Orient regular data grid to oblique aspect

**Syntax**

```
[Z,lat,lon] = neworig(Z0,R,origin)
[Z,lat,lon] = neworig(Z0,R,origin,'forward')
[Z,lat,lon] = neworig(Z0,R,origin,'inverse')
```

**Description** [Z,lat,lon] = neworig(Z0,R,origin) and [Z,lat,lon] = neworig(Z0,R,origin,'forward') will transform regular data grid Z0 into an oblique aspect, while preserving the matrix storage format. In other words, the oblique map origin is not necessarily at (0,0) in the Greenwich coordinate frame. This allows operations to be performed on the matrix representing the oblique map. For example, azimuthal calculations for a point in a data grid become row and column operations if the data grid is transformed so that the north pole of the oblique map represents the desired point on the globe. R is either a 1-by-3 vector containing elements:

```
[cells/degree northern_latitude_limit western_longitude_limit]
```

or a 3-by-2 referencing matrix that transforms raster row and column indices to/from geographic coordinates according to:

```
[lon lat] = [row col 1] * R
```

If R is a referencing matrix, it must define a (non-rotational, non-skewed) relationship in which each column of the data grid falls along a meridian and each row falls along a parallel.

[Z,lat,lon] = neworig(Z0,R,origin,'inverse') transforms the regular data grid from the oblique frame to the Greenwich coordinate frame.

The neworig function transforms a regular data grid into a new matrix in an altered coordinate system. An analytical use of the new matrix can be realized in conjunction with the newpole function. If a selected point is made the *north pole* of the new system, then when a new matrix is created with neworig, each row of the new matrix is a constant

distance from the selected point, and each column is a constant azimuth from that point.

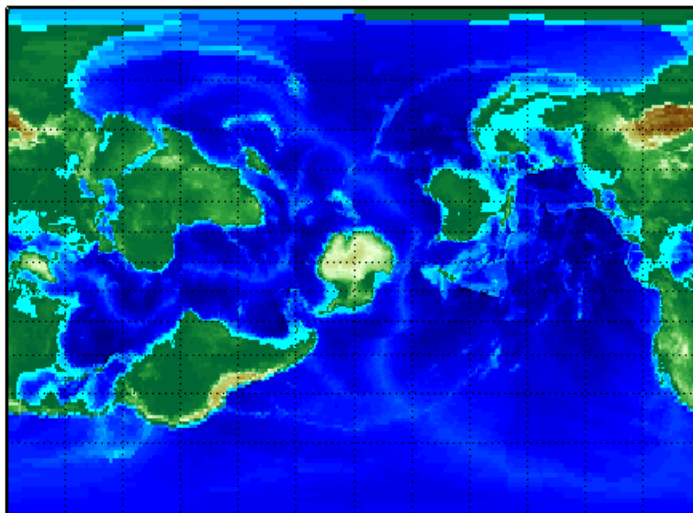
## Limitations

neworig only supports data grids that cover the entire globe.

## Example

This is the topo map transformed to put Sri Lanka at the North Pole:

```
load topo
origin = newpole(7,80)
origin =
    83.0000 -100.0000      0
[Z,lat,lon] = neworig(topo,topolegend,origin);
axesm miller
latlim = [ -90 90];
lonlim = [-180 180];
gratsize = [90 180];
[lat,lon] = meshgrat(latlim,lonlim,gratsize);
surfm(lat,lon,Z)
demcmap(topo)
tightmap
```



# neworig

---

## **See Also**

org2pol, rotatem, setpostn

<b>Purpose</b>	Origin vector to place specific point at pole
<b>Syntax</b>	<pre>origin = newpole(polelat,polelon) origin = newpole(polelat,polelon,units)</pre>
<b>Description</b>	<p><code>origin = newpole(polelat,polelon)</code> provides the origin vector for a transformed coordinate system based upon moving the point (<code>polelat</code>, <code>polelon</code>) to become the north pole singularity in the new system. The <code>origin</code> is a three-element vector of the form [<code>latitude longitude orientation</code>], where the latitude and longitude are the coordinates the new center (<code>origin</code>) had in the untransformed system, and the orientation is the azimuth of the true North Pole from the new origin point. For the <code>newpole</code> calculation, this orientation is constrained to be always 0°.</p> <p><code>origin = newpole(polelat,polelon,units)</code> specifies the units of the inputs and output, where <i>units</i> is any valid angle units string. The default is 'degrees'.</p> <p>When developing transverse or oblique projections, you need transformed coordinate systems. One way to define these systems is to establish the point in the original (untransformed) system that will become the new (transformed) <i>north pole</i>.</p>
<b>Examples</b>	<p>Take a point and make it the new North Pole:</p> <pre>origin = newpole(60,180)  origin =     30.0000         0         0</pre> <p>This makes sense: as a point 30° beyond the true North Pole on the original origin's meridian is pulled up to become the <i>pole</i>, the point originally 30° above the origin is pulled down into the origin spot.</p>
<b>See Also</b>	<code>neworig</code> , <code>org2pol</code> , <code>putpole</code>

# northarrow

---

**Purpose** Add graphic element pointing to geographic north pole

**Syntax** northarrow  
northarrow('property',value,...)

**Description** northarrow creates a default north arrow.

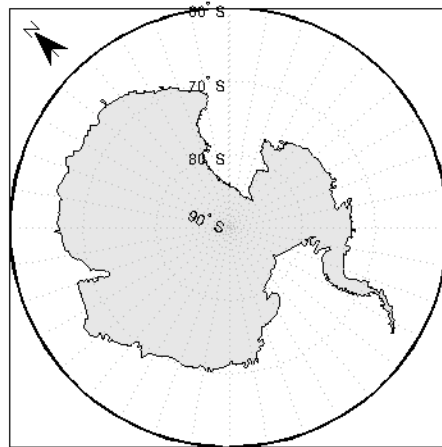
northarrow('property',value,...) creates a north arrow using the specified property/value pairs. Valid entries for properties are 'latitude', 'longitude', 'facecolor', 'edgecolor', 'linewidth', and 'scaleratio'. The 'latitude' and 'longitude' properties specify the location of the north arrow. The 'facecolor', 'edgecolor', and 'linewidth' properties control the appearance of the north arrow. The 'scaleratio' property represents the size of the north arrow as a fraction of the size of the axes. A 'scaleratio' value of 0.10 creates a north arrow one-tenth (1/10) the size of the axes. You can change the appearance ('facecolor', 'edgecolor', and 'linewidth') of the north arrow using the set command.

northarrow creates a north arrow symbol at the map origin on the displayed map. You can reposition the north arrow symbol by clicking and dragging its icon. Alternate clicking the icon creates an input dialog box that you can also use to change the location of the north arrow.

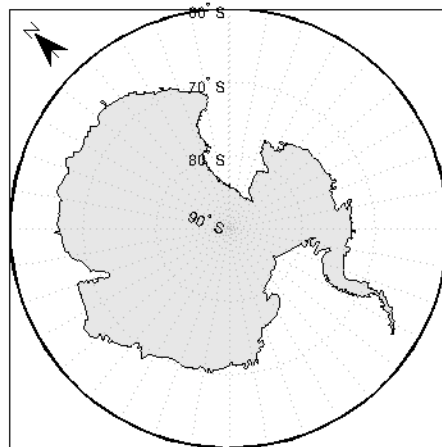
Modifying some of the properties of the north arrow results in replacement of the original object. Use HANDLEM('NorthArrow') to get the handles associated with the north arrow.

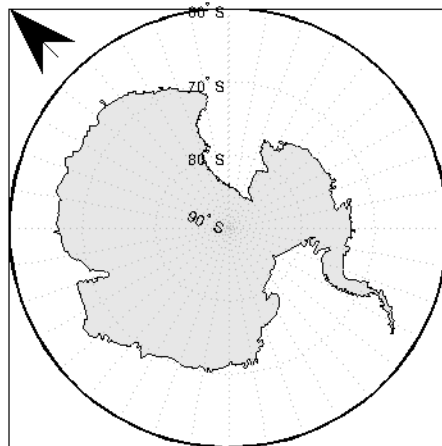
**Examples** Create a map of the South Pole and then add the north arrow in the upper left of the map.

```
Antarctica = shaperead('landareas', 'UseGeoCoords', true, ...  
    'Selector',{@(name) strcmpi(name,{'Antarctica'})}, 'Name');  
figure;  
worldmap('south pole')  
geoshow(Antarctica,'FaceColor',[.9 .9 .9])  
northarrow('latitude', -57, 'longitude', 135);
```



Right-click the north arrow icon to activate the input dialog box. Increase the size of the north arrow symbol by changing the 'ScaleRatio' property.

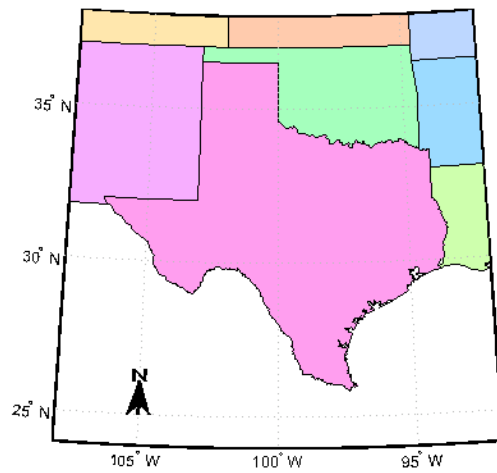




Create a map of Texas and add the north arrow in the lower left of the map.

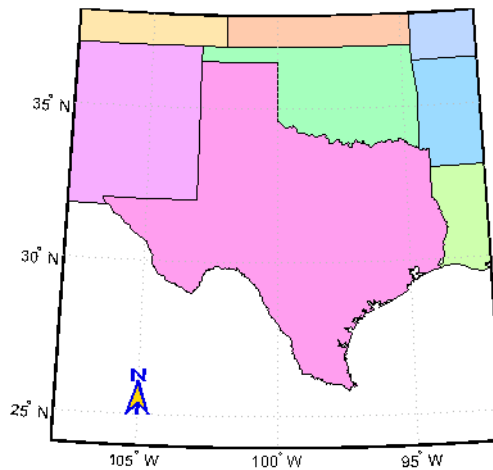
```
figure; usamap('texas')
states = shaperead('usastatelo.shp','UseGeoCoords',true);
faceColors = makesymbolspec('Polygon',...
    {'INDEX', [1 numel(states)], 'FaceColor', ...
    polcmap(numel(states))});
geoshow(states, 'DisplayType', 'polygon', ...
    'SymbolSpec', faceColors)
northarrow('latitude',25,'longitude',-105,'linewidth',1.5);
```





Change the 'FaceColor' and 'EdgeColor' properties of the north arrow.

```
h = handle('NorthArrow');  
set(h,'FaceColor',[1.000 0.8431 0.0000],...  
    'EdgeColor',[0.0100 0.0100 0.9000])
```



## Limitations

You can draw multiple north arrows on the map. However, the callbacks will only work with the most recently created north arrow. In addition, since it can be displayed outside the map frame limits, the north arrow is not converted into a “mapped” object. Hence, the location and orientation of the north arrow have to be updated manually if the map origin or projection changes.

## See Also

`scaleruler`

**Purpose** Wrap longitudes to [-180 180] degree interval

---

**Note** The `npi2pi` function has been replaced by `wrapTo180` and `wrapToPi`.

---

**Syntax**

```
anglout = npi2pi(anglin)
anglout = npi2pi(anglin,units)
anglout = npi2pi(anglin,units,method)
```

**Description** `anglout = npi2pi(anglin)` wraps the input angle `anglin` (typically representing a longitude) to lie on the range -180 to 180 (e.g.,  $270^\circ$  is renamed  $-90^\circ$ ).

`anglout = npi2pi(anglin,units)` specifies the angle units with any valid angle units string `units`. The default is 'degrees'.

`anglout = npi2pi(anglin,units,method)` allows special alternative computations to be used when `npi2pi` is called from within certain Mapping Toolbox functions. `method` can be one of the following strings:

- 'exact', for exact wrapping (the default value)
- 'inward', where angles are scaled by a factor of  $(1 - \text{epsm}('radians'))$  before wrapping
- 'outward', where angles are scaled by a factor of  $(1 + \text{epsm}('radians'))$  before wrapping

**Examples**

```
npi2pi(315)
```

```
ans =
    -45
```

```
npi2pi(181)
```

```
ans =
   -179
```

# npi2pi

---

## **See Also**

`wrapToPi`, `wrapTo180`

**Purpose** Construct regular data grid of 1s

**Syntax** `[Z,refvec] = onem(latlim,lonlim,scale)`

**Description** `[Z,refvec] = onem(latlim,lonlim,scale)` returns a regular data grid consisting entirely of 1s and a three-element referencing vector for the returned data grid, Z. The two-element vectors `latlim` and `lonlim` define the latitude and longitude limits of the geographic region. They should be of the form `[south north]` and `[west east]`, respectively. The scalar `scale` specifies the number of rows and columns per degree of latitude and longitude.

**Examples** `[Z,refvec] = onem([46,51],[-79,-75],1)`

```
Z =
    1     1     1     1
    1     1     1     1
    1     1     1     1
    1     1     1     1
    1     1     1     1
refvec =
    1     51    -79
```

**See Also** `limitm`, `nanm`, `size`, `spzeros`, `zeros`

**Purpose** Location of north pole in rotated map

**Syntax**  
`pole = org2pol(origin)`  
`pole = org2pol(origin,units)`

**Description** `pole = org2pol(origin)` returns the location of the North Pole in terms of the coordinate system after transformation based on the input `origin`. The `origin` is a three-element vector of the form `[latitude longitude orientation]`, where `latitude` and `longitude` are the coordinates that the new center (`origin`) had in the untransformed system, and `orientation` is the azimuth of the true North Pole from the new origin point in the transformed system. The output `pole` is a three-element vector of the form `[latitude longitude meridian]`, which gives the latitude and longitude point in terms of the original untransformed system of the new location of the true North Pole. The meridian is the longitude from the original system upon which the new system is centered.

`pole = org2pol(origin,units)` allows the specification of the angular units of the `origin` vector, where `units` is any valid angle units string. The default is 'degrees'.

When developing transverse or oblique projections, transformed coordinate systems are required. One way to define these systems is to establish the point at which, in terms of the original (untransformed) system, the (transformed) true North Pole will lie.

## Examples

Perhaps you want to make (30°N,0°) the new origin. Where does the North Pole end up in terms of the original coordinate system?

```
pole = org2pol([30 0 0])  
  
pole =  
    60.0000      0      0
```

This makes sense: pull a point 30° down to the origin, and the North Pole is pulled down 30°. A little less obvious example is the following:

```
pole = org2pol([5 40 30])  
  
pole =  
    59.6245    80.0750    40.0000
```

**See Also**      neworig, putpole

# outlinegeoquad

---

**Purpose** Polygon outlining geographic quadrangle

**Syntax** `[lat, lon] = outlinegeoquad(latlim, lonlim, dlat, dlon)`

**Description** `[lat, lon] = outlinegeoquad(latlim, lonlim, dlat, dlon)` constructs a polygon that traces the outline of the geographic quadrangle defined by `latlim` and `lonlim`. Such a polygon can be useful for displaying the quadrangle graphically, especially on a projection where the meridians and/or parallels do not project to straight lines. `latlim` is a two-element vector of the form: [southern-limit northern-limit] and `lonlim` is two-element vectors of the form: [western-limit eastern-limit]. `dlat` is a positive scalar that specifies a minimum vertex spacing in degrees to be applied along the meridians that bound the eastern and western edges of the quadrangle. Likewise, `dlon` is a positive scalar that specifies a minimum vertex spacing in degrees of longitude to be applied along the parallels that bound the northern and southern edges of the quadrangle. The outputs `lat` and `lon` contain the vertices of a simple closed polygon with clockwise vertex ordering.

**Remarks** All input and output angles are in units of degrees. Choose a reasonably small value for `dlat` (a few degrees, perhaps) when using a projection with curved meridians or curved parallels.

To avoid interpolating extra vertices along meridians or parallels, set `dlat` or `dlon` to a value of `Inf`.

## Special Cases

The insertion of additional vertices is suppressed at the poles (that is, if `latlim(1) == -90` or `latlim(2) == 90`). If `lonlim` corresponds to a quadrangle width of exactly 360 degrees (`lonlim == [-180 180]`, for example), then it covers a full latitudinal zone and includes two separate, NaN-separated parts, unless either

- `latlim(1) == -90` or `latlim(2) == 90`, so that only one part is needed—a polygon that follows a parallel clockwise around one of the poles.



- `latlim(1) == -90` and `latlim(2) == 90`, so that the quadrangle encompasses the entire planet. In this case, the quadrangle cannot be represented by a latitude-longitude polygon, and an error results.

## Example

Display the outlines of three geographic quadrangles having very different qualities on top of a simple base map:

```
figure('Color','white')
axesm('ortho','Origin',[-45 110],'frame','on','grid','on')
axis off
coast = load('coast');
geoshow(coast.lat, coast.long)

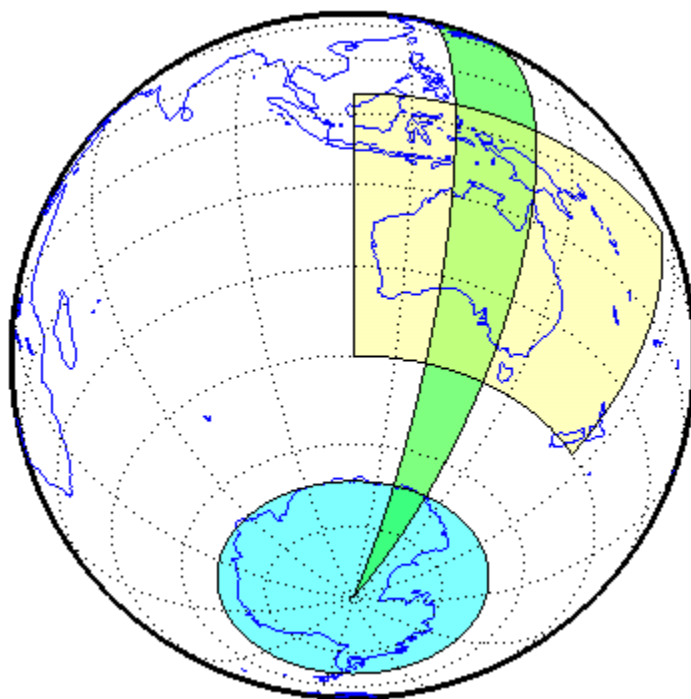
% Quadrangle covering Australia and vicinity
[lat, lon] = outlinegeoquad([-45 5],[110 175],5,5);
geoshow(lat,lon,'DisplayType','polygon','FaceAlpha',0.5);

% Quadrangle covering Antarctic region
antarcticCircleLat = dms2degrees([-66 33 39]);
[lat, lon] = outlinegeoquad([-90 antarcticCircleLat], ...
    [-180 180],5,5);
geoshow(lat,lon,'DisplayType','polygon', ...
    'FaceColor','cyan','FaceAlpha',0.5);

% Quadrangle covering nominal time zone 9 hours ahead of UTC
[lat, lon] = outlinegeoquad([-90 90], 135 + [-7.5 7.5], 5, 5);
geoshow(lat,lon,'DisplayType','polygon', ...
    'FaceColor','green','FaceAlpha',0.5);
```

# outlinegeoquad

---



**See Also**      `ingeoquad`, `intersectgeoquad`

**Purpose**

Set figure properties for printing at specified map scale

**Syntax**

```
paperscale(paperdist,punits,surfdist,sunits)
paperscale(paperdist,punits,surfdist,sunits,lat,long)
paperscale(paperdist,punits,surfdist,sunits,lat,long,az)
paperscale(paperdist,punits,surfdist,sunits,lat,long,az,
           gunits)
paperscale(paperdist,punits,surfdist,sunits,lat,long,az,gunits,
           radius)
paperscale(scale,...)
[paperXdim,paperYdim] = paperscale(...)
```

**Description**

`paperscale(paperdist,punits,surfdist,sunits)` sets the figure paper position to print the map in the current axes at the desired scale. The scale is described by the geographic distance that corresponds to a paper distance. For example, a scale of 1 inch = 10 kilometers is specified as `degrees(1,'inch',10,'km')`. See below for an alternate method of specifying the map scale. The surface distance units string *sunits* can be any string recognized by `unitsratio`. The paper units string *punits* can be any dimensional units string recognized for the figure `PaperUnits` property.

`paperscale(paperdist,punits,surfdist,sunits,lat,long)` sets the paper position so that the scale is correct at the specified geographic location. If omitted, the default is the center of the map limits.

`paperscale(paperdist,punits,surfdist,sunits,lat,long,az)` also specifies the direction along which the scale is correct. If omitted, 90 degrees (east) is assumed.

`paperscale(paperdist,punits,surfdist,sunits,lat,long,az,gunits)` also specifies the units in which the geographic position and direction are given. If omitted, 'degrees' is assumed.

`paperscale(paperdist,punits,surfdist,sunits,lat,long,az,gunits,radius)` uses the last input to determine the radius of the sphere. If `radius` is a string, then it is evaluated as an almanac body to determine the spherical radius. If numerical, it is the radius of the desired

sphere in the same units as the surface distance. If omitted, the default radius of the Earth is used.

`paperscale(scale, ...)`, where the numeric scale replaces the two property/value pairs, specifies the scale as a ratio between distance on the sphere and on paper. This is commonly notated on maps as 1:scale (e.g. 1:100 000, or 1:1 000 000). For example, `paperscale(100000)` or `paperscale(100000, lat, long)`.

`[paperXdim, paperYdim] = paperscale(...)` returns the computed paper dimensions. The dimensions are in the paper units specified. For the scale calling form, the returned dimensions are in centimeters.

## Background

Maps are usually printed at a size that allows an easy comparison of distances measured on paper to distances on the Earth. The relationship of geographic distance and paper distance is termed *scale*. It is usually expressed as a ratio, such as 1 to 100,000 or 1:100,000 or 1 cm = 1 km.

## Examples

The small circle measures 10 cm across when printed.

```
axesm mercator
[lat,lon] = scircle1(0,0,km2deg(5));
plotm(lat,lon)
[x,y] = paperscale(1,'centimeter',1,'km'); [x y]

ans =
    13.154    12.509

set(gca,'pos',[ 0 0 1 1])
[x,y] = paperscale(1,'centimeter',1,'km'); [x y]

ans =
    10.195    10.195
```

## Limitations

The relationship between the paper and geographic coordinates holds only as long as there are no changes to the display that affect the axes limits or the relationship between geographic coordinates and projected coordinates. Changes of this type include the ellipsoid or scale factor

properties of the map axes, or adding elements to the display that cause MATLAB to modify the axes autoscaling. To be sure that the scale is correct, execute `paperscale` just before printing.

## See Also

`pagesetupdlg`, `axesscale`, `daspectm`

# patchesm

---

**Purpose** Project patches on map axes as individual objects

**Syntax**

```
patchesm(lat,lon,cdata)
patchesm(lat,lon,z,cdata)
patchesm(...,'PropertyName',PropertyValue,...)
h = patchesm(...)
```

**Description** `patchesm(lat,lon,cdata)` projects 2-D patch objects onto the current map axes. The input latitude and longitude data must be in the same units as specified in the current map axes. The input `cdata` defines the patch face color. If the input vectors are NaN clipped, then multiple patches are drawn each with a single face. Unlike `fillm` and `fill3m`, `patchesm` will always add the patches to the current map regardless of the current hold state.

`patchesm(lat,lon,z,cdata)` projects 3-D planar patches at the uniform elevation given by scalar `z`.

`patchesm(...,'PropertyName',PropertyValue,...)` uses the patch properties supplied to display the patch. Except for `xdata`, `ydata`, and `zdata`, all patch properties available through `patch` are supported by `patchesm`.

`h = patchesm(...)` returns the handles to the patch objects drawn.

## Remarks

### Differences between `patchesm` and `patchm`

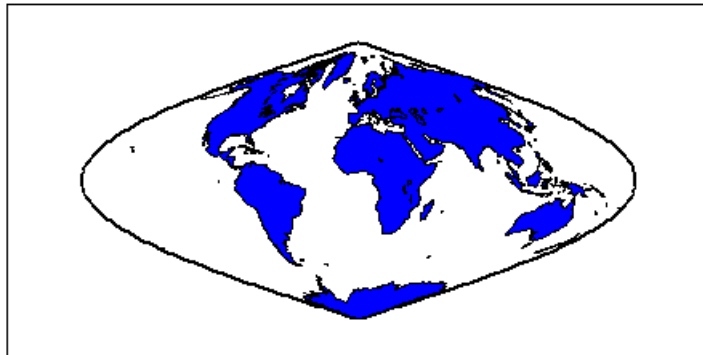
The `patchesm` function is very similar to the `patchm` function. The significant difference is that in `patchesm`, separate patches (delineated by NaNs in the inputs `lat` and `lon`) are separated and plotted as distinct patch objects on the current map axes. The advantage to this is that less memory is required. The disadvantage is that multifaced objects cannot be treated as a single object. For example, the archipelago of the Philippines cannot be treated and handled as a single Handle Graphics object.

### When Patches Are Completely Trimmed Away

Removing graphic objects that fall outside the map frame is called trimming. If, after trimming no polygons remain to be seen within it, patchesm creates no patches and returns an empty 1-by-0 list of handles. When this occurs, automatic reprojection of the patch data (by changing the projection or any of its parameters) is not possible. In cases where some polygons are completely trimmed away but not others, handles returned for the trimmed polygons will be empty. No polygons or rings that have been totally trimmed away can be reprojected; to plot them again, you will need to call patchesm again with the original data.

### Examples

```
load coast
axesm sinusoid; framem
h = patchesm(lat,long,'b');
```



```
length(h)
```

```
ans =
    238
```

### See Also

geoshow, fill3m, fillm, patchm

# patchm

---

## Purpose

Project patch objects on map axes

## Syntax

```
h = patchm(lat,lon,cdata)
h = patchm(lat,lon,cdata,PropertyName,PropertyValue,...)
h = patchm(lat,lon,PropertyName,PropertyValue,...)
h = patchm(lat,lon,z,cdata)
h = patchm(lat,lon,z,cdata,PropertyName,PropertyValue,...)
```

## Description

`h = patchm(lat,lon,cdata)` and `h = patchm(lat,lon,cdata,PropertyName,PropertyValue,...)` project and display patch (polygon) objects defined by their vertices given in `lat` and `lon` on the current map axes. `lat` and `lon` must be vectors. The color data, `cdata`, can be any color data designation supported by the standard MATLAB `patch` function. The object handle or handles, `h`, can be returned.

`h = patchm(lat,lon,PropertyName,PropertyValue,...)` allows any property name/property value pair supported by `patch` to be assigned to the `patchm` object.

`h = patchm(lat,lon,z,cdata)` and `h = patchm(lat,lon,z,cdata,PropertyName,PropertyValue,...)` allow the assignment of an altitude, `z`, to each patch object. The default altitude is `z = 0`.

## Remarks

### How patchm Works

This Mapping Toolbox function is very similar to the standard MATLAB `patch` function. Like its analog, and unlike higher level functions such as `fillm` and `fill3m`, `patchm` adds patch objects to the current map axes regardless of hold state. Except for `XData`, `YData`, and `ZData`, all line properties and styles available through `patch` are supported by `patchm`.

### When A Patch Is Completely Trimmed Away

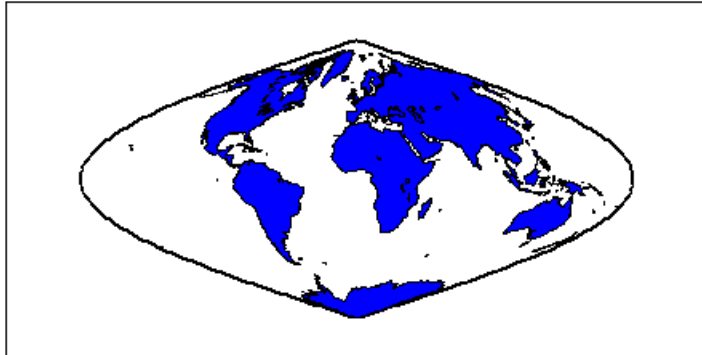
Removing graphic objects that fall outside the map frame is called trimming. If, after trimming to the map frame no polygons remain to be seen within it, `patchm` creates no patches and returns an empty 0-by-1 handle. When this occurs, automatic reprojection of the patch data (by



changing the projection or any of its parameters) will not be possible. Instead, after changing the projection, call `patchm` again.

## Examples

```
load coast
axesm sinusoid; framem
h = patchm(lat,long,'b');
```



```
length(h)
```

```
ans =  
     1
```

## See Also

`patchesm`, `fill3m`, `fillm`

# pcolorm

---

**Purpose** Project regular data grid on map axes in  $z = 0$  plane

**Syntax**

```
pcolorm(lat,lon,Z)
pcolorm(latlim,lonlim,Z)
pcolorm(...,prop1,val1,prop2,val2,...)
h = pcolorm(...)
```

**Description** `pcolorm(lat,lon,Z)` constructs a surface to represent the data grid  $Z$  in the current map axes. The surface lies flat in the horizontal plane with its `CData` property set to  $Z$ . `lat` and `lon` are vectors or 2-D arrays that define the latitude-longitude graticule mesh on which  $Z$  is displayed. For a complete description of the various forms that `lat` and `lon` can take, see `surf`. If the hold state is 'off', `pcolorm` clears the current map.

`pcolorm(latlim,lonlim,Z)` defines the graticule using the latitude and longitude limits `latlim` and `lonlim`. These limits should match the geographic extent of  $Z$ , the data grid. `latlim` is a two-element vector of the form:

```
[southern_limit northern_limit]
```

Likewise, `lonlim` has the form:

```
[western_limit eastern_limit]
```

A latitude-longitude graticule of size 50-by-100 is constructed. The surface `FaceColor` property is 'texturemap', except when  $Z$  is precisely 50-by-100, in which case it is 'flat'.

`pcolorm(...,prop1,val1,prop2,val2,...)` applies additional MATLAB graphics properties to the surface via property/value pairs. Any property accepted by the surface may be specified, except for `XData`, `YData`, and `ZData`.

`h = pcolorm(...)` returns a handle to the surface object.

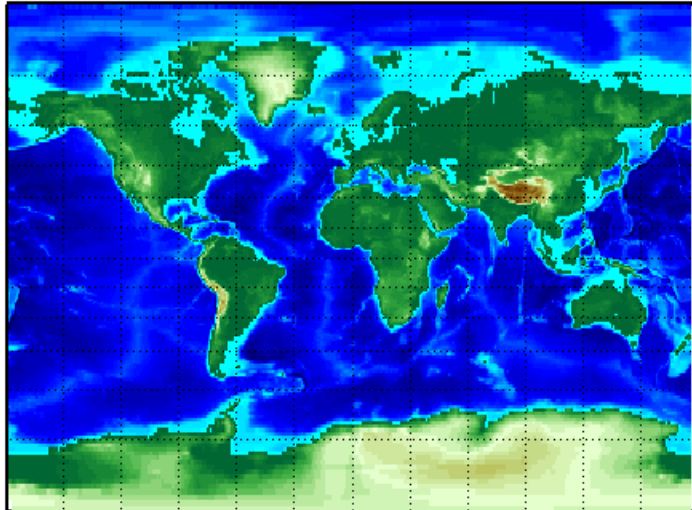
**Remarks** This function warps a data grid to a graticule mesh, which is projected according to the map axes property `MapProjection`. The fineness, or

resolution, of this grid determines the quality of the projection and the speed of plotting it. There is no hard and fast rule for sufficient graticule resolution, but in general, cylindrical projections need fewer graticule points in the longitudinal direction than do complex curve-generating projections.

## Example

Construct a surface to represent the data grid topo.

```
figure('Color','white')
load topo
axesm miller
axis off; framem on; gridm on;
[lat lon] = meshgrat(topo,topolegend,[90 180]);
pcolorm(lat,lon,topo)
demcmap(topo)
tightmap
```



## See Also

geoshow, meshgrat, meshm, surfacem, surfm

# pix2latlon

---

**Purpose** Convert pixel coordinates to latitude-longitude coordinates

**Syntax** `[lat, lon] = pix2latlon(r,row,col)`

**Description** `[lat, lon] = pix2latlon(r,row,col)` calculates latitude-longitude coordinates `lat`, `lon` from pixel coordinates `row`, `col`. `r` is a 3-by-2 referencing matrix defining a two-dimensional affine transformation from pixel coordinates to spatial coordinates. `row` and `col` are vectors or arrays of matching size. The outputs `lat` and `lon` have the same size as `row` and `col`.

**Example**

```
% Find the lat and lon of the upper left and lower right
% outer corners of a 2-by-2 degree gridded data set.
R = makerefmat(1, 89, 2, 2);
[UL_lat, UL_lon] = pix2latlon(R, .5, .5)

UL_lat =
    88
UL_lon =
    0

[LR_lat, LR_lon] = pix2latlon(R, 90.5, 180.5)

LR_lat =
    268
LR_lon =
    360
```

**See Also** `latlon2pix`, `makerefmat`, `pix2map`

<b>Purpose</b>	Convert pixel coordinates to map coordinates
<b>Syntax</b>	<pre>[x,y] = pix2map(R,row,col) s = pix2map(R,row,col) [...] = pix2map(R,p)</pre>
<b>Description</b>	<p><code>[x,y] = pix2map(R,row,col)</code> calculates map coordinates <code>x,y</code> from pixel coordinates <code>row,col</code>. <code>R</code> is a 3-by-2 referencing matrix defining a two-dimensional affine transformation from pixel coordinates to spatial coordinates. <code>row</code> and <code>col</code> are vectors or arrays of matching size. The outputs <code>x</code> and <code>y</code> have the same size as <code>row</code> and <code>col</code>.</p> <p><code>s = pix2map(R,row,col)</code> combines <code>X</code> and <code>Y</code> into a single array <code>s</code>. If <code>row</code> and <code>col</code> are column vectors of length <code>n</code>, then <code>s</code> is an <code>n</code>-by-2 matrix and each row (<code>s(k,:)</code>) specifies the map coordinates of a single point. Otherwise, <code>s</code> has size <code>[size(row) 2]</code>, and <code>s(k1,k2,...,kn,:)</code> contains the map coordinates of a single point.</p> <p><code>[...] = pix2map(R,p)</code> combines <code>row</code> and <code>col</code> into a single array <code>p</code>. If <code>row</code> and <code>col</code> are column vectors of length <code>n</code>, then <code>p</code> should be an <code>n</code>-by-2 matrix such that each row (<code>p(k,:)</code>) specifies the pixel coordinates of a single point. Otherwise, <code>p</code> should have size <code>[size(row) 2]</code>, and <code>p(k1,k2,...,kn,:)</code> should contain the pixel coordinates of a single point.</p>
<b>Example</b>	<pre>% Find the map coordinates for the pixel at (100,50). R = worldfileread('concord_ortho_w.tfw'); [x,y] = pix2map(R,100,50)  x =     2.0704950000000000e+005  y =     9.1290050000000000e+005</pre>
<b>See Also</b>	<code>makereformat</code> , <code>map2pix</code> , <code>pix2latlon</code> , <code>worldfileread</code>

# pixcenters

---

**Purpose** Compute pixel centers for georeferenced image or data grid

**Syntax**

```
[x,y] = pixcenters(R, height, width)
[x,y] = pixcenters(r,sizea)
[x,y] = pixcenters(..., 'makegrid')
```

**Description** `[x,y] = pixcenters(R, height, width)` returns the spatial coordinates of a spatially-referenced image or regular gridded data set. `R` is the 3-by-2 affine referencing matrix. `height` and `width` are the image dimensions. If `r` does not include a rotation (i.e.,  $r(1,1) = r(2,2) = 0$ ), then `x` is a 1-by-width vector and `y` is a height-by-1 vector. In this case, the spatial coordinates of the pixel in row `row` and column `col` are given by `x(col)`, `y(row)`. Otherwise, `x` and `y` are each a height-by-width matrix such that `x(col,row)`, `y(col,row)` are the coordinates of the pixel with subscripts `(row,col)`.

`[x,y] = pixcenters(r,sizea)` accepts the size vector `sizea = [height, width, ...]` instead of `height` and `width`.

`[x,y] = pixcenters(info)` accepts a scalar struct array with the fields

'RefMatrix'	3-by-2 referencing matrix
'Height'	Scalar number
'Width'	Scalar number

`[x,y] = pixcenters(..., 'makegrid')` returns `x` and `y` as height-by-width matrices even if `r` is irrotational. This syntax can be helpful when you call `pixcenters` from within a function or script.

**Remarks** For more information on referencing matrices, see the `makerefmat` reference page.

`pixcenters` is useful for working with `surf`, `mesh`, or `surface`, and for coordinate transformations.

**Example**

```
[Z,R] = arcgridread('MtWashington-ft.grd');
[x,y] = pixcenters(R, size(Z));
```

```
h = surf(x,y,Z); axis equal; colormap(demcmap(Z))
set(h,'EdgeColor','none')
xlabel('x (easting in meters)')
ylabel('y (northing in meters)')
zlabel('elevation in feet')colormap(terrain)
```

**See Also**

`arcgridread`, `makerefmat`, `mapbbox`, `mapoutline`, `pix2map`,  
`worldfileread`

The help for `mapshow` provides an alternative version of the preceding example.

# plabel

---

**Purpose** Toggle and control display of parallel labels

**Syntax**

```
plabel  
plabel('on')  
plabel('off')  
plabel(meridian)  
plabel(MapAxesPropertyName,PropertyValue,...)
```

**Description** plabel toggles the visibility of parallel labeling on the current map axes.

plabel('on') sets the visibility of parallel labels to 'on'.

plabel('off') sets the visibility of parallel labels to 'off'.

plabel('reset') resets the displayed parallel labels using the currently defined parallel label properties.

plabel(meridian) sets the value of the PLabelMeridian property of the map axes to the value meridian. This determines the meridian upon which the labels are placed (see axesm). The options for meridian are a scalar longitude or the strings 'east', 'west', or 'prime'.

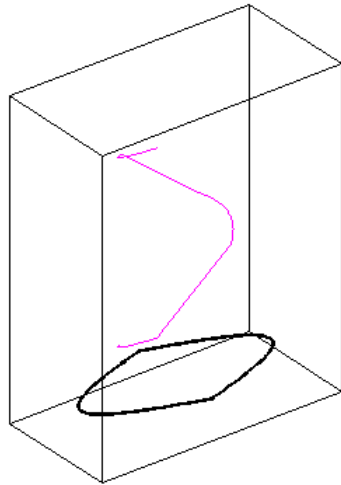
plabel(*MapAxesPropertyName*,PropertyValue,...) allows paired map axes property names and property values to be passed in. For a complete description of map axes properties, see the axesm reference page.

Parallel label handles can be returned in h if desired.

**See Also** axesm, setm, mlabel



<b>Purpose</b>	Project 3-D lines and points on map axes
<b>Syntax</b>	<pre> h = plot3m(lat,lon,z) h = plot3m(lat,lon,<i>linetype</i>) h = plot3m(lat,lon,<i>PropertyName</i>,<i>PropertyValue</i>,...) </pre>
<b>Description</b>	<p><code>h = plot3m(lat,lon,z)</code> displays projected line objects on the current map axes. <code>lat</code> and <code>lon</code> are the latitude and longitude coordinates, respectively, of the line object to be projected. Note that this ordering is conceptually reversed from the MATLAB line function, because the <i>vertical</i> (<i>y</i>) coordinate comes first. However, the ordering latitude, then longitude, is standard geographic usage. <code>lat</code> and <code>lon</code> must be the same size, and in the <code>AngleUnits</code> of the map axes. <code>z</code> is the altitude data associated with each point in <code>lat</code> and <code>lon</code>. The object handle for the displayed line can be returned in <code>h</code>.</p> <p>The units of <code>z</code> are arbitrary, except when using the Globe projection. In the case of <code>globe</code>, <code>z</code> should have the same units as the radius of the earth or semimajor axis specified in the <code>'geoid'</code> (reference ellipsoid) property of the map axes. This implies that for a reference ellipsoid vector of <code>[1 0]</code> (a unit sphere), the units of <code>z</code> are earth radii.</p> <p><code>h = plot3m(lat,lon,<i>linetype</i>)</code> allows the specification of the line style, where <i>linetype</i> is any string recognized by the MATLAB line function.</p> <p><code>h = plot3m(lat,lon,<i>PropertyName</i>,<i>PropertyValue</i>,...)</code> allows the specification of any number of property name/property value pairs for any properties recognized by the MATLAB line function except for <code>XData</code>, <code>YData</code>, and <code>ZData</code>.</p>
<b>Remarks</b>	<code>plot3m</code> is the mapping equivalent of the MATLAB <code>plot3</code> function.
<b>Example</b>	<pre> axesm sinusoid; framem; view(3) [lats,longs] = interp([45 -45 -45 45 45 -45]',...                     [-100 -100 100 100 -100 -100]',1); z = (1:671)'/100; plot3m(lats,longs,z,'m') </pre>



**See Also**

`linem`, `plot3`, `plotm`

**Purpose**

Project 2-D lines and points on map axes

**Syntax**

```
h = plotm(lat,lon)
h = plotm(lat,lon,linetype)
h = plotm(lat,lon,PropertyName,PropertyValue,...)
h = plotm([lat lon],...)
```

**Description**

`h = plotm(lat,lon)` displays projected line objects on the current map axes. `lat` and `lon` are the latitude and longitude coordinates, respectively, of the line object to be projected. Note that this ordering is conceptually reversed from the MATLAB line function, because the *vertical* (*y*) coordinate comes first. However, the ordering latitude, then longitude, is standard geographic usage. `lat` and `lon` must be the same size, and in the `AngleUnits` of the map axes. The object handle for the displayed line can be returned in `h`.

`h = plotm(lat,lon,linetype)` allows the specification of the line style, where *linetype* is any string recognized by the MATLAB line function.

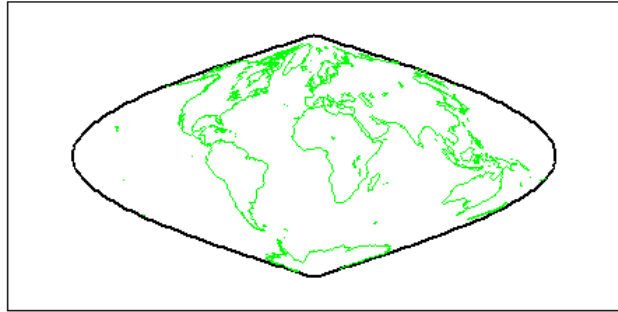
`h = plotm(lat,lon,PropertyName,PropertyValue,...)` allows the specification of any number of property name/property value pairs for any properties recognized by the MATLAB line function except for `XData`, `YData`, and `ZData`.

`h = plotm([lat lon],...)` allows the coordinates to be packed into a single two-column matrix.

`plotm` is the mapping equivalent of the MATLAB `plot` function.

**Example**

```
load coast
axesm sinusoid; framem
plotm(lat,long,'g')
```



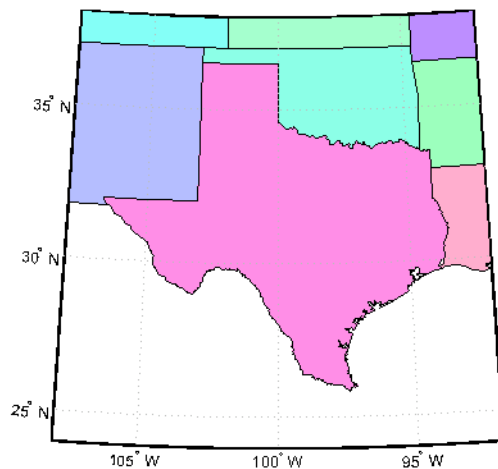
**See Also**

`linem`, `plot`, `plot3m`

---

<b>Purpose</b>	Colormaps appropriate to political regions
<b>Syntax</b>	<pre>polcmap polcmap(ncolors) polcmap(ncolors,maxsat) polcmap(ncolors,huelimits,saturationlimits,valuelimits) cmap = polcmap(...)</pre>
<b>Description</b>	<p><code>polcmap</code> applies a random muted colormap to the current figure. The size of the colormap is the same as the existing colormap.</p> <p><code>polcmap(ncolors)</code> creates a colormap with the specified number of colors.</p> <p><code>polcmap(ncolors,maxsat)</code> controls the maximum saturation of the colors. Larger maximum saturation values produce brighter, more saturated colors. If omitted, the default is 0.5.</p> <p><code>polcmap(ncolors,huelimits,saturationlimits,valuelimits)</code> controls the colors. Hue, saturation, and value are randomly selected values within the limit vectors. These are two-element vectors of the form [min max]. Valid values range from 0 to 1. As the hue varies from 0 to 1, the resulting color varies from red, through yellow, green, cyan, blue, and magenta, back to red. When the saturation is 0, the colors are unsaturated; they are simply shades of gray. When the saturation is 1, the colors are fully saturated; they contain no white component. As the value varies from 0 to 1, the brightness increases.</p> <p><code>cmap = polcmap(...)</code> returns the colormap without applying it to the figure.</p>
<b>Remarks</b>	You cannot use <code>polcmap</code> to alter the colors of displayed patches drawn by <code>geoshow</code> or <code>mapshow</code> . The patches must have been rendered by <code>displaym</code> . However, you can color patches using <code>polcmap</code> when you call <code>geoshow</code> or <code>mapshow</code> , as shown below.
<b>Example</b>	Draw a map of Texas and surrounding states. Color the patches with a <code>symbolspec</code> constructed using <code>polcmap</code> :

```
figure; usamap('texas')
states = shaperead('usastatelo.shp','UseGeoCoords',true);
faceColors = makesymbolspec('Polygon',...
    {'INDEX', [1 numel(states)], 'FaceColor', ...
    polcmap(numel(states))});
geoshow(states, 'DisplayType', 'polygon', ...
    'SymbolSpec', faceColors)
```



Note that the colors you obtain for this example can vary from what you see above because `polcmap` computes them randomly.

## See Also

`demcmap`, `colormap`

**Purpose** Convert polygon contour to counterclockwise vertex ordering

**Syntax** `[x2, y2] = poly2ccw(x1, y1)`

**Description** `[x2, y2] = poly2ccw(x1, y1)` arranges the vertices in the polygonal contour `(x1, y1)` in counterclockwise order, returning the result in `x2` and `y2`. If `x1` and `y1` can contain multiple contours, represented either as NaN-separated vectors or as cell arrays, then each contour is converted to clockwise ordering. `x2` and `y2` have the same format (NaN-separated vectors or cell arrays) as `x1` and `y1`.

**Example** Convert a clockwise-ordered square to counterclockwise ordering.

```
x1 = [0 0 1 1 0];
y1 = [0 1 1 0 0];
ispolycw(x1, y1)

ans =
     1

[x2, y2] = poly2ccw(x1, y1);
ispolycw(x2, y2)
ans =
     0
```

**See also** `ispolycw`, `poly2cw`, `polybool`

**Purpose** Convert polygon contour to clockwise vertex ordering

**Syntax** `[x2, y2] = poly2cw(x1, y1)`

**Description** `[x2, y2] = poly2cw(x1, y1)` arranges the vertices in the polygonal contour (x1, y1) in clockwise order, returning the result in x2 and y2. If x1 and y1 can contain multiple contours, represented either as NaN-separated vectors or as cell arrays, then each contour is converted to clockwise ordering. x2 and y2 have the same format (NaN-separated vectors or cell arrays) as x1 and y1.

**Example** Convert a counterclockwise-ordered square to clockwise ordering.

```
x1 = [0 1 1 0 0];
y1 = [0 0 1 1 0];
ispolycw(x1, y1)

ans =

     0

[x2, y2] = poly2cw(x1, y1);
ispolycw(x2, y2)

ans =

     1
```

**See also** `ispolycw`, `poly2ccw`, `polybool`



**Purpose** Convert polygonal region to patch faces and vertices

**Syntax** [F, V] = poly2fv(x, y)

**Description** [F, V] = poly2fv(x, y) converts the polygonal region represented by the contours (x, y) into a faces matrix, F, and a vertices matrix, V, that can be used with the patch function to display the region. The contour vertices can be represented either in NaN-separated vector format or cell array format.

Individual contours in x and y are assumed to be external contours if their vertices are arranged in clockwise order; otherwise they are assumed to be internal contours. Use poly2cw or poly2ccw, if necessary, to achieve the desired vertex ordering.

**Example** Display a rectangular region with two holes using a single patch object.

```
% External contour, rectangle, clockwise ordered.
x1 = [0 0 6 6 0];
y1 = [0 3 3 0 0];

% First hole contour, square, counterclockwise ordered.
x2 = [1 2 2 1 1];
y2 = [1 1 2 2 1];

% Second hole contour, triangle, counterclockwise ordered.
x3 = [4 5 4 4];
y3 = [1 1 2 1];

% Compute face and vertex matrices.
[f, v] = poly2fv({x1, x2, x3}, {y1, y2, y3});

% Display the patch.
patch('Faces', f, 'Vertices', v, 'FaceColor', 'r', ...
      'EdgeColor', 'none');
axis off, axis equal
```

## poly2fv

---

See the documentation for `polybool` for additional examples illustrating `poly2fv`.

**See also** `ispolycw`, `patch`, `poly2cw`, `poly2ccw`, `polybool`

**Purpose**

Set operations on polygonal regions

**Syntax**

```
[x,y] = polybool(flag,x1,y1,x2,y2)
```

**Description**

`[x,y] = polybool(flag,x1,y1,x2,y2)` performs the polygon set operation identified by `flag`. A valid flag string is any one of the following alternatives:

- Region intersection: 'intersection', 'and', '&'
- Region union: 'union', 'or', '|', '+', 'plus'
- Region subtraction: 'subtraction', 'minus', '-'
- Region exclusive or: 'exclusiveor', 'xor'

The polygon inputs are NaN-delimited vectors, or cell arrays containing individual polygonal contours. The result is output using the same format as the input.

`polybool` assumes that individual contours whose vertices are clockwise ordered are external contours, and that contours whose vertices are counterclockwise ordered are internal contours. You can use `poly2cw` to convert a polygonal contour to clockwise ordering.

**Limitations**

Polygons processed via `polybool` are assumed to be in a Cartesian coordinate system. Therefore, geographic data that encompasses a pole cannot be used directly. Use `flatearthpoly` to convert polygons that contain a pole to Cartesian coordinates.

**Examples****Example 1**

Set operations on two overlapping circular regions:

```
theta = linspace(0, 2*pi, 100);
x1 = cos(theta) - 0.5;
y1 = -sin(theta);    % -sin(theta) to make a clockwise contour
x2 = x1 + 1;
y2 = y1;
```

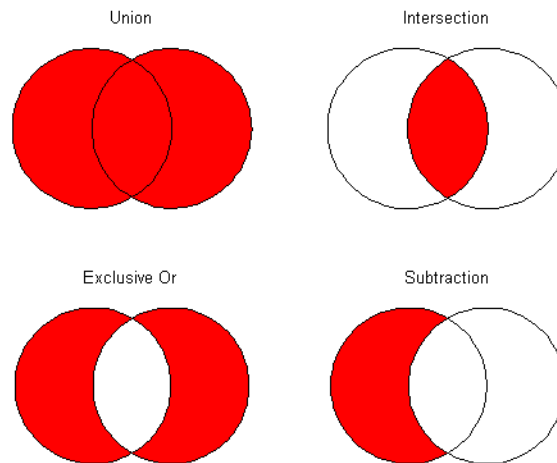
```
[xa, ya] = polybool('union', x1, y1, x2, y2);
[xb, yb] = polybool('intersection', x1, y1, x2, y2);
[xc, yc] = polybool('xor', x1, y1, x2, y2);
[xd, yd] = polybool('subtraction', x1, y1, x2, y2);

subplot(2, 2, 1)
patch(xa, ya, 1, 'FaceColor', 'r')
axis equal, axis off, hold on
plot(x1, y1, x2, y2, 'Color', 'k')
title('Union')

subplot(2, 2, 2)
patch(xb, yb, 1, 'FaceColor', 'r')
axis equal, axis off, hold on
plot(x1, y1, x2, y2, 'Color', 'k')
title('Intersection')

subplot(2, 2, 3)
% The output of the exclusive-or operation consists of disjoint
% regions. It can be plotted as a single patch object using the
% face-vertex form. Use poly2fv to convert a polygonal region
% to face-vertex form.
[f, v] = poly2fv(xc, yc);
patch('Faces', f, 'Vertices', v, 'FaceColor', 'r', ...
'EdgeColor', 'none')
axis equal, axis off, hold on
plot(x1, y1, x2, y2, 'Color', 'k')
title('Exclusive Or')

subplot(2, 2, 4)
patch(xd, yd, 1, 'FaceColor', 'r')
axis equal, axis off, hold on
plot(x1, y1, x2, y2, 'Color', 'k')
title('Subtraction')
```



## Example 2

Set operations on regions with holes

```
Ax = {[1 1 6 6 1], [2 5 5 2 2], [2 5 5 2 2]};
Ay = {[1 6 6 1 1], [2 2 3 3 2], [4 4 5 5 4]};
subplot(2, 3, 1)
[f, v] = poly2fv(Ax, Ay);
patch('Faces', f, 'Vertices', v, 'FaceColor', 'r', ...
      'EdgeColor', 'none')
axis equal, axis off, axis([0 7 0 7]), hold on
for k = 1:numel(Ax), plot(Ax{k}, Ay{k}, 'Color', 'k'), end
title('A')
```

```
Bx = {[0 0 7 7 0], [1 3 3 1 1], [4 6 6 4 4]};
By = {[0 7 7 0 0], [1 1 6 6 1], [1 1 6 6 1]};
subplot(2, 3, 4);
[f, v] = poly2fv(Bx, By);
patch('Faces', f, 'Vertices', v, 'FaceColor', 'r', ...
      'EdgeColor', 'none')
axis equal, axis off, axis([0 7 0 7]), hold on
for k = 1:numel(Bx), plot(Bx{k}, By{k}, 'Color', 'k'), end
```

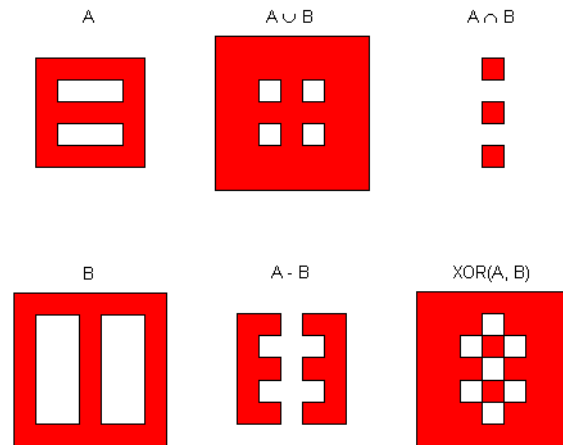
```
title('B')

subplot(2, 3, 2)
[Cx, Cy] = polybool('union', Ax, Ay, Bx, By);
[f, v] = poly2fv(Cx, Cy);
patch('Faces', f, 'Vertices', v, 'FaceColor', 'r', ...
      'EdgeColor', 'none')
axis equal, axis off, axis([0 7 0 7]), hold on
for k = 1:numel(Cx), plot(Cx{k}, Cy{k}, 'Color', 'k'), end
title('A \cup B')

subplot(2, 3, 3)
[Dx, Dy] = polybool('intersection', Ax, Ay, Bx, By);
[f, v] = poly2fv(Dx, Dy);
patch('Faces', f, 'Vertices', v, 'FaceColor', 'r', ...
      'EdgeColor', 'none')
axis equal, axis off, axis([0 7 0 7]), hold on
for k = 1:numel(Dx), plot(Dx{k}, Dy{k}, 'Color', 'k'), end
title('A \cap B')

subplot(2, 3, 5)
[Ex, Ey] = polybool('subtraction', Ax, Ay, Bx, By);
[f, v] = poly2fv(Ex, Ey);
patch('Faces', f, 'Vertices', v, 'FaceColor', 'r', ...
      'EdgeColor', 'none')
axis equal, axis off, axis([0 7 0 7]), hold on
for k = 1:numel(Ex), plot(Ex{k}, Ey{k}, 'Color', 'k'), end
title('A - B')

subplot(2, 3, 6)
[Fx, Fy] = polybool('xor', Ax, Ay, Bx, By);
[f, v] = poly2fv(Fx, Fy);
patch('Faces', f, 'Vertices', v, 'FaceColor', 'r', ...
      'EdgeColor', 'none')
axis equal, axis off, axis([0 7 0 7]), hold on
for k = 1:numel(Fx), plot(Fx{k}, Fy{k}, 'Color', 'k'), end
title('XOR(A, B)')
```

**See Also**

[bufferm](#), [flatearthpoly](#), [ispolycw](#), [poly2cw](#), [poly2ccw](#), [poly2fv](#), [polyjoin](#), [polysplit](#)

# polycut

---

<b>Purpose</b>	Polygon branch cuts for holes
<b>Syntax</b>	<code>[lat2,long2] = polycut(lat,long)</code>
<b>Description</b>	<code>[lat2,long2] = polycut(lat,long)</code> connects the contour and holes of polygons using optimal branch cuts. Polygons are input as NaN-delimited vectors, or as cell arrays containing individual polygons in each element with the outer face separated from the subsequent inner faces by NaNs. Multiple polygons outputs are separated by NaNs.
<b>See Also</b>	<code>polybool</code> , <code>polysplit</code> , <code>polyjoin</code>



**Purpose** Convert line or polygon parts from cell arrays to vector form

**Syntax** `[lat,lon] = polyjoin(latcells,loncells)`

**Description** `[lat,lon] = polyjoin(latcells,loncells)` converts polygons from cell array format to column vector format. In cell array format, each element of the cell array is a vector that defines a separate polygon.

**Remarks** A polygon may consist of an outer contour followed by holes separated with NaNs. In vector format, each vector may contain multiple faces separated by NaNs. There is no structural distinction between outer contours and holes in vector format.

**Example**

```
latcells = {[1 2 3]'; 4; [5 6 7 8 NaN 9]'};
loncells = {[9 8 7]'; 6; [5 4 3 2 NaN 1]'};
[lat,lon] = polyjoin(latcells,loncells);
[lat lon]
```

```
ans =
     1     9
     2     8
     3     7
    NaN    NaN
     4     6
    NaN    NaN
     5     5
     6     4
     7     3
     8     2
    NaN    NaN
     9     1
```

**See Also** `polybool`, `polycut`, `polysplit`

# polymerge

---

**Purpose** Merge line segments with matching endpoints

**Syntax**

```
[latMerged, lonMerged] = polymerge(lat, lon)
[latMerged, lonMerged] = polymerge(lat, lon, tol)
[latMerged, lonMerged] = polymerge(lat, lon, tol,
    outputFormat)
```

**Description** `[latMerged, lonMerged] = polymerge(lat, lon)` accepts a multipart line in latitude-longitude with vertices stored in arrays `lat` and `lon`, and merges the parts wherever a pair of end points coincide. For this purpose, an end point can be either the first or last vertex in a given part. When a pair of parts are merged, they are combined into a single part and the duplicate common vertex is removed. If two first vertices coincide or two last vertices coincide, then the vertex order of one of the parts will be reversed. A merge is applied anywhere that the end points of exactly two distinct parts coincide, so that an indefinite number of parts can be chained together in a single call to `polymerge`. If three or more distinct parts share a common end point, however, the choice of which parts to merge is ambiguous and therefore none of the corresponding parts are connected at that common point.

The inputs `lat` and `lon` can be column or row vectors with NaN-separated parts (and identical NaN locations in each array), or they can be cell arrays with each part in a separate cell. The form of the output arrays, `latMerged` and `lonMerged`, matches the inputs in this regard.

`[latMerged, lonMerged] = polymerge(lat, lon, tol)` combines line segments whose endpoints are separated by less than the circular tolerance, `tol`. `tol` has the same units as the polygon input.

`[latMerged, lonMerged] = polymerge(lat, lon, tol, outputFormat)` allows you to request either the NaN-separated vector form for the output (set `outputFormat` to `'vector'`), or the cell array form (set `outputFormat` to `'cell'`).

**Example**

```
lat = [1 2 3 NaN 6 7 8 9 NaN 6 5 4 3 NaN 12 13 14 ...
      NaN 9 10 11 12]';
lon = lat;
[lat2, lon2] = polymerge(lat, lon);
[lat2, lon2]
```

```
ans =
```

```
1     1
2     2
3     3
4     4
5     5
6     6
7     7
8     8
9     9
10    10
11    11
12    12
13    13
14    14
NaN   NaN
```

**See Also**

polyjoin, polysplit

# polysplit

---

**Purpose** Convert line or polygon parts from vector form to cell arrays

**Syntax** `[latcells,loncells] = polysplit(lat,lon)`

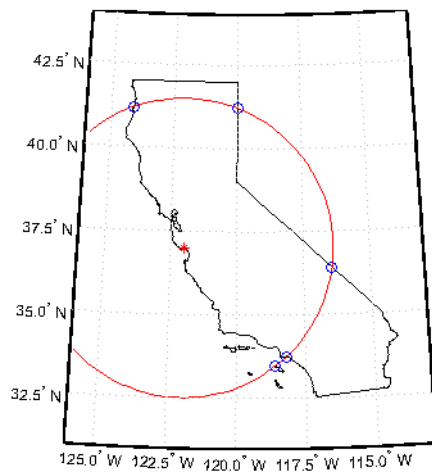
**Description** `[latcells,loncells] = polysplit(lat,lon)` returns the NaN-delimited segments of the vectors `lat` and `lon` as N-by-1 cell arrays with one polygon segment per cell. `lat` and `lon` must be the same size and have identically-placed NaNs. The polygon segments are column vectors if `lat` and `lon` are column vectors, and row vectors otherwise.

**Example**

```
lat = [1 2 3 NaN 4 NaN 5 6 7 8 9]';  
lon = [9 8 7 NaN 6 NaN 5 4 3 2 1]';  
[latcells,loncells] = polysplit(lat,lon);  
[latcells loncells]  
  
ans =  
    [3x1 double]    [3x1 double]  
    [         4]    [         6]  
    [5x1 double]    [5x1 double]
```

**See Also** `isshapemultipart`, `polybool`, `polycut`, `polyjoin`

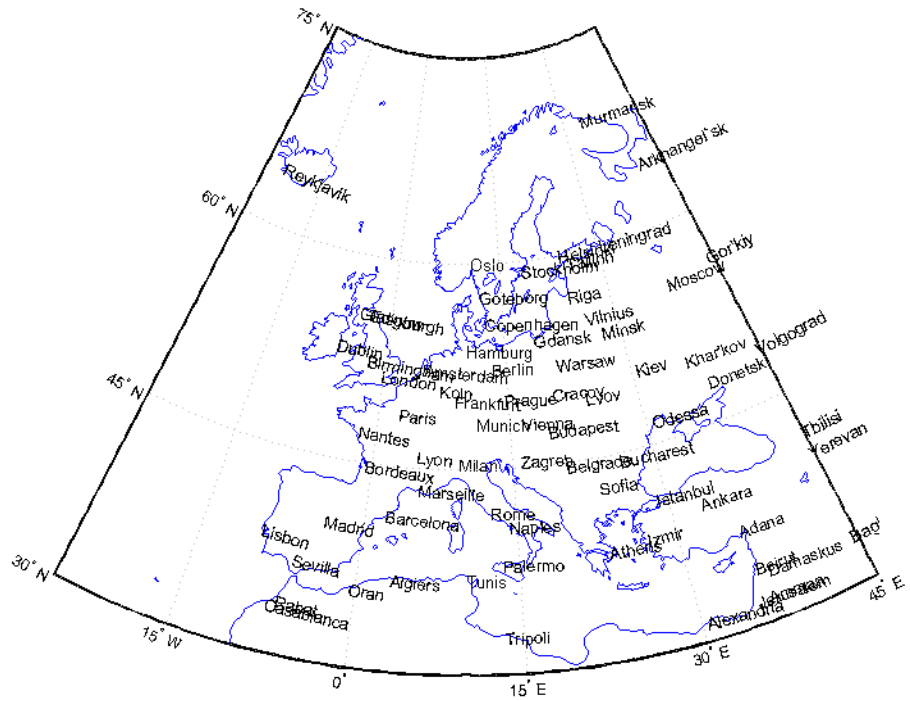
<b>Purpose</b>	Intersection points for lines or polygon edges
<b>Syntax</b>	<pre>[xi,yi] = polyxpoly(x1,y1,x2,y2) [xi,yi] = polyxpoly(...,'unique') [xi,yi,ii] = polyxpoly(...)</pre>
<b>Description</b>	<p><code>[xi,yi] = polyxpoly(x1,y1,x2,y2)</code> returns the intersection points of two sets of lines and/or polygons.</p> <p><code>[xi,yi] = polyxpoly(...,'unique')</code> returns only unique intersections.</p> <p><code>[xi,yi,ii] = polyxpoly(...)</code> also returns a two-column index of line segment numbers corresponding to the intersection points.</p>
<b>Example</b>	<pre>california = shaperead('usastatehi',...     'UseGeoCoords', true,...     'Selector',{@(name) strcmpi(name,'California'), 'Name'}); usamap('california') geoshow(california, 'FaceColor', 'none')  lat0 = 37; lon0 = -122; rad = 500; [latc, lonc] = scircle1(lat0, lon0, km2deg(rad)); plotm(lat0, lon0, 'r*') plotm(latc, lonc, 'r')  [lat, lon] = reducem(california.Lat', california.Lon'); [loni, lati] = polyxpoly(lon, lat, lonc, latc); plotm(lati, loni, 'bo')</pre>



## See Also

crossfix, gcxgc, gcxsc, navfix, rhxrh, scxsc

<b>Purpose</b>	View map at printed size
<b>Description</b>	The appearance of a map onscreen can differ from the final printed output. This results from the difference in the size and shape of the figure window and the area the figure occupies on the printed page. A map that appears readable on screen might be cluttered when the printed output is smaller. Likewise, the relative position of multiple axes can appear different when printed. This function resizes the figure to the printed size.
<b>Remarks</b>	previewmap changes the size of the current figure to match the printed output. If the resulting figure size exceeds the screen size, the figure is enlarged as much as possible.
<b>Examples</b>	<p>Is the text small enough to avoid overlapping in a map of Europe?</p> <pre>figure worldmap europe land=shaperead('landareas.shp','UseGeoCoords',true); geoshow([land.Lat],[land.Lon]) m=gcm; latlim = m.maplatlimit; lonlim = m.maplonlimit; BoundingBox = [lonlim(1) latlim(1);lonlim(2) latlim(2)]; cities=shaperead('worldcities.shp', ...     'BoundingBox',BoundingBox,'UseGeoCoords',true); for index=1:numel(cities)     h=textm(cities(index).Lat, cities(index).Lon, ...         cities(index).Name);     trimcart(h)     rotatetext(h) end orient landscape tightmap axis off previewmap</pre>



**Limitations**

The figure cannot be made larger than the screen.

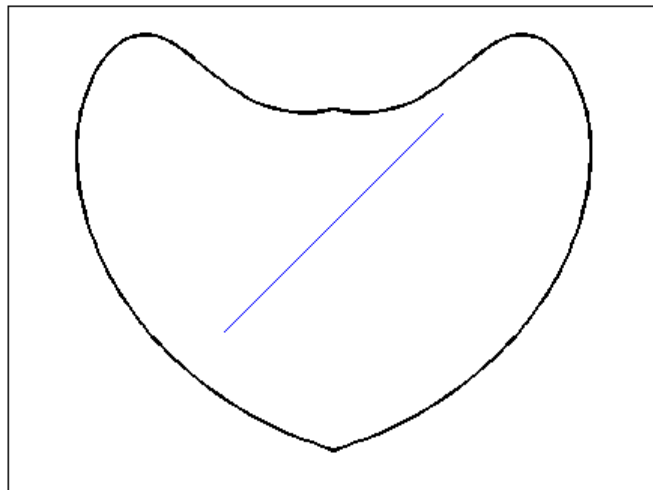
**See Also**

pagesetupd1g, paperscale, axesscale

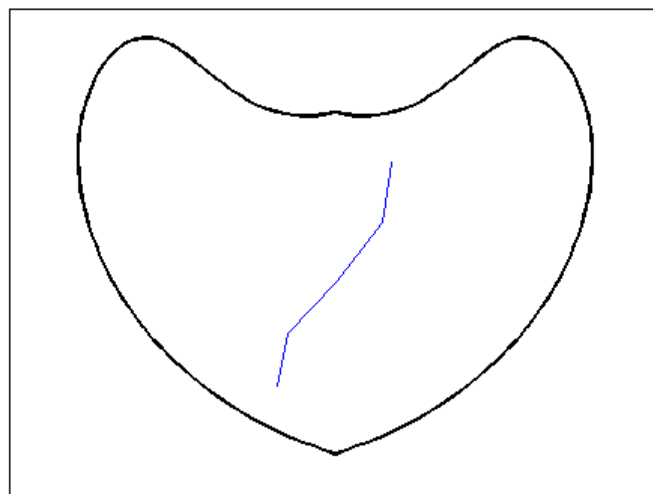


---

<b>Purpose</b>	Project displayed map graphics object
<b>Syntax</b>	<pre>project(h) project(h, 'xy') project(h, 'yx')</pre>
<b>Description</b>	<p><code>project(h)</code> takes unprojected objects with handles <code>h</code> that are displayed on map axes and projects them. For example, <code>project</code> takes a line created on a map axes with the <code>plot</code> function and projects it as though it had been created with the <code>plotm</code> function. This can be useful if a standard MATLAB function was accidentally executed. The map structure of the existing map axes determines the specifics of the projection. If <code>h</code> is the handle of the map axes, then all the children of <code>h</code> are projected. Do not attempt this if any children of <code>h</code> have already been projected!</p> <p><code>project(h, 'xy')</code> specifies that the <code>XData</code> of the unprojected objects corresponds to longitudes and the <code>YData</code> to latitudes. This is the default assumption.</p> <p><code>project(h, 'yx')</code> specifies that the <code>XData</code> of the unprojected objects corresponds to latitudes and the <code>YData</code> to longitudes.</p>
<b>Example</b>	<p>Create an axes, plot a line, then project it:</p> <pre>axesm('bonne','AngleUnits','radians');framem; h = plot([-1 -.5 0 .5 1],[-1 -.5 0 .5 1]);</pre>



project(h)



The line is straight in  $x$ - $y$  space, but when converted to a projected map object, it bends with the projection.

**See Also**

`linem`, `patchm`, `surfacem`, `textm`

**Purpose** Forward map projection using PROJ.4 map projection library

**Syntax** `[x, y] = projfwd(proj, lat, lon)`

**Description** `[x, y] = projfwd(proj, lat, lon)` returns the x and y map coordinates from the forward projection transformation. `proj` is a structure defining the map projection. `proj` can be an `mstruct` or a `GeoTIFF info` structure. `lat` and `lon` are arrays of the latitude and longitude coordinates.

For a complete list of `GeoTIFF info` and map projection structures that you can use with `projfwd`, see the reference page for `projlist`.

## **Example** **Overlay the boundary of Massachusetts on an orthophoto of Boston**

Read vector data for state boundary of Massachusetts (in latitude and longitude):

```
S = shaperead('usastatehi', 'UseGeoCoords', true, ...  
            'Selector',{@(name) strcmpi(name,'Massachusetts')}, 'Name');
```

Obtain the projection structure for the orthophoto and project the state boundary vectors to it (Massachusetts State Plane coordinate system, U.S. Survey Feet):

```
proj = geotiffinfo('boston.tif');  
lat = [S.Lat];  
lon = [S.Lon];  
[x, y] = projfwd(proj, lat, lon);
```

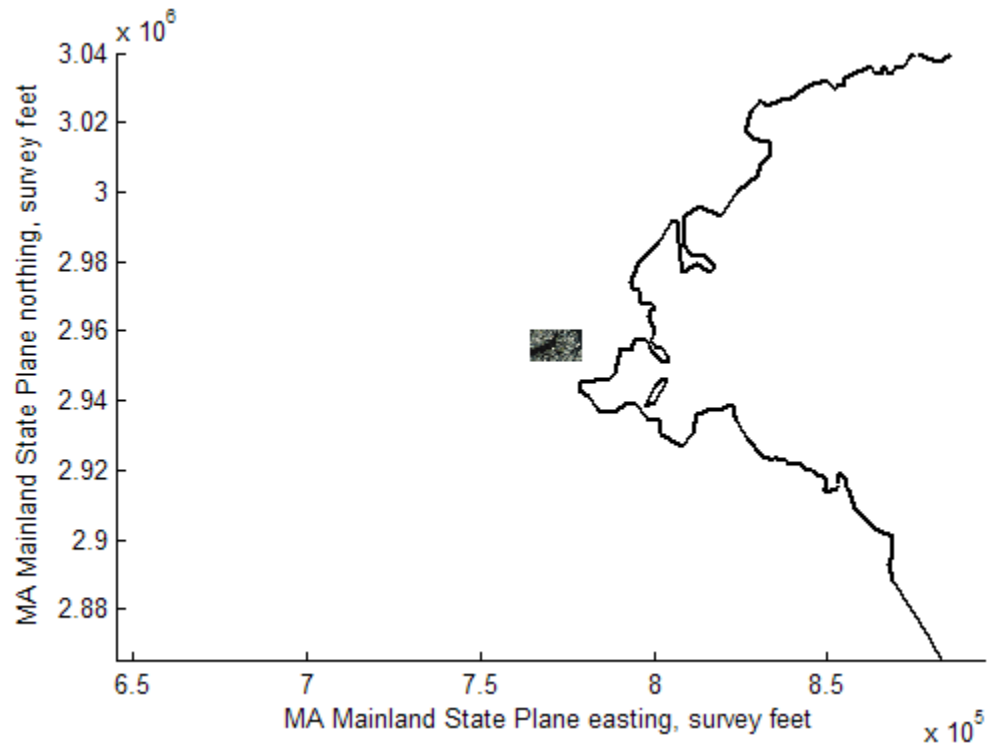
Read and display the 'boston.tif' orthophoto image:

```
[RGB, R, bbox] = geotiffread('boston.tif');  
figure  
mapshow(RGB, R)  
xlabel('MA Mainland State Plane easting, survey feet')  
ylabel('MA Mainland State Plane northing, survey feet')
```

Overlay the state boundary and set map limits to show a little more detail:

```
hold on
mapshow(gca, x, y, 'Color', 'black', 'LineWidth', 2.0)
set(gca, 'XLim', [ 645000,  895000], ...
        'YLim', [2865000, 3040000]);
```

boston.tif image copyright © GeoEye, all rights reserved.



# projfwd

---

## **See Also**

geotiffinfo, mfwdtran, minvtran, projinv, projlist

**Purpose** Inverse map projection using PROJ.4 map projection library

**Syntax** [lat, lon] = projinv(proj, x, y)

**Description** [lat, lon] = projinv(proj, x, y) returns the latitude and longitude values from the inverse projection transformation. proj is a structure defining the map projection. proj can be a map projection mstruct or a GeoTIFF info structure. x and y are x-y map coordinate arrays. For a complete list of GeoTIFF info and map projection structures that you can use with projinv, see the reference page for projlist.

### **Example**      **Display Boston Orthophoto on a Mercator projection**

- 1** Import the Boston roads from the shapefile and obtain the projection structure from the 'boston.tif' orthophoto:

```
roads = shaperead('boston_roads.shp');  
proj = geotiffinfo('boston.tif');
```

- 2** Convert the road coordinates to the projection's length unit. As shown by the UOMLength field of the projection structure, the units of length in the projected coordinate system is US Survey Feet. Coordinates in the roads shapefile are in meters:

```
proj.UOMLength  
  
ans =  
US survey foot  
  
x = [roads.X] * unitsratio('survey feet','meter');  
y = [roads.Y] * unitsratio('survey feet','meter');  
  
% Now convert the scaled coordinates of the roads  
% to latitude and longitude.  
[roadsLat, roadsLon] = projinv(proj, x, y);
```

- 3** Read the boston\_ovr.jpg image and worldfile:

```
RGB = imread('boston_ovr.jpg');  
R = worldfileread(getworldfilename('boston_ovr.jpg'));
```

- 4** Read state boundary vectors for Massachusetts from the `usastatehi` shapefile using a selector to eliminate other states:

```
S = shaperead('usastatehi', 'UseGeoCoords', true, ...  
    'Selector',{@(name) strcmpi(name,'Massachusetts'), 'Name'});
```

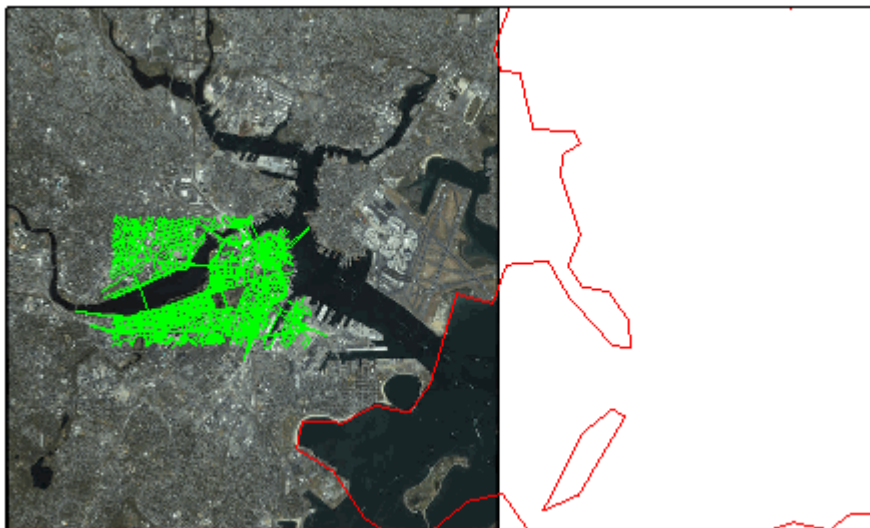
- 5** Open a figure with a Mercator projection and display the state boundary, image, and roads:

```
figure  
axesm('mercator')  
  
geoshow(S.Lat, S.Lon, 'Color','red')  
geoshow(RGB, R)  
geoshow(roadsLat, roadsLon, 'Color', 'green')
```

- 6** Set the map boundary to the image's northern, western, and southern limits, and the eastern limit of the state boundary within the image latitude bounding box:

```
[lon, lat] = mapoutline(R, size(RGB(:,:,1)));  
ltvals = find((S.Lat>=min(lat(:))) & (S.Lat<=max(lat(:))));  
setm(gca,'maplonlimit',[min(lon(:)) max(S.Lon(ltvals))], ...  
    'maplatlimit',[min(lat(:)) max(lat(:))])  
tightmap
```





boston\_ovr.jpg image copyright © GeoEye, all rights reserved.

**See Also**

[geotiffinfo](#), [mfwdran](#), [minvtran](#), [projfwd](#), [projlist](#)

# projlist

---

**Purpose** Map projections supported by `projfwd` and `projinv`

**Syntax** `projlist(listmode)`  
`S = projlist(listmode)`

**Description** `projlist(listmode)` displays a table of projection names, IDs, and availability. `listmode` is a string with value 'mapprojection', 'geotiff', 'geotiff2mstruct', or 'all'. The default value is 'mapprojection'.

`S = projlist(listmode)` returns a structure array containing projection names, IDs, and availability. The output of `projlist` for each `listmode` is described below:

- `mapprojection` — Lists the map projection IDs that are available for use with `projfwd` and `projinv`. The output structure contains the fields
  - `Name` — Projection name
  - `MapProjection` — Projection ID string
- `geotiff` — Lists the GeoTIFF projection IDs that are available for use with `projfwd` and `projinv`. The output structure contains the fields
  - `GeoTIFF` — GeoTIFF projection ID string.
  - `Available`— Logical array with values 1 or 0
- `geotiff2mstruct` — Lists the GeoTIFF projection IDs that are available for use with `geotiff2mstruct`. The output structure contains the fields
  - `GeoTIFF` — GeoTIFF projection ID string
  - `MapProjection` — Projection ID string
- `all` — Lists the map and GeoTIFF projection IDs that are available for use with `projfwd` and `projinv`. The output structure contains the fields

- `GeoTIFF` — GeoTIFF projection ID string
- `MapProjection` — Projection ID string
- `info` — Logical array with values 1 or 0
- `mstruct` — Logical array with values 1 or 0

## Remarks

`projfwd` and `projinv` can be used to process certain forward or inverse map projections. These functions are implemented in C using the PROJ.4 library. `projlist` provides a convenient list of the projections that can be used with `projfwd` or `projinv`. Because `projfwd` and `projinv` accept either a map projection structure (`mstruct`) or a GeoTIFF `info` structure, `projlist` provides separate lists for each case. It can also list the projections for which a GeoTIFF `info` structure can be converted to an `mstruct`.

## Examples

```
s=projlist

s =
1x19 struct array with fields:
    Name
    MapProjection

s=projlist('geotiff2mstruct')

s =
1x19 struct array with fields:
    GeoTIFF
    MapProjection
```

## See Also

`geotiff2mstruct`, `projfwd`, `projinv`, `maplist`, `maps`

# putpole

---

**Purpose** Origin vector to place north pole at specified point

**Syntax** `origin = putpole(pole)`  
`origin = putpole(pole,units)`

**Description** `origin = putpole(pole)` returns an origin vector required to transform a coordinate system in such a way as to put the true North Pole at a point specified by the three- (or two-) element vector `pole`. This vector is of the form `[latitude longitude meridian]`, specifying the coordinates in the original system at which the true North Pole is to be placed in the transformed system. The meridian is the longitude upon which the new system is to be centered, which is the new pole longitude if omitted. The output is a three-element vector of the form `[latitude longitude orientation]`, where the latitude and longitude are the coordinates in the untransformed system of the new origin, and the orientation is the azimuth of the true North Pole in the transformed system.

`origin = putpole(pole,units)` allows the specification of the angular units of the origin vector, where *units* is any valid angle units string. The default is 'degrees'.

**Remarks** When developing transverse or oblique projections, you need transformed coordinate systems. One way to define these systems is to establish the point in the original (untransformed) system that will become the new (transformed) origin.

**Examples** Pull the North Pole down the 0° meridian by 30° to 60°N. What is the resulting origin vector?

```
origin = putpole([60 0])

origin =
    30.0000         0         0
```

This makes sense: when the pole slid down 30°, the point that was 30° north of the origin slid down to become the origin. Following is a less obvious transformation:

```
origin = putpole([60 80 0]) % constrain to original central
                        % meridian

origin =
    4.9809         0    29.6217

origin = putpole([60 80 40]) % constrain to arbitrary meridian

origin =
    4.9809    40.0000    29.6217
```

**See Also**

`neworig`, `org2pol`

# quiver3m

---

**Purpose** Project 3-D quiver plot on map axes

**Syntax**

```
h = quiver3m(lat,lon,alt,u,v,w)
h = quiver3m(lat,lon,alt,u,v,w,linespec)
h = quiver3m(lat,lon,alt,u,v,w,linespec,'filled')
h = quiver3m(lat,lon,alt,u,v,w,scale)
h = quiver3m(lat,lon,alt,u,v,w,linespec,scale)
h = quiver3m(lat,lon,alt,u,v,w,linespec,scale,'filled')
```

**Description** `h = quiver3m(lat,lon,alt,u,v,w)` displays *velocity* vectors with components  $(u,v,w)$  at the geographic points  $(lat,lon)$  and altitude `alt` on a displayed map axes. The inputs `u`, `v`, and `w` determine the direction of the vectors in latitude, longitude, and altitude, respectively. The function automatically determines the length of these vectors to make them as long as possible without overlap. The object handles of the displayed vectors can be returned in `h`.

`h = quiver3m(lat,lon,alt,u,v,w,linespec)` allows the control of the line specification of the displayed vectors with a *linespec* string recognized by the MATLAB line function. If symbols are indicated in *linespec*, they are plotted at the start points of the vectors, i.e., the input points  $(lat,lon,alt)$ .

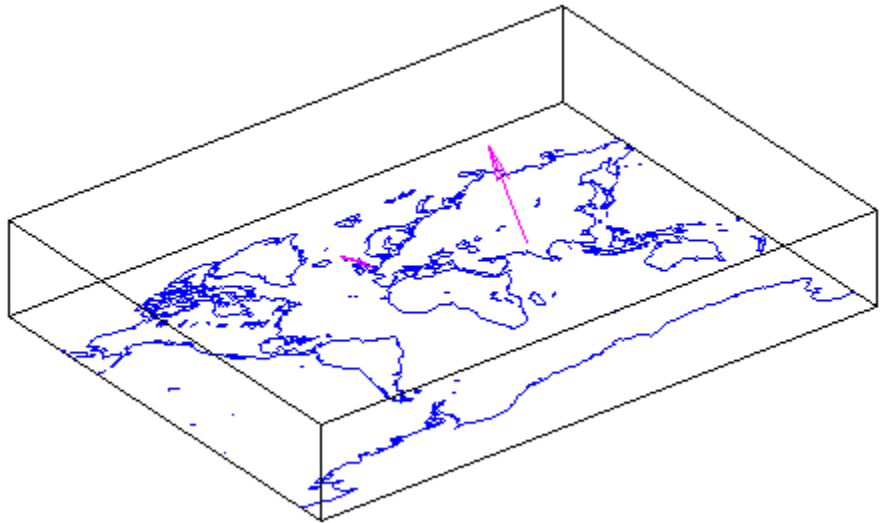
`h = quiver3m(lat,lon,alt,u,v,w,linespec,'filled')` results in the filling in of any symbols specified by *linespec*.

`h = quiver3m(lat,lon,alt,u,v,w,scale)`, `h = quiver3m(lat,lon,alt,u,v,w,linespec,scale)` and `h = quiver3m(lat,lon,alt,u,v,w,linespec,scale,'filled')` alter the automatically calculated vector lengths by multiplying them by the scalar value `scale`. For example, if `scale` is 2, the displayed vectors are twice as long as they would be if `scale` were 1 (the default). When `scale` is set to 0, the automatic scaling is suppressed and the length of the vectors is determined by the inputs. In this case, the vectors are plotted from  $(lat,lon,alt)$  to  $(lat+u,lon+v,alt+w)$ .

**Examples** Plot 3-D quiver vectors from London (51.5°N,0°) and New Delhi (29°N,77.5°E), both at an altitude of 0. Suppress the automatic scaling.

Terminate both vectors at an altitude of 1; the London vector should terminate  $100^\circ$  southward and  $70^\circ$  eastward, while the New Delhi vector should terminate  $50^\circ$  northward and  $10^\circ$  eastward.

```
load coast
axesm miller; view(3)
plotm(lat,long)
lat0 = [51.5,29]; lon0 = [0 77.5]; alt = [0 0];
u = [-40 50]; v = [-70 10]; w = [1 1];
quiver3m(lat0,lon0,alt,u,v,w,'m')
tightmap
```

**See Also**

quiverm, quiver3

**Purpose** Project 2-D quiver plot on map axes

**Syntax**

```
h = quiverm(lat,lon,u,v)
h = quiverm(lat,lon,u,v,linespec)
h = quiverm(lat,lon,u,v,linespec,'filled')
h = quiverm(lat,lon,u,v,scale)
h = quiverm(lat,lon,u,v,...linespec,scale,'filled')
```

**Description** `h = quiverm(lat,lon,u,v)` displays *velocity* vectors with components  $(u,v)$  at the geographic points  $(lat,lon)$  on displayed map axes. All four inputs should be in the `AngleUnits` of the map axes. The inputs `u` and `v` determine the direction of the vectors in latitude and longitude, respectively. The function automatically determines the length of these vectors to make them as long as possible without overlap. The object handles of the displayed vectors can be returned in `h`.

`h = quiverm(lat,lon,u,v,linespec)` allows the control of the line specification of the displayed vectors with a *linespec* string recognized by the MATLAB line function. If symbols are indicated in *linespec*, they are plotted at the start points of the vectors, i.e., the input points  $(lat,lon)$ .

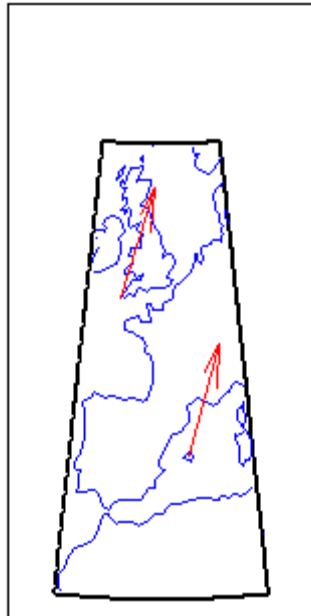
`h = quiverm(lat,lon,u,v,linespec,'filled')` results in the filling in of any symbols specified by *linespec*.

`h = quiverm(lat,lon,u,v,scale)` and `h = quiverm(lat,lon,u,v,...linespec,scale,'filled')` alter the automatically calculated vector lengths by multiplying them by the scalar value `scale`. For example, if `scale` is 2, the displayed vectors are twice as long as they would be if `scale` were 1 (the default). When `scale` is set to 0, the automatic scaling is suppressed, and the length of the vectors is determined by the inputs. In this case, the vectors are plotted from  $(lat,lon)$  to  $(lat+u,lon+v)$ .

**Example** Plot quiver vectors from Land's End (50°N,5.4°W) and Majorca (39.7°N,2.9°E) in a direction corresponding to +5° latitude and +3° longitude. Use automatic scaling.



```
load coast
axesm('eqaconic','MapLatLimit',[30 60],'MapLonLimit',[-10 10])
framem; plotm(lat,long)
lat0 = [50 39.7]; lon0 = [-5.4 2.9];
u = [5 5]; v = [3 3];
quiverm(lat0,lon0,u,v,'r')
```

**See Also**

quiver3m, quiver

# rad2km, rad2nm, rad2sm

---

**Purpose** Convert distance from radians to kilometers, nautical miles, or statute miles

**Syntax**

```
km = rad2km(rad)
nm = rad2nm(rad)
sm = rad2sm(rad)
km = rad2km(rad,radius)
nm = rad2nm(rad,radius)
sm = rad2sm(rad,radius)
km = rad2km(rad,sphere)
nm = rad2nm(rad,sphere)
sm = rad2sm(rad,sphere)
```

**Description** `km = rad2km(rad)` converts distances from radians to kilometers as measured along a great circle on a sphere with a radius of 6371 km, the mean radius of the Earth.

`nm = rad2nm(rad)` and `sm = rad2sm(rad)` work identically, except that the output units are nautical miles and statute miles, respectively.

`km = rad2km(rad,radius)` converts distances from radians to kilometers as measured along a great circle on a sphere having the specified radius. `radius` must be in units of kilometers.

For `nm = rad2nm(rad,radius)` and `sm = rad2sm(rad,radius)`, make sure your input radius is in the appropriate units.

`km = rad2km(rad,sphere)` converts distances from degrees to kilometers, as measured along a great circle on a sphere approximating an object in the Solar System. `sphere` may be one of the following strings: 'sun', 'moon', 'mercury', 'venus', 'earth', 'mars', 'jupiter', 'saturn', 'uranus', 'neptune', or 'pluto', and is case-insensitive.

`nm = rad2nm(rad,sphere)` and `sm = rad2sm(rad,sphere)` work identically, except that the output units are nautical miles and statute miles, respectively.

## Examples

How long is a trip around the equator in statute miles?

```
sm = rad2sm(2*pi)
```

```
sm =  
2.4874e+04
```

How about on Jupiter?

```
sm = rad2sm(2*pi, 'jupiter')
```

```
sm =  
2.7283e+005
```

## See Also

km2rad, degtorad, radtodeg, deg2km, km2deg, km2nm, km2sm, deg2nm,  
nm2rad, nm2km, nm2sm, deg2sm, sm2rad, sm2km, sm2nm

# radtodeg

---

**Purpose** Convert angles from radians to degrees

**Syntax** `angleInDegrees = radtodeg(angleInRadians)`

**Description** `angleInDegrees = radtodeg(angleInRadians)` converts angle units from radians to degrees. This is both an angle conversion function and a distance conversion function, because arc length can be a measure of distance in either radians or degrees (provided the radius is known).

**Examples** There are  $180^\circ$  in  $\pi$  radians:

```
anglout = radtodeg(pi)
```

```
anglout =  
180
```

**See Also** `degtorad` | `fromDegrees` | `fromRadians` | `toDegrees` | `toRadians`

**Purpose**

Radii of curvature of ellipsoid

**Syntax**

```
r = rcurve(ellipsoid,lat)
r = rcurve('parallel',ellipsoid,lat)
r = rcurve(ellipsoid,lat,units)
r = rcurve('meridian',ellipsoid,lat,units)
r = rcurve('transverse',ellipsoid,lat,units)
```

**Description**

`r = rcurve(ellipsoid,lat)` and `r = rcurve('parallel',ellipsoid,lat)` return the parallel radius of curvature at the latitude `lat` for a given elliptical definition, where `ellipsoid` is a two-element ellipsoid vector. This is the radius of the small circle encompassing the ellipsoid at the given latitude. The radius is a distance in units consistent with the semimajor axis, the first element of `ellipsoid`.

`r = rcurve(ellipsoid,lat,units)` specifies the units of the input `lat`, where `units` is any valid angle units string. The default is 'degrees'.

`r = rcurve('meridian',ellipsoid,lat,units)` returns the meridional radius, which is the radius of curvature at the latitude `lat` for the ellipse described by a meridian on the ellipsoid.

`r = rcurve('transverse',ellipsoid,lat,units)` returns the transverse radius, which is the radius of a curve described by the intersection of the ellipsoid with a plane normal to the surface of the ellipsoid at the latitude `lat`.

**Examples**

The radii of curvature of the default ellipsoid at 45°, in kilometers:

```
r = rcurve('transverse',almanac('earth','ellipsoid','km'),...
          45,'degrees')

r =
    6.3888e+03

r = rcurve('meridian',almanac('earth','ellipsoid','km'),...
```

```
45, 'degrees')  
  
r =  
  6.3674e+03  
  
r = rcurve('parallel',almanac('earth','ellipsoid','km'),...  
          45,'degrees')  
  
r =  
  4.5024e+03
```

## See Also

rsphere

**Purpose**

Read fields or records from fixed-format files

**Syntax**

```
struc = readfields(fname,fstruc)
struc = readfields(fname,fstruc,recordIDs)
struc = readfields(fname,fstruc,fieldIDs)
struc = readfields(fname,fstruc,recordIDs,mformat)
struc = readfields(fname,fstruc,recordIDs,mformat,fid)
struc = readfields(fname,fstruc,recordIDs,mformat,fid,
    'sparse')
```

**Description**

`struc = readfields(fname,fstruc)` reads all the records from a fixed format file. *fname* is a string containing the name of the file. If it is empty, the file is selected interactively. *fstruc* is a structure defining the format of the file. The contents of *fstruc* are described below. The result is returned in a structure.

`struc = readfields(fname,fstruc,recordIDs)` reads only the records specified in the vector *recordIDs*. For example, *recordIDs* = [1 2 3 4]. All the fields in the selected records are read.

`struc = readfields(fname,fstruc,fieldIDs)` reads only the fields specified in the cell array *fieldIDs*. For example, *fieldIDs* = {1 2 4}. The selected fields are read from all the records. *fieldIDs* can be used in place of *recordIDs* in all calling forms.

`struc = readfields(fname,fstruc,recordIDs,mformat)` opens the file with the specified machine format. *mformat* must be recognized by `fopen`.

`struc = readfields(fname,fstruc,recordIDs,mformat,fid)` reads from a file that is already open. *fid* is the file identifier returned by `fopen`. The records are read starting from the current location in the file.

`struc = readfields(fname,fstruc,recordIDs,mformat,fid,'sparse')` disables error messages when the number of elements read does not agree with the stated format of the file. This is useful for formatted files

# readfields

---

with empty fields. Use `fid = []` for files that are not already open. This option is only compatible with reading selected records.

## Background

Map data is often provided as binary or ASCII files with a fixed format. Writing your own functions to read the data into the MATLAB workspace can be difficult and time-consuming, particularly for binary files. This function allows you to read the data by simply specifying the format of the file.

## Examples

Write a binary file and read it.

```
fid = fopen('testbin','wb');
for i = 1:3
    fwrite(fid,['character' num2str(i) ],'char');
    fwrite(fid,i,'int8');
    fwrite(fid,[i i],'int16');
    fwrite(fid,i,'integer*4');
    fwrite(fid,i,'real*8');
end
fclose(fid);

fs(1).length = 10;fs(1).type = 'char';fs(1).name = 'field 1';
fs(2).length = 1;fs(2).type = 'int8'; fs(2).name = 'field 2';
fs(3).length = 2;fs(3).type = 'int16';fs(3).name = 'field 3';
fs(4).length = 1;fs(4).type = 'integer*4';fs(4).name = 'field 4';
fs(5).length = 1;fs(5).type = 'float64'; fs(5).name = 'field 5';

s = readfields('testbin',fs);

s(1)
ans =
    field1: 'character1'
    field2: 1
    field3: [1 1]
    field4: 1
    field5: 1
```



## Limitations

Formatted numbers must stay within the width specified for them. Files must have a size that is an integer multiple of the computed record length. This is potentially a problem for formatted files on DOS platforms that use a carriage return/linefeed line ending everywhere except the last record. File sizes are not checked when an open file is provided.

## Remarks

The format of the file is described in the input argument `fstruc`. `fstruc` is a structure with one entry for every field in the file. `fstruc` has three required fields: `length`, `name`, and `type`. For fields containing binary data of the type that would be read by `fread`, `length` is the number of elements to be read, `name` is a string containing the field name under which the read data is stored in the output structure, and `type` is a format string recognized by `fread`. Repetition modifiers such as `'40*char'` are *not* supported. Fields with empty field names are omitted from the output.

The following `fstruc` definition is for a file with a 40-character field, a field containing two integers, and a field with a single-precision floating-point number.

```
fstruc(1).length = 40;
fstruc(1).name = 'character Field'; % spaces will be suppressed
filestruc(1).type = 'char';

fstruc(2).length = 2;
fstruc(2).name = 'integer Field'; % spaces will be suppressed
fstruc(2).type = 'int16';

fstruc(3).length = 1;
fstruc(3).name = 'float Field'; % spaces will be suppressed
fstruc(3).type = 'real*4';
```

The `type` can also be a `fscanf` and `scanf`-style format string of the form `'%nX'`, where `n` is the number of characters within which the formatted data is found, and `X` is the conversion character such as `'g'` or `'d'`. For formatted fields, the `length` entry in `fstruc` is the number of elements, each of which has the width specified in the `type` string. Fortran-style

## readfields

---

double-precision output such as '0.0D00' can be read using a type string such as '%nD', where n is the number of characters per element. This is an extension to the C-style format strings accepted by `sscanf`. Users unfamiliar with C should note that '%d' is preferred over '%i' for formatted integers. MATLAB syntax follows C in interpreting '%i' integers with leading zeros as octal. Line-ending characters in ASCII files must also be counted in the `fstruc` specification. Note that the number of line-ending characters differs across platforms.

A field specification for a formatted field with two integers each six characters wide would be of the form

```
fstruc(4).length = 2;  
fstruc(4).name = 'Elevation Units';  
fstruc(4).type = '%6d'
```

To summarize, `length` is the number of elements for binary numbers, the number of characters for strings, and the number of elements for formatted data.

You can omit fields from all output by providing an empty string for the `fstruc` name field.

### See Also

`grepfields`, `readmtx`, `textread`, `spread`, `dlmread`

---

<b>Purpose</b>	Read Fifth Fundamental Catalog of Stars
<b>Syntax</b>	<pre>struc = readfk5(filename) struc = readfk5(filename, struc)</pre>
<b>Description</b>	<p><code>struc = readfk5(filename)</code> reads the FK5 file and returns the contents in a structure. Each star is an element in the structure, with the different data items stored in appropriately named fields.</p> <p><code>struc = readfk5(filename, struc)</code> appends the data in the file to the existing structure <code>struc</code>.</p>
<b>Background</b>	<p>The Fifth Fundamental Catalog of Stars (FK5), Parts I and II, is a compilation of data on more than 4500 stars. The catalog contains positions, errors in positions, proper motions, and characteristics such as magnitudes, spectral types, parallaxes, and radial velocities. There are also cross-references to the identities of stars in other catalogs. It was compiled by researchers at the Astronomisches Rechen-Institut in Heidelberg.</p>
<b>Remarks</b>	<p>Positions are given in terms of right ascension and declination. “Using Map Projections and Coordinate Systems” in the Mapping Toolbox documentation shows how to convert these to latitude and longitude for display by the toolbox.</p> <p>The Fifth Fundamental Catalog of Stars (FK5), Parts I and II data and documentation are available over the Internet by anonymous ftp.</p> <hr/> <p><b>Note</b> For details on locating map data for download over the Internet, see the following documentation at the MathWorks Web site: <a href="http://www.mathworks.com/support/tech-notes/2100/2101.html">http://www.mathworks.com/support/tech-notes/2100/2101.html</a>.</p> <hr/>
<b>Examples</b>	<pre>FK5 = readfk5('FK5.dat'); FK5e = readfk5('FK5_ext.dat'); whos</pre>

# readfk5

---

Name	Size	Bytes	Class
FK5	1x1535	5042752	struct array
FK5e	1x3117	10226424	struct array

FK5e(1)

ans =

FK5: 2003  
RAh: 0  
RAm: 5  
RAs: 1.1940  
pmRA: 0.6230  
DEd: 27  
DEm: 40  
DEs: 29.0100  
pmDE: -1.1100  
RAh1950: 0  
RAm1950: 2  
RAs1950: 26.5900  
pmRA1950: 0.6210  
DEd1950: 27  
DEm1950: 23  
DEs1950: 47.4400  
pmDE1950: -1.1100  
EpRA1900: 51.7200  
e\_RAs: 2  
e\_pmRA: 9  
EpDE1900: 46.8200  
e\_DEs: 3.4000  
e\_pmDE: 14  
Vmag: 6.4700  
n\_Vmag: ''  
SpType: 'G5'  
plx: []  
RV: 12  
AGK3R: '38'  
SRS: ''

HD: '225292'  
DM: 'BD+26 4744'  
GC: '48'

**References**

See references [5] and [6] in the Bibliography located at the end of this chapter.

**See Also**

dms2degrees, scatterm

# readmtx

---

## Purpose

Read matrix stored in file

## Syntax

```
mtx = readmtx(fname,nrows,ncols,precision)
mtx =
readmtx(fname,nrows,ncols,precision,readrows,readcols)
mtx = readmtx(fname,nrows,ncols,precision,... readrows,
            readcols,mformat)
mtx = readmtx(fname,nrows,ncols,precision,... readrows,
            readcols,mformat,nheadbytes)
mtx = readmtx(fname,nrows,ncols,precision,... readrows,
            readcols,mformat,nheadbytes,nRowHeadBytes)
mtx = readmtx(fname,nrows,ncols,precision,... readrows,
            readcols,mformat,nheadbytes,nRowHeadBytes,nRowTrailBytes)
mtx = readmtx(fname,nrows,ncols,precision,... readrows,
            readcols,mformat,nheadbytes,nRowHeadBytes,
            ... nRowTrailBytes,nFileTrailBytes)
mtx = readmtx(fname,nrows,ncols,precision,... readrows,
            readcols,mformat,nheadbytes,nRowHeadBytes,
            ... nRowTrailBytes,nFileTrailBytes,recordlen)
```

## Description

`mtx = readmtx(fname,nrows,ncols,precision)` reads a matrix stored in a file. The file contains only a matrix of numbers with the dimensions *nrows* by *ncols* stored with the specified *precision*. Recognized *precision* strings are described below.

`mtx = readmtx(fname,nrows,ncols,precision,readrows,readcols)` reads a subset of the matrix. *readrows* and *readcols* specify which rows and columns are to be read. They can be vectors containing the row or column numbers, or two-element vectors of the form [*start end*], which are expanded using the colon operator to *start:end*. To read just two rows or columns, without expansion by the colon operator, provide the indices as a column matrix.

`mtx = readmtx(fname,nrows,ncols,precision,... readrows,readcols,mformat)` specifies the machine format used to write the file. *mformat* can be any string recognized by `fopen`. This

option is used to automatically swap bytes for files written on platforms with a different byte ordering.

```
mtx = readmtx(fname,nrows,ncols,precision,...  
readrows,readcols,mformat,nheadbytes) skips the file header,  
whose length is specified in bytes.
```

```
mtx = readmtx(fname,nrows,ncols,precision,...  
readrows,readcols,mformat,nheadbytes,nRowHeadBytes) also skips  
a header that precedes every row of the matrix. The length of the  
header is specified in bytes.
```

```
mtx = readmtx(fname,nrows,ncols,precision,...  
readrows,readcols,mformat,nheadbytes,nRowHeadBytes,nRowTrailBytes)  
also skips a trailer that follows every row of the matrix. The  
length of the trailer is specified in bytes.
```

```
mtx = readmtx(fname,nrows,ncols,precision,...  
readrows,readcols,mformat,nheadbytes,nRowHeadBytes,...  
nRowTrailBytes,nFileTrailBytes) accounts for the length of data  
following the matrix. The sizes of the components of the matrix are  
used to compute an expected file size, which is compared to the actual  
file size.
```

```
mtx = readmtx(fname,nrows,ncols,precision,...  
readrows,readcols,mformat,nheadbytes,nRowHeadBytes,...  
nRowTrailBytes,nFileTrailBytes,recordlen) overrides the record  
length calculated from the precision and number of columns, and  
instead uses the record length given in bytes. This is used for formatted  
data with extra spaces or line breaks in the matrix.
```

## Background

Map data is often provided as binary or ASCII files with a fixed format. Writing your own functions to read the data into the MATLAB workspace can be difficult and time-consuming, particularly for binary files. This function allows you to read the data by simply specifying the format of the file.

## Examples

Write and read a binary matrix file:

```
fid = fopen('binmat','w');
fwrite(fid,1:100,'int16');
fclose(fid);
mtx = readmtx('binmat',10,10,'int16')
```

```
mtx =
    1     2     3     4     5     6     7     8     9    10
   11    12    13    14    15    16    17    18    19    20
   21    22    23    24    25    26    27    28    29    30
   31    32    33    34    35    36    37    38    39    40
   41    42    43    44    45    46    47    48    49    50
   51    52    53    54    55    56    57    58    59    60
   61    62    63    64    65    66    67    68    69    70
   71    72    73    74    75    76    77    78    79    80
   81    82    83    84    85    86    87    88    89    90
   91    92    93    94    95    96    97    98    99   100
```

```
mtx = readmtx('binmat',10,10,'int16',[2 5],3:2:9)
```

```
mtx =
   13    15    17    19
   23    25    27    29
   33    35    37    39
   43    45    47    49
```

## Limitations

Every row of the matrix must have the same number of elements.

## Remarks

This function reads files that have a general format consisting of a header, a matrix, and a trailer. Each row of the matrix can have a certain number of bytes of extraneous information preceding or following the matrix data.

Both binary and formatted data files can be read. If the file is binary, the precision argument is a format string recognized by `fread`. Repetition modifiers such as `'40*char'` are *not* supported. If the file is formatted, precision is a `fscanf` and `sscanf`-style format string of



the form `'%nX'`, where `n` is the number of characters within which the formatted data is found, and `X` is the conversion character such as `'g'` or `'d'`. Fortran-style double-precision output such as `'0.0D00'` can be read using a precision string such as `'%nD'`, where `n` is the number of characters per element. This is an extension to the C-style format strings accepted by `sscanf`. Users unfamiliar with C should note that `'%d'` is preferred over `'%i'` for formatted integers. MATLAB syntax follows C in interpreting `'%i'` integers with leading zeros as octal. Formatted files with line endings need to provide the number of trailing bytes per row, which can be 1 for platforms with carriage returns *or* linefeed (Macintosh, UNIX), or 2 for platforms with carriage returns *and* linefeeds (DOS).

**See Also**

`readfields`, `textread`, `spreadd`, `dlmread`

# reckon

---

## Purpose

Point at specified azimuth, range on sphere or ellipsoid

## Syntax

```
[latout,lonout] = reckon(lat,lon,rng,az)
[latout,lonout] = reckon(lat,lon,rng,az,units)
[latout,lonout] = reckon(lat,lon,rng,az,ellipsoid)
[latout,lonout] = reckon(lat,lon,rng,az,ellipsoid,units)
[latout,lonout] = reckon(track,...)
```

## Description

[latout,lonout] = reckon(lat,lon,rng,az), for scalar inputs, calculates a position (latout,lonout) at a given range rng and azimuth az along a great circle from a starting point defined by lat and lon. The range is in degrees of arc length on a sphere, lat and lon are in degrees, and the input azimuth is also in degrees, measured clockwise from due north. reckon calculates multiple positions when given four non-scalar inputs of matching size. When given a combination of scalar and array inputs, the scalar inputs are automatically expanded to match the size of the arrays.

[latout,lonout] = reckon(lat,lon,rng,az,units), where *units* is any valid angle units string, specifies the angular units of the inputs and outputs, including rng. The default value is 'degrees'.

[latout,lonout] = reckon(lat,lon,rng,az,ellipsoid) calculates positions along a geodesic on an ellipsoid, as specified by the two-element vector *ellipsoid*. The range, rng, is in linear distance units matching the units of the semimajor axis of the ellipsoid (the first element of *ellipsoid*).

[latout,lonout] = reckon(lat,lon,rng,az,ellipsoid,units) calculates positions on the specified ellipsoid with lat, lon, az, latout, and lonout in the specified angle units.

[latout,lonout] = reckon(track,...) calculates positions on great circles (or geodesics) if *track* is 'gc' and along rhumb lines if *track* is 'rh'. The default value is 'gc'.

## Examples

Find the coordinates of the point 600 nautical miles northwest of London, UK (51.5°N,0°) in a great circle sense:

```
% convert nm distance to degrees
dist = nm2deg(600)
dist =
    9.9933

% northwest is 315 degrees
pt1 = reckon(51.5,0,dist,315)
pt1 =
    57.8999  -13.3507
```

Now, determine where a plane from London traveling on a constant northwesterly course for 600 nautical miles would end up:

```
pt2 = reckon('rh',51.5,0,dist,315)

pt2 =
    58.5663  -12.3699
```

How far apart are the points above (distance in great circle sense)?

```
separation = distance('gc',pt1,pt2)

separation =
    0.8430

% convert answer to nautical miles
nmsep = deg2nm(separation)
nmsep =
    50.6156
```

Over 50 nautical miles separate the two points.

## See Also

[azimuth](#) | [distance](#) | [km2deg](#) | [dreckon](#) | [track](#) | [track1](#) | [track2](#)

# reducem

---

**Purpose** Reduce density of points in vector data

**Syntax**

```
[latout,lonout] = reducem(latin,lonin)
[latout,lonout] = reducem(latin,lonin,tol)
[latout,lonout,cerr] = reducem(...)
[latout,lonout,cerr,tol] = reducem(...)
```

**Description**

[latout,lonout] = reducem(latin,lonin) reduces the number of points in vector map data. In this case the tolerance is computed automatically.

[latout,lonout] = reducem(latin,lonin,tol) uses the provided tolerance. The units of the tolerance are degrees of arc on the surface of a sphere.

[latout,lonout,cerr] = reducem(...) in addition returns a measure of the error introduced by the simplification. The output cerr is the difference in the arc length of the original and reduced data, normalized by the original length.

[latout,lonout,cerr,tol] = reducem(...) also returns the tolerance used in the reduction, which is useful when the tolerance is computed automatically.

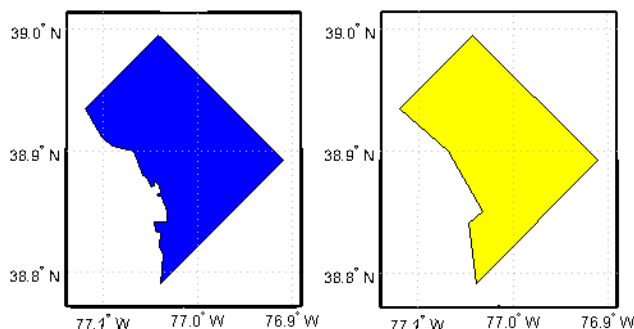
**Example** Compare the original and reduced outlines of the District of Columbia from the usastatehi demo state outline data:

```
dc = shaperead('usastatehi',...
    'UseGeoCoords', true,...
    'Selector',{'@(name) ...
        strcmpi(name,'district of columbia'), 'Name'});
lat = extractfield(dc, 'Lat');
lon = extractfield(dc, 'Lon');
[latreduced, lonreduced] = reducem(lat, lon);

lonlim = dc.BoundingBox(:,1)' + [-0.02 0.02];
latlim = dc.BoundingBox(:,2)' + [-0.02 0.02];
```

```
subplot(1,2,1)
usamap(latlim, lonlim); axis off
geoshow(lat, lon,...
        'DisplayType', 'polygon', 'FaceColor', 'blue')

subplot(1,2,2)
usamap(latlim, lonlim); axis off
geoshow(latreduced, lonreduced,...
        'DisplayType', 'polygon', 'FaceColor', 'yellow')
```



## Remarks

Vector data is reduced using the Douglas-Peucker line simplification algorithm. This method recursively subdivides a polygon until a run of points can be replaced by a straight line segment, with no point in that run deviating from the straight line by more than the tolerance. The distances used to decide on which runs of points to eliminate are computed in a Plate Carrée projection.

Reduced geographic data might not always be appropriate for display. If all intermediate points in a data set are reduced, then lines appearing straight in one projection are incorrectly displayed as straight lines in others.

# reducem

---

## See Also

interp

Interpolate vector data to a specified data separation

resizem

Resize a data grid

**Purpose** Convert referencing matrix to referencing vector

**Syntax** `refvec = refmat2vec(R,s)`

**Description** `refvec = refmat2vec(R,s)` converts a referencing matrix, `R`, to the three-element referencing vector `refvec`. `R` is a 3-by-2 referencing matrix defining a two-dimensional affine transformation from pixel coordinates to spatial coordinates. `s` is the size of the array (data grid) that is being referenced. `refvec` is a 1-by-3 referencing vector having elements [cells/degree north-latitude west-longitude] with latitude and longitude limits specified in degrees.

**Example**

```
% Verify the conversion of the geoid referencing vector to a
% referencing matrix.
load geoid;
R = refvec2mat(geoidlegend, size(geoid));
V = refmat2vec(R, size(geoid));
```

**See Also** `makerefmat`, `refvec2mat`

# refvec2mat

---

**Purpose** Convert referencing vector to referencing matrix

**Syntax** `R = refvec2mat(refvec,s)`

**Description** `R = refvec2mat(refvec,s)` converts a referencing vector, `refvec`, to the referencing matrix `R`. `refvec` is a 1-by-3 referencing vector having elements [cells/degree north-latitude west-longitude] with latitude and longitude limits specified in degrees. `s` is the size of the array (data grid) that is being referenced. `R` is a 3-by-2 referencing matrix defining a two-dimensional affine transformation from pixel coordinates to spatial coordinates.

**Example**

```
% Convert the geoid referencing vector to a referencing matrix
load geoid;
R = refvec2mat(geoidlegend, size(geoid));
```

**See Also** `makerefmat`, `refmat2vec`



## Purpose

Clean up NaN separators in polygons and lines

## Syntax

```
[xdata, ydata] = removeExtraNaNSeparators(xdata,ydata)
[xdata, ydata, zdata] = removeExtraNaNSeparators(xdata,ydata,
    zdata)
```

## Description

[xdata, ydata] = removeExtraNaNSeparators(xdata,ydata) removes NaNs from the vectors xdata and ydata, leaving only isolated NaN separators. If present, one or more leading NaNs are removed entirely. If present, a single trailing NaN is preserved. NaNs are removed, but never added, so if the input lacks a trailing NaN, so will the output. xdata and ydata must match in size and have identical NaN locations.

```
[xdata, ydata, zdata] =
removeExtraNaNSeparators(xdata,ydata,zdata) removes NaNs
from the vectors xdata, ydata, and zdata, leaving only isolated NaN
separators and optionally, if consistent with the input, a single
trailing NaN.
```

## Examples

```
xin = [NaN NaN 1:3 NaN 4:5 NaN NaN NaN 6:9 NaN NaN];
yin = xin;
[xout, yout] = removeExtraNaNSeparators(xin, yin);
xout
```

```
xout =
    1  2  3  NaN  4  5  NaN  6  7  8  9  NaN
```

```
xin = [NaN 1:3 NaN NaN 4:5 NaN NaN NaN 6:9]'
yin = xin;
zin = xin;
[xout, yout, zout] = removeExtraNaNSeparators(xin, yin, zin);
xout
```

```
xout =
    1
    2
    3
```

# removeExtraNaNSeparators

---

NaN

4

5

NaN

6

7

8

9

**Purpose**

Resize regular data grid

**Syntax**

```
Z = resizing(Z1, scale)
Z = resizing(Z1, [numrows numcols])
[Z, R] = resizing(Z1, scale, R1)
[Z, R] = resizing(Z1, [numrows numcols], R1)
[...] = resizing(..., method)
```

**Description**

`Z = resizing(Z1, scale)` returns a regular data grid `Z` that is `scale` times the size of the input, `Z1`. `resizing` uses interpolation to resample to a new sample density/cell size. If `scale` is between 0 and 1, the size of `Z` is smaller than the size of `Z1`. If `scale` is greater than 1, the size of `Z` is larger. For example, if `scale` is 0.5, the number of rows and the number of columns will be halved. By default, `resizing` uses nearest neighbor interpolation.

`Z = resizing(Z1, [numrows numcols])` resizes `Z1` to have `numrows` rows and `numcols` columns. `numrows` and `numcols` must be positive whole numbers.

`[Z, R] = resizing(Z1, scale, R1)` or `[Z, R] = resizing(Z1, [numrows numcols], R1)` resizes a regular data grid with a referencing vector or matrix, `R1`, and returns a new grid and its referencing vector or matrix, `R`. `R1` is either a 1-by-3 vector containing elements:

```
[cells/degree northern_latitude_limit western_longitude_limit]
```

or a 3-by-2 referencing matrix that transforms raster row and column indices to/from geographic coordinates according to:

```
[lon lat] = [row col 1] * R1
```

If `R1` is a referencing matrix, it must define a (non-rotational, non-skewed) relationship in which each column of the data grid falls along a meridian and each row falls along a parallel. If `R1` is a referencing vector, then `R` is a referencing vector. Likewise, if `R1` is a referencing matrix, then `R` is a referencing matrix. If `R1` is a referencing

# resize

---

vector, then `scale` must be a scalar resizing factor; the form `[numrows numcols]` is supported only for referencing matrices.

`[...] = resize(..., method)` resizes a regular data grid using one of the following three interpolation methods:

Method	Description
'nearest'	nearest neighbor interpolation (default)
'bilinear'	bilinear interpolation
'bicubic'	bicubic interpolation

If the grid size is being reduced (`scale` is less than 1 or `[numrows numcols]` is less than the size of the input grid) and `method` is 'bilinear' or 'bicubic', `resize` applies a low-pass filter before interpolation, to reduce aliasing. The default filter size is 11-by-11. You can specify a different length for the default filter using:

```
[...] = resize(..., method, n)
```

`n` is an integer scalar specifying the size of the filter, which is `n`-by-`n`. If `n` is 0 or `method` is 'nearest', `resize` omits the filtering step. You can also specify your own filter `h` using:

```
[...] = resize(..., method, h)
```

`h` is any two-dimensional FIR filter (such as those returned by Image Processing Toolbox functions `ftrans2`, `fwind1`, `fwind2`, or `fsamp2`). If `H` is specified, filtering is applied even when `method` is 'nearest'.

## Example

Double the size of a grid then reduce it using different methods:

```
Z = [1 2; 3 4]
```

```
Z =  
    1  2  
    3  4
```

```
neargrid = resizing(Z,2)
```

```
neargrid =
    1  1  2  2
    1  1  2  2
    3  3  4  4
    3  3  4  4
```

```
bilingrid = resizing(Z,2,'bilinear')
```

```
bilingrid =
    1.0000    1.3333    1.6667    2.0000
    1.6667    2.0000    2.3333    2.6667
    2.3333    2.6667    3.0000    3.3333
    3.0000    3.3333    3.6667    4.0000
```

```
bicubgrid = resizing(bilingrid,[3 2],'bicubic')
```

```
bicubgrid =
    0.7406    1.2994
    1.6616    2.3462
    1.9718    2.5306
```

**See Also**

`filter2` (MATLAB function)

# restack

---

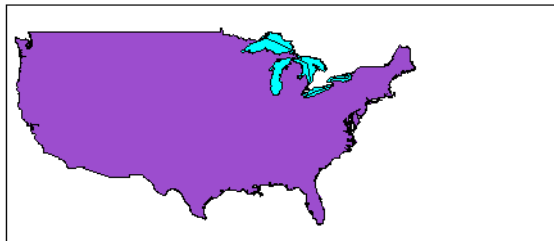
**Purpose** Restack objects within map axes

**Syntax** `restack(h,position)`

**Description** `restack(h,position)` changes the stacking position of the object `h` within the axes. `h` can be a handle, a vector of handles to graphics objects, or a name string recognized by `handlem`. Recognized *position* strings are 'top', 'bottom', 'bot', 'up', or 'down'.

**Examples** Restack the great lakes to lie on top of conus:

```
figure; axesm miller
load conus
h = geoshow(gtlakelat, gtlakelon,...
    'DisplayType', 'polygon', 'FaceColor', 'cyan');
geoshow(uslat, uslon,...
    'DisplayType', 'polygon', 'FaceColor', [0.6 0.3 0.8])
% The great lakes were plotted first but need to be on top
% Cast handle to great lakes object to double in call to RESTACK
restack(double(h),'top')
```



**Remarks** This function is the command line equivalent of the stacking buttons in the `mobjects` graphical user interface. The stacking order is the order of the children of the axes.

**See Also** `mobjects`

<b>Purpose</b>	Intersection points for pairs of rhumb lines
<b>Syntax</b>	<pre>[newlat,newlong] = rhxrh(lat1,lon1,az1,lat2,lon2,az2) [newlat,newlon] = rhxrh(lat1,lon1,az1,lat2,lon2,az2,units)</pre>
<b>Description</b>	<p>[newlat,newlong] = rhxrh(lat1,lon1,az1,lat2,lon2,az2) returns in newlat and newlon the location of the intersection point for each pair of rhumb lines input in <i>rhumb line notation</i>. For example, the first line in the pair passes through the point (lat1,lon1) and has a constant azimuth of az1. When the two rhumb lines are identical or do not intersect (conditions that are not, in general, apparent by inspection), two NaNs are returned instead and a warning is displayed. The inputs must be column vectors.</p> <p>[newlat,newlon] = rhxrh(lat1,lon1,az1,lat2,lon2,az2,units) specifies the units used, where <i>units</i> is any valid units string. The default units are 'degrees'.</p> <p>For any pair of rhumb lines, there are three possible intersection conditions: the lines are identical, they intersect once, or they do not intersect at all (except at the poles, where all nonequatorial rhumb lines meet—this is not considered an intersection). rhxrh does not allow multiple rhumb line intersections, although it is possible to construct cases in which such a condition occurs. See the following discussion of Limitations.</p> <p><i>Rhumb line notation</i> consists of a point on the line and the constant azimuth of the line.</p>
<b>Examples</b>	<p>Given a starting point at (10°N,56°W), a plane maintains a constant heading of 35°. Another plane starts at (0°,10°W) and proceeds at a constant heading of 310° (−50°). Where would their two paths cross each other?</p> <pre>[newlat,newlong] = rhxrh(10,-56,35,0,-10,310)  newlat =     26.9774</pre>

```
newlong =  
-43.4088
```

## Limitations

Rhumb lines are specifically helpful in navigation because they represent lines of constant heading, whereas great circles have, in general, continuously changing heading. In fact, the Mercator projection was originally designed so that rhumb lines plot as straight lines, which facilitates both manual plotting with a straightedge and numerical calculations using a Cartesian planar representation. When a rhumb line proceeds off the left or right *edge* of this representation at some latitude, it reappears on the other edge at the same latitude and continues on the same slope. For rhumb lines where this occurs—for example, one with a heading of 85°—it is easy to imagine another rhumb line, say one with a heading of 0°, repeatedly intersecting the first. The real-world uses of rhumb lines make this merely an intellectual exercise, however, for in practice it is always clear which *crossing* line segment is relevant. The function `rhxrh` returns at most one intersection, selecting in each case that line segment containing the input starting point for its computation.

## See Also

`gcxgc`, `gcxsc`, `scxsc`, `crossfix`, `polyxpoly`, `navfix`



**Purpose** Construct cell array of workspace variables for `mlayers` tool

**Syntax** `rootlayr`

**Description** `rootlayr` allows the `mlayers` tool to be used with workspace variables. It constructs a cell array that contains all the structure variables in the current workspace. This cell array is returned in the variable `ans`, which can then be an input to `mlayers`. If there is an existing variable named `ans`, it is overwritten.

The recommended calling procedure is `rootlayr;mlayers(ans)`;

**Examples** `rootlayr` creates a cell array named `ans`, consisting of the three structure variables in the following workspace.

```
whos
  Name          Size          Bytes  Class
  borders       1x1             38390  struct array
  lats          2345x1         18760  double array
  lons          2345x1         18760  double array
  nation        1x1             70224  struct array
  states        1x51         254970  struct array
```

```
rootlayr
ans
ans =
  [1x1 struct]    'borders'
  [1x1 struct]    'nation'
  [1x51 struct]   'states'
```

The function `mlayers(ans)` can now be used to activate the `mlayers` tool for the structures contained in `ans`.

**See Also** `mlayers`

# rotatem

---

**Purpose** Transform vector map data to new origin and orientation

**Syntax**

```
[lat1,lon1] = rotatem(lat,lon,origin,'forward')
[lat1,lon1] = rotatem(lat,lon,origin,'inverse')
[lat1,lon1] = rotatem(lat,lon,origin,'forward',units)
[lat1,lon1] = rotatem(lat,lon,origin,'forward',units)
```

**Description** [lat1,lon1] = rotatem(lat,lon,origin,'forward') transforms latitude and longitude data (lat and lon) to their new coordinates (lat1 and lon1) in a coordinate system resulting from Euler angle rotations as specified by origin. The input origin is a three- (or two-) element vector having the form [latitude longitude orientation]. The latitude and longitude are the coordinates of the point in the original system, which is the center of the output system. The orientation is the azimuth from the new origin point to the original North Pole in the new system. If origin has only two elements, the orientation is assumed to be 0°. This origin vector might be the output of putpole or newpole.

[lat1,lon1] = rotatem(lat,lon,origin,'inverse') transforms latitude and longitude data (lat and lon) in a coordinate system *that has been transformed* by Euler angle rotations specified by origin to their coordinates (lat1 and lon1) in the coordinate system *from which they were originally transformed*. In a sense, this *undoes* the 'forward' process. Be warned, however, that if data is rotated forward and then inverted, the final data might not be identical to the original. This is because of roundoff and *data collapse* at the original and intermediate singularities (the poles).

[lat1,lon1] = rotatem(lat,lon,origin,'forward',units) and [lat1,lon1] = rotatem(lat,lon,origin,'forward',units) specify the angle units of the data, where *units* is any recognized angle units string. The default is 'radians'. Note that this default is different from that of most functions.

The rotatem function transforms vector map data to a new coordinate system.

An analytical use of the new data can be realized in conjunction with the newpole function. If a selected point is made the *north pole* of

the new system, then when new vector data is created with `rotatem`, the distance of every data point from this new north pole is its new colatitude ( $90^\circ$  minus latitude). The absolute difference in the great circle azimuths between every pair of points from their new *pole* is the same as the difference in their new longitudes.

## Examples

What are the coordinates of Rio de Janeiro ( $23^\circ\text{S}, 43^\circ\text{W}$ ) in a coordinate system in which New York ( $41^\circ\text{N}, 74^\circ\text{W}$ ) is made the North Pole? Use the `newpole` function to get the origin vector associated with putting New York at the pole:

```
nylat = 41; nylon = -74;
riolat = -23; riolon = -43;
origin = newpole(nylat, nylon);
[riolat1, riolon1] = rotatem(riolat, riolon, origin, ...
                            'forward', 'degrees')

riolat1 =
    19.8247
riolon1 =
   -149.7375
```

What does this mean? For one thing, the colatitude of Rio in this new system is its distance from New York. Compare the distance between the original points and the new colatitude:

```
dist = distance(nylat, nylon, riolat, riolon)

dist =
    70.1753

90-riolat1

ans =
    70.1753
```

## See Also

`neworig`, `newpole`, `org2pol`, `putpole`

# rotatetext

---

**Purpose** Rotate text to projected graticule

**Syntax** `rotatetext`  
`rotatetext(objects)`  
`rotatetext(objects, 'inverse')`

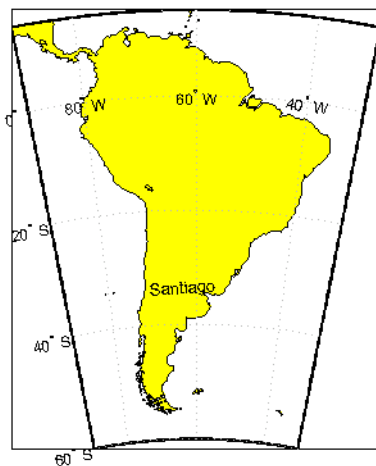
**Description** `rotatetext` rotates displayed text objects to account for the curvature of the graticule. The objects are selected interactively from a graphical user interface.

`rotatetext(objects)` rotates the selected objects. `objects` can be a name string recognized by `handlem` or a vector of handles to displayed text objects.

`rotatetext(objects, 'inverse')` removes the rotation added by an earlier use of `rotatetext`. If omitted, 'forward' is assumed.

**Examples** Add text to a map and rotate the text to the graticule.

```
figure
worldmap('south america')
geoshow('landareas.shp','facecolor','yellow')
cities = shaperead('worldcities.shp', 'UseGeoCoords', true);
Santiago = strmatch('Santiago',{cities(:).Name});
h=textm(cities(Santiago).Lat, cities(Santiago).Lon, ...
        'Santiago');
rotatetext(h)
```

**Remarks**

You can rotate meridian and parallel labels automatically by setting the map axes LabelRotation property to 'on'.

**See Also**

vfdtran, vinvtran

# roundn

---

**Purpose** Round to multiple of  $10^n$

**Syntax** `roundn(x,n)`

**Description** `roundn(x,n)` rounds each element of `x` to the nearest multiple of  $10^n$ . `n` must be scalar, and integer-valued. For complex `x`, the imaginary and real parts are rounded independently. For `n = 0`, `roundn` gives the same result as `round`. That is, `roundn(x,0) == round(x)`.

**Examples** Round pi to the nearest hundredth.

```
roundn(pi, -2)
```

```
ans =
```

```
3.1400
```

Round the equatorial radius of the Earth, 6378137 meters, to the nearest kilometer.

```
roundn(6378137, 3)
```

```
ans =
```

```
6378000
```

**See Also** `round`

**Purpose**

Radii of auxiliary spheres

**Syntax**

```
r = rsphere('biaxial',ellipsoid)
r = rsphere('biaxial',ellipsoid,method)
r = rsphere('triaxial',ellipsoid)
r = rsphere('eqavol',ellipsoid)
r = rsphere('authalic',ellipsoid)
r = rsphere('rectifying',ellipsoid)
r = rsphere('curve',ellipsoid,lat,method,units)
r = rsphere('euler',lat1,lon1,lat2,lon2,ellipsoid)
r = rsphere('euler',lat1,lon1,lat2,lon2,ellipsoid,units)
```

**Description**

`r = rsphere('biaxial',ellipsoid)` calculates the radius of a biaxial auxiliary sphere for the ellipsoid specified by the two-element ellipsoid vector `ellipsoid`. The output, `r`, is the radius of this sphere in units consistent with the semimajor axis, that is, the first element of `ellipsoid`. The biaxial radius is calculated by averaging the semimajor and semiminor axes of the ellipsoid, giving each equal weight.

`r = rsphere('biaxial',ellipsoid,method)` specifies the averaging method. If the string `method` is 'mean' (the default), an arithmetic mean is used. If `method` is 'norm', a geometric mean is used.

`r = rsphere('triaxial',ellipsoid)` results in a triaxial radius, which is calculated by averaging the ellipsoidal axes while giving double weight to the semimajor axis to reflect its role in two of the ellipsoid's three dimensions.

`r = rsphere('eqavol',ellipsoid)` returns the radius of a sphere with a volume equal to that of the ellipsoid.

`r = rsphere('authalic',ellipsoid)` returns the radius of a sphere with a surface area equal to that of the ellipsoid.

`r = rsphere('rectifying',ellipsoid)` returns the radius of a sphere with meridional distances equal to those of the ellipsoid.

`r = rsphere('curve',ellipsoid,lat,method,units)` returns a radius that is the result of averaging the meridional and transverse radii of curvature at the specified latitude, `lat`. The units of the input

# rsphere

---

lat can be specified by the valid angle units string *units*. The default units are 'degrees', the default averaging method is 'mean', and the default latitude is 45°.

`r = rsphere('euler',lat1,lon1,lat2,lon2,ellipsoid)` and `r = rsphere('euler',lat1,lon1,lat2,lon2,ellipsoid,units)` calculate a radius using Euler's Theorem. This calculation requires the specification of an arc that is defined by its endpoints, (lat1,lon1) and (lat2,lon2).

The `rsphere` function calculates the radii of auxiliary spheres for the ellipsoid. An auxiliary sphere is a sphere that shares certain desired characteristics with the ellipsoid.

## Examples

Different criteria result in different spheres:

```
r = rsphere('biaxial',almanac('earth','ellipsoid','km'))
```

```
r =  
6.3674e+03
```

```
r = rsphere('triaxial',almanac('earth','ellipsoid','km'))
```

```
r =  
6.3710e+03
```

```
r = rsphere('curve',almanac('earth','ellipsoid','km'))
```

```
r =  
6.3781e+03
```

## See Also

`rcurve`



**Purpose**

Read 2-minute terrain/bathymetry from Smith and Sandwell

**Syntax**

```
[latgrat, longrat, z] = satbath
[latgrat, longrat, z] = satbath(scalefactor)
[latgrat, longrat, z] = satbath(scalefactor, latlim, lonlim)
[latgrat, longrat, z] = satbath(scalefactor, latlim, lonlim,
    gsize)
```

**Description**

`[latgrat, longrat, z] = satbath` reads the global topography file for the entire world (`topo_8.2.img`), returning every 50<sup>th</sup> point. The result is returned as a geolocated data grid. If you use a different version of the global topography file, you need to rename it to “`topo_8.2.img`”. If the file is not found on the MATLAB path, a dialog opens to request the file.

`[latgrat, longrat, z] = satbath(scalefactor)` returns the data for the entire world, subsampled by the integer `scalefactor`. A `scalefactor` of 10 returns every 10th point. The matrix at full resolution has 6336 by 10800 points.

`[latgrat, longrat, z] = satbath(scalefactor, latlim, lonlim)` returns data for the specified region. The returned data extends slightly beyond the requested area. If omitted, the entire area covered by the data file is returned. The limits are two-element vectors in units of degrees, with `latlim` in the range `[-90 90]` and `lonlim` in the range `[-180 180]`.

`[latgrat, longrat, z] = satbath(scalefactor, latlim, lonlim, gsize)` controls the size of the graticule matrices. `gsize` is a two-element vector containing the number of rows and columns desired. If omitted, a graticule the size of the data grid is returned.

**Background**

This is a global bathymetric model derived from ship soundings and satellite altimetry by W.H.F. Smith and D.T. Sandwell. The model was developed by iteratively adjusting gravity anomaly data from Geosat and ERS-1 against historical track line soundings. This technique takes advantage of the fact that gravity mirrors the large variations in the ocean floor as small variations in the height of the ocean's

surface. The computational procedure uses the ship track line data to calibrate the scaling between the observed surface undulations and the inferred bathymetry. Land elevations are reduced-resolution versions of GTOPO30 data.

## Remarks

Land elevations are given in meters above mean sea level. The data is stored in a Mercator projection grid. As a result, spatial resolution varies with latitude. The grid spacing is 2 minutes (about 4 kilometers) at the equator.

This data is available over the Internet, but subject to copyright. The data file is binary, and should be transferred with no line-ending conversion or byte swapping. This function carries out any byte swapping that might be required. The data requires about 133 MB uncompressed.

The data and documentation are available over the Internet via http and anonymous ftp. Download the latest version of file `topo_x.2.img`, where `x` is the version number, and rename it `topo_8.w.img` for compatibility with the `satbath` function.

`satbath` returns a geolocated data grid rather than a regular data grid and a referencing vector or matrix. This is because the data is in a Mercator projection, with columns evenly spaced in longitude, but with decreasing spacing for rows at higher latitudes. Referencing vectors and matrices assume that the number of cells per degrees of latitude and longitude are both constant across a data grid.

---

**Note** For details on locating map data for download over the Internet, see the following documentation at the MathWorks Web site: <http://www.mathworks.com/support/tech-notes/2100/2101.html>.

---

## Examples

Read the data for the Falklands Islands (Islas Malvinas) at full resolution.

```
[latgrat,longrat,mat] = satbath(1,[-55 -50],[-65 -55]);
```

whos

Name	Size	Bytes	Class
latgrat	247x301	594776	double array
longrat	247x301	594776	double array
mat	247x301	594776	double array

**See Also**

tbase, gtopo30, egm96geoid

# scaleruler

---

**Purpose** Add or modify graphic scale on map axes

**Syntax**

```
scaleruler
scaleruler on
scaleruler off
scaleruler(property,value,...)
h = scaleruler(...)
```

**Description**

scaleruler toggles the display of a graphic scale. If no graphic scale is currently displayed in the current map axes, one is added. If any graphic scales are currently displayed, they are removed.

scaleruler on adds a graphic scale to the current map axes. Multiple graphic scales can be added to the same map axes.

scaleruler off removes any currently displayed graphic scales.

scaleruler(*property*,*value*,...) adds a graphic scale and sets the properties to the values specified. You can display a list of graphic scale properties using the command `setm(h)`, where `h` is the handle to a graphic scale object. The current values for a displayed graphic scale object can be retrieved using `getm`. The properties of a displayed graphic scale object can be modified using `setm`.

`h = scaleruler(...)` returns the `hggroup` handle to the graphic scale object.

**Background**

Cartographers often add graphic elements to the map to indicate its scale. Perhaps the most commonly used is the graphic scale, a ruler-like object that shows distances on the ground at the correct size for the projection.

**Examples**

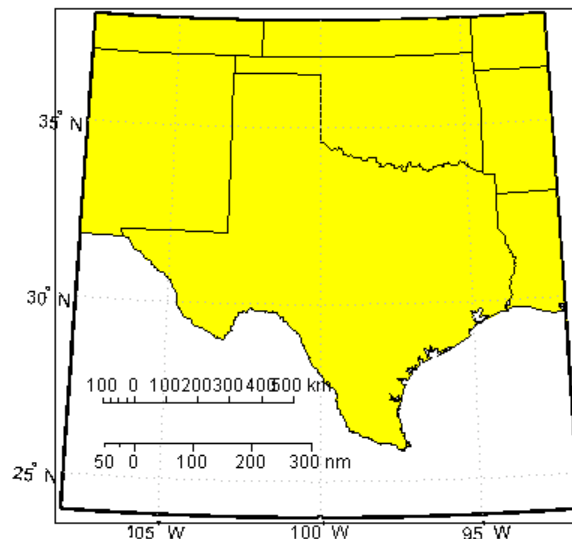
Create a map, add a graphic scale with the default settings, and shift it up a bit. Add a second scale showing nautical miles, and change the tick marks and direction.

```
figure
usamap('Texas')
```

```

geoshow('usastatelo.shp', 'FaceColor', [0.9 0.9 0])
scaleruler on
setm(handlem('scaleruler1'),'YLoc',.5)
scaleruler('units','nm')
setm(handlem('scaleruler2'), ...
    'YLoc', .48, ...
    'MajorTick', 0:100:300,...
    'MinorTick', 0:25:50, ...
    'TickDir', 'down', ...
    'MajorTickLength', km2nm(25),...
    'MinorTickLength', km2nm(12.5))

```



## Remarks

You can reposition graphic scale objects by dragging them with the mouse. You can also change their positions by modifying the XLoc and YLoc properties using `setm`.

Modifying the properties of the graphic scale results in the replacement of the original object (dragging a scaleruler, however, does not replace it). For this reason, handles to the graphic scale object will change.

Use `handlem('scaleruler')` to get a list of the current handles to all graphic scale objects. Use `handlem('scalerulerN')`, where `N` is an integer, to get the handle to a particular graphic scale. Use `namem` to see the names of existing graphic scale objects. The name of a graphic scale object is also stored in the read-only 'Children' property, which is accessed using `getm`.

Use `scaleruler off`, `clmo scaleruler`, or `clmo scalerulerN` to remove the scale rulers. You can also remove a graphic scale object with `delete(h)`, or `delete(handlem('scalerulerN'))`, where `N` is the corresponding integer.

## Object Properties

### Properties That Control Appearance

#### Color

`ColorSpec {no default}`

*Color of the displayed graphic scale* — Controls the color of the graphic scale lines and text. You can specify a color using a vector of RGB values or one of the MATLAB predefined names. By default, the graphic scale is displayed in black ([0 0 0]).

#### FontAngle

`{normal} | italic | oblique`

*Angle of the graphic scale label text* — Controls the appearance of the graphic scale text components. Use any MATLAB font angle string.

#### FontName

`courier | {helvetica} | symbol | times`

*Font family name for all graphic scale labels* — Sets the font for all displayed graphic scale labels. To display and print properly `FontName` must be a font that your system supports.

#### FontSize

`scalar in units specified in FontUnits {9}`

*Font size* — Specifies the font size to use for all displayed graphic scale labels, in units specified by the `FontUnits` property. The default point size is 9.

**FontUnits**

inches | centimeters | normalized | {points} | pixels

*Units used to interpret the `FontSize` property* — When set to `normalized`, the toolbox interprets the value of `FontSize` as a fraction of the height of the axes. For example, a `normalized` `FontSize` of 0.16 sets the text characters to a font whose height is one-tenth of the axes' height. The default units, points, are equal to 1/72 of an inch.

**FontWeight**

light | {normal} | demi | bold

*Select bold or normal font* — The character weight for all displayed graphic scale labels.

**Label**

string

*Label text for the graphic scale* — Contains a string used to label the graphic scale. The text is displayed centered on the scale. The label is often used to indicate the scale of the map, for example “1:50,000,000.”

**LineWidth**

scalar {0.5}

*Graphic scale line width* — Sets the line width of the displayed scale. The value is a scalar representing points, which is 0.5 by default.

**MajorTick**

vector

*Graphic scale major tick locations* — Sets the major tick locations for the graphic scale. The default values are chosen to give a reasonably sized scale. You can specify the locations of the tick marks by providing a vector of locations. These are usually equally spaced values as generated by `start:step:end`. The values are distances in the units of the `Units` property.

`MajorTickLabel`  
Cell array of strings

*Graphic scale major tick labels* — Sets the text labels associated with the major tick locations. By default, the labels are identical to the major tick locations. You can override these by providing a cell array of strings. There must be as many strings as tick locations.

`MajorTickLength`  
scalar

*Length of the major tick lines* — Controls the length of the major tick lines. The length is a distance in the units of the `Units` property.

`MinorTick`  
vector

*Graphic scale minor tick locations* — Sets the minor tick locations for the graphic scale. The default values are chosen to give a reasonably sized scale. You can specify the locations of the tick marks by providing a vector of locations. These are usually equally spaced values as generated by `start:step:end`. The values are distances in the units of the `Units` property.

`MinorTickLabel`  
strings

*Graphic scale minor tick labels* — Sets the text labels associated with the minor tick locations. By default, the label is identical to the last minor tick location. You can override this by providing a string label.



MinorTickLength  
scalar

*Length of the minor tick lines* — Controls the length of the minor tick lines. The length is a distance in the units of the Units property.

RulerStyle  
{ruler} | lines | patches

*Style of the graphic scale* — Selects among three different kinds of graphic scale displays. The default ruler style looks like n axes' x-axis. The lines style has three horizontal lines across the tick marks. This type of graphic scale is often used on maps from the U.S. Geological Survey. The patches style has alternating black and white rectangles in place of lines and tick marks.

TickDir  
{up} | down

*Direction of the tick marks and text* — Controls the direction in which the tick marks and text labels are drawn. In the default up direction, the tick marks and text labels are placed above the baseline, which is placed at the location given in the XLoc property. In the down position, the tick marks and labels are drawn below the baseline.

TickMode  
{auto} | manual

*Tick locations mode* — Controls whether the tick locations and labels are computed automatically or are user-specified. Explicitly setting the tick labels or locations results in a 'manual' tick mode. Setting any of the tick labels or locations to an empty matrix resets the tick mode to 'auto'. Setting the tick mode to 'auto' clears any explicitly specified tick locations and labels, which are then replaced by default values.

XLoc

scalar

*X-location of the graphic scale* — Controls the horizontal location of the graphic scale within the axes. The location is specified in the axes Cartesian projected coordinates. Use `showaxes` to make the Cartesian grid labels visible. You can also move the graphic scale by dragging the baseline with the mouse.

YLoc

scalar

*Y-location of the graphic scale* — Controls the vertical location of the graphic scale within the axes. The location is specified in the axes Cartesian projected coordinates. Use `showaxes` to make the Cartesian grid labels visible. You can also move the graphic scale by dragging the baseline with the mouse.

## Properties That Control Scaling

Azimuth

scalar

*Azimuth of scale computation* — The scale of a map varies, within the projection, with geographic location and azimuth. This property controls the azimuth along which the scaling between geographic and projected coordinates is computed. The azimuth is given in the current angle units of the map axes. The default azimuth is 0.

Lat

scalar

*Latitude of scale computation* — The scale of a map varies, within the projection, with geographic location and azimuth. This property controls the geographic location at which the scaling between geographic and projected coordinates is computed. The

latitude is given in the current angle units of the map axes. The default location is the center of the displayed map.

#### Long

scalar

*Longitude of scale computation* — The scale of a map varies, within the projection, with geographic location and azimuth. This property controls the geographic location at which the scaling between geographic and projected coordinates is computed. The longitude is given in the current angle units of the map axes. The default location is the center of the displayed map.

#### Radius

almanac body or scalar

*Planetary radius* — The radius property controls the scaling between angular and surface distances. If radius is a string, then it is evaluated as an almanac body to determine the spherical radius. If numerical, it is the radius of the desired sphere in the same units as the Units property. The default is 'earth'.

#### Units

(valid distance unit strings)

*Surface distance units* — Defines the distance units displayed in the graphic scale. Units can be any distance unit string recognized by `unitsratio`. The distance string is also used in the last graphic scale text label.

### Other Properties

#### Children

(read-only)

*Name string of graphic scale elements* — Contains the tag string assigned to the graphic elements that compose the graphic scale. All elements of the graphic scale have hidden handles except the baseline. You do not normally need to access the elements directly.

# scaleruler

---

## **See Also**

distance, surfdist, axesscale, paperscale, distortcalc, mdistort

**Purpose** Project point markers with variable color and area

**Syntax**

```
scatterm(lat,lon,s,c)
scatterm(lat,lon)
scatterm(lat,lon,s)
scatterm(...,m)
scatterm(...,'filled')
scatterm(ax,...)
h = scatterm(...)
```

**Description** `scatterm(lat,lon,s,c)` displays colored circles at the locations specified by the vectors `lat` and `lon` (which must be the same size). The area of each marker is determined by the values in the vector `s` (in points<sup>2</sup>) and the colors of each marker are based on the values in `c`. `s` can be a scalar, in which case all the markers are drawn the same size, or a vector the same length as `lat` and `lon`.

When `c` is a vector the same length as `lat` and `lon`, the values in `c` are linearly mapped to the colors in the current colormap. When `c` is a `length(lat)-by-3` matrix, the values in `c` specify the colors of the markers as RGB values. `c` can also be a color string.

`scatterm(lat,lon)` draws the markers in the default size and color.

`scatterm(lat,lon,s)` draws the markers with a single color.

`scatterm(...,m)` uses the marker `m` instead of 'o'.

`scatterm(...,'filled')` fills the markers.

`scatterm(ax,...)` plots into axes `ax` instead of `gca`. `ax` is a handle to a map axes.

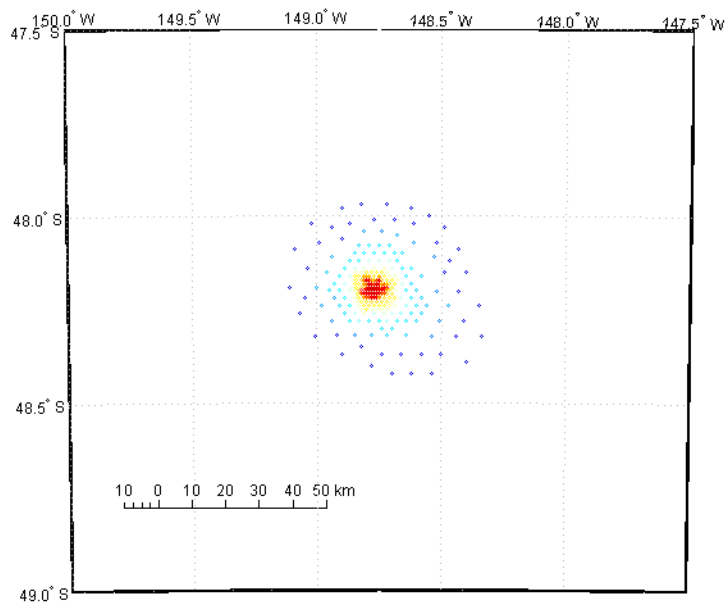
`h = scatterm(...)` returns a handle to an `hgroup`.

**Examples** Plot the seamount MATLAB demo data as symbols with the color proportional to the height.

```
load seamount
worldmap([-49 -47.5],[-150 -147.5])
```

# scatterm

```
scatterm(y,x,5,z)  
scaleruler  
set(gca,'Visible','off')
```



## See Also

`stem3m`

**Purpose**

Small circles from center, range, and azimuth

**Syntax**

```
[lat,lon] = scircle1(lat0,lon0,rad)
[lat,lon] = scircle1(lat0,lon0,rad,az)
[lat,lon] = scircle1(lat0,lon0,rad,az,geoid)
[lat,lon] = scircle1(lat0,lon0,rad,units)
[lat,lon] = scircle1(lat0,lon0,rad,az,units)
[lat,lon] = scircle1(lat0,lon0,rad,az,geoid,units)
[lat,lon] = scircle1(lat0,lon0,rad,az,geoid,units,npts)
[lat,lon] = scircle1(track,...)
```

**Description**

[lat,lon] = scircle1(lat0,lon0,rad) computes small circles (on a sphere) with a center at the point lat0,lon0 and radius rad. The inputs can be scalar or column vectors. The input radius is in degrees of arc length on a sphere.

[lat,lon] = scircle1(lat0,lon0,rad,az) uses the input az to define the small circle arcs computed. The arc azimuths are measured clockwise from due north. If az is a column vector, then the arc length is computed from due north. If az is a two-column matrix, then the small circle arcs are computed starting at the azimuth in the first column and ending at the azimuth in the second column. If az = [], then a complete small circle is computed.

[lat,lon] = scircle1(lat0,lon0,rad,az,geoid) computes small circles on the ellipsoid defined by the input geoid, rather than by assuming a sphere. The geoid vector is of the form [semimajor axis, eccentricity]. If the semimajor axis is non-zero, rad is assumed to be in distance units matching the units of the semimajor axis. However, if geoid = [], or if the semimajor axis is zero, then rad is interpreted as an angle and the small circles are computed on a sphere as in the preceding syntax.

[lat,lon] = scircle1(lat0,lon0,rad,units),  
[lat,lon] = scircle1(lat0,lon0,rad,az,units), and  
[lat,lon] = scircle1(lat0,lon0,rad,az,geoid,units)  
are all valid calling forms, which use the input string units to define

# scircle1

---

the angle units of the inputs and outputs. If the *units* string is omitted, 'degrees' is assumed.

`[lat,lon] = scircle1(lat0,lon0,rad,az,geoid,units,npts)` uses the scalar input *npts* to determine the number of points per small circle computed. The default value of *npts* is 100.

`[lat,lon] = scircle1(track,...)` uses the *track* string to define either a great circle or rhumb line radius. If *track* = 'gc', then small circles are computed. If *track* = 'rh', then the circles with radii of constant rhumb line distance are computed. If the *track* string is omitted, 'gc' is assumed.

`mat = scircle1(...)` returns a single output argument where `mat = [lat lon]`. This is useful if a single small circle is computed.

Multiple circles can be defined from a single starting point by providing scalar *lat0,lon0* inputs and column vectors for *rad* and *az* if desired.

## Definitions

A *small circle* is the locus of all points an equal surface distance from a given center. For true small circles, this distance is always calculated in a great circle sense; however, the `scircle1` function allows a locus to be calculated using distances in a rhumb line sense as well. An example of a small circle is *all points exactly 100 miles from the Washington Monument*. Parallels on the globe are all small circles. Great circles are a subset of small circles, specifically those with a radius of 90° or its angular equivalent, so all meridians on the globe are small circles as well.

*Small circle notation* consists of a center point and a radius in units of angular arc length.

## Examples

Create and plot a small circle centered at (0°,0°) with a radius of 10°.

```
axesm('mercator','MapLatLimit',[-30 30],'MapLonLimit',[-30 30]);  
[latc,longc] = scircle1(0,0,10);  
plotm(latc,longc,'g')
```

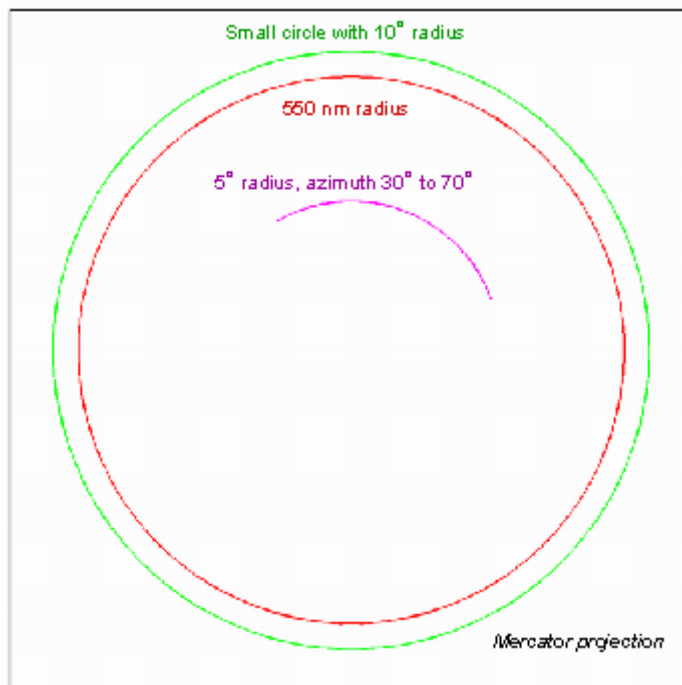


If the desired radius is known in some nonangular distance unit, use the radius returned by the `almanac` function as the ellipsoid to set the range units. (Use an empty azimuth entry to indicate a full circle.)

```
earthradius = almanac('earth','radius','nm');
[latc,longc] = scircle1(0,0,550,[],earthradius);
plotm(latc,longc,'r')
```

For just an arc of the circle, enter an azimuth range.

```
[latc,longc] = scircle1(0,0,5,[-30 70]);
plotm(latc,longc,'m')
```



## See Also

[scircle2](#) | [scircleg](#) | [track](#) | [trackg](#) | [track1](#) | [track2](#)

# scircle2

---

## Purpose

Small circles from center and perimeter

## Syntax

```
[lat,lon] = scircle2(lat1,lon1,lat2,lon2)
[lat,lon] = scircle2(lat1,lon1,lat2,lon2,geoid)
[lat,lon] = scircle2(lat1,lon1,lat2,lon2,units)
[lat,lon] = scircle2(lat1,lon1,lat2,lon2,geoid,units)
[lat,lon] = scircle2(lat1,lon1,lat2,lon2,geoid,units,npts)
[lat,lon] = scircle2(track,...)
mat = scircle2(...)
mat = [lat lon]
```

## Description

`[lat,lon] = scircle2(lat1,lon1,lat2,lon2)` computes small circles (on a sphere) with centers at the points `lat1,lon1` and points on the circles at `lat2,lon2`. The inputs can be scalar or column vectors.

`[lat,lon] = scircle2(lat1,lon1,lat2,lon2,geoid)` computes the small circle on the ellipsoid defined by the input `geoid`, rather than by assuming a sphere. The `geoid` vector is of the form `[semimajor axis, eccentricity]`. If `geoid = []`, a sphere is assumed.

`[lat,lon] = scircle2(lat1,lon1,lat2,lon2,units)` and `[lat,lon] = scircle2(lat1,lon1,lat2,lon2,geoid,units)` are valid calling forms, which use the input string `units` to define the angle units of the inputs and outputs. If the input string `units` is omitted, 'degrees' is assumed.

`[lat,lon] = scircle2(lat1,lon1,lat2,lon2,geoid,units,npts)` uses the scalar input `npts` to determine the number of points per track computed. The default value of `npts` is 100.

`[lat,lon] = scircle2(track,...)` uses the `track` string to define either a great circle or a rhumb line radius. If `track = 'gc'`, then small circles are computed. If `track = 'rh'`, then circles with radii of constant rhumb line distance are computed. If the `track` string is omitted, 'gc' is assumed.

`mat = scircle2(...)` returns a single output argument where `mat = [lat lon]`. This is useful if a single circle is computed.

Multiple circles can be defined from a single center point by providing scalar `lat1, lon1` inputs and column vectors for the points on the circumference, `lat2, lon2`.

## Definitions

A *small circle* is the locus of all points an equal surface distance from a given center. For true small circles, this distance is always calculated in a great circle sense. However, the `scircle2` function allows a locus to be calculated using distances in a rhumb line sense as well. An example of a small circle is *all points exactly 100 miles from the Washington Monument*.

## Examples

Plot the locus of all points the same distance from New Delhi as Kathmandu:

```
axesm('mercator','MapLatLimit',[0 40],'MapLonLimit',[60 110]);
load coast

% For reference
plotm(lat, long, 'k');

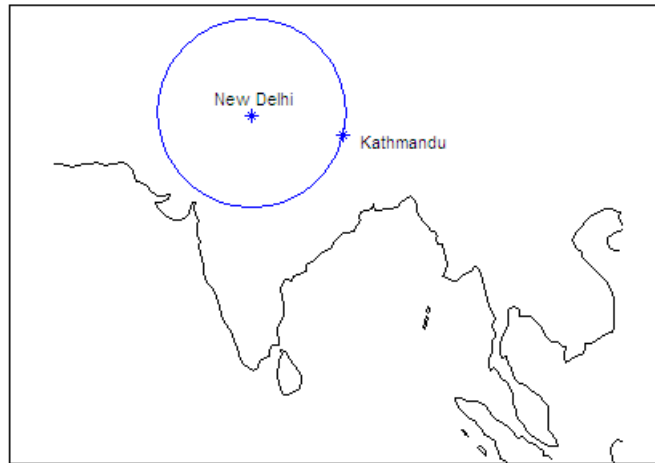
% New Delhi
lat1 = 29; lon1 = 77.5;

% Kathmandu
lat2 = 27.6; lon2 = 85.5;

% Plot the cities
plotm([lat1 lat2],[lon1 lon2],'b*')
[latc, lonc] = scircle2(lat1, lon1, lat2, lon2);
plotm(latc, lonc, 'b')
```

## scircle2

---



### See Also

[scircle1](#) | [track](#) | [track1](#) | [track2](#)

**Purpose**

Small circle defined via mouse input

**Syntax**

```
h = scircleg(ncirc)
h = scircleg(ncirc,npts)
h = scircleg(ncirc,linestyle)
h = scircleg(ncirc,PropertyName,PropertyValue,...)
[lat,lon] = scircleg(ncirc,npts,...)
h = scircleg(track,ncirc,...)
```

**Description**

`h = scircleg(ncirc)` brings forward the current map axes and waits for the user to make ( $2 * \text{ncirc}$ ) mouse clicks. The output `h` is a vector of handles for the `ncirc` small circles, which are then displayed.

`h = scircleg(ncirc,npts)` specifies the number of plotting points to be used for each small circle. `npts` is 100 by default.

`h = scircleg(ncirc,linestyle)` specifies the line style for the displayed small circles, where *linestyle* is any line style string recognized by the standard MATLAB function `line`.

`h = scircleg(ncirc,PropertyName,PropertyValue,...)` allows property name/property value pairs to be set, where *PropertyName* and *PropertyValue* are recognized by the `line` function.

`[lat,lon] = scircleg(ncirc,npts,...)` returns the coordinates of the plotted points rather than the handles of the small circles. Successive circles are stored in separate columns of `lat` and `lon`.

`h = scircleg(track,ncirc,...)` specifies the logic with which ranges are calculated. If the string `track` is 'gc' (the default), great circle distance is used. If `track` is 'rh', rhumb line distance is used.

This function is used to define small circles for display using mouse clicks. For each circle, two clicks are required: one to mark the center of the circle and one to mark any point on the circle itself, thereby defining the radius.

**Background**

A small circle is the locus of all points an equal surface distance from a given center. For true small circles, this distance is always calculated

# scircleg

---

in a great circle sense; however, the `scircleg` function allows a locus to be calculated using distances in a rhumb line sense as well. You can modify the circle after creation by **shift**+clicking it. The circle is then in edit mode, during which you can change the size and position by dragging control points, or by entering values into a control panel. **Shift**+clicking again exits edit mode.

## See Also

`scircle1`, `scircle2`

**Purpose**

Intersection points for pairs of small circles

**Syntax**

```
[newlat,newlon] = scxsc(lat1,lon1,range1,lat2,lon2,range2)
[newlat,newlon]=scxsc(lat1,lon1,range1,lat2,lon2,range2,
    units)
```

**Description**

[newlat,newlon] = scxsc(lat1,lon1,range1,lat2,lon2,range2) returns in newlat and newlon the locations of the points of intersection of two small circles in *small circle notation*. For example, the first small circle in a pair would be centered on the point (lat1,lon1) with a radius of range1 (in angle units). The inputs must be column vectors. If the circles do not intersect, or are identical, two NaNs are returned and a warning is displayed. If the two circles are tangent, the single intersection point is returned twice.

[newlat,newlon]=scxsc(lat1,lon1,range1,lat2,lon2,range2,units) specifies the angle units used for all inputs, where *units* is any valid angle units string. The default units are 'degrees'.

For any pair of small circles, there are four possible intersection conditions: the circles are identical, they do not intersect, they are tangent to each other and hence they intersect once, or they intersect twice.

*Small circle notation* consists of a center point and a radius in units of angular arc length.

**Examples**

Given a small circle centered at (10°S,170°W) with a radius of 20° (~1200 nautical miles), where does it intersect with a small circle centered at (3°N, 179°E), with a radius of 15° (~900 nautical miles)?

```
[newlat,newlong] = scxsc(-10,-170,20,3,179,15)
```

```
newlat =
    -8.8368    9.8526
newlong =
    169.7578 -167.5637
```

Note that in this example, the two small circles cross the date line.

**Remarks**

Great circles are a subset of small circles—a great circle is just a small circle with a radius of  $90^\circ$ . This provides two methods of notation for defining great circles. *Great circle notation* consists of a point on the circle and an azimuth at that point. *Small circle notation* for a great circle consists of a center point and a radius of  $90^\circ$  (or its equivalent in radians).

**See Also**

gc2sc, gcxgc, gcxsc, rhxrh, crossfix, polyxpoly



**Purpose** Read data from SDTS raster/DEM data set

**Syntax** `[Z, R] = sdtsdemread(filename)`

**Description** `[Z, R] = sdtsdemread(filename)` reads data from an SDTS DEM data set. `Z` is a matrix containing the elevation values. `R` is a referencing matrix (see `makerefmat`). NaNs are assigned to elements of `Z` corresponding to null data values or fill data values in the cell module.

`filename` can be the name of the SDTS catalog directory file (\*CATD.DDF) or the name of any of the other files in the data set. `filename` can include the directory name; otherwise `filename` is searched for in the current directory and the MATLAB path. If any of the files specified in the catalog directory are missing, `sdtsdemread` fails.

**Remarks** Elevation values can be imported with `sdtsdemread` from DEMs that use the SPRE Raster Profile (in use since January, 2001) as well as from older SDTS DEM data sets. Under this profile, elevations can be encoded either as 32-bit floating-point numbers (when their units are “decimal meters”), or as 16-bit integers (when units are “feet” or “meters”). The output class from `sdtsdemread` for both types of elevation encoding is `double`.

---

**Note** For details on locating map data for download over the Internet, see the following documentation at the MathWorks Web site: <http://www.mathworks.com/support/tech-notes/2100/2101.html>.

---

**Example**

```
[Z, R] = sdtsdemread('9129CATD.ddf');  
mapshow(Z,R, 'DisplayType', 'contour')
```

**See Also** `arcgridread`, `makerefmat`, `mapshow`, `sdtsinfo`

# sdtsinfo

---

**Purpose** Information about SDTS data set

**Syntax** `info = sdtsinfo(filename)`

**Description** `info = sdtsinfo(filename)` returns a structure whose fields contain information about the contents of a SDTS data set.

`filename` is a string that specifies the name of the SDTS catalog directory file, such as 7783CATD.DDF. The filename can also include the directory name. If `filename` does not include the directory, then it must be in the current directory or in a directory on the MATLAB path. If `sdtsinfo` cannot find the SDTS catalog file, it returns an error.

If any of the other files in the data set as specified by the catalog file is missing, a warning message is returned. Subsequent calls to read data from the file might also fail.

## Field Descriptions

The `info` structure contains the following fields:

Filename	String containing the name of the catalog directory file of the SDTS transfer set
Title	String containing the name of the data set
ProfileID	String containing the Profile Identifier, e.g., 'SRPE: SDTS RASTER PROFILE and EXTENSIONS'
ProfileVersion	String containing the Profile Version Identifier, e.g., 'VER 1.1 1998 01'
MapDate	String specifying the date associated with the cartographic information contained in the data set
DataCreationDate	String specifying the creation date of the data set
HorizontalDatum	String representing the horizontal datum to which the data is referenced

MapRefSystem	String describing the projection and reference system used: 'GEO', 'SPCS', 'UTM', 'UPS', or ' '
ZoneNumber	Scalar value representing the zone number
XResolution	Scalar value representing the X component of the horizontal coordinate resolution
YResolution	Scalar value representing the Y component of the horizontal coordinate resolution
NumberOfRows	Scalar value representing the number of rows of the DEM
NumberOfCols	Scalar value representing the number of columns of the DEM
HorizontalUnits	String specifying the units used for the horizontal coordinate values
VerticalUnits	String specifying the units used for the vertical coordinate values
MinElevation	Scalar value of the minimum elevation value for the data set
MaxElevation	Scalar value of the maximum elevation value for the data set

**Example**

```
info = sdtsinfo('9129CATD.DDF');
```

**See Also**

```
sdtsdemread, makerefmat
```

# sectorg

---

<b>Purpose</b>	Sector of small circle defined via mouse input
<b>Syntax</b>	sectorg
<b>Description</b>	<p>sectorg prompts the user to indicate by two successive mouse clicks two points that define the center and radius of a small circle arc. By default, the angular width of the sector is 60°. The sector is constructed using the vector defined by the mouse clicks as the reference azimuth (defined to run through the center of the sector).</p> <p>Once a sector has been drawn, <b>Shift</b>+clicking on it displays four control points (center point, arc resize, radial resize, and rotation controls), and the associated <b>Sector</b> control window. You can graphically interact with sectors as follows:</p> <ul style="list-style-type: none"><li>• To translate the circle, click and drag the center (o) control.</li><li>• To change the arc size, click and drag the resize control (square).</li><li>• To change the radial size of the sector, click and drag the radial control (down triangle).</li><li>• To rotate the arc, click and drag the rotation control (x).</li></ul> <p>You can also modify a selected sector by entering the appropriate values in the <b>Sector</b> control window and then pressing <b>Enter</b> or clicking the <b>Close</b> button. Display of the control panel is toggled by <b>Shift</b>+clicking the sector. If you select multiple sectors, a separate <b>Sector</b> control window will appear for each one.</p>
<b>Remarks</b>	<b>Sector</b> control windows are superimposed at the same location. A valid map axes must exist prior to running this function.
<b>See also</b>	scircleg, trackg

**Purpose**

Convert data grid rows and columns to latitude-longitude

**Syntax**

```
[lat, lon] = setltn(Z, R, row, col)
[lat, lon, indxPointOutsideGrid] = setltn(Z, R, row, col)
latlon = setltn(Z, R, row, col)
```

**Description**

`[lat, lon] = setltn(Z, R, row, col)` returns the latitude and longitudes associated with the input row and column coordinates of the regular data grid Z. R is either a 1-by-3 vector containing elements:

```
[cells/degree northern_latitude_limit western_longitude_limit]
```

or a 3-by-2 referencing matrix that transforms raster row and column indices to/from geographic coordinates according to:

$$[\text{lon lat}] = [\text{row col 1}] * R$$

If R is a referencing matrix, it must define a (non-rotational, non-skewed) relationship in which each column of the data grid falls along a meridian and each row falls along a parallel. All input and output angles are in units of degrees.

`[lat, lon, indxPointOutsideGrid] = setltn(Z, R, row, col)` returns the indices of the elements of the row and col vectors that lie outside the input grid. The outputs lat and lon always ignore these points; the third output accounts for them.

`latlon = setltn(Z, R, row, col)` returns the coordinates in a single two-column matrix of the form [latitude longitude].

**Examples**

Find the coordinates of row 45, column 65 of topo:

```
load topo
[lat,lon,indxPointOutsideGrid] = setltn(topo,topolegend,45,65)

lat =
    -45.5000
lon =
```

## setltn

---

```
64.5000  
indxPointOutsideGrid = [] % Empty because the point is valid
```

**See Also** `ltln2val`, `pix2latlon`, `setpostn`

**Purpose**

Set properties of map axes and graphics objects

**Syntax**

```
setm(h,MapAxesPropertyName,PropertyValue,...)
setm(texthdl,'MapPosition',position)
setm(surfhdl,'Graticule',lat,lon,alt)
setm(surfhdl,'MeshGrat',npts,alt)
```

**Description**

`setm(h,MapAxesPropertyName,PropertyValue,...)`, where `h` is a valid map axes handle, sets the map axes properties specified in the input list. The map axes properties must be recognized by `axesm`.

`setm(texthdl,'MapPosition',position)` alters the position of the projected text object specified by its handle to the [latitude longitude] or the [latitude longitude altitude] specified by the position vector.

`setm(surfhdl,'Graticule',lat,lon,alt)` alters the graticule of the projected surface object specified by its handle. The graticule is specified by the latitude and longitude matrices, specifying locations of the graticule vertices. The altitude can be specified by a scalar, or by a matrix providing a value for each vertex.

`setm(surfhdl,'MeshGrat',npts,alt)` alters the mesh graticule of projected surface objects displayed using the `meshm` function. In this case, the two-element vector `npts` specifies the graticule size in the manner described under `meshm`. The altitude can be a scalar or a matrix with a size corresponding to `npts`.

**Examples**

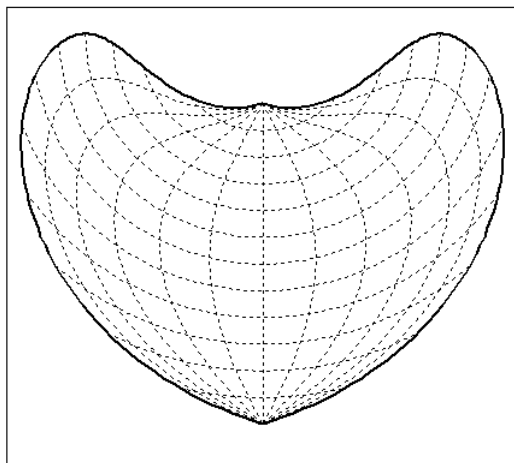
Display a map axes and alter it:

```
axesm('bonne','Frame','on','Grid','on')
```

The standard Bonne projection has a standard parallel at 30°N.

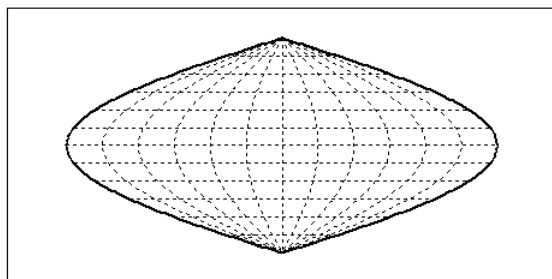
# setm

---



Setting this standard parallel to  $0^\circ$  results in a Sinusoidal projection:

```
setm(gca, 'MapParallels', 0)
```



## See Also

axesm, getm



**Purpose**

Convert latitude-longitude to data grid rows and columns

**Syntax**

```
[row, col] = setpostn(Z, R, lat, lon)
indx = setpostn(...)
[row, col, indxPointOutsideGrid] = setpostn(...)
```

**Description**

`[row, col] = setpostn(Z, R, lat, lon)` returns the row and column indices of the regular data grid `Z` for the points specified by the vectors `lat` and `lon`. `R` is either a 1-by-3 vector containing elements:

```
[cells/degree northern_latitude_limit western_longitude_limit]
```

or a 3-by-2 referencing matrix that transforms raster row and column indices to/from geographic coordinates according to:

$$[\text{lon } \text{lat}] = [\text{row } \text{col } 1] * R$$

If `R` is a referencing matrix, it must define a (non-rotational, non-skewed) relationship in which each column of the data grid falls along a meridian and each row falls along a parallel. Points falling outside the grid are ignored in `row` and `col`. All input angles are in degrees.

`indx = setpostn(...)` returns the indices of `Z` corresponding to the points in `lat` and `lon`. Points falling outside the grid are ignored in `indx`.

`[row, col, indxPointOutsideGrid] = setpostn(...)` returns the indices of `lat` and `lon` corresponding to points outside the grid. These points are ignored in `row` and `col`.

**Examples**

What are the matrix coordinates in `topo` of Denver, Colorado, at (39.7°N,105°W)?

```
load topo
[row,col] = setpostn(topo,topolegend,39.7,105)

row =
```

# setpostn

---

```
    130  
col =  
    105
```

**See Also**      latlon2pix, ltl2val, setltln

**Purpose**

Construct cdata and colormap for shaded relief

**Syntax**

```
[cindx,cimap,clim] = shaderel(X,Y,Z,cmap)
[cindx,cimap,clim] = shaderel(X,Y,Z,cmap,[azim elev])
[cindx,cimap,clim] = shaderel(X,Y,Z,cmap,[azim elev],cmap1)
[cindx,cimap,clim] = shaderel(X,Y,Z,cmap,[azim elev],cmap1,
    clim)
```

**Description**

`[cindx,cimap,clim] = shaderel(X,Y,Z,cmap)` constructs the colormap and color indices to allow a surface to be displayed in colored shaded relief. The colors are proportional to the magnitude of Z, but modified by shades of gray based on the surface normals to simulate surface lighting. This representation allows both large and small-scale differences to be seen. X, Y, and Z define the surface. `cmap` is the colormap used to create the new shaded colormap `cimap`. `cindx` is a matrix of color indices to `cimap`, based on the elevation and surface normal of the Z matrix element. `clim` contains the color axis limits.

`[cindx,cimap,clim] = shaderel(X,Y,Z,cmap,[azim elev])` places the light at the specified azimuth and elevation. By default, the direction of the light is East (90° azimuth) at an elevation of 45°.

`[cindx,cimap,clim] = shaderel(X,Y,Z,cmap,[azim elev],cmap1)` chooses the number of grays to give a `cimap` of length `cmap1`. By default, the number of grayscales is chosen to keep the shaded colormap below 256. If the vector of azimuth and elevation is empty, the default locations are used.

`[cindx,cimap,clim] = shaderel(X,Y,Z,cmap,[azim elev],cmap1,clim)` uses the color limits to index Z into `cmap`.

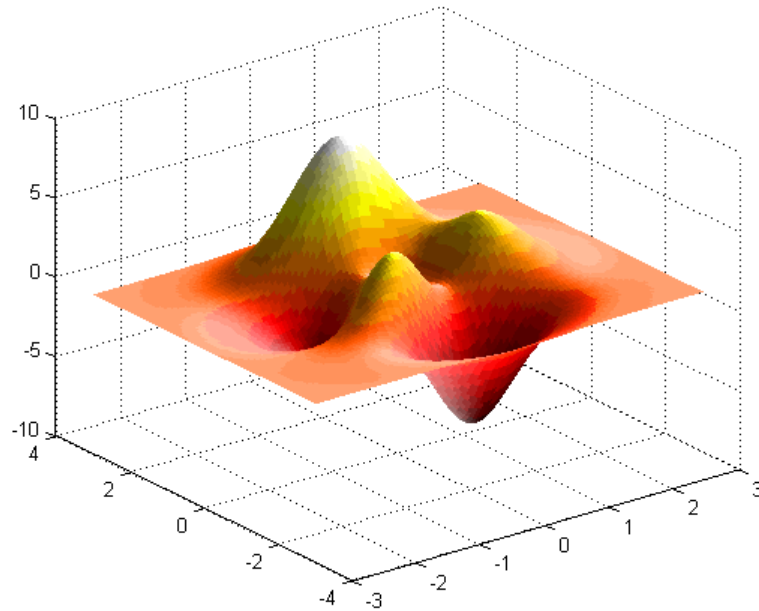
**Remarks**

This function effectively multiplies two colormaps, one with color based on elevation, the other with a grayscale based on the slope of the surface, to create a new color map. This produces an effect similar to using a light on a surface, but with all of the visible colors actually in the colormap. Lighting calculations are performed on the unprojected data.

## Examples

Display the peaks surface with a shaded colormap:

```
[X,Y,Z] = peaks(100);  
cmap = hot(16);  
[cindx,cimap,clim] = shaderel(X,Y,Z,cmap);  
surf(X,Y,Z,cindx); colormap(cimap); caxis(clim)  
shading flat
```



## See Also

[caxis](#), [colormap](#), [light](#), [meshlstrm](#), [surf](#), [surf1strm](#)

**Purpose** Information about shapefile

**Syntax** `info = shapeinfo(filename)`

**Description** `info = shapeinfo(filename)` returns a structure, `info`, whose fields contain information about the contents of a shapefile. `filename` can be the base name or the full name of any one of the component files. `shapeinfo` reads all three files as long as they exist in the same directory and the unit of length or angle is not specified. If the main file (with extension `.SHP`) is missing, `shapeinfo` returns an error. If either of the other files is missing, `shapeinfo` returns a warning.

**Tips** `shapeinfo` cannot tell you which coordinate system the data in a shapefile uses. Coordinates can be either planar ( $x, y$ ) or geographic ( $lat, lon$ ) and have a variety of units. This information can be critical to the proper display of shapefile vector data. For more information on this topic, see “Mapstructs and Geostructs”.

**Output Arguments** The `info` structure contains the following fields:

Filename	Char array containing the names of the files that were read
ShapeType	String containing the shape type
BoundingBox	Numerical array of size 2-by-N that specifies the minimum (row 1) and maximum (row 2) values for each dimension of the spatial data in the shapefile
Attributes	Structure array of size 1-by-numAttributes that describes the attributes of the data
NumFeatures	The number of spatial features in the shapefile

The `Attributes` structure contains these fields:

# shapeinfo

---

Name	String containing the attribute name as given in the xBASE table
Type	String specifying the MATLAB class of the attribute data returned by <code>shaperead</code> . The following attribute (xBASE) types are supported: Numeric, Floating, Character, and Date.

## See Also

`shaperead` | `shapewrite`

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<b>Purpose</b>	Read vector features and attributes from shapefile
<b>Syntax</b>	<pre>S = shaperead(filename) S = shaperead(filename, parameter, value, ...) [S, A] = shaperead(...)</pre>
<b>Description</b>	<p><code>S = shaperead(filename)</code> reads in a shapefile, <code>filename</code>, and returns an <math>N</math>-by-1 geographic data structure array in projected map coordinates (a mapstruct). The geographic data structure combines geometric and feature attribute information. <code>shaperead</code> supports the ordinary 2-D shape types: 'Point', 'Multipoint', 'PolyLine', and 'Polygon'.</p> <p><code>S = shaperead(filename, parameter, value, ...)</code> returns a subset of the shapefile contents in <code>S</code>, as determined by the parameters. The geographic data structure, <code>S</code>, is a mapstruct unless <code>UseGeoCoords</code> is true.</p> <p><code>[S, A] = shaperead(...)</code> returns an <math>N</math>-by-1 geographic data structure array, <code>S</code>, containing geometric information, and a parallel <math>N</math>-by-1 attribute structure array, <code>A</code>, containing feature attribute information.</p>
<b>Input Arguments</b>	<p><code>filename</code></p> <p>Refers to the base name or full name of one of the component files in a shapefile. If the main file (with extension <code>.shp</code>) is missing, <code>shaperead</code> throws an error. If either of the other files is missing, <code>shaperead</code> issues a warning.</p> <p>Make sure that your machine is set to the same character encoding scheme as the data you are importing. For example, if you are trying to import a shapefile that contains Japanese characters, configure your machine to support the Shift-JIS encoding scheme.</p> <p><i>parameter, value</i></p> <p>Determines the subset of the shapefile contents that <code>shaperead</code> returns. If you do not specify any parameters, <code>shaperead</code></p>

# shaperead

---

returns an entry for every non-null feature and creates a field for every attribute. Use the parameters `RecordNumbers`, `BoundingBox`, and `Selector` to select which features to read. If you use more than one of these parameters in the same call, you receive the intersection of the records that match the individual specifications. For instance, if you specify values for both `RecordNumbers` and `BoundingBox`, you import only those features with record numbers that appear in your list and that also have bounding boxes intersecting the specified bounding box. Use the parameter `Attributes` to control which attributes to keep. Use the `UseGeoCoords` parameter to control the output field names.

Parameter	Data Type	Purpose
<code>RecordNumbers</code>	Integer-valued vector of class <code>double</code>	Importing only features with listed record numbers.
<code>BoundingBox</code>	2-by-2 array of class <code>double</code>	Importing only features whose bounding boxes intersect the specified box. The <code>shaperead</code> function does not trim features that partially intersect the box.
<code>Selector</code>	Cell array containing a function handle and one or more attribute names. (The function must return a logical scalar.)	Importing only features for which the function, when applied to the corresponding attribute values, returns <code>true</code> .



Parameter	Data Type	Purpose
Attributes	Cell array of attribute names	Including listed attributes and setting the order of attributes in the structure array. Use {} to omit all attributes.
UseGeoCoords	Logical scalar	Returning shapefile contents in a geostruct, if set to true. Defaults to false. Use this parameter when you know that the <i>x</i> - and <i>y</i> - coordinates in the shapefile actually represent longitude and latitude data. (If you do not know whether you are working with geographic or map coordinates, see “Mapstructs and Geostructs” in the User’s Guide.)

## Output Arguments

S

An *N*-by-1 geographic data structure array containing an element for each non-null, spatial feature in the shapefile.

[S, A]

An *N*-by-1 geographic data structure array, S, and a parallel *N*-by-1 attribute structure array, A. The fields in the output structure arrays S and A depend on (1) the type of shape contained in the file and (2) the names and types of attributes included in the file. The shaperead function supports the following four attribute types: numeric and floating (stored as type double in MATLAB) and character and date (stored as char array).

## Examples

Read a shapefile of Concord roads and analyze the data.

```
% Read the entire concord_roads.shp shapefile, including
% the attributes, in concord_roads.dbf.
S = shaperead('concord_roads.shp')
```

Your output appears as follows:

```
S =  
  
609x1 struct array with fields:  
    Geometry  
    BoundingBox  
    X  
    Y  
    STREETNAME  
    RT_NUMBER  
    CLASS  
    ADMIN_TYPE  
    LENGTH
```

You have a mapstruct with X and Y coordinate vectors.

```
% Restrict output based on bounding box and read only two  
% of the feature attributes.  
bbox = [2.08 9.11; 2.09 9.12] * 1e5;  
S = shaperead('concord_roads','BoundingBox',bbox,...  
             'Attributes',{'STREETNAME','CLASS'})
```

Your output appears as follows:

```
S =  
  
87x1 struct array with fields:  
    Geometry  
    BoundingBox  
    X  
    Y  
    STREETNAME  
    CLASS  
  
% Select the class 4 and higher road segments that are at least 200  
% meters in length. Note the use of an anonymous function in the  
% selector.  
S = shaperead('concord_roads.shp','Selector',...  
             {@(v1,v2) (v1 >= 4) && (v2 >= 200)},'CLASS','LENGTH')
```

Your output appears as follows:

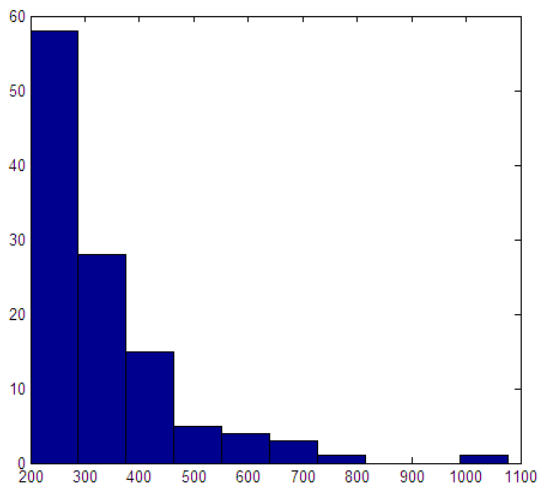
```
S =  
  
115x1 struct array with fields:  
    Geometry  
    BoundingBox  
    X  
    Y  
    STREETNAME  
    RT_NUMBER  
    CLASS  
    ADMIN_TYPE  
    LENGTH  
  
% Determine the number of roads of each class.  
N = hist([S.CLASS],1:7)
```

Your output appears as follows:

```
N =  
  
    0    0    0    7   93   15    0  
  
% Display a histogram of the number of roads  
% that fall in each category of length.  
hist([S.LENGTH])
```

# shaperead

---



---

Read a shapefile of worldwide city names and locations in latitude and longitude.

```
S = shaperead('worldcities.shp', 'UseGeoCoords', true)
```

Your output appears as follows:

```
S =  
318x1 struct array with fields:  
    Geometry  
    Lon  
    Lat  
    Name
```

You set 'UseGeoCoords' to true, so you received a geostruct.

## See Also

[shapeinfo](#) | [shapewrite](#)

## How To

- “Mapping Toolbox Geographic Data Structures”

**Related  
Links**

- 2101 - Accessing Geospatial Data on the Internet for the Mapping Toolbox

# shapewrite

---

**Purpose** Write geographic data structure to shapefile

**Syntax**  
shapewrite(S, filename)  
shapewrite(S, filename, 'DbfSpec', dbfspec)

**Description** shapewrite(S, filename) writes a geographic data structure to disk in shapefile format. shapewrite creates three output files: [basename '.shp'], [basename '.shx'], and [basename '.dbf'], where basename is filename without its extension. If a given attribute is integer-valued for all features, then it is written to the [basename '.dbf'] file as an integer. If an attribute is non-integer-valued for any feature, then it is written as a fixed point decimal value with six digits to the right of the decimal place.

shapewrite(S, filename, 'DbfSpec', dbfspec) writes a shapefile in which the content and layout of the DBF file is controlled by a DBF specification, indicated here by the parameter value dbfspec.

- Tips**
- The xBASE (.dbf) file specifications require that geostruct and mapstruct attribute names are truncated to 11 characters when copied as DBF field names. Consider shortening long field names before calling shapewrite. By doing this, you make field names in the DBF file more readable and avoid introducing duplicate names as a result of truncation.
  - Remember to set your character encoding scheme to match that of the geographic data structure you are exporting. For instance, if you are exporting a map that displays Japanese text, configure your machine to support Shift-JIS character encoding.

**Input Arguments**

S  
A valid mapstruct or geostruct with specific restrictions on its attribute fields:

- Each attribute field value must be either a real, finite, scalar double or a character string.

- The type of a given attribute must be consistent across all features.

`filename`

A character string specifying the output file name and location. If an extension is included, it must be `'.shp'` or `'.SHP'`.

`'DbfSpec', dbfspec`

A scalar MATLAB structure containing one field for each feature attribute to be included in the output shapefile. To include an attribute in the output, provide a field in `dbfspec` with a name identical to the attribute name as given in `S`. Assign to that field a scalar structure with the following four fields:

- `FieldName` — The field name to be used in the file
- `FieldType` — The field type to be used in the file ('N' or 'C')
- `FieldLength` — The field length in the file, in bytes
- `FieldDecimalCount` — For numeric fields, the number of digits to the right of the decimal place

Call `makedbfspec` to construct a DBF spec. Modify the output to remove attributes or change the `FieldName`, `FieldLength`, or `FieldDecimalCount` for one or more attributes.

## Examples

Derive a shapefile from `concord_roads.shp` in which roads of CLASS 5 and greater are omitted. Note the use of the `'Selector'` option in `shaperead`, together with an anonymous function, to read only the main roads from the original shapefile.

```
shapeinfo('concord_roads') % 609 features

ans =
    Filename: [3x67 char]
    ShapeType: 'PolyLine'
    BoundingBox: [2x2 double]
```

# shapewrite

---

```
NumFeatures: 609
Attributes: [5x1 struct]
```

```
S = shaperead('concord_roads', 'Selector', ...
    {@(roadclass) roadclass < 4, 'CLASS'});
shapewrite(S, 'main_concord_roads.shp')
shapeinfo('main_concord_roads') % 107 features
```

```
ans =
    Filename: [3x24 char]
    ShapeType: 'PolyLine'
    BoundingBox: [2x2 double]
    NumFeatures: 107
    Attributes: [5x1 struct]
```

## See Also

[makedbfspec](#) | [shapeinfo](#) | [shaperead](#)

## How To

- “Mapping Toolbox Geographic Data Structures”



**Purpose** Toggle display of map coordinate axes

**Syntax** `showaxes(action)`  
`showaxes`

**Description** `showaxes(action)` modifies the Cartesian axes based on the value of *action*, as defined in the Inputs section below.

`showaxes` toggles between displaying the default axes ticks on the MATLAB Cartesian axes and removing the axes ticks.

**Inputs** *action*

A string or RGB triple that specifies how to modify the Cartesian axes

Value	Data Type	Action
'on'	string	Displays the MATLAB Cartesian axes and default axes ticks
'off'	string	Removes the axes ticks from the MATLAB Cartesian axes
'hide'	string	Hides the Cartesian axes
'show'	string	Shows the Cartesian axes
'reset'	string	Sets the Cartesian axes to the default settings
'boxoff'	string	Removes axes ticks, color, and box from the Cartesian axes
<i>colorstr</i>	string	Sets the Cartesian axes to the color specified by <i>colorstr</i>
<i>colorvec</i>	RGB triple	Uses <i>colorvec</i> to set the Cartesian axes color

**See Also** `axesm`

# showm

---

**Purpose** Specify graphic objects to display on map axes

**Syntax** `showm`  
`showm(handle)`  
`showm(object)`

**Description** `showm` brings up a dialog box for selecting the objects to show (set their `Visible` property to 'on').  
`showm(handle)` shows the objects specified by a vector of handles.  
`showm(object)` shows those objects specified by the `object` string, which can be any string recognized by the `handlem` function.

**See Also** `clma`, `clmo`, `handlem`, `hidem`, `namem`, `tagm`

---

<b>Purpose</b>	Row and column dimensions needed for regular data grid
<b>Syntax</b>	<pre>[r,c] = sized(latlim,lonlim,scale) rc = sized(latlim,lonlim,scale) [r,c,refvec] = sized(latlim,lonlim,scale)</pre>
<b>Description</b>	<p><code>[r,c] = sized(latlim,lonlim,scale)</code> returns the required size for a regular data grid lying between the latitude and longitude limits specified by the two-element input vectors <code>latlim</code> and <code>lonlim</code>, which are of the form <code>[south-limit north-limit]</code> and <code>[west-limit east-limit]</code>, respectively. The <code>scale</code> is the desired cells-per-degree measure of the desired data grid.</p> <p><code>rc = sized(latlim,lonlim,scale)</code> returns the size of the matrix in one two-element vector.</p> <p><code>[r,c,refvec] = sized(latlim,lonlim,scale)</code> also returns the three-element referencing vector geolocating the desired regular data grid.</p>
<b>Examples</b>	<p>How large a matrix would be required for a map of the world at a scale of 25 matrix cells per degree? (That's 25x25=625 cells per "square" degree.)</p> <pre>[r,c] = sized([90,-90],[-180,180],25)  r =     4500 c =     9000</pre> <p>Bear in mind for memory purposes — 9000 x 4500 = 4.05 x 10<sup>7</sup> entries!</p>
<b>See Also</b>	<code>findm</code> , <code>limitm</code> , <code>nanm</code> , <code>onem</code> , <code>spzerom</code> , <code>zerom</code>

# smoothlong

---

**Purpose** Remove discontinuities in longitude data

---

**Note** The `smoothlong` function is obsolete and has been replaced by `unwrapMultipart`, which requires input to be in radians. When working in degrees, use `radtodeg(unwrapMultipart(degtorad(lon)))`.

---

**Syntax**

```
ang = smoothlong(angin)
ang = smoothlong(angin, angleunits)
```

**Description** `ang = smoothlong(angin)` removes discontinuities in longitude data. The resulting angles can cover more than one revolution.

`ang = smoothlong(angin, angleunits)` uses the units defined by the input string *angleunits*. If omitted, default units of 'degrees' are assumed. Valid *angleunits* are:

- 'degrees' — decimal degrees
- 'radians'

**See Also** `unwrapMultipart`

**Purpose**

Read columns of data from ASCII text file

**Syntax**

```
mat = spread
mat = spread(filename)
mat = spread(cols)
```

**Description**

`mat = spread` reads an ASCII file of space-delimited data in two columns and returns the data in a matrix, `mat`. The file is selected by dialog box.

`mat = spread(filename)` specifies the file from which to read by its name, given as the string *filename*.

`mat = spread(cols)` specifies the number of columns of space-delimited data in the file with the integer `cols`. The default value of `cols` is 2.

**Remarks**

The `spread` function is similar to the standard MATLAB function `dlmread`. `spread`, however, is much faster at reading large data sets of the type common for geographic purposes.

**See Also**

`nanclip`

**Purpose** Construct sparse regular data grid of 0s

**Syntax** `[Z,refvec] = spzerom(latlim,lonlim,scale)`

**Description** `[Z,refvec] = spzerom(latlim,lonlim,scale)` returns a sparse regular data grid consisting entirely of 0s and a three-element referencing vector for the returned Z. The two-element vectors `latlim` and `lonlim` define the latitude and longitude limits of the geographic region. They should be of the form `[south north]` and `[west east]`, respectively. The scalar `scale` specifies the number of rows and columns per degree of latitude and longitude.

**Examples** `[Z,refvec] = spzerom([46,51],[-79,-75],1)`

```
Z =  
All zero sparse: 5-by-4  
refvec =  
    1    51   -79
```

**See Also** `limitm`, `nanm`, `onem`, `sizem`, `zerom`

**Purpose**

Standard distance for geographic points

**Syntax**

```
dist = stdist(lat,lon)
dist = stdist(lat,lon,units)
dist = stdist(lat,lon,ellipsoid)
dist = stdist(lat,lon,ellipsoid,units,method)
```

**Description**

`dist = stdist(lat,lon)` returns a row vector of the latitude and longitude geographic standard distance for the data points specified by the columns of `lat` and `lon`.

`dist = stdist(lat,lon,units)` indicates the angular units of the data. When the standard angle string `units` is omitted, 'degrees' is assumed. Output measurements are in terms of these `units` (as arc length distance).

`dist = stdist(lat,lon,ellipsoid)` specifies the elliptical definition of the Earth to be used with the two-element `ellipsoid` vector. The default ellipsoid model is a spherical Earth, which is sufficient for most applications. Output measurements are in terms of the distance units of the `ellipsoid` vector.

`dist = stdist(lat,lon,ellipsoid,units,method)` specifies the method of calculating the standard distance of the data. The default, 'linear', is simply the average great circle distance of the data points from the centroid. Using 'quadratic' results in the square root of the average of the squared distances, and 'cubic' results in the cube root of the average of the cubed distances.

**Background**

The function `stdm` provides independent standard deviations in latitude and longitude of data points. `stdist` provides a means of examining data scatter that does not separate these components. The result is a *standard distance*, which can be interpreted as a measure of the scatter in the great circle distance of the data points from the centroid as returned by `meanm`.

The output distance can be thought of as the radius of a circle centered on the geographic mean position, which gives a measure of the spread of the data.

## Examples

Create latitude and longitude lists using the `worldcities` data set and obtain standard distance deviation for group (compare with the example for `stdm`):

```
cities = shaperead('worldcities.shp', 'UseGeoCoords', true);
Paris = strmatch('Paris',{cities(:).Name});
London = strmatch('London',{cities(:).Name});
Rome = strmatch('Rome',{cities(:).Name});
Madrid = strmatch('Madrid',{cities(:).Name});
Berlin = strmatch('Berlin',{cities(:).Name});
Athens = strmatch('Athens',{cities(:).Name});
lat = [cities(Paris).Lat cities(London).Lat...
       cities(Rome).Lat cities(Madrid).Lat...
       cities(Berlin).Lat cities(Athens).Lat]
lon = [cities(Paris).Lon cities(London).Lon...
       cities(Rome).Lon cities(Madrid).Lon...
       cities(Berlin).Lon cities(Athens).Lon]

dist =stdist(lat,lon)

lat =
    48.8708    51.5188    41.9260    40.4312    52.4257    38.0164
lon =
     2.4131    -0.1300    12.4951    -3.6788    13.0802    23.5183
dist =
     8.1827
```

## See Also

`meanm`, `stdm`



**Purpose**

Standard deviation for geographic points

**Syntax**

```
[latdev,londev] = stdm(lat,lon)
[latdev,londev] = stdm(lat,lon,ellipsoid)
[latdev,londev] = stdm(lat,lon,units)
```

**Description**

[latdev,londev] = stdm(lat,lon) returns row vectors of the latitude and longitude geographic standard deviations for the data points specified by the columns of lat and lon.

[latdev,londev] = stdm(lat,lon,ellipsoid) specifies the elliptical definition of the Earth to be used with the two-element ellipsoid vector. The default ellipsoid model is a spherical Earth, which is sufficient for most applications. Output measurements are in terms of the distance units of the ellipsoid vector.

[latdev,londev] = stdm(lat,lon,units) indicates the angular units of the data. When the standard angle string units is omitted, 'degrees' is assumed. Output measurements are in terms of these units (as arc length distance).

If a single output argument is used, then geodevs = [latdev longdev]. This is particularly useful if the original lat and lon inputs are column vectors.

**Background**

Determining the deviations of geographic data in latitude and longitude is more complicated than simple sum-of-squares deviations from the data averages. For latitude deviation, a straightforward angular standard deviation calculation is performed from the *geographic mean* as calculated by meanm. For longitudes, a similar calculation is performed based on data *departure* rather than on angular deviation. See “Geographic Statistics” in the *Mapping Toolbox User’s Guide*.

**Examples**

Create latitude and longitude lists using the worldcities data set and obtain standard distance deviation for group (compare with the example for stdist):

```
cities = shaperead('worldcities.shp', 'UseGeoCoords', true);
```

```
Paris = strmatch('Paris',{cities(:).Name});
London = strmatch('London',{cities(:).Name});
Rome = strmatch('Rome',{cities(:).Name});
Madrid = strmatch('Madrid',{cities(:).Name});
Berlin = strmatch('Berlin',{cities(:).Name});
Athens = strmatch('Athens',{cities(:).Name});
lat = [cities(Paris).Lat cities(London).Lat...
       cities(Rome).Lat cities(Madrid).Lat...
       cities(Berlin).Lat cities(Athens).Lat]
lon = [cities(Paris).Lon cities(London).Lon...
       cities(Rome).Lon cities(Madrid).Lon...
       cities(Berlin).Lon cities(Athens).Lon]
[latstd,lonstd]=stdm(lat,lon)

lat =
    48.8708    51.5188    41.9260    40.4312    52.4257    38.0164
lon =
     2.4131    -0.1300    12.4951    -3.6788    13.0802    23.5183
latstd =
     2.7640
lonstd =
    68.7772
```

## See Also

departure, filterm, hista, histr, meanm, stdist

**Purpose**

Project stem plot map on map axes

**Syntax**

```
h = stem3m(lat,lon,z)
h = stem3m(lat,lon,z,LineStyle)
h = stem3m(lat,lon,z,PropertyName,PropertyValue,...)
```

**Description**

`h = stem3m(lat,lon,z)` displays a stem plot on the current map axes. Stems are located at the points (lat,lon) and extend from an altitude of 0 to the values of `z`. The coordinate inputs should be in the same `AngleUnits` as the map axes. It is important to note that the selection of `z`-values will greatly affect the 3-D look of the plot. Regardless of `AngleUnits`, the `x` and `y` limits of the map axes are at most  $-\pi$  to  $+\pi$  and  $-\pi/2$  to  $+\pi/2$ , respectively. This means that for most purposes, appropriate `z` values would be on the order of 1 to 3, not 10 to 30. The axes `DataAspectRatio` property can be used to adjust the appearance of the graphic. The handles of the displayed stem lines can be returned in `h`.

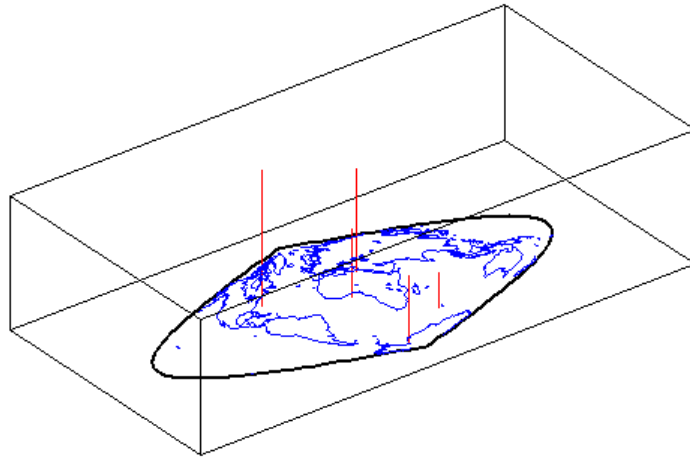
`h = stem3m(lat,lon,z,LineStyle)` allows the style of the stem plot's lines to be specified with any string `LineStyle` recognized by the MATLAB line function.

`h = stem3m(lat,lon,z,PropertyName,PropertyValue,...)` allows any property/value pair recognized by the MATLAB line function to be specified for the stems.

A stem plot displays data as lines extending normal to the `xy`-plane, in this case, on a map.

**Examples**

```
load coast
axesm sinusoid; view(3)
h = framem; set(h,'zdata',zeros(size(lat)))
plotm(lat,long)
ptlat = [0 30 30 -50 -78]';
ptlon = [0 30 -70 65 -35]';
ptz = [1 1.5 2 .5 1]';
stem3m(ptlat,ptlon,ptz,'r-')
```



**See Also**

scatterm

**Purpose** Convert strings to angles in degrees

**Syntax** `angles = str2angle(strings)`

**Description** `angles = str2angle(strings)` converts strings containing latitudes and/or longitudes, expressed in one of four different formats of degree-minutes-seconds, to numeric angles in units of degrees.

Format Description	Example
Degree Symbol, Single/Double Quotes	'123 30' '00"W'
'd', 'm', 's' Separators	'123d30m00sW'
Minus Signs as Separators	'123-30-00W'
"Packed DMS"	'1233000W'

Input must conform closely to the examples provided; in particular, the seconds field must be included, even if it is not significant. Except in Packed DMS format, the seconds field can contain a fractional component. Sign characters are not supported; terminate each string with 'N' for positive latitude, 'S' for negative latitude, 'E' for positive longitude, or 'W' for negative longitude. `strings` is string or a cell array of strings. For backward compatibility, `strings` can also be a character matrix. If more than one angle is represented, `strings` can either contain homogeneous or heterogeneous formatting (see example). `angles` is a column vector of class double.

**Example**

```

strs = {'23 30' '00"N', '23-30-00S', '123d30m00sE', '1233000W'}

strs =
    '23 30' '00"N'    '23-30-00S'    '123d30m00sE'    '1233000W'

str2angle(strs)

ans =
    23.5

```

# str2angle

---

-23.5  
123.5  
-123.5

**See Also**      `angl2str`

**Purpose** Project and add geolocated data grid to current map axes

**Syntax**

```
surfacem(lat,lon,Z)
surfacem(latlim,lonlim,Z)
surfacem(lat,lon,Z,alt)
surfacem(...,prop1,val1,prop2,val2,...)
h = surfacem(...)
```

**Description** `surfacem(lat,lon,Z)` constructs a surface to represent the data grid `Z` in the current map axes. The surface lies flat in the horizontal plane with its `CData` property set to `Z`. The vectors or 2-D arrays `lat` and `lon` define the latitude-longitude graticule mesh on which `Z` is displayed. For a complete description of the various forms that `lat` and `lon` can take, see `surfm`.

`surfacem(latlim,lonlim,Z)` defines the graticule using the latitude and longitude limits `latlim` and `lonlim`. These limits should match the geographic extent of the data grid `Z`. The two-element vector `latlim` has the form:

```
[southern_limit northern_limit]
```

Likewise, `lonlim` has the form:

```
[western_limit eastern_limit]
```

A latitude-longitude graticule of size 50-by-100 is constructed. The surface `FaceColor` property is `'texturemap'`, except when `Z` is precisely 50-by-100, in which case it is `'flat'`.

`surfacem(lat,lon,Z,alt)` sets the `ZData` property of the surface to `'alt'`, resulting in a 3-D surface. `lat` and `lon` must result in a graticule mesh that matches `alt` in size. `CData` is set to `Z`. `Facecolor` is `'texturemap'`, unless `Z` matches `alt` in size, in which case it is `'flat'`.

`surfacem(...,prop1,val1,prop2,val2,...)` applies additional MATLAB graphics properties to the surface via property/value pairs. You can specify any property accepted by the surface function, except `XData`, `YData`, and `ZData`.

# surfacem

---

`h = surfacem(...)` returns a handle to the surface object.

---

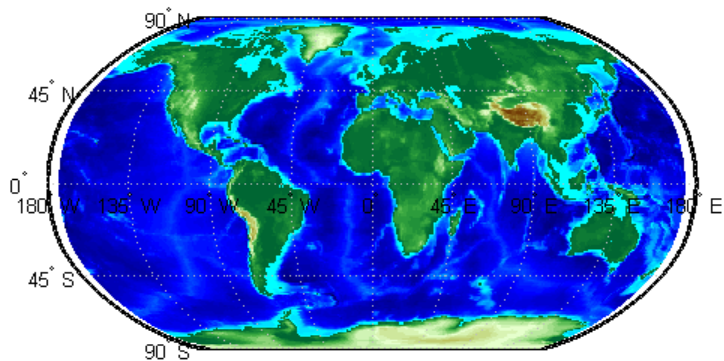
**Note** Unlike `meshm` and `surfm`, `surfacem` always adds a surface to the current axes, regardless of hold state.

---

## Example

Construct a surface to represent the data grid topo.

```
figure('Color','white')
load topo
latlim = [-90 90];
lonlim = [ 0 360];
gratsize = 1 + [diff(latlim), diff(wrapTo360(lonlim))]/6;
[lat, lon] = meshgrat(latlim, lonlim, gratsize);
worldmap world
surfacem(lat, lon, topo)
demcmmap(topo)
```



## See Also

`geoshow`, `meshm`, `pcolorm`, `surfm`



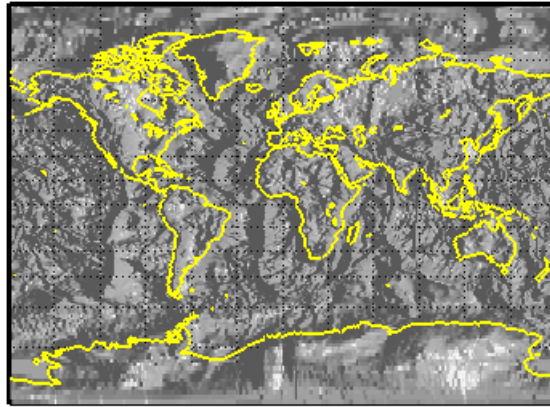
---

<b>Purpose</b>	3-D shaded surface with lighting on map axes
<b>Syntax</b>	<pre>surflm(lat,lon,Z) surflm(latlim,lonlim,Z) surflm(...,s) surflm(...,s,k) h = surflm(...)</pre>
<b>Description</b>	<p><code>surflm(lat,lon,Z)</code> and <code>surflm(latlim,lonlim,Z)</code> are the same as <code>surfm(...)</code> except that they highlight the surface with a light source. The default light source (45 degrees counterclockwise from the current view) and reflectance constants are the same as in <code>surfl</code>.</p> <p><code>surflm(...,s)</code> and <code>surflm(...,s,k)</code> use a light source vector, <code>s</code>, and a vector of reflectance constants, <code>k</code>. For more information on <code>s</code> and <code>k</code>, see the help for <code>surfl</code>.</p> <p><code>h = surflm(...)</code> returns a handle to the surface object.</p>
<b>Remarks</b>	<p><code>surflm</code> is like <code>surfm</code>, except that it shades the monochrome map surface with a light source, and the only allowed graticule is the size of the data matrix.</p>
<b>Example</b>	<p>Project a 3-D shaded surface with lighting on the current map axes. Note that in the following example, the graticule is the size of <code>topo</code> (180 x 360) and is rendered in 3-D, so it might take a while. It is also memory intensive:</p> <pre>figure('Color','white') load topo axesm miller axis off; framem on; gridm on; [lat,lon] = meshgrat(topo,topolegend); surflm(lat,lon,topo) colormap(gray) coast = load('coast'); plotm(coast.lat,coast.long,max(topo(:)),...</pre>

# surfm

---

```
'LineWidth',1.5,'Color','yellow')
```



## See Also

`surfm`

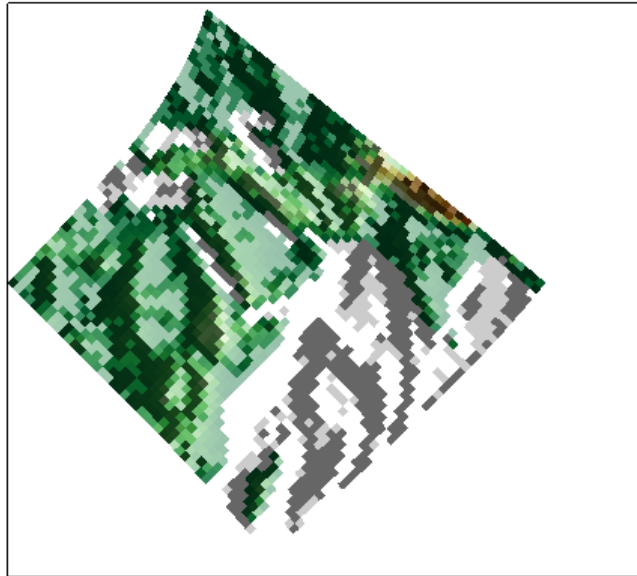
---

<b>Purpose</b>	3-D lighted shaded relief of geolocated data grid
<b>Syntax</b>	<pre>surflsrm(lat,long,Z) surflsrm(lat,long,Z,[azim elev]) surflsrm(lat,long,Z,[azim elev],cmap) surflsrm(lat,long,Z,[azim elev],cmap,clim) h = surflsrm(...)</pre>
<b>Description</b>	<p><code>surflsrm(lat,long,Z)</code> displays the geolocated data grid, colored according to elevation and surface slopes. The current axes must have a valid map projection definition.</p> <p><code>surflsrm(lat,long,Z,[azim elev])</code> displays the geolocated data grid with the light coming from the specified azimuth and elevation. Lighting is applied before the data is projected. Angles are in degrees, with the azimuth measured clockwise from North, and elevation up from the zero plane of the surface. By default, the direction of the light source is east (90° azimuth) at an elevation of 45°.</p> <p><code>surflsrm(lat,long,Z,[azim elev],cmap)</code> displays the geolocated data grid using the provided colormap. The number of grayscales is chosen to keep the size of the shaded colormap below 256. By default, the colormap is constructed from 16 colors and 16 grays. If the vector of azimuth and elevation is empty, the default locations are used.</p> <p><code>surflsrm(lat,long,Z,[azim elev],cmap,clim)</code> uses the provided color axis limits, which are, by default, automatically computed from the data.</p> <p><code>h = surflsrm(...)</code> returns the handle to the surface drawn.</p>
<b>Remarks</b>	<p>This function effectively multiplies two colormaps, one with color based on elevation, the other with a grayscale based on the slope of the surface, to create a new colormap. This produces an effect similar to using a light on a surface, but with all of the visible colors actually in the colormap. Lighting calculations are performed on the unprojected data.</p>

## Examples

Create a new colormap using `demcmap` with white colors for the sea and default colors for land. Use this colormap for the lighted shaded relief map of the Middle East region:

```
load mapmtx
[cmap,clim] = demcmap(map1,[],[1 1 1],[]);
axesm loximuth
surflsrm(lt1,lg1,map1,[],cmap,clim)
```



## See Also

`meshlsrm`, `meshm`, `pcolorm`, `shaderel`, `surfacem`, `surflm`, `surfm`

**Purpose**

Project geolocated data grid on map axes

**Syntax**

```
surfm(lat,lon,Z)
surfm(latlim,lonlim,Z)
surfm(lat,lon,Z,alt)
surfm(...,prop1,val1,prop2,val2,...)
h = surfm(...)
```

**Description**

`surfm(lat,lon,Z)` constructs a surface to represent the data grid `Z` in the current map axes. The surface lies flat in the horizontal plane with its `CData` property set to `Z`. The 2-D arrays or vectors `lat` and `lon` define the latitude-longitude graticule mesh on which `Z` is displayed. The sizes and shapes of `lat` and `lon` affect their interpretation, and also determine whether the default `FaceColor` property of the surface is `'flat'` or `'texturemap'`. There are three options:

- 2-D arrays (matrices) having the same size as `Z`. `lat` and `lon` are treated as geolocation arrays specifying the precise location of each vertex. `FaceColor` is `'flat'`.
- 2-D arrays having a different size than `Z`. The arrays `lat` and `lon` define a graticule mesh that might be either larger or smaller than `Z`. `lat` and `lon` must match each other in size. `FaceColor` is `'texturemap'`.
- Vectors having more than two elements. The elements of `lat` and `lon` are repeated to form a graticule mesh with size equal to `numel(lat)-by-numel(lon)`. `FaceColor` is `'flat'` if the graticule mesh matches `Z` in size. Otherwise, `FaceColor` is `'texturemap'`.

`surfm` clears the current map if the hold state is `'off'`.

`surfm(latlim,lonlim,Z)` defines the graticule using the latitude and longitude limits `latlim` and `lonlim`, which should match the geographic extent of the data grid `Z`. `latlim` is a two-element vector of the form:

```
[southern_limit northern_limit]
```

Likewise `lonlim` has the form:

```
[western_limit eastern_limit]
```

A latitude-longitude graticule is constructed to match Z in size. The surface FaceColor property is 'flat' by default.

`surfm(lat,lon,Z,alt)` sets the ZData property of the surface to 'alt', resulting in a 3-D surface. `lat` and `lon` must result in a graticule mesh that matches `alt` in size. CData is set to Z. The FaceColor property is 'texturemap', unless Z matches `alt` in size, in which case it is 'flat'.

`surfm(...,prop1,val1,prop2,val2,...)` applies additional MATLAB graphics properties to the surface via property/value pairs. You can specify any property accepted by the `surface` function except XData, YData, and ZData.

`h = surfm(...)` returns a handle to the surface object.

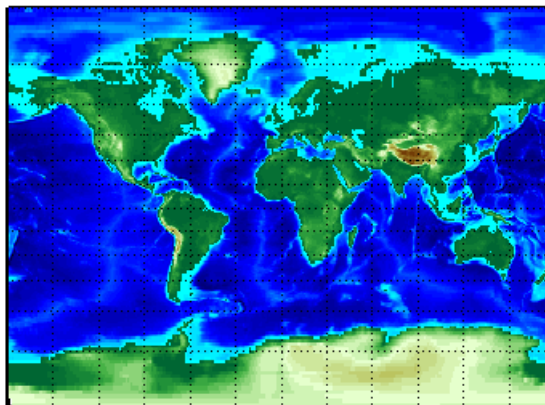
## Remarks

This function warps a data grid to a graticule mesh, which is projected according to the map axes property `MapProjection`. The fineness, or resolution, of this grid determines the quality of the projection and the speed of plotting it. There is no hard and fast rule for sufficient graticule resolution, but in general, cylindrical projections need very few graticule points in the longitudinal direction, while complex curve-generating projections require more.

## Examples

Construct a surface to represent the data grid `topo`.

```
figure('Color','white')
load topo
axesm miller
axis off; framem on; gridm on;
[lat,lon] = meshgrat(topo,topolegend,[90 180]);
surfm(lat,lon,topo)
demcmap(topo)
```



**See Also**

`geoshowmeshgrat`, `meshm`, `pcolorm`, `surfacem`

# symbolm

---

## Purpose

Project point markers with variable size

## Syntax

```
symbolm(lat,lon,z,'MarkerType')  
symbolm(lat,lon,z,'MarkerType','PropertyName',PropertyValue,  
    ...)  
h = symbolm(...)
```

## Description

`symbolm(lat,lon,z,'MarkerType')` constructs a thematic map where the symbol size of each data point (`lat`, `lon`) is proportional to its weighting factor (`z`). The point corresponding to `min(z)` is drawn at the default marker size, and all other points are plotted with proportionally larger markers. The `MarkerType` string is a `LineStyle` string specifying a marker and optionally a color.

`symbolm(lat,lon,z,'MarkerType','PropertyName',PropertyValue,...)` applies the line properties to all the symbols drawn.

`h = symbolm(...)` returns a vector of handles to the projected symbols. Each symbol is projected as an individual line object.

## See also

`stem3m`, `plotm`, `plot`



**Purpose** Set Tag property of map graphics object

**Syntax** tagm(hndl,tagstr)

**Description** tagm(hndl,tagstr) sets the Tag property of each object designated in the vector of handles hndl to the associated string (row) of the matrix of strings tagstr.

This property is recognized by the namem and handlem functions.

**Examples** Normally, a plotted line has a name of 'line':

```
axesm miller
lats = [3 2 1 1 2 3]; longs = [7 8 9 7 8 9];
h=plotm(lats,longs);
```

```
untagged = namem(h)
untagged =
line
```

The tagm function can rename it:

```
tagm(h,'testpath');
tagged = namem(h)
tagged =
testpath
```

**See Also** clma, clmo, handlem, hidem, namem, showm

# tbase

---

**Purpose** Read 5-minute global terrain elevations from TerrainBase

**Syntax**  
`[Z,refvec] = tbase(scalefactor)`  
`[Z,refvec] = tbase(scalefactor,latlim,lonlim)`

**Description** `[Z,refvec] = tbase(scalefactor)` reads the data for the entire world, reducing the resolution of the data by the specified scale factor. The result is returned as a regular data grid and an associated three-element referencing vector.

`[Z,refvec] = tbase(scalefactor,latlim,lonlim)` reads the data for the part of the world within the latitude and longitude limits. The limits must be two-element vectors in units of degrees.

**Background** TerrainBase is a global model of terrain and bathymetry on a regular 5-minute grid (approximately 10 km resolution). It is a compilation of the public domain data from almost 20 different sources, including the DCW-DEM and ETOPO5. The data set was created by the National Geophysical Data Center and World Data Center-A for Solid Earth Geophysics in Boulder, Colorado.

---

**Note** TerrainBase is no longer available for download. You can only use this function if you have previously downloaded the data.

---

**Examples** Read every 10th point in the data set:

```
[Z,refvec] = tbase(10);
```

```
whos
```

Name	Size	Bytes	Class
Z	216x432	746496	double array
refvec	1x3	24	double array

```
limitm(Z,refvec)
```

```
ans =  
    -90    90     0   360
```

Read data for Korea and Japan at the full resolution:

```
scalefactor = 1; latlim = [30 45]; lonlim = [115 145];  
[Z,refvec] = tbase(scalefactor,latlim,lonlim);  
whos datagrid
```

Name	Size	Bytes	Class
Z	180x360	518400	double array

## See Also

gtopo30, etopo, usgsdem

# textm

---

**Purpose** Project text annotation on map axes

**Syntax**

```
textm(lat,lon,string)
textm(lat,lon,z,string)
textm(lat,lon,z,string,PropertyName,PropertyValue,...)
h = textm(...)
```

**Description** `textm(lat,lon,string)` projects the text in `string` onto the current map axes at the locations specified by the `lat` and `lon`. The units of `lat` and `lon` must match the 'angleunits' property of the map axes. If `lat` and `lon` contain multiple elements, `textm` places a text object at each location. In this case `string` may be a cell array of strings with the same number of elements as `lat` and `lon`. (For backward compatibility, `string` may also be a 2-D character array such that `size(string,1)` matches `numel(lat)`).

`textm(lat,lon,z,string)` draws the text at the altitude(s) specified in `z`, which must be the same size as `lat` and `lon`. The default altitude is 0.

`textm(lat,lon,z,string,PropertyName,PropertyValue,...)` sets the text object properties. All properties supported by the MATLAB text function are supported by `textm`.

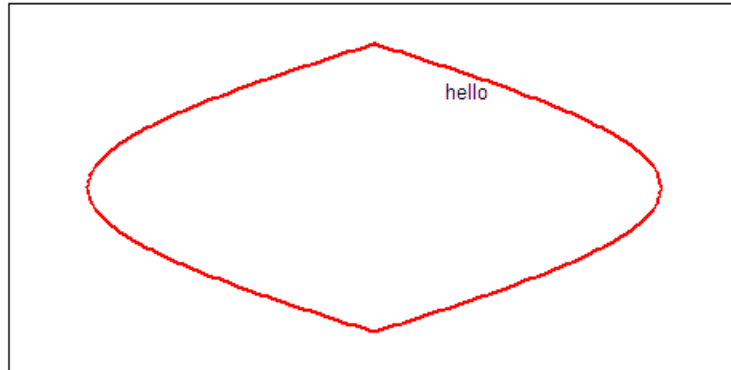
`h = textm(...)` returns the handles to the text objects drawn.

**Remarks** You may be working with scalar `lat` and `lon` data or vector `lat` and `lon` data. If you are in scalar mode and you enter a cell array of strings, you will get a text object with a multiline string. Also note that vertical slash characters, rather than producing multiline strings, will yield a single line string containing vertical slashes. On the other hand, if `lat` and `lon` are nonscalar, then the size of the cell array input must match their size exactly.

**Example** The feature of `textm` that distinguishes it from the standard MATLAB text function is that the text object is projected appropriately. Type the following:

```
axesm sinusoid
```

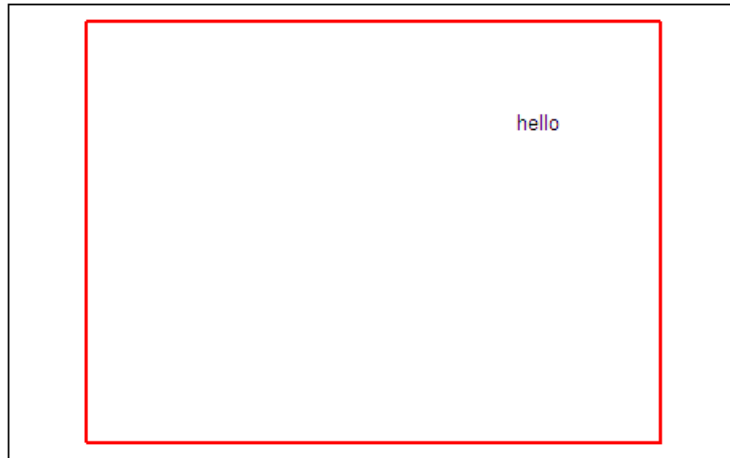
```
framem('FEdgeColor','red')  
textm(60,90,'hello')
```



```
figure; axesm miller  
framem('FEdgeColor','red')  
textm(60,90,'hello')
```

## textm

---



The string 'hello' is placed at the same geographic point, but it appears to have moved relative to the axes because of the different projections. If you change the projection using the `setm` function, the text moves as necessary. Use `text` to fix text objects in the axes independent of projection.

### See Also

`axesm`, `text` (MATLAB function)

**Purpose** Read TIGER/Line data

---

**Note** tgrline will be removed in a future version. More recent TIGER/Line data sets are available in shapefile format and can be imported using shaperead.

---

**Syntax**

```
[CL,PR,SR,RR,H,AL,PL] = tgrline(filename)
[CL,PR,SR,RR,H,AL,PL] = tgrline(filename,year)
[CL,PR,SR,RR,H,AL,PL] = tgrline(filename,year,countyname)
```

**Description** [CL,PR,SR,RR,H,AL,PL] = tgrline(filename) reads a set of 1994 TIGER/Line files which share the same filename, but different extensions. The results are returned in a set of Mapping Toolbox display structures tagged with feature names and containing:

- county boundaries (CL)
- primary roads (PR)
- secondary roads (SR)
- railroads (RR)
- hydrography (H)
- area landmarks (AL)
- point landmarks (PL)

[CL,PR,SR,RR,H,AL,PL] = tgrline(filename,year) reads the TIGER line files in the format from that year. The layout of TIGER/Line files is updated periodically and filename extensions may change from year to year. Valid years are 1990, 1992, 1994, 1995, 1999, 2000, 2002, 2003, and 2004.

[CL,PR,SR,RR,H,AL,PL] = tgrline(filename,year,countyname) uses the string countyname to tag the county data.

---

**Note** For details on locating map data for download over the Internet, see the following documentation at the MathWorks Web site: <http://www.mathworks.com/support/tech-notes/2100/2101.html>.

---

## Background

The United States Census Bureau distributes TIGER/Line data over the Internet and via CD-ROM or DVD.

TIGER/Line files contain vector map data used to support mapping for the U.S. Census Bureau. TIGER is an acronym for Topographically Integrated Geographic Encoding and Referencing. These files contain data for political boundaries, including states, counties, Indian reservations, and census tracts, as well as roads, railroads, hydrography, and landmarks. In addition to the geographically referenced information, the files also contain data to determine the address of an object. The data covers the United States of America and its territories or administrative units: Puerto Rico, the Virgin Islands of the United States, American Samoa, Guam, the Commonwealth of the Northern Mariana Islands, the Republic of Palau, the other Pacific entities that were part of the Trust Territory of the Pacific Islands (the Republic of the Marshall Islands and the Federated States of Micronesia), and the Midway Islands. The most common application of this data is to commercial CD-ROM road atlases.

TIGER/Line is a registered trademark of the United States Census Bureau.

## Remarks

This function reads only a subset of the data in the TIGER/Line files. For example, the function does not return local roads, zip codes, or census tract numbers.

Data are returned as Mapping Toolbox display structures, which you can then update to geographic data structures. For information about display structure format, see “Version 1 Display Structures” on page 3-144 in the reference page for `displaym`. The `updategeostruct` function performs such conversions.



## Examples

Read from the data for Washington, D.C.:

```
[CL,PR,SR,RR,H,AL,PL] = tgrline('TGR11001',1994,'Wash,DC');
```

## See Also

shaperead, updategeostruct

# tightmap

---

**Purpose** Remove white space around map

**Syntax** `tightmap`

**Description** `tightmap` sets the axis limits to be tight around the map in the current axes. This eliminates or reduces the white border between the map frame and the axes box. Use `axis auto` to undo `tightmap`.

**Examples** Display a map of Africa. Notice the white space between the map frame and the edge of the axes box.

```
axesm('miller','maplatlim',[-40 40],'maplonlim',[-20 60])
framem; gridm; mlabel; plabel
load coast
plotm(lat, long)
```

Now use `tightmap` to reduce the wasted space:

```
tightmap
```

**Limitations** The axis limits are fixed. If a change in the projection parameters changes the size or position of the map display within the projected coordinate system, execute `tightmap` again. Also note that `tightmap` needs to be re-applied following any call to `setm` that causes projected map objects to be re-projected.

**See Also** `panzoom`, `zoom`, `paperscale`, `axesscale`, `previewmap`

**Purpose** Time zone based on longitude

**Syntax**

```
[zd,zltr,zone] = timezone(long)
[zd,zltr,zone] = timezone(long,units)
```

**Description**

[zd,zltr,zone] = timezone(long) returns an integer zone description, zd, an alphabetical string zone indicator, zltr, and a string, zone, with the complete zone description and alphabetical zone indicator corresponding to the input longitude long.

[zd,zltr,zone] = timezone(long,units) specifies the angular units with a standard angle *units* string. The default value is 'degrees'. Valid *units* are:

- 'degrees' — decimal degrees
- 'radians'

**Examples** Given that it is locally 1330 (1:30 p.m.) at a longitude of 75°W, determine GMT:

```
[zd,zltr,zone] = timezone(-75,'degrees')

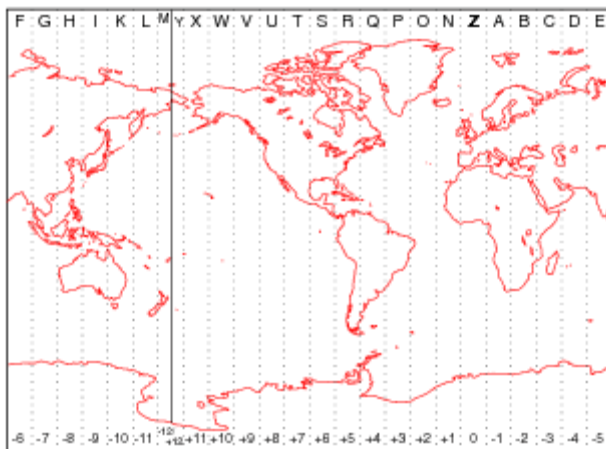
zd =
     5
zltr =
    R
zone =
    +5 R
```

Greenwich Mean Time (GMT) is 1330 plus five hours, or 1830 (6:30 p.m.).

**Background** Time is determined by the position of the Sun relative to the prime meridian, the zero longitude line running through Greenwich, England. When this meridian lies directly below the Sun, it is noon GMT. For local times elsewhere, the Earth is divided into 15° longitude bands, each centered on a central meridian. When a central meridian lies

# timezone

directly below the Sun, Local Mean Time (LMT) in that zone is noon. The zone description is an integer that when added to LMT gives GMT. For notational convenience, each zone is also given an alphabetical indicator. The indicator at Greenwich is Z, so GMT is often called *ZULU time*.



Note that there are actually 25 time zones, because the zone centered on the International Date Line (180° E/W) is split into two: “+12 Y” and “-12 M.”

## Limitations

National and local governments set their own time zone boundaries for political or geographic convenience. The `timezone` function does not account for statutory deviations from the meridian-based system.

**Purpose**

Project Tissot indicatrices on map axes

**Syntax**

```
h = tissot
h = tissot(spec)
h = tissot(spec,linestyle)
h = tissot(linestyle)
h = tissot(spec,PropertyName,PropertyValue,...)
h = tissot(linestyle,PropertyName,PropertyValue,...)
```

**Description**

`h = tissot` plots the default Tissot diagram, as described above, on the current map axes and returns handles for the displayed indicatrices.

`h = tissot(spec)` allows you to specify plotting parameters of the displayed Tissot diagram as described above.

`h = tissot(spec,linestyle)` and `h = tissot(linestyle)` specify any *linestyle* string recognized by the standard MATLAB line function to set the line style of the Tissot indicatrices.

`h = tissot(spec,PropertyName,PropertyValue,...)` and `h = tissot(linestyle,PropertyName,PropertyValue,...)` allow the specification of any property and value recognized by the line function.

**Background**

Tissot indicatrices are plotting symbols that are useful for understanding the various distortions of a given map projection. The indicatrices are circles of identical true radius on the Earth's surface. When plotted on a map projection, they indicate whether the projection has certain features. If the plotted indicatrices all enclose the same area, the projection is equal area (for example, a Sinusoidal projection would have this feature). If they all remain circular, then conformality is indicated (a Mercator projection has this property). Distortions in meridional or parallel distance are exhibited by flattened or stretched indicatrices. Many projections will show very even, circular indicatrices in some regions, often near the center, and wildly distorted indicatrices in others, such as near the edges. The Tissot diagram is therefore very useful in analyzing the appropriateness of a projection to a given purpose or region. "Map Projections Reference" of this guide includes Tissot diagrams for every projection on a global scale.

The general layout of the Tissot diagram is defined by the specification vector `spec`.

```
spec = [Radius]
spec = [Latint,Longint]
spec = [Latint,Longint,Radius]
spec = [Latint,Longint,Radius,Points]
```

`Radius` is the small circle radius of each indicatrix circle. If entered, it should be in the same units as the map axes `Geoid`. The default radius is 1/10th the radius of the sphere.

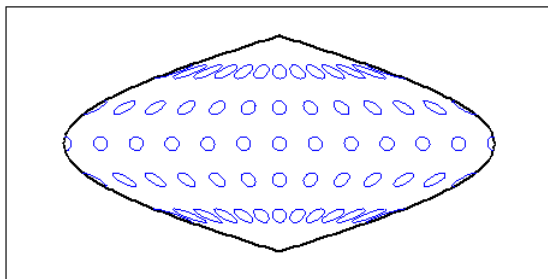
`Latint` is the latitude interval between indicatrix circle centers. If entered it should be in the map axes `AngleUnits`. The default value is one circle every 30° of latitude (that is, 0°, +/-30°, etc.).

`Longint` is the longitude interval between indicatrix circle centers. If entered it should be in the map axes `AngleUnits`. The default value is one circle every 30° of longitude (that is, 0°, +/-30°, etc.).

`Points` is the number of plotting points per circle. The default is 100 points.

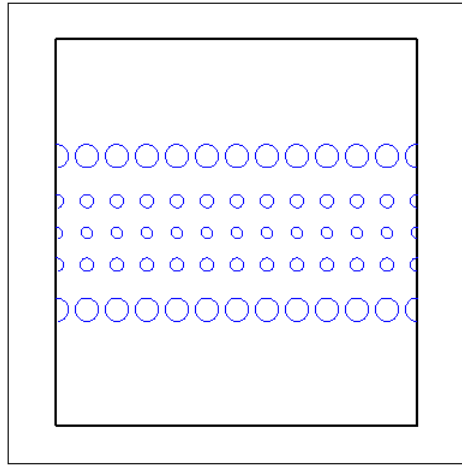
## Examples

```
axesm sinusoid; framem
tissot
```



The Sinusoidal projection is equal area.

```
setm(gca, 'MapProjection', 'Mercator')
```



The Mercator projection is conformal.

**See Also**

`mdistort`, `distortcalc`

See “Map Projections Reference”

# toDegrees

---

<b>Purpose</b>	Convert angles to degrees
<b>Syntax</b>	<pre>[angle1InDegrees, angle2InDegrees, ...] = toDegrees(<i>fromUnits</i>, angle1, angle2, ...)</pre>
<b>Description</b>	<pre>[angle1InDegrees, angle2InDegrees, ...] = toDegrees(<i>fromUnits</i>, angle1, angle2, ...) converts angle1, angle2, ... to degrees from the specified angle units. <i>fromUnits</i> can be either 'degrees' or 'radians' and may be abbreviated. The inputs angle1, angle2, ... and their corresponding outputs are numeric arrays of various sizes, with size(angleNinDegrees) matching size(angleN).</pre>
<b>See Also</b>	<code>fromDegrees</code> , <code>fromRadians</code> , <code>radtodeg</code> , <code>toRadians</code>



<b>Purpose</b>	Convert angles to radians
<b>Syntax</b>	<pre>[angle1InRadians, angle2InRadians, ...] = toRadians(<i>fromUnits</i>, angle1, angle2, ...)</pre>
<b>Description</b>	<pre>[angle1InRadians, angle2InRadians, ...] = toRadians(<i>fromUnits</i>, angle1, angle2, ...) converts angle1, angle2, ... to radians from the specified angle units. <i>fromUnits</i> can be either 'degrees' or 'radians' and may be abbreviated. The inputs angle1, angle2, ... and their corresponding outputs are numeric arrays of various sizes, with size(angleNinRadians) matching size(angleN).</pre>
<b>See Also</b>	degtorad, fromDegrees, fromRadians, toDegrees

**Purpose** Track segments to connect navigational waypoints

**Syntax**

```
[latrkr,lonrkr] = track(waypts)
[latrkr,lonrkr] = track(waypts,units)
[latrkr,lonrkr] = track(lat,lon)
[latrkr,lonrkr] = track(lat,lon,ellipsoid)
[latrkr,lonrkr] = track(lat,lon,ellipsoid,units,npts)
[latrkr,lonrkr] = track(method,lat,...)
trkpts = track(lat,lon...)
```

**Description** [latrkr,lonrkr] = track(waypts) returns points in latrkr and lonrkr along a track between the waypoints provided in navigational track format in the two-column matrix waypts. The outputs are column vectors in which successive segments are delineated with NaNs.

[latrkr,lonrkr] = track(waypts,units) specifies the units of the inputs and outputs, where units is any valid angle unit string. The default is 'degrees'.

[latrkr,lonrkr] = track(lat,lon) allows the user to input the waypoints in two vectors, lat and lon.

[latrkr,lonrkr] = track(lat,lon,ellipsoid) specifies the elliptical definition of the Earth with a two-element ellipsoid model vector ellipsoid. The default ellipsoid is a spherical Earth, which is sufficient for most applications.

[latrkr,lonrkr] = track(lat,lon,ellipsoid,units,npts) establishes how many intermediate points are to be calculated for every track segment. By default, npts is 30.

[latrkr,lonrkr] = track(method,lat,...) establishes the logic to be used to determine the intermediate points along the track between waypoints. Because this is a navigationally motivated function, the default method is 'rh', which results in rhumb line logic. Great circle logic can be specified with 'gc'.

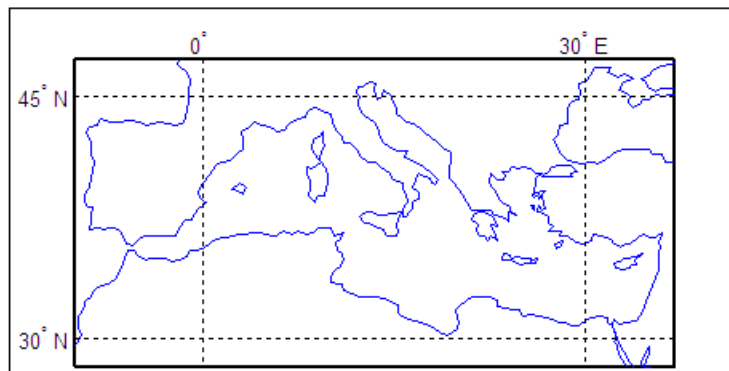
trkpts = track(lat,lon...) compresses the output into one two-column matrix, trkpts, in which the first column represents latitudes and the second column, longitudes.

## Examples

The track function is useful for generating data in order to display tracks. Lieutenant Sextant is the navigator of the USS Neversail. He is charged with plotting a track to take Neversail from the Straits of Gibraltar to Port Said, Egypt, the northern end of the Suez Canal. He has picked appropriate waypoints and now would like to display the track for his captain's approval.

First, display a chart of the Mediterranean Sea:

```
load coast
axesm('mercator','MapLatLimit',[28 47],'MapLonLimit',[-10 37],...
      'Grid','on','Frame','on','MeridianLabel','on','ParallelLabel','on')
geoshow(lat,long,'DisplayType','line','color','b')
```



These are the waypoints Lt. Sextant has selected:

```
waypoints = [36,-5; 36,-2; 38,5; 38,11; 35,13; 33,30; 31.5,32]
```

```
waypoints =
  36.0000   -5.0000
  36.0000   -2.0000
  38.0000    5.0000
  38.0000   11.0000
```

# track

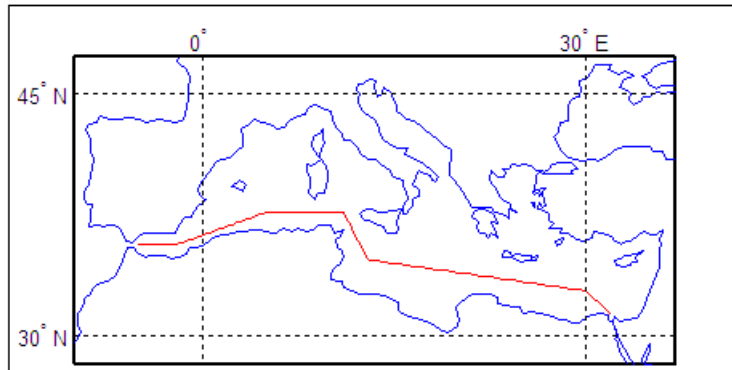
---

```
35.0000  13.0000
33.0000  30.0000
31.5000  32.0000
```

Now display the track:

```
[lptrk,lptrk] = track('rh',waypoints,'degrees');
geoshow(lptrk,lptrk,'DisplayType','line','color','r')
```

With a display this clear, the captain gladly approves the plan.



## See Also

[dreckon](#), [gcwaypts](#), [legs](#), [navfix](#)

**Purpose**

Geographic tracks from starting point, azimuth, and range

**Syntax**

```
[lat,lon] = track1(lat0,lon0,az)
[lat,lon] = track1(lat0,lon0,az,rng)
[lat,lon] = track1(lat0,lon0,az,rng,geoid)
[lat,lon] = track1(lat0,lon0,az,units)
[lat,lon] = track1(lat0,lon0,az,rng,units)
[lat,lon] = track1(lat0,lon0,az,rng,geoid,units)
[lat,lon] = track1(lat0,lon0,az,rng,geoid,units,npts)
[lat,lon] = track1(track,...)
mat = track1(...)
```

**Description**

`[lat,lon] = track1(lat0,lon0,az)` computes complete great circle tracks on a sphere starting at the point `lat0,lon0` and bearing along the input azimuth, `az`. The inputs can be scalar or column vectors.

`[lat,lon] = track1(lat0,lon0,az,rng)` uses the input `rng` to define the range of the great circle computed. The range input is in degrees of arc length along a sphere. If range is a column vector, then the track is computed from the starting point, with positive distance measured easterly. If range is a two column matrix, then the track is computed starting at the range in the first column and ending at the range in the second column. If `rng = []`, then the complete track is computed.

`[lat,lon] = track1(lat0,lon0,az,rng,geoid)` computes the great circle track on the ellipsoid defined by the input `geoid`. The `geoid` vector is of the form `[semimajor axis,eccentricity]`. If the semimajor axis is non-zero, `rng` is assumed to be in distance units matching the units of the semimajor axis. However, if `geoid = []`, or if the semimajor axis is zero, then `rad` is interpreted as an angle and the tracks are computed on a sphere as in the preceding syntax.

`[lat,lon] = track1(lat0,lon0,az,units)`,  
`[lat,lon] = track1(lat0,lon0,az,rng,units)`, and  
`[lat,lon] = track1(lat0,lon0,az,rng,geoid,units)` are all valid calling forms, which use the input string `units` to define the angle units of the inputs and outputs. If the input string `units` is omitted, 'degrees' is assumed.

`[lat,lon] = track1(lat0,lon0,az,rng,geoid,units,npts)` uses the scalar input `npts` to determine the number of points per track computed. The default value of `npts` is 100.

`[lat,lon] = track1(track,...)` uses the `track` string to define either a great circle or a rhumb line track. If `track = 'gc'`, then great circle tracks are computed. If `track = 'rh'`, then rhumb line tracks are computed. If the `track` string is omitted, 'gc' is assumed.

`mat = track1(...)` returns a single output argument where `mat = [lat lon]`. This is useful if a single track is computed.

Multiple tracks can be defined from a single starting point by providing scalar `lat0,lon0` inputs and column vectors for `az` and `rng` if desired.

## Definitions

A path along the surface of the Earth connecting two points is a *track*. Two types of track lines are of interest geographically, *great circles* and *rhumb lines*. Great circles represent the shortest possible path between two points. Rhumb lines are paths with constant angular headings. They are not, in general, the shortest path between two points.

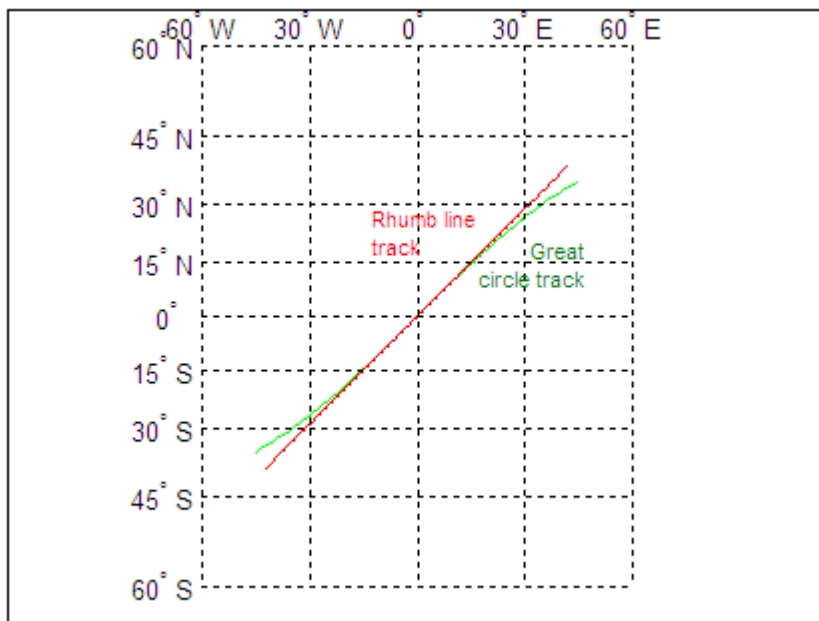
Full great circles bisect the Earth; the ends of the track meet to form a complete circle. Rhumb lines with true east or west azimuths are parallels; the ends also meet to form a complete circle. All other rhumb lines terminate at the poles; their ends do not meet.

## Examples

```
% Set up the axes.
axesm('mercator','MapLatLimit',[-60 60],'MapLonLimit',[-60 60])
gridm on; plabel on; mlabel on;

% Plot the great circle track in green.
[latrkgc,lonrkgc] = track1(0,0,45,[-55 55]);
plotm(latrkgc,lonrkgc,'g')

% Plot the rhumb line track in red.
[latrkrh,lonrkrh] = track1('rh',0,0,45,[-55 55]);
plotm(latrkrh,lonrkrh,'r')
```



**See Also**

azimuth | distance | reckon | scircle1 | scircle2 | track | track2 | trackg

# track2

---

**Purpose** Geographic tracks from starting and ending points

**Syntax**

```
[lat,lon] = track2(lat1,lon1,lat2,lon2)
[lat,lon] = track2(lat1,lon1,lat2,lon2,geoid)
[lat,lon] = track2(lat1,lon1,lat2,lon2,units)
[lat,lon] = track2(lat1,lon1,lat2,lon2,geoid,units)
[lat,lon] = track2(lat1,lon1,lat2,lon2,geoid,units,npts)
[lat,lon] = track2(track,...)
mat = track2(...)
```

**Description**

`[lat,lon] = track2(lat1,lon1,lat2,lon2)` computes great circle tracks on a sphere starting at the point `lat1,lon1` and ending at `lat2,lon2`. The inputs can be scalar or column vectors.

`[lat,lon] = track2(lat1,lon1,lat2,lon2,geoid)` computes the great circle track on the ellipsoid defined by the input `geoid`. The `geoid` vector is of the form `[semimajor axis,eccentricity]`. If `geoid = []`, a sphere is assumed.

`[lat,lon] = track2(lat1,lon1,lat2,lon2,units)` and `[lat,lon] = track2(lat1,lon1,lat2,lon2,geoid,units)` are both valid calling forms, which use the input string `units` to define the angle units of the inputs and outputs. If the input string `units` is omitted, 'degrees' is assumed.

`[lat,lon] = track2(lat1,lon1,lat2,lon2,geoid,units,npts)` uses the scalar input `npts` to determine the number of points per track computed. The default value of `npts` is 100.

`[lat,lon] = track2(track,...)` uses the `track` string to define either a great circle or a rhumb line track. If `track = 'gc'`, then great circle tracks are computed. If `track = 'rh'`, then rhumb line tracks are computed. If the `track` string is omitted, 'gc' is assumed.

`mat = track2(...)` returns a single output argument where `mat = [lat lon]`. This is useful if a single track is computed. Multiple tracks can be defined from a single starting point by providing scalar inputs for `lat1,lon1` and column vectors for `lat2,lon2`.



## Definitions

A path along the surface of the Earth connecting two points is a *track*. Two types of track lines are of interest geographically, *great circles* and *rhumb lines*. Great circles represent the shortest possible path between two points. Rhumb lines are paths with constant angular headings. They are not, in general, the shortest path between two points.

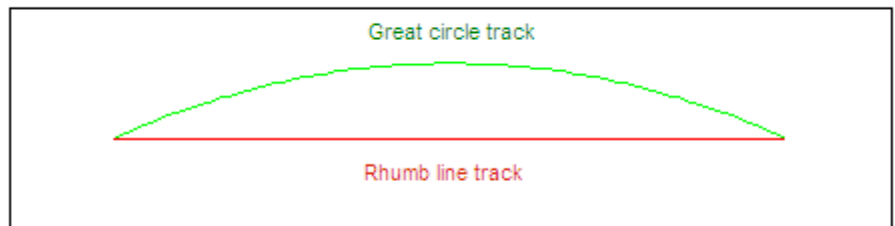
## Examples

```
% Set up the axes.
axesm('mercator','MapLatLimit',[30 50],'MapLonLimit',[-40 40])

% Calculate the great circle track.
[lattrkgc,lontrkgc] = track2(40,-35,40,35);

% Calculate the rhumb line track.
[lattrkrh,lontrkrh] = track2('rh',40,-35,40,35);

% Plot both tracks.
plotm(lattrkgc,lontrkgc,'g')
plotm(lattrkrh,lontrkrh,'r')
```



## See Also

[azimuth](#) | [distance](#) | [reckon](#) | [scircle1](#) | [scircle2](#) | [track](#) | [track1](#) | [trackg](#)

**Purpose** Great circle or rhumb line defined via mouse input

**Syntax**

```
h = trackg(ntrax)
h = trackg(ntrax,npts)
h = trackg(ntrax,linestyle)
h = trackg(ntrax,PropertyName,PropertyValue,...)
[lat,lon] = trackg(ntrax,npts,...)
h = trackg(track,ntrax,...)
```

**Description** `h = trackg(ntrax)` brings forward the current map axes and waits for the user to make (2 x ntrax) mouse clicks. The output `h` is a vector of handles for the ntrax track segments, which are then displayed.

`h = trackg(ntrax,npts)` specifies the number of plotting points to be used for each track segment. `npts` is 100 by default.

`h = trackg(ntrax,linestyle)` specifies the line style for the displayed track segments, where *linestyle* is any line style string recognized by the standard MATLAB line function.

`h = trackg(ntrax,PropertyName,PropertyValue,...)` allows property name/property value pairs to be set, where *PropertyName* and *PropertyValue* are recognized by the line function.

`[lat,lon] = trackg(ntrax,npts,...)` returns the coordinates of the plotted points rather than the handles of the track segments. Successive segments are stored in separate columns of `lat` and `lon`.

`h = trackg(track,ntrax,...)` specifies the logic with which tracks are calculated. If the string *track* is 'gc' (the default), a great circle path is used. If *track* is 'rh', rhumb line logic is used.

This function is used to define great circles or rhumb lines for display using mouse clicks. For each track, two clicks are required, one for each endpoint of the desired track segment. You can modify the track after creation by **Shift**+clicking it. The track is then in edit mode, during which you can change the length and position by dragging control points, or by entering values into a control panel. **Shift**+clicking again exits edit mode.

**See Also**      track1, track2, scircleg

# trimcart

---

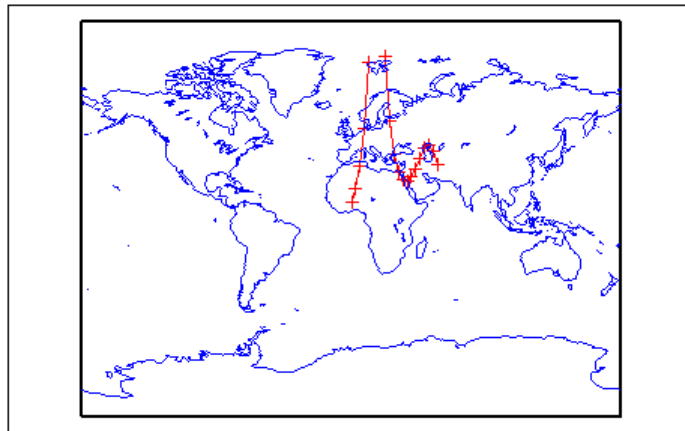
**Purpose** Trim graphic objects to map frame

**Syntax** trimcart(h)

**Description** trimcart(h) clips the graphic objects to the map frame. h can be a handle or a vector of handles to graphics objects. h can also be any object name recognized by handlem. trimcart clips lines, surfaces, and text objects.

**Examples**

```
figure; axesm('miller')
framem
[x, y] = humps(0:.05:1);
h = plot(x, y/25, 'r+-');
load coast
geoshow(lat, long)
trimcart(h)
```



**Limitations** trimcart does not trim patch objects.

**See Also** handlem, makemapped

---

<b>Purpose</b>	Trim map data exceeding projection limits
<b>Syntax</b>	<code>[ymat,xmat,trimpts] = trimdata(ymat,ylim,xmat,xlim,'object')</code>
<b>Description</b>	<p><code>[ymat,xmat,trimpts] = trimdata(ymat,ylim,xmat,xlim,'object')</code> identifies points in map data that exceed projection limits. The projection limits are defined by the lower and upper inputs. The particular object to be trimmed is identified by the 'object' input.</p> <p>Allowable object strings are</p> <ul style="list-style-type: none"><li>• 'surface' for trimming graticules</li><li>• 'light' for trimming lights,</li><li>• 'line' for trimming lines</li><li>• 'patch' for trimming patches</li><li>• 'text' for trimming text object location points</li><li>• 'none' to skip all trimming operations</li></ul>
<b>See Also</b>	<code>clipdata</code> , <code>undotrim</code> , <code>undoclip</code>

# undoclip

---

**Purpose** Remove object clips introduced by `clipdata`

**Syntax** `[lat,long] = undoclip(lat,long,clippts,'object')`

**Description** `[lat,long] = undoclip(lat,long,clippts,'object')` removes the object clips introduced by `clipdata`. This function is necessary to properly invert projected data from the Cartesian space to the original latitude and longitude data points.

The input variable, `clippts`, must be constructed by the function `clipdata`.

Allowable object strings are

- 'surface' for trimming graticules
- 'light' for trimming lights
- 'line' for trimming lines
- 'patch' for trimming patches
- 'text' for trimming text object location points
- 'none' to skip all trimming operations

**See Also** `clipdata`, `trimdata`, `undotrim`

**Purpose** Remove object trims introduced by `trimdata`

**Syntax** `[ymat,xmat] = undotrim(ymat,xmat,trimpts,'object')`

**Description** `[ymat,xmat] = undotrim(ymat,xmat,trimpts,'object')` removes the object trims introduced by `trimdata`. This function is necessary to properly invert projected data from the Cartesian space to the original latitude and longitude data points.

The input variable, `trimpts`, must be constructed by the function `trimdata`.

Allowable object strings are

- 'surface' for trimming graticules
- 'light' for trimming lights
- 'line' for trimming lines
- 'patch' for trimming patches
- 'text' for trimming text object location points
- 'none' to skip all trimming operations

**See Also** `clipdata`, `trimdata`, `undoclip`

# unitsratio

---

**Purpose** Unit conversion factors

**Syntax** `ratio = unitsratio(to, from)`

**Description** `ratio = unitsratio(to, from)` returns the number of `to` units per one `from` unit. For example, `unitsratio('cm', 'm')` returns 100 because there are 100 centimeters per meter. `unitsratio` makes it easy to convert from one system of units to another. Specifically, if `x` is in units `from` and

$$y = \text{unitsratio}(\text{to}, \text{from}) * x$$

then `Y` is in units `to`.

`to` and `from` can be any strings from the second column of one of the following tables (both must come from the same table). `to` and `from` are case insensitive and can be either singular or plural.

## Units of Length

`unitsratio` recognizes the following identifiers for converting units of length:

Unit Name	String(s)
Meter	'm', 'meter(s)', 'metre(s)'
Centimeter	'cm', 'centimeter(s)', 'centimetre(s)'
Millimeter	'mm', 'millimeter(s)', 'millimetre(s)'
Micron	'micron(s)'
Kilometer	'km', 'kilometer(s)', 'kilometre(s)'
Nautical mile	'nm', 'nautical mile(s)'
International foot	'ft', 'international ft', 'foot', 'international foot', 'feet', 'international feet'
Inch	'in', 'inch', 'inches'
Yard	'yd', 'yard(s)'



Unit Name	String(s)
international mile	'mi', 'mile(s)', 'international mile(s)'
U.S. survey foot	'sf', 'survey ft', 'U.S. survey ft', 'survey foot', 'U.S. survey foot', 'survey feet', 'U.S. survey feet'
U.S. survey mile (statute mile)	'sm', 'survey mile(s)', 'statute mile(s)', 'U.S. survey mile(s)'

## Units of Angle

unitsratio recognizes the following identifiers for converting units of angle:

Unit Name	String(s)
radian	'rad', 'radian(s)'
degree	'deg', 'degree(s)'

## Examples

```
% Approximate mean earth radius in meters
radiusInMeters = 6371000
% Conversion factor
feetPerMeter = unitsratio('feet', 'meter')
% Radius in (international) feet:
radiusInFeet = feetPerMeter * radiusInMeters
% The following prints a true statement for valid TO, FROM pairs:
to = 'feet';
from = 'mile';
sprintf('There are %g %s per %s.', unitsratio(to,from), to, from)
% The following prints a true statement for valid TO, FROM pairs:
to = 'degrees';
from = 'radian';
sprintf('One %s is %g %s.', from, unitsratio(to,from), to)
```

# unitstr

---

## Purpose

Check spatiotemporal unit strings and abbreviations

---

**Note** The `unitstr` function is obsolete and will be removed in a future release. The syntax `str = unitstr(str, 'times')` has already been removed.

---

## Syntax

```
unitstr
str = unitstr(str0, 'angles')
str = unitstr(str0, 'distances')
```

## Description

`unitstr`, with no arguments, displays a list of strings and abbreviations, recognized by certain Mapping Toolbox functions, for units of angle and length/distance.

`str = unitstr(str0, 'angles')` checks for valid angle unit strings or abbreviations. If a valid string or abbreviation is found, it is converted to a standardized, preset string. 'angles' can be abbreviated.

`str = unitstr(str0, 'distances')` checks for valid length unit strings or abbreviations. If a valid string or abbreviation is found, it is converted to a standardized, preset string. 'distances' can be abbreviated. Note that input strings 'miles' and 'mi' are converted to 'statutemiles'; there is no way to specify international miles in the `unitstr` function.

## Examples

This function recognizes and standardizes certain abbreviations:

```
str = unitstr('sm', 'distances')

str =
statutemiles
```

And any unique truncation:

```
str = unitstr('ra', 'angles')
```

```
str =  
radians
```

**See Also**

`unitsratio`

# unwrapMultipart

---

**Purpose** Unwrap vector of angles with NaN-delimited parts

**Syntax** `unwrapped = unwrapMultipart(p)`

**Description** `unwrapped = unwrapMultipart(p)` unwraps a row or column vector of azimuths, longitudes, or phase angles. Input and output units are both radians. If `p` is separated into multiple parts delimited by values of NaN, each part is unwrapped independently. If `p` has only one part, the result is equivalent to `unwrap(p)`. The output is the same size as the input and has NaNs in the same locations.

## Examples

### Example 1

Compare the behavior `unwrapMultipart` to that of `unwrap`. The output of `unwrapMultipart` starts over again at 6.11 following the NaN, unlike the output of `unwrap`. The output of `unwrapMultipart` is equivalent to a concatenation (with NaN-separator) of separate calls to `unwrap`:

```
p1 = [0.17      5.67      4.89      4.10];
p2 = [6.11      1.05      2.27];
unwrap([p1 NaN p2])

ans =
    0.1700   -0.6132   -1.3932   -2.1832         NaN   -0.1732    1.0500    2.2700

unwrapMultipart([p1 NaN p2])

ans =
    0.1700   -0.6132   -1.3932   -2.1832         NaN    6.1100    7.3332    8.5532

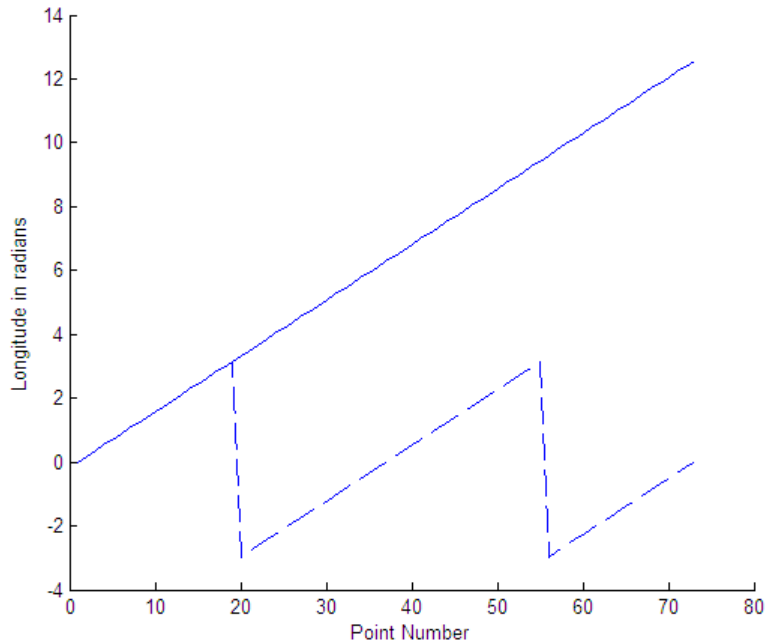
[unwrap(p1) NaN unwrap(p2)]

ans =
    0.1700   -0.6132   -1.3932   -2.1832         NaN    6.1100    7.3332    8.5532
```

## Example 2

Wrap two revolutions of a sphere to  $\pi$  with `wrapToPi`, and then unwrap it with `unwrapMultipart`:

```
lon = wrapToPi(degtorad(0:10:720));  
unwrappedlon = unwrapMultipart(lon);  
figure; hold on  
plot(lon, '--')  
plot(unwrappedlon)  
xlabel 'Point Number'  
ylabel 'Longitude in radians'
```



## See Also

`unwrap`, `wrapTo180`, `wrapTo360`, `wrapToPi`, `wrapTo2Pi`

# updategeostruct

---

## Purpose

Convert line or patch display structure to geostruct

## Syntax

```
geostruct = updategeostruct(displaystruct)
geostruct = updategeostruct(displaystruct, str)
[geostruct,symbolspec] = updategeostruct(displaystruct, ...)
[geostruct,symbolspec] = updategeostruct(displaystruct, ...,
    cmap)
```

## Description

`geostruct = updategeostruct(displaystruct)` accepts a Mapping Toolbox display structure `displaystruct`. If `displaystruct` is a vector display structure for which the 'type' field has value 'line' or 'patch', `updategeostruct` restructures its elements to create a `geostruct`, `geostruct`. If `displaystruct` is a already geographic data structure, it is copied unaltered to `geostruct`. `updategeostruct` does not update display structure arrays of type 'text', 'light', 'regular', or 'surface'.

`geostruct = updategeostruct(displaystruct, str)` selects only elements whose tag field begins with the string `str` (and whose type field is either 'line' or 'patch'). The selection is case insensitive.

`[geostruct,symbolspec] = updategeostruct(displaystruct, ...)` restructures a display structure and determines a `symbolspec` based on the graphic properties specified in the `otherproperty` field for each element of `displaystruct` and, if necessary, the jet colormap.

`[geostruct,symbolspec] = updategeostruct(displaystruct, ..., cmap)` specifies a colormap, `cmap`, to define the colors used in `symbolspec`.

## Remarks

There are two Mapping Toolbox encodings for vector features that use MATLAB structure arrays. In both cases there is one feature per array element, and in both cases a given array's elements all held the same type of feature. Version 1.3.1 and earlier of the Mapping Toolbox software only supported Mapping Toolbox display structures. Version 2.0 introduced a data structure for vector geodata which was less rigidly defined and more open-ended. The new structures are called *geostructs* (if they contain geographic coordinate data) and *mapstructs* (if they

contain projected coordinate data). Over time, display structures are being phased out of the toolbox; the `updategeostruct` function is provided to help users migrate from the old display structure format to the current `geostruct/mapstruct` format.

A Version 1 Mapping Toolbox display structure is a MATLAB structure that can contain line, patch, text, regular data grid, geolocated data grid, and light objects. The `displaym` function does not accept `geostructs` produced by Version 2 of the Mapping Toolbox software.

Display structures for lines and patches and Line and Polygon `geostructs` have the following things in common:

- A field that specifies the type of feature geometry:
  - A `type` field a display structure (value: `'line'` or `'patch'`)
  - A `Geometry` field for a `geostruct` (value: `'Line'` or `'Polygon'`)
- A latitude field:
  - `lat` for a display structure
  - `Lat` for a `geostruct`
- A longitude field:
  - `long` for a display structure
  - `Lon` for a `geostruct`

In terms of their differences,

- A `geostruct` has a `BoundingBox` field; there is no display structure counterpart for this
- A `geostruct` typically has one or more “attribute” fields, whose values must be either scalar doubles or strings, with arbitrary field names. The presence or absence of a given attribute field—and its value—is dependent on the specific data set that the `geostruct` represents.
- A (line or patch) display structure has the following fields:

## updategeostruct

---

- A `tag` field that names an individual feature or object
- An altitude coordinate array that extends coordinates to 3-D
- An `otherproperty` field in which MATLAB graphics can be specified explicitly, on a per-feature basis

Object properties used in the display are taken from the `otherproperty` field of the structure. If a line or patch object's `otherproperty` field is empty, `displaym` uses default colors. A patch is assigned an index into the current colormap based on the structure's `tag` field. Lines are assigned colors from the current color order according to their tags.

The newer `geostruct` representation has significant advantages:

- It can represent a much wider range of attributes (display structures essentially can represent only a feature name).
- The `geostruct` representation (in combination with `geoshow` and `makesymbolspec`) keeps graphics display properties separate from the intrinsic properties of the geographic features themselves.

For example, a road-class attribute can be used to display major highways with a distinctive color and greater line width than secondary roads. The same geographic data structure can be displayed in many different ways, without altering any of its contents, and shapefile data imported from external sources need not be altered to control its graphic display.

For information about the display structure format, see “Version 1 Display Structures” on page 3-144 in the reference page for `displaym`. For a discussion of the characteristics of geographic data structures, see “Mapping Toolbox Geographic Data Structures” in the *Mapping Toolbox User's Guide*.

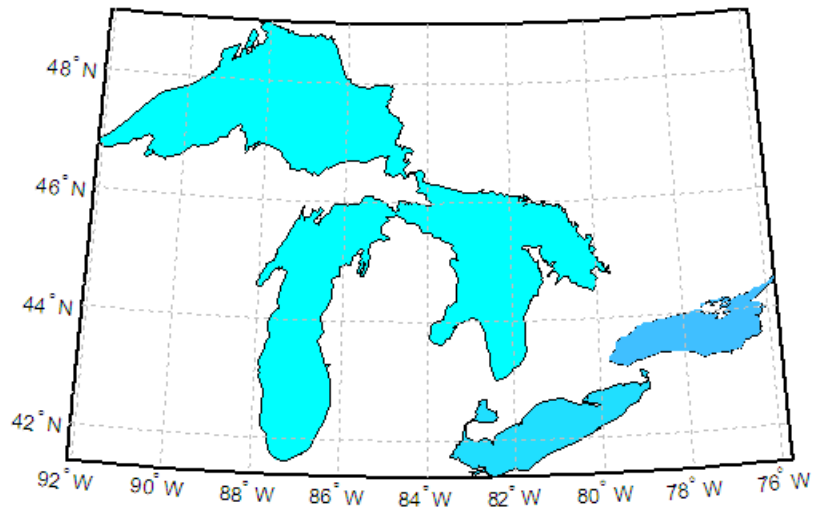
### Example

Update and display the Great Lakes display structure to a `geostruct`:

```
load greatlakes
cmap = cool(3*numel(greatlakes));
```



```
[gtlakes, spec] = updategeostruct(greatlakes, cmap);  
lat = extractfield(gtlakes, 'Lat');  
lon = extractfield(gtlakes, 'Lon');  
lonlim = [min(lon) max(lon)];  
latlim = [min(lat) max(lat)];  
figure  
usamap(latlim, lonlim);  
geoshow(gtlakes, 'SymbolSpec', spec)
```



## See Also

displaym, geoshow, makesymbolspec, mapshow, mapview, shaperead

# usamap

---

**Purpose** Construct map axes for United States of America

**Syntax**

```
usamap state
usamap(state)
usamap 'conus'
usamap('conus')
usamap
usamap(latlim, lonlim)
usamap(Z, R)
h = usamap(...)
h = usamap('all')
h = usamap('allequal')
```

**Description** `usamap state` or `usamap(state)` constructs an empty map axes with a Lambert Conformal Conic projection and map limits covering a U.S. state or group of states specified by input `state`. `state` may be a string or a cell array of strings, where each string contains the name of a state or 'District of Columbia'. Alternatively, `state` may be a standard two-letter U.S. Postal Service abbreviation. The map axes is created in the current axes and the axis limits are set tight around the map frame.

`usamap 'conus'` or `usamap('conus')` constructs an empty map axes for the conterminous 48 states (i.e. excluding Alaska and Hawaii).

`usamap` with no arguments asks you to choose from a menu of state names plus 'District of Columbia', 'conus', 'all', and 'allequal'.

`usamap(latlim, lonlim)` constructs an empty Lambert Conformal map axes for a region of the U.S. defined by its latitude and longitude limits in degrees. `latlim` and `lonlim` are two-element vectors of the form `[southern_limit northern_limit]` and `[western_limit eastern_limit]`, respectively.

`usamap(Z, R)` derives the map limits from the extent of a regular data grid georeferenced by `R`. `R` is either a 1-by-3 vector containing elements:

```
[cells/degree northern_latitude_limit western_longitude_limit]
```

or a 3-by-2 referencing matrix that transforms raster row and column indices to/from geographic coordinates according to:

$$[\text{lon lat}] = [\text{row col 1}] * R$$

If  $R$  is a referencing matrix, it must define a (non-rotational, non-skewed) relationship in which each column of the data grid falls along a meridian and each row falls along a parallel.

`h = usamap(...)` returns the handle of the map axes.

`h = usamap('all')` constructs three empty axes, inset within a single figure, for the conterminous states, Alaska, and Hawaii, respectively, using projection parameters suggested by the U.S. Geological Survey. The handles for the three map axes are returned in `h`. `h(1)` is for the conterminous states, `h(2)` is for Alaska, and `h(3)` is for Hawaii.

`h = usamap('allequal')` constructs the map axes with Alaska and Hawaii at the same scale as the conterminous states.

## Remarks

`usamap` uses `tightmap` set the axis limits tight around the map. If you change the projection, or just want more white space around the map frame, use `tightmap` again or `axis auto`.

`axes(h(n))`, where  $n = 1, 2, \text{ or } 3$ , makes the desired axes current.

`set(h, 'Visible', 'on')` makes the axes visible.

`set(h, 'ButtonDownFcn', 'selectmoveresize')` allows interactive repositioning of the axes. `set(h, 'ButtonDownFcn', 'uimaptbx')` restores the Mapping Toolbox interfaces.

`axesscale(h(1))` resizes the axes containing Alaska and Hawaii to the same scale as the conterminous states.

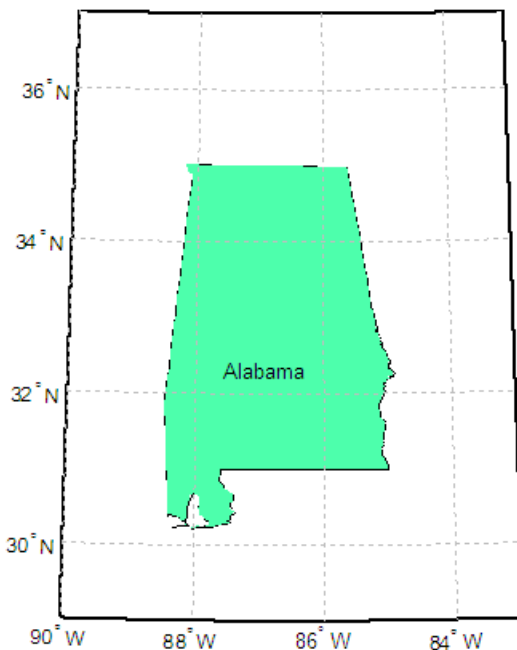
## Examples

### Example 1

Make a map of Alabama only:

```
usamap('Alabama')
alabamahi = shaperead('usastatehi', 'UseGeoCoords', true,...
```

```
        'Selector',{@(name) strcmpi(name,'Alabama'), 'Name'});  
geoshow(alabamahi, 'FaceColor', [0.3 1.0, 0.675])  
textm(alabamahi.LabelLat, alabamahi.LabelLon, alabamahi.Name,...  
      'HorizontalAlignment', 'center')
```



## Example 2

Map a region extending from California to Montana:

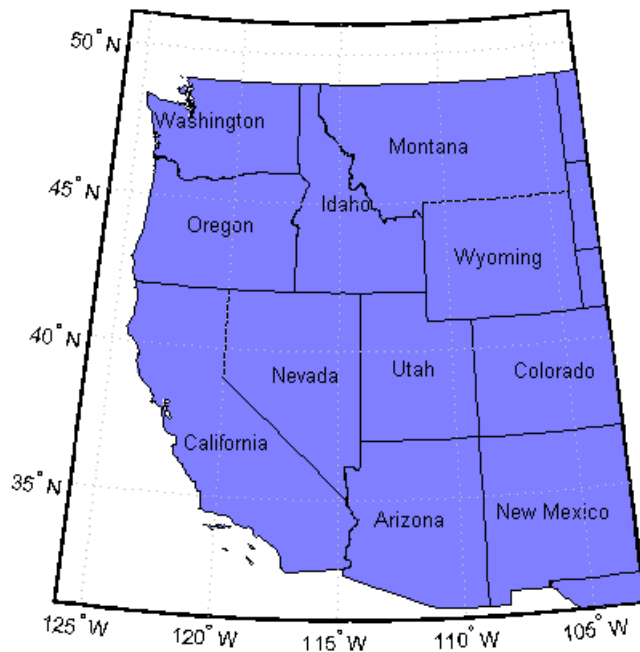
```
figure; ax = usamap({'CA','MT'});  
set(ax, 'Visible', 'off')  
latlim = getm(ax, 'MapLatLimit');  
lonlim = getm(ax, 'MapLonLimit');  
states = shaperead('usastatehi',...  
                  'UseGeoCoords', true, 'BoundingBox', [lonlim, latlim]);
```

```

geoshow(ax, states, 'FaceColor', [0.5 0.5 1])

lat = [states.LabelLat];
lon = [states.LabelLon];
tf = ingeoquad(lat, lon, latlim, lonlim);
textm(lat(tf), lon(tf), {states(tf).Name}, ...
      'HorizontalAlignment', 'center')

```



### Example 3

Map the Conterminous United States with a different fill color for each state:

```

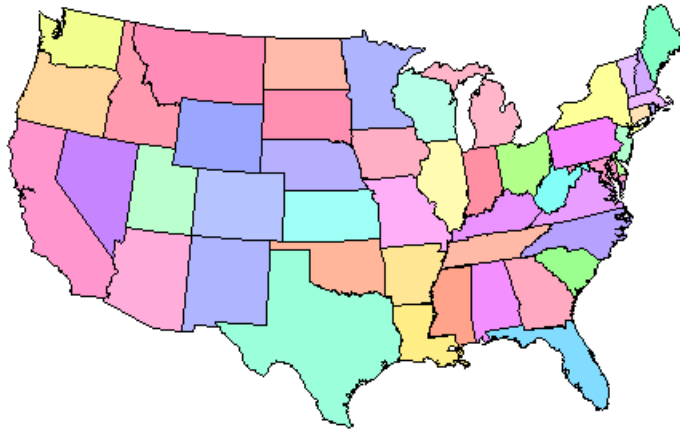
figure; ax = usamap('conus');
states = shaperead('usastatelo', 'UseGeoCoords', true,...

```

# usamap

---

```
'Selector',...
{@(name) ~any(strcmp(name,{'Alaska','Hawaii'})), 'Name'}};
faceColors = makesymbolspec('Polygon',...
    {'INDEX', [1 numel(states)], 'FaceColor', ...
    polcmap(numel(states))}); %NOTE - colors are random
geoshow(ax, states, 'DisplayType', 'polygon', ...
    'SymbolSpec', faceColors)
framem off; gridm off; mlabel off; plabel off
```

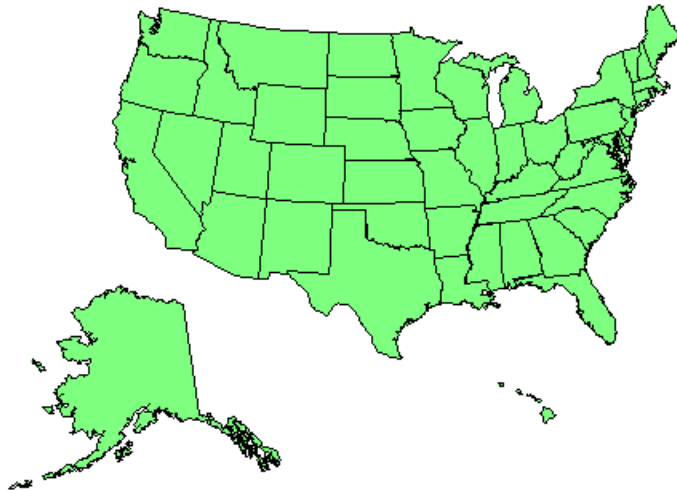


## Example 4

Map of the USA with separate axes for Alaska and Hawaii:

```
figure; ax = usamap('allequal');
set(ax, 'Visible', 'off')
states = shaperead('usastatelo', 'UseGeoCoords', true);
names = {states.Name};
indexHawaii = strmatch('Hawaii',names);
indexAlaska = strmatch('Alaska',names);
indexConus = 1:numel(states);
indexConus(indexHawaii) = [];
```

```
indexConus(indexAlaska) = [];  
stateColor = [0.5 1 0.5];  
geoshow(ax(1), states(indexConus), 'FaceColor', stateColor)  
geoshow(ax(2), states(indexAlaska), 'FaceColor', stateColor)  
geoshow(ax(3), states(indexHawaii), 'FaceColor', stateColor)  
for k = 1:3  
    setm(ax(k), 'Frame', 'off', 'Grid', 'off',...  
        'ParallelLabel', 'off', 'MeridianLabel', 'off')  
end
```

**See also**

`axesm`, `axesscale`, `geoshow`, `paperscale`, `selectmoveresize`,  
`tightmap`, `worldmap`

# usgs24kdem

---

**Purpose** Read USGS 7.5-minute (30-m or 10-m) Digital Elevation Models

**Syntax**

```
[lat,lon,Z] = usgs24kdem
[lat,lon,Z] = usgs24kdem(filename)
[lat,lon,Z] = usgs24kdem(filename,samplefactor)
[lat,lon,Z] =
usgs24kdem(filename,samplefactor,latlim,lonlim)
[lat,lon,Z] = ...usgs24kdem(filename,samplefactor,latlim,
lonlim,gsize)
[lat,lon,Z,header,profile] = usgs24kdem(...)
```

**Description** [lat,lon,Z] = usgs24kdem reads a USGS 1:24,000 digital elevation map (DEM) file in standard format. The file is selected interactively. The entire file is read and subsampled by a factor of 5. A geolocated data grid is returned with a latitude array, lat, longitude array, lon, and elevation array, Z. Horizontal units are in degrees, vertical units may vary. The 1:24,000 series of DEMs are stored as a grid of elevations spaced either at 10 or 30 meters apart. The number of points in a file will vary with the geographic location.

[lat,lon,Z] = usgs24kdem(*filename*) reads the USGS DEM specified by *filename* and returns the result as a geolocated data grid.

[lat,lon,Z] = usgs24kdem(*filename*,*samplefactor*) reads a subset of the DEM data from *filename*. *samplefactor* is a scalar integer, which when equal to 1 reads the data at its full resolution. When *samplefactor* is an integer *n* greater than one, every *n*th point is read. If *samplefactor* is omitted or empty, it defaults to 5.

[lat,lon,Z] = usgs24kdem(*filename*,*samplefactor*,*latlim*,*lonlim*) reads a subset of the elevation data from *filename*. The limits of the desired data are specified as two-element vectors of latitude, *latlim*, and longitude, *lonlim*, in degrees. The elements of *latlim* and *lonlim* must be in ascending order. The data may extend somewhat outside the requested area. If limits are omitted, data for the entire area covered by the DEM file is returned.



```
[lat,lon,Z] =
...usgs24kdem(filename,samplefactor,latlim,lonlim,gsize)
```

specifies the graticule size in `gsize`. `gsize` is a two-element vector specifying the number of rows and columns in the latitude and longitude coordinated grid. If omitted, a graticule the same size as the geolocated data grid is returned. Use empty matrices for `latlim` and `lonlim` to specify the coordinated grid size without specifying the geographic limits.

`[lat, lon, Z, header, profile] = usgs24kdem(...)` also returns the contents of the header and raw profiles of the DEM file. The `header` structure contains descriptions of the data from the file header. The `profile` structure is the raw profile data from which the geolocated data grid is constructed.

## Background

The U.S. Geological Survey has created a series of digital elevation models based on their paper 1:24,000 scale maps. The grid spacing for these elevations models is either 10 or 30 meters on a Universal Transverse Mercator grid. Each file covers a 7.5 minute quadrangle. The map and data series are available for much of the conterminous United States, Hawaii, and Puerto Rico. The data has been released in a number of formats. This function reads the data in the “standard” file format.

## Example

Use the archived San Francisco South 24K DEM file `sanfranciscos.dem.gz`, which is provided in the Mapping Toolbox `mapdemos` directory.

- 1 Gunzip the demo file to a temporary directory:

```
filenames = gunzip('sanfranciscos.dem.gz', tempdir);
demFilename = filenames{1};
```

- 2 Read every other point of the 1:24,000 DEM file.

```
[lat, lon,Z,header,profile] = usgs24kdem(demFilename,2);
```

- 3 Delete the temporary gunzipped file.

```
delete(demFilename);
```

- 4** As no negative elevations exist, move all points at sea level to -1 to color them blue:

```
Z(Z==0) = -1;
```

- 5** Compute the latitude and longitude limits for the DEM:

```
latlim = [min(lat(:)) max(lat(:))]
```

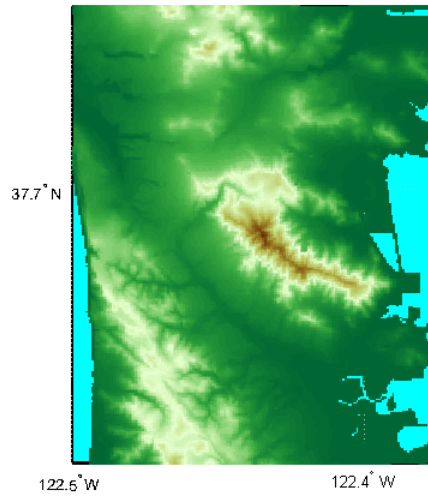
```
latlim =  
    37.6249    37.7504
```

```
lonlim = [min(lon(:)) max(lon(:))]
```

```
lonlim =  
   -122.5008   -122.3740
```

- 6** Display the DEM values:

```
figure  
usamap(latlim, lonlim)  
geoshow(lat, lon, Z, 'DisplayType','surface')  
demcmap(Z)  
daspectm('m',1)
```



7 Examine the metadata in the header:

header

header =

```

Quadranglename: 'SAN FRANCISCO SOUTH, CA
                BIG BASIN DEM'
TextualInfo: 'WMC          CTOG'
  Filler: ''
ProcessCode: ''
  Filler2: ''
SectionalIndicator: ''
MCoriginCode: ''
DEMlevelCode: 2
ElevationPatternCode: 'regular'
PlanimetricReferenceSystemCode: 'UTM'
      Zone: 10
ProjectionParameters: [0 0 0 0 0 0 0 0 0 0 0 0 0]
HorizontalUnits: 'meters'
ElevationUnits: 'feet'
    
```

```
NsidesToBoundingBox: 4
  BoundingBox: [1x8 double]
MinMaxElevations: [0 1314]
  RotationAngle: 0
  AccuracyCode: 'accuracy information in record C'
XYZresolutions: [30 30 1]
  NrowsCols: [1 371]
  MaxPcontourInt: NaN
SourceMaxCintUnits: NaN
  SmallestPrimary: NaN
SourceMinCintUnits: NaN
  DataSourceDate: NaN
DataInspRevDate: NaN
  InspRevFlag: ''
DataValidationFlag: NaN
  SuspectVoidFlag: NaN
  VerticalDatum: NaN
  HorizontalDatum: NaN
  DataEdition: NaN
  PercentVoid: NaN
```

## Remarks

This function reads USGS DEM files stored in the UTM projection. The function unprojects the grid back to latitude and longitude. Use `usgsdem` for data stored in geographic grids.

The number of points in a file varies with the geographic location. Unlike the USGS DEM products, which use an equal-angle grid, the UTM projection grid DEMs cannot simply be concatenated to cover larger areas. There can be data gaps between DEMs.

You can obtain the data files from the U.S. Geological Survey and from commercial vendors. Other agencies have made some local area data available online. The DEM files are ASCII files, and can be transferred as text. Line-ending conversion is not necessarily required.

## See Also

`demdataui`, `dted`, `gtopo30`, `tbase`, `etopo`, `usgsdem`, `usgsdems`

---

<b>Purpose</b>	Read USGS 1-degree (3-arc-second) Digital Elevation Model
<b>Syntax</b>	<pre>[Z,refvec] = usgsdem(filename,scalefactor) [Z,refvec] = usgsdem(filename,scalefactor,latlim,lonlim)</pre>
<b>Description</b>	<p>[Z,refvec] = usgsdem(filename,scalefactor) reads the specified file and returns the data in a regular data grid along with referencing vector refvec, a 1-by-3 vector having elements [cells/degree north-latitude west-longitude] with latitude and longitude limits specified in degrees. The data can be read at full resolution (scalefactor = 1), or can be downsampled by the scalefactor. A scalefactor of 3 returns every third point, giving 1/3 of the full resolution.</p> <p>[Z,refvec] = usgsdem(filename,scalefactor,latlim,lonlim) reads data within the latitude and longitude limits. These limits are two-element vectors with the minimum and maximum values specified in units of degrees.</p>
<b>Background</b>	<p>The U.S. Geological Survey has made available a set of digital elevation maps of 1-degree quadrangles covering the contiguous United States, Hawaii, and limited portions of Alaska. The data is on a regular grid with a spacing of 30 arc-seconds (or about 100-meter resolution). 1-degree DEMs are also referred to as <i>3-arc-second</i> or <i>1:250,000 scale</i> DEM data.</p> <p>The data is derived from the U.S. Defense Mapping Agency's DTED-1 digital elevation model, which itself was derived from cartographic and photographic sources. The cartographic sources were maps from the 7.5-minute through 1-degree series (1:24,000 scale through 1:250,000 scale).</p>
<b>Remarks</b>	<p>The grid for the digital elevation maps is based on the 1984 World Geodetic System (WGS84). Older DEMs were based on WGS72. Elevations are in meters relative to National Geodetic Vertical Datum of 1929 (NGVD 29) in the continental U.S. and local mean sea level in Hawaii.</p>

The absolute horizontal accuracy of the DEMs is 130 meters, while the absolute vertical accuracy is  $\pm 30$  meters. The relative horizontal and vertical accuracy is not specified, but is probably much better than the absolute accuracy.

These DEMs have a grid spacing of 3 arc-seconds in both the latitude and longitude directions. The exception is DEM data in Alaska, where latitudes between 50 and 70 degrees North have grid spacings of 6 arc-seconds, and latitudes greater than 70 degrees North have grid spacings of 9 arc-seconds.

Statistical data in the files is not returned.

You can obtain the data files from the U.S. Geological Survey and from commercial vendors. Other agencies have made some local area data available online.

---

**Note** For details on locating map data for download over the Internet, see the following documentation at the MathWorks Web site: <http://www.mathworks.com/support/tech-notes/2100/2101.html>.

---

## Examples

Read every fifth point in the file containing part of Rhode Island and Cape Cod:

```
[Z,refvec] = usgsdem('providence-e',5);
```

Read the elevation data for Martha's Vineyard at full resolution:

```
[Z,refvec] = usgsdem('providence-e',1,...  
[41.2952 41.4826],[-70.8429 -70.4392]);  
whos Z
```

Name	Size	Bytes	Class
Z	226x485	876880	double array

## See Also

usgs24kdem, gtopo30, etopo, tbase, usgsdems

---

<b>Purpose</b>	USGS 1-degree (3-arc-sec) DEM filenames for latitude-longitude quadrangle
<b>Syntax</b>	<code>[fname,qname] = usgsdems(latlim,lonlim)</code>
<b>Description</b>	<code>[fname,qname] = usgsdems(latlim,lonlim)</code> returns cell arrays of the DEM filenames and quadrangle names covering the geographic region. The region is specified by scalar latitude and longitude points or two-element vectors of latitude and longitude limits in units of degrees.
<b>Background</b>	The U.S. Geological Survey has made available a set of digital elevation maps of 1-degree quadrangles covering the contiguous United States, Hawaii, and limited portions of Alaska. These are referred to as <i>1-degree, 3-arc second</i> or <i>1:250,000 scale</i> DEMs. Because the filenames of these 1 degree data sets are taken from the names of cities or features in the quadrangle, determining the files needed to cover a particular region generally requires consulting an index map or other reference. This function takes the place of such a reference by returning the filenames for a given geographic region.
<b>Remarks</b>	This function only returns filenames for the contiguous United States.
<b>Examples</b>	Which files are needed to map part of New England?  <pre>usgsdems([41 44], [-72 -69])  ans =     'providence-w'     'providence-e'     'chatham-w'     'boston-w'     'boston-e'     'portland-w'     'portland-e'     'bath-w'</pre>

# usgsdems

---

## See Also

[usgsdem](#)



**Purpose**

Select ellipsoids for given UTM zone

**Syntax**

```
ellipsoid = utmgeoid,  
ellipsoid = utmgeoid(zone)  
[ellipsoid,ellipsoidstr] = utmgeoid(...)
```

**Description**

`ellipsoid = utmgeoid`, without any arguments, opens the `utmzoneui` interface for selecting a UTM zone. This zone is then used to return the recommended ellipsoid definitions for that particular zone.

`ellipsoid = utmgeoid(zone)` uses the input `zone` to return the recommended ellipsoid definitions.

`[ellipsoid,ellipsoidstr] = utmgeoid(...)` returns the ellipsoid string used by the `almanac` function.

**Background**

The Universal Transverse Mercator (UTM) system of projections tiles the world into quadrangles called zones. Each zone has different projection parameters and commonly used ellipsoidal models of the Earth. This function returns a list of ellipsoid models commonly used in a zone.

**Examples**

```
zone = utmzone(0,100) % degrees  
  
zone =  
47N  
  
[ellipsoid,names] = utmgeoid(zone)  
  
ellipsoid =  
    6377.3    0.081473  
    6377.4    0.081697  
names =  
everest  
bessel
```

**See Also**

`utmzone`

# utmzone

---

**Purpose** Select UTM zone given latitude and longitude

**Syntax**

```
zone = utmzone
zone = utmzone(lat,long)
zone = utmzone(mat),
[latlim,lonlim] = utmzone(zone),
lim = utmzone(zone)
```

**Description** `zone = utmzone` selects a Universal Transverse Mercator (UTM) zone with a graphical user interface. The zone designation is returned as a string.

`zone = utmzone(lat,long)` returns the UTM zone containing the geographic coordinates. If `lat` and `long` are vectors, the zone containing the geographic mean of the data set is returned. The geographic coordinates must be in units of degrees.

`zone = utmzone(mat)`, where `mat` is of the form `[lat long]`.

`[latlim,lonlim] = utmzone(zone)`, where `zone` is a valid UTM zone designation, returns the geographic limits of the zone. Valid UTM zones designations are numbers, or numbers followed by a single letter. For example, '31' or '31N'. The returned limits are in units of degrees.

`lim = utmzone(zone)` returns the limits in a single vector output.

**Background** The Universal Transverse Mercator (UTM) system of projections tiles the world into quadrangles called zones. This function can be used to identify which zone is used for a geographic area and, conversely, what geographic limits apply to a UTM zone.

**Examples**

```
[latlim,lonlim] = utmzone('12F')

latlim =
    -56    -48
lonlim =
   -114   -108
```

```
utmzone(latlim,lonlim)
```

```
ans =  
12F
```

**Limitations**

The UTM zone system is based on a regular division of the globe, with the exception of a few zones in northern Europe. `utmzone` does not account for these deviations.

**See Also**

`utmgeoid`

**Purpose** Convert latitude-longitude vectors to regular data grid

**Syntax**

```
[Z, R] = vec2mtx(lat, lon, density)
[Z, R] = vec2mtx(lat, lon, density, latlim, lonlim)
[Z, R] = vec2mtx(lat, lon, Z1, R1)
[Z, R] = vec2mtx(..., 'filled')
```

**Description** `[Z, R] = vec2mtx(lat, lon, density)` creates a regular data grid `Z` from vector data, placing ones in grid cells intersected by a vector and zeroes elsewhere. `R` is the referencing vector for the computed grid. `lat` and `lon` are vectors of equal length containing geographic locations in units of degrees. `density` indicates the number of grid cells per unit of latitude and longitude (a value of 10 indicates 10 cells per degree, for example), and must be scalar-valued. Whenever there is space, a buffer of two grid cells is included on each of the four sides of the grid. The buffer is reduced as needed to keep the latitudinal limits within [-90 90] and to keep the difference in longitude limits from exceeding 360 degrees.

`[Z, R] = vec2mtx(lat, lon, density, latlim, lonlim)` uses the two-element vectors `latlim` and `lonlim` to define the latitude and longitude limits of the grid.

`[Z, R] = vec2mtx(lat, lon, Z1, R1)` uses a pre-existing data grid `Z1`, georeferenced by `R1`, to define the limits and density of the output grid. `R1` is either a 1-by-3 vector containing elements:

```
[cells/degree northern_latitude_limit western_longitude_limit]
```

or a 3-by-2 referencing matrix that transforms raster row and column indices to/from geographic coordinates according to:

```
[lon lat] = [row col 1] * R1
```

If `R1` is a referencing matrix, it must define a (non-rotational, non-skewed) relationship in which each column of the data grid falls along a meridian and each row falls along a parallel. With this syntax,

output `R` is equal to `R1`, and may be either a referencing vector or a referencing matrix.

`[Z, R] = vec2mtx(..., 'filled')`, where `lat` and `lon` form one or more closed polygons (with NaN-separators), fills the area outside the polygons with the value two instead of the value zero.

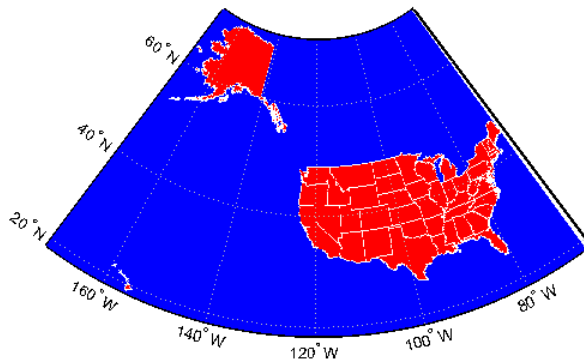
## Notes

Empty `lat`, `lon` vertex arrays will result in an error unless the grid limits are explicitly provided (via `latlim`, `lonlim` or `Z1`, `R1`). In the case of explicit limits, `Z` will be filled entirely with 0s if the `'filled'` parameter is omitted, and 2s if it is included.

It's possible to apply `vec2mtx` to sets of polygons that tile without overlap to cover an area, as in Example 1 below, but using `'filled'` with polygons that actually overlap may lead to confusion as to which areas are inside and which are outside.

## Example 1

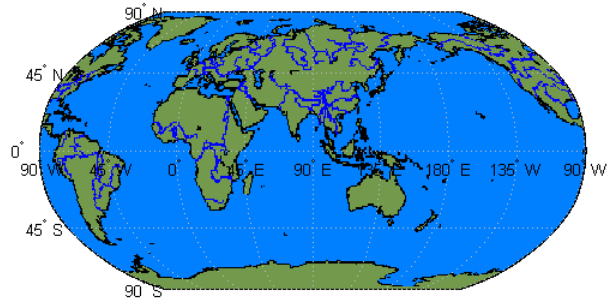
```
states = shaperead('usastatelo', 'UseGeoCoords', true);
lat = [states.Lat];
lon = [states.Lon];
[Z, R] = vec2mtx(lat, lon, 5, 'filled');
figure; worldmap(Z, R);
meshm(Z,R)
colormap(flag(3))
```



## Example 2

Combine two separate calls to `vec2mtx` to create a 4-color raster map showing interior land areas, coastlines, oceans, and world rivers.

```
coast = load('coast.mat');  
[Z, R] = vec2mtx(coast.lat, coast.long, ...  
    1, [-90 90], [-90 270], 'filled');  
rivers = shaperead('worldrivers.shp', 'UseGeoCoords', true);  
A = vec2mtx([rivers.Lat], [rivers.Lon], Z, R);  
Z(A == 1) = 3;  
figure; worldmap(Z, R)  
geoshow(Z, R, 'DisplayType', 'texturemap')  
colormap([.45 .60 .30; 0 0 0; 0 0.5 1; 0 0 1])
```



**See Also**

imbedm

# vfdtran

---

**Purpose** Direction angle in map plane from azimuth on ellipsoid

**Syntax**

```
th = vfdtran(lat,lon,az)
th = vfdtran(mstruct,lat,lon,az)
[th,len] = vfdtran(...)
```

**Description** `th = vfdtran(lat,lon,az)` transforms the azimuth angle at specified latitude and longitude points on the sphere into the projection space. The map projection currently displayed is used to define the projection space. The input angles must be in the same units as specified by the current map projection. The inputs can be scalars or matrices of the equal size. The angle in the projection space is defined as positive counterclockwise from the  $x$ -axis.

`th = vfdtran(mstruct,lat,lon,az)` uses the map projection defined by the input `mstruct` to compute the map projection.

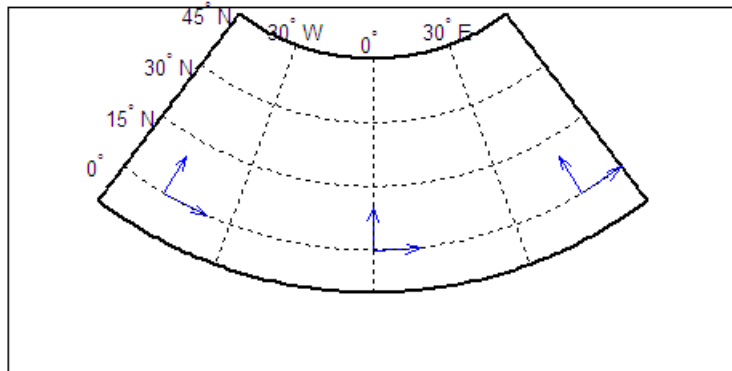
`[th,len] = vfdtran(...)` also returns the vector length in the projected coordinate system. A value of 1 indicates no scale distortion.

**Background** The direction of north is easy to define on the three-dimensional sphere, but more difficult on a two-dimensional map. For cylindrical projections in the normal aspect, north is always in the positive  $y$ -direction. For conic projections, north can be to the left or right of the  $y$ -axis. This function transforms any azimuth angle on the sphere to the corresponding angle in the projected paper coordinates.

**Examples** Sample calculations:

```
axesm('eqdconic','maplatlim',[-10 45],'maplonlim',[-55 55])
gridm; framem; mlabel; plabel
quiverm([0 0 0],[-45 0 45],[0 0 0],[10 10 10],0)
quiverm([0 0 0],[-45 0 45],[10 10 10],[0 0 0],0)
```





```
vfdtran([0 0 0],[-45 0 45],[0 0 0])
```

```
ans =
    59.614         90    120.39
```

```
vfdtran([0 0 0],[-45 0 45],[90 90 90])
```

```
ans =
   -30.385    0.0001931    30.386
```

## Limitations

This transformation is limited to the region specified by the frame limits in the current map definition.

## Remarks

The geographic azimuth angle is measured clockwise from north. The projection space angle is measured counterclockwise from the  $x$ -axis.

This function uses a finite difference technique. The geographic coordinates are perturbed slightly in different directions and projected. A small amount of error is introduced by numerical computation of derivatives and the variation of map distortion parameters.

## See Also

vinvtran, mfdtran, minvtran, defaultm

# viewshed

---

## Purpose

Areas visible from point on terrain elevation grid

## Syntax

```
[vis,R] = viewshed(Z,R,lat1,lon1)
viewshed(Z,R,lat1,lon1,observerAltitude)
viewshed(Z,R,lat1,lon1,observerAltitude,targetAltitude)
viewshed(Z,R,lat1,lon1,observerAltitude,targetAltitude, ...
    observerAltitudeOption)
viewshed(Z,R,lat1,lon1,observerAltitude,targetAltitude, ...
    observerAltitudeOption,targetAltitudeOption)
viewshed(Z,R,lat1,lon1,observerAltitude,targetAltitude, ...
    observerAltitudeOption,targetAltitudeOption,actualRadius)
viewshed(Z,R,lat1,lon1,observerAltitude,targetAltitude, ...
    observerAltitudeOption,targetAltitudeOption, ...
    actualRadius,effectiveRadius)
```

## Description

[vis,R] = viewshed(Z,R,lat1,lon1) computes areas visible from a point on a digital elevation grid. Z is a regular data grid containing elevations in units of meters. The observer location is provided as scalar latitude and longitude in units of degrees. The visibility grid vis contains 1s at the surface locations visible from the observer location, and 0s where the line of sight is obscured by terrain. R is either a 1-by-3 vector containing elements:

```
[cells/degree northern_latitude_limit western_longitude_limit]
```

or a 3-by-2 referencing matrix that transforms raster row and column indices to/from geographic coordinates according to:

```
[lon lat] = [row col 1] * R
```

If R is a referencing matrix, it must define a (non-rotational, non-skewed) relationship in which each column of the data grid falls along a meridian and each row falls along a parallel. The value of R on output is identical to the value supplied as input.

viewshed(Z,R,lat1,lon1,observerAltitude) places the observer at the specified altitude in meters above the surface. This is equivalent

to putting the observer on a tower. If omitted, the observer is assumed to be on the surface.

`viewshed(Z,R,lat1,lon1,observerAltitude,targetAltitude)` checks for visibility of target points a specified distance above the terrain. This is equivalent to putting the target points on towers that do not obstruct the view. If omitted, the target points are assumed to be on the surface.

`viewshed(Z,R,lat1,lon1,observerAltitude,targetAltitude, ... observerAltitudeOption)` controls whether the observer is at a relative or absolute altitude. If the `observerAltitudeOption` is 'AGL', then `observerAltitude` is in meters above ground level. If `observerAltitudeOption` is 'MSL', `observerAltitude` is interpreted as altitude above zero, or mean sea level. If omitted, 'AGL' is assumed.

`viewshed(Z,R,lat1,lon1,observerAltitude,targetAltitude, ... observerAltitudeOption,targetAltitudeOption)` controls whether the target points are at a relative or absolute altitude. If the target altitude option is 'AGL', the `targetAltitude` is in meters above ground level. If `targetAltitudeOption` is 'MSL', `targetAltitude` is interpreted as altitude above zero, or mean sea level. If omitted, 'AGL' is assumed.

`viewshed(Z,R,lat1,lon1,observerAltitude,targetAltitude, ... observerAltitudeOption,targetAltitudeOption,actualRadius)` does the visibility calculation on a sphere with the specified radius. If omitted, the radius of the earth in meters is assumed. The altitudes, the elevations, and the radius should be in the same units. This calling form is most useful for computations on bodies other than the Earth.

`viewshed(Z,R,lat1,lon1,observerAltitude,targetAltitude, ... observerAltitudeOption,targetAltitudeOption, ... actualRadius,effectiveRadius)` assumes a larger radius for propagation of the line of sight. This can account for the curvature of the signal path due to refraction in the atmosphere. For example, radio propagation in the atmosphere is commonly treated as straight line propagation on a sphere with  $4/3$  the radius of the Earth. In that case the last two arguments would be `R_e` and  $4/3 * R_e$ , where `R_e` is the

radius of the earth. Use `Inf` for flat Earth viewshed calculations. The altitudes, the elevations, and the radii should be in the same units.

## Remarks

The observer should be located within the latitude-longitude limits of the elevation grid. If the observer is located outside the grid, there is insufficient information to calculate a viewshed. In this case `viewshed` issues a warning and sets all elements of `vis` to zero.

## Example

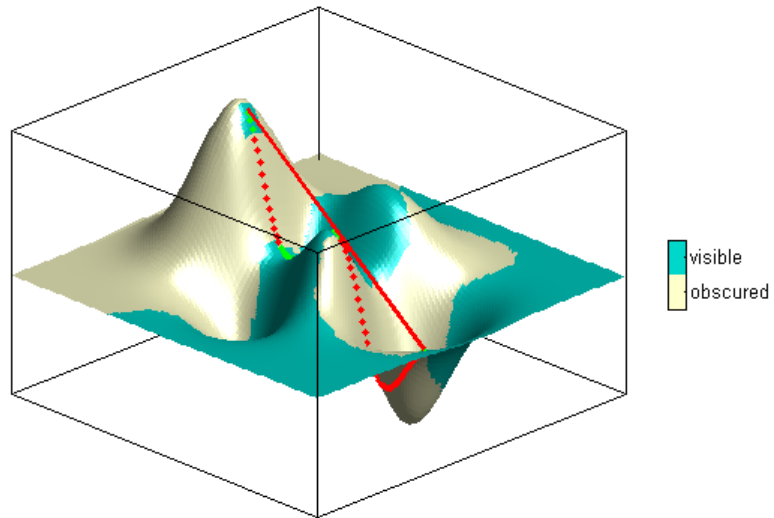
Compute visibility for a point on the peaks map. Add the detailed information for the line of sight calculation between two points from `los2`.

```
Z = 500*peaks(100);
refvec = [ 1000 0 0];
[lat1,lon1,lat2,lon2]=deal(-0.027,0.05,-0.093,0.042);

[visgrid,visleg] = viewshed(Z,refvec,lat1,lon1,100);
[vis,visprofile,dist,zi,lattrk,lontrk] ...
    = los2(Z,refvec,lat1,lon1,lat2,lon2,100);

axesm('globe','geoid',almanac('earth','sphere','meters'))
meshm(visgrid,visleg,size(Z),Z); axis tight
camposm(-10,-10,1e6); camupm(0,0)
colormap(flipud(summer(2))); brighten(0.75);
shading interp; camlight
h = lcolorbar({'obscured','visible'});
set(h,'Position',[.875 .45 .02 .1])

plot3m(lattrk([1;end]),lontrk([1; end]), ...
    zi([1; end])+[100; 0],'r','linewidth',2)
plotm(lattrk(~visprofile),lontrk(~visprofile), ...
    zi(~visprofile),'r.','markersize',10)
plotm(lattrk(visprofile),lontrk(visprofile), ...
    zi(visprofile),'g.','markersize',10)
```



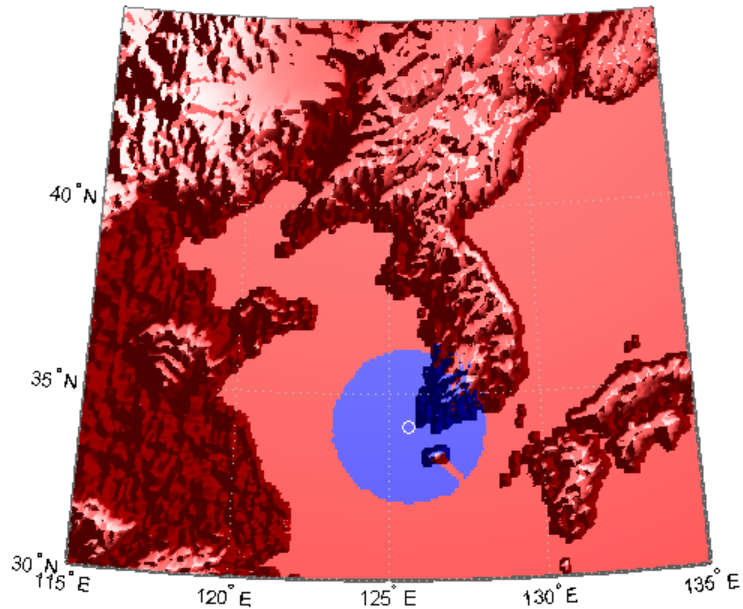
Compute the surface areas visible by radar from an aircraft 3000 meters above the Yellow Sea. Assume that radio wave propagation in the atmosphere can be modeled as straight lines on a  $4/3$  radius Earth. Display the visible areas as blue and the obscured areas as red. Drape the visibility colors on an elevation map, and use lighting to bring out the surface topography. The aircraft's radar can see out a certain radius on the surface of the ocean, but some ocean areas are shadowed by the island of Jeju-Do. Also some mountain valleys closer than the ocean horizon are obscured, while some mountain tops further away are visible.

```
load korea
map(map<0) = -1;
figure
worldmap(map,refvec)
da = daspect;
pba = pbaspect;
```

# viewshed

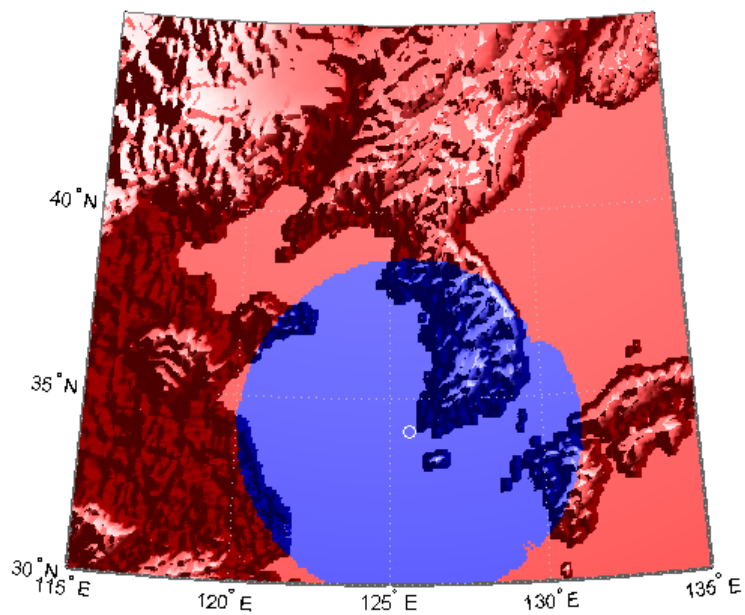
---

```
da(3) = 7.5*pba(3)/da(3);
daspect(da);
demcmap(map)
camlight(90,5);
camlight(0,5);
lighting phong
material([0.25 0.8 0])
lat = 34.0931; lon = 125.6578;
altobs = 3000; alttarg = 0;
plotm(lat,lon,'wo')
Re = almanac('earth','radius','m');
[vmap,vmapl] = viewshed( ...
    map,refvec,lat,lon,altobs,alttarg, ...
    'MSL','AGL',Re,4/3*Re);
meshm(vmap,vmapl,size(map),map)
caxis auto; colormap([1 0 0; 0 0 1])
lighting phong; material metal
axis off
```



Over what area can the radar plane flying at an altitude of 3000 meters have line-of-sight to other aircraft flying at 5000 meters? Now the area is much larger. Some edges of the area are reduced by shadowing from Jeju-Do and the mountains on the Korean peninsula.

```
[vmap,vmap1] = viewshed(map,refvec,lat,lon,3000,5000, ...
                        'MSL','MSL',Re,4/3*Re);
clmo surface
meshm(vmap,vmap1,size(map),map)
material metal
lighting phong
```



## See Also

1os2



**Purpose**

Azimuth on ellipsoid from direction angle in map plane

**Syntax**

```
az = vinvtran(x,y,th)
az = vinvtran(mstruct,x,y,th)
[az,len] = vinvtran(...)
```

**Description**

`az = vinvtran(x,y,th)` transforms an angle in the projection space at the point specified by `x` and `y` into an azimuth angle in geographic coordinates. The map projection currently displayed is used to define the projection space. The input angles must be in the same units as specified by the current map projection. The inputs can be scalars or matrices of equal size. The angle in the projection space `angle th` is defined as positive counterclockwise from the `x`-axis.

`az = vinvtran(mstruct,x,y,th)` uses the map projection defined by the input `struct` to compute the map projection.

`[az,len] = vinvtran(...)` also returns the vector length in the geographic coordinate system. A value of 1 indicates no scale distortion for that angle.

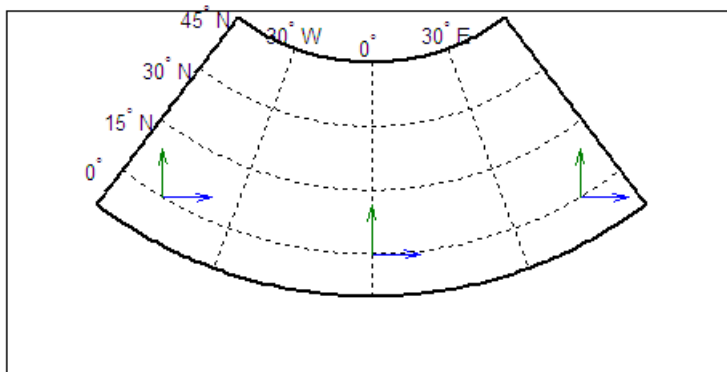
**Background**

While vectors along the `y`-axis always point to north in a cylindrical projection in the normal aspect, they can point east or west of north on conics, azimuthals, and other projections. This function computes the geographic azimuth for angles in the projected space.

**Examples**

Sample calculations:

```
axesm('eqdconic','maplatlim',[-10 45],'maplonlim',[-55 55])
gridm; framem; mlabel; plabel
[x,y] = mfwdtran([0 0 0],[-45 0 45]);
quiver(x,y,[.2 .2 .2],[0 0 0],0)
quiver(x,y,[0 0 0],[.2 .2 .2],0)
```



```
vinvtran(x,y,[ 0 0 0])
```

```
ans =  
    57.345    90.338    124.98
```

```
vinvtran(x,y,[ 90 90 90])
```

```
ans =  
    331.99         0    28.008
```

## Limitations

This transformation is limited to the region specified by the frame limits in the current map definition.

## Remarks

The geographic azimuth angle is measured clockwise from north. The projection space angle is measured counterclockwise from the  $x$ -axis.

This function uses a finite difference technique. The geographic coordinates are perturbed slightly in different directions and projected. A small amount of error is introduced by numerical computation of derivatives and the variation of map distortion parameters.

## See Also

`v fwdtran`, `m fwdtran`, `minvtran`, `defaultm`

**Purpose**

Read selected data from Vector Map Level 0

**Syntax**

```
struct = vmap0data(library,latlim,lonlim,theme,topolevel)
struct = vmap0data(devicename,library, ... )
[struct1, struct2, ...] = vmap0data(...,{topolevel1,
    topolevel2,...})
```

**Description**

`struct = vmap0data(library,latlim,lonlim,theme,topolevel)` reads the data for the specified theme and topology level directly from the VMAP0 CD-ROM. There are four CDs, one for each of the libraries: 'NOAMER' (North America), 'SASAUS' (Southern Asia and Australia), 'EURNASIA' (Europe and Northern Asia), and 'SOAMAFR' (South America and Africa). The desired *theme* is specified by a two-letter code string. A list of valid codes is displayed when an invalid code, such as '?', is entered. *topolevel* defines the type of data returned. It is a string containing 'patch', 'line', 'point', or 'text'. The region of interest can be given as a point latitude and longitude or as a region with two-element vectors of latitude and longitude limits. The units of latitude and longitude are degrees. The data covering the requested region is returned, but will include data extending to the edges of the tiles. The result is returned as a Mapping Toolbox Version 1 display structure.

`struct = vmap0data(devicename,library, ... )` specifies the logical device name of the CD-ROM for computers that do not automatically name the mounted disk.

`[struct1, struct2, ...] = vmap0data(...,{topolevel1,topolevel2,...})` reads several topology levels. The levels must be specified as a cell array with the entries 'patch', 'line', 'point', or 'text'. Entering {'all'} for the topology level argument is equivalent to {'patch', 'line', 'point', 'text'}. Upon output, the data structures are returned in the output arguments by topology level in the same order as they were requested.

**Background**

The Vector Map (VMAP) Level 0 database represents the third edition of the *Digital Chart of the World*. The second edition was a limited

release item published in 1995. The product is dual named to show its lineage to the original DCW, published in 1992, while positioning the revised product within a broader emerging family of VMAP products. VMAP Level 0 is a comprehensive 1:1,000,000 scale vector base map of the world. It consists of cartographic, attribute, and textual data stored on compact disc read-only memory (CD-ROM). The primary source for the database is the Operational Navigation Chart (ONC) series of the U. S. National Geospatial Intelligence Agency (NGA), formerly the National Imagery and Mapping Agency (NIMA), and before that, the Defense Mapping Agency (DMA). This is the largest scale unclassified map series in existence that provides consistent, continuous global coverage of essential base map features. The database contains more than 1,900 MB of vector data and is organized into 10 thematic layers. The data includes major road and rail networks, major hydrologic drainage systems, major utility networks (cross-country pipelines and communication lines), all major airports, elevation contours (1000 foot (ft), with 500 ft and 250 ft supplemental contours), coastlines, international boundaries, and populated places. The database can be accessed directly from the four optical CD-ROMs that store the database or can be transferred to magnetic media.

## Remarks

Data are returned as Mapping Toolbox display structures, which you can then update to geographic data structures. For information about display structure format, see “Version 1 Display Structures” on page 3-144 in the reference page for `displaym`. The `updategeostruct` function performs such conversions.

Latitudes and longitudes use WGS84 as a horizontal datum. Elevations and depths are in meters above mean sea level.

Some VMAP0 themes do not contain all topology levels. In those cases, empty matrices are returned.

Patches are broken at the tile boundaries. Setting the `EdgeColor` to 'none' and plotting the lines gives the map a normal appearance.

The major differences between VMAP0 and the DCW are the elimination of the gazette layer, addition of bathymetric data, and updated political boundaries.

Vector Map Level 0, created in the 1990s, is still probably the most detailed global database of vector map data available to the public. VMAP0 CD-ROMs are available from through the U.S. Geological Survey (USGS):

USGS Information Services (Map and Book Sales)  
Box 25286  
Denver Federal Center  
Denver, CO 80225  
Telephone: (303) 202-4700  
Fax: (303) 202-4693

---

**Note** For details on locating map data for download over the Internet, see the following documentation at the MathWorks Web site: <http://www.mathworks.com/support/tech-notes/2100/2101.html>.

---

## Examples

The *devicename* is platform dependent. On an MS-DOS based operating system it would be something like 'd:', depending on the logical device code assigned to the CD-ROM drive. On a UNIX operating system, the CD-ROM might be mounted as '\cdrom', '\CDROM', '\cdrom1', or something similar. Check your computer's documentation for the right *devicename*.

```
s = vmap0data(devicename, 'NOAMER', 41, -69, '?', 'patch');
```

```
??? Error using ==> vmap0data  
Theme not present in library NOAMER
```

Valid theme identifiers are:

```
libref : Library Reference  
tileref: Tile Reference  
bnd    : Boundaries  
dq     : Data Quality  
elev   : Elevation  
hydro  : Hydrography
```

# vmap0data

---

```
ind      : Industry
phys     : Physiography
pop      : Population
trans    : Transportation
util     : Utilities
veg      : Vegetation
```

```
BNDpatch = vmap0data(devicename, 'NOAMER', ...
                  [41 44], [-72 -69], 'bnd', 'patch')
```

```
BNDpatch =
1x169 struct array with fields:
  type
  otherproperty
  altitude
  lat
  long
  tag
```

Here are other examples:

```
[TRtext, TRline] = vmap0data(devicename, 'SASAUS', ...
                             [-48 -34], [164 180], 'trans', {'text', 'line'});
```

```
[BNDpatch, BNDline, BNDpoint, BNDtext] = vmap0data(devicename, ...
                                                    'EURNASIA', -48 ,164, 'bnd', {'all'});
```

## See Also

vmap0read, vmap0rhead, geoshow, extractm, mlayers, updategeostruct

**Purpose**

Read Vector Map Level 0 file

**Syntax**

```
vmap0read
vmap0read(filepath,filename)
vmap0read(filepath,filename,recordIDs)
vmap0read(filepath,filename,recordIDs,field,varlen)
struc = vmap0read(...)
[struc,field] = vmap0read(...)
[struc,field,varlen] = vmap0read(...)
[struc,field,varlen,description] = vmap0read(...)
[struc,field,varlen,description,
  narrativefield] = vmap0read(...)
```

**Description**

vmap0read reads a VMAP0 file. The user selects the file interactively.

vmap0read(*filepath*,*filename*) reads the specified file. The combination [*filepath filename*] must form a valid complete filename.

vmap0read(*filepath*,*filename*,recordIDs) reads selected records or fields from the file. If recordIDs is a scalar or a vector of integers, the function returns the selected records. If recordIDs is a cell array of integers, all records of the associated fields are returned. vmap0read(*filepath*,*filename*,recordIDs,*field*,*varlen*)

uses previously read field and variable-length record information to skip parsing the file header (see below).

struc = vmap0read(...) returns the file contents in a structure.

[*struc*,*field*] = vmap0read(...) returns the file contents and a structure describing the format of the file.

[*struc*,*field*,*varlen*] = vmap0read(...) also returns a vector describing which fields have variable-length records.

[*struc*,*field*,*varlen*,*description*] = vmap0read(...) also returns a string describing the contents of the file.

[*struc*,*field*,*varlen*,*description*,*narrativefield*] = vmap0read(...) also returns the name of the narrative file for the current file.

## Background

The Vector Map Level 0 (VMAPO) uses binary files in a variety of formats. This function determines the format of the file and returns the contents in a structure. The field names of this structure are the same as the field names in the VMAPO file.

## Remarks

This function reads all VMAPO files except index files (files with names ending in 'X'), thematic index files (files with names ending in 'TI'), and spatial index files (files with names ending in 'SI').

File separators are platform dependent. The *filepath* input must use appropriate file separators, which you can determine using the MATLAB `filesep` function.

## Examples

The following examples use the UNIX directory system and file separators for the pathname:

```
s = vmap0read('VMAP/VMAPLVO/NOAMER/', 'GRT')

s =
    id: 1
    data_type: 'GEO'
    units: 'M'
    ellipsoid_name: 'WGS 84'
    ellipsoid_detail: 'A=6378137 B=6356752 Meters'
    vert_datum_name: 'MEAN SEA LEVEL'
    vert_datum_code: '015'
    sound_datum_name: 'N/A'
    sound_datum_code: 'N/A'
    geo_datum_name: 'WGS 84'
    geo_datum_code: 'WGE'
    projection_name: 'Dec. Deg. (unproj.)'

s = vmap0read('VMAP/VMAPLVO/NOAMER/TRANS/', 'INT.VDT')

s =
34x1 struct array with fields:
    id
```



```
table
attribute
value
description

s(1)

ans =
    id: 1
    table: 'aerofacp.pft'
    attribute: 'use'
    value: 8
    description: 'Military'
s = vmap0read('VMAP/VMAPLV0/NOAMER/TRANS/', 'AEROFACP.PFT', 1)

s =
    id: 1
    f_code: 'GB005'
    iko: 'BGTL'
    nam: 'THULE AIR BASE'
    na3: 'GL52085'
    use: 8
    zv3: 77
    tile_id: 10
    end_id: 1

s = vmap0read('VMAP/VMAPLV0/NOAMER/TRANS/', 'AEROFACP.PFT', {1,2})

s =
1x4424 struct array with fields:
    id
    f_code
```

**See Also**

vmap0data, vmap0rhead

# vmap0rhead

---

**Purpose** Read Vector Map Level 0 file headers

**Syntax**

```
vmap0rhead  
vmap0rhead(filepath,filename)  
vmap0rhead(filepath,filename,fid)  
vmap0rhead(...),  
str = vmap0rhead(...)
```

**Description** vmap0rhead allows the user to select the header file interactively. vmap0rhead(*filepath*,*filename*) reads from the specified file. The combination [*filepath filename*] must form a valid complete *filename*. vmap0rhead(*filepath*,*filename*,*fid*) reads from the already open file associated with *fid*. vmap0rhead(...), with no output arguments, displays the formatted header information on the screen. str = vmap0rhead(...) returns a string containing the VMAP0 header.

**Background** The Vector Map Level 0 (VMAP0) uses header strings in most files to document the contents and format of that file. This function reads the header string and displays a formatted version in the Command Window, or returns it as a string.

**Remarks** This function reads all VMAP0 files except index files (files with names ending in 'X'), thematic index files (files with names ending in 'TI') and spatial index files (files with names ending in 'SI'). File separators are platform dependent. The *filepath* input must use appropriate file separators, which you can determine using the MATLAB filesep function.

**Examples** The following example uses UNIX file separators and pathname:

```
s = vmap0rhead('VMAP/VMAPLV0/NOAMER/', 'GRT')
```

```

S =
L;Geographic Reference Table;-;id=I,1,P,Row
Identifier,-,-,-:data_type=T,3,N,Data
Type,-,-,-:units=T,3,N,Units of Measure Code for
Library,-,-,-:ellipsoid_name=T,15,N,Ellipsoid,-,-,-:ellipsoid
_detail=T,50,N,Ellipsoid
Details,-,-,-:vert_datum_name=T,15,N,Datum Vertical
Reference,-,-,-:vert_datum_code=T,3,N,Vertical Datum
Code,-,-,-:sound_datum_name=T,15,N,Sounding
Datum,-,-,-:sound_datum_code=T,3,N,Sounding Datum
Code,-,-,-:geo_datum_name=T,15,N,Datum Geodetic
Name,-,-,-:geo_datum_code=T,3,N,Datum Geodetic
Code,-,-,-:projection_name=T,20,N,Projection Name,-,-,-,;;

vmap0rhead('VMAP/VMAPLVO/NOAMER/TRANS/' , 'AEROFACP.PFT')
L
Airport Point Feature Table
aerofacp.doc
id=I,1,P,Row Identifier,-,-,-,
f_code=T,5,N,FACC Feature Code,char.vdt,-,-,
iko=T,4,N,ICAO Designator,char.vdt,-,-,
nam=T,*N,Name,char.vdt,-,-,
na3=T,*N,Name,char.vdt,-,-,
use=S,1,N,Usage,int.vdt,-,-,
zv3=S,1,N,Airfield/Aerodrome Elevation (meters),int.vdt,-,-,
tile_id=S,1,N,Tile Reference ID,-,tile1_id.pti,-,
end_id=I,1,N,Entity Node Primitive ID,-,end1_id.pti,-,

```

## See Also

vmap0data, vmap0read

# WebMapServer class

---

**Purpose** Web map server object

**Description** A `WebMapServer` handle object represents a Web Map Service (WMS) and acts as a proxy to a WMS server. The `WebMapServer` handle object resides physically on the client side. The object can access the capabilities document on the WMS server and perform requests to obtain maps. It supports multiple WMS versions and negotiates with the server automatically to use the highest known version that the server can support.

**Construction** `server = WebMapServer(serverURL)` constructs a `WebMapServer` object from the `serverURL` string parameter. The `serverURL` string parameter must include the protocol `'http://'` or `'https://'`. `WebMapServer` automatically communicates to the server defined by the `serverURL` using the highest known version that the server can support. `serverURL` can contain additional WMS keywords.

**Properties** `Timeout`  
Indicates the number of milliseconds before a server times out.

**Data Type:** double

**Default:** 0 (Indicates that the `WebMapServer` handle object ignores the time-out mechanism.)

`EnableCache`  
Indicates if the `WebMapServer` handle object allows caching. If `true`, the `WebMapServer` handle object caches the `WMSCapabilities` object, which is returned when you use the `getCapabilities` method. The cache expires if the `AccessDate` property of the cached `WMSCapabilities` object is not the current day.

**Data Type:** logical

**Default:** true

## ServerURL

Indicates the URL of the server.

**Data Type:** string

## RequestURL

Indicates the URL of the last request to the server. RequestURL specifies a request for either the XML capabilities document or a map. You can insert the RequestURL into a browser.

**Data Type:** string

## Methods

getCapabilities	Get capabilities document from server
getMap	Get raster map from server
updateLayers	Update layer properties

## Example

Construct a WebMapServer object that communicates with the Jet Propulsion Laboratory (JPL) WMS server and obtains its capabilities document:

```
jpl = wmsfind('jpl', 'SearchField', 'serverurl');
serverURL = jpl(1).ServerURL;
server = WebMapServer(serverURL);
capabilities = server.getCapabilities();
```

## See Also

WMSCapabilities | wmsfind | wmsinfo | WMSMapRequest | wmsread | wmsupdate

# WebMapServer.getCapabilities

---

<b>Purpose</b>	Get capabilities document from server
<b>Syntax</b>	<code>capabilities = server.getCapabilities()</code>
<b>Description</b>	<code>capabilities = server.getCapabilities()</code> retrieves the capabilities document from the server as a <code>WMSCapabilities</code> object and updates the <code>RequestURL</code> property.
<b>Tips</b>	The <code>getCapabilities</code> method accesses the Internet to retrieve the document. Periodically, the WMS server is unavailable. Retrieving the document can take several minutes.
<b>Examples</b>	Retrieve the capabilities document from the Jet Propulsion Laboratory (JPL) server: <pre>layers = wmsfind('jpl', 'SearchField', 'serverurl'); server = WebMapServer(layers(1).ServerURL); capabilities = server.getCapabilities();</pre>

<b>Purpose</b>	Get raster map from server
<b>Syntax</b>	<code>A = server.getMap(mapRequestURL)</code>
<b>Description</b>	<code>A = server.getMap(mapRequestURL)</code> dynamically renders and retrieves a color or grayscale, geographically referenced, raster map from the server and stores it in <code>A</code> . Parameters in the URL, <code>mapRequestURL</code> , define the map. The <code>getMap</code> method also updates the <code>WMSMapRequest.RequestURL</code> property <code>mapRequestURL</code> .
<b>Tips</b>	<code>getMap</code> accesses the Internet to retrieve the map. Periodically, the WMS server is unavailable. Retrieving the map can take several minutes.
<b>Examples</b>	Retrieve a map of the <code>global_mosaic</code> layer: <pre>layers = wmsfind('global_mosaic', ...   'SearchField', 'layername', 'MatchType', 'exact'); layer = layers(1); server = WebMapServer(layer.ServerURL); mapRequest = WMSMapRequest(layer, server); globalMosaic = server.getMap(mapRequest.RequestURL);</pre>

# WebMapServer.updateLayers

---

**Purpose** Update layer properties

**Syntax** [updatedLayer, index] = server.updateLayers(layer)

**Description** [updatedLayer, index] = server.updateLayers(layer) returns a WMSLayer array with properties updated with values from the server. The WMSLayer array Layer must contain only one unique ServerURL. The updateLayers method removes layers no longer available on the server. The logical array index contains true for each available layer, such that updatedLayers has the same size as layer (index).

The updateLayers method accesses the Internet to update the properties. Occasionally, a WMS server is unavailable, or several minutes elapse before the properties are updated.

**Examples** Update the properties of the global\_mosaic layer:

```
layers = wmsfind('global_mosaic', ...
    'SearchField', 'layername', 'MatchType', 'exact');
layer = layers(1);
server = WebMapServer(layer.ServerURL);
updatedLayer = server.updateLayers(layer);
```

---

Update the properties of layers from multiple servers:

```
% Find layers with the name 'terra' in
% the server URL.
terra = wmsfind('terra', 'SearchField', 'serverurl');

% Find the layers for an individual server in the
% terra layer, update their properties, and append
% them to the updatedTerraLayers array.
servers = terra.servers();
updatedTerraLayers = [];
fprintf('Updating layer properties from %d servers.\n', ...
    numel(servers));
```



```
for k=1:numel(servers)
    serverLayers = ...
        terra.refine(servers{k}, 'SearchField', 'serverurl');
    fprintf('Updating properties from server %d:\n%s\n', ...
        k, serverLayers(1).ServerURL);
    server = WebMapServer(serverLayers(1).ServerURL);
    layers = server.updateLayers(serverLayers);

% Grow using concatenation; layers can have any length
% ranging from 0 to numel(serverLayers).
    updatedTerraLayers = [updatedTerraLayers; layers];
end
```

# westof

---

## Purpose

Wrap longitudes to values west of specified meridian

---

**Note** The `westof` function is obsolete and will be removed in a future release of the toolbox. Replace it with the following calls, which are also more efficient:

```
westof(lon,meridian,'degrees') ==> meridian-mod(meridian-lon,360)
```

```
westof(lon,meridian,'radians') ==> meridian-mod(meridian-lon,2*pi)
```

---

## Syntax

```
lonWrapped = westof(lon,meridian)
```

```
lonWrapped = westof(lon,meridian,angleunits)
```

## Description

`lonWrapped = westof(lon,meridian)` wraps angles in `lon` to values in the interval `(meridian-360 meridian]`. `lon` is a scalar longitude or vector of longitude values. All inputs and outputs are in degrees.

`lonWrapped = westof(lon,meridian,angleunits)` specifies the input and output units with the string *angleunits*. *angleunits* can be either 'degrees' or 'radians'. It may be abbreviated and is case-insensitive. If *angleunits* is 'radians', the input is wrapped to the interval `(meridian-2*pi meridian]`.

<b>Purpose</b>	Web Map Service capabilities object												
<b>Description</b>	A WMSCapabilities object represents a Web Map Service (WMS) capabilities document obtained from a WMS server.												
<b>Construction</b>	<code>capabilities = WMSCapabilites(ServerURL, capabilitiesResponse)</code> constructs a WMSCapabilities object from the input string parameters. The <code>ServerURL</code> string, a WMS server URL, includes the protocol <code>'http://'</code> or <code>'https://'</code> . The <code>capabilitiesResponse</code> string contains XML elements that describe the capabilities of the <code>ServerURL</code> WMS server.												
<b>Properties</b>	<table><tr><td><code>ServerTitle</code></td><td>Title of server <b>Data Type:</b> string</td></tr><tr><td><code>ServerURL</code></td><td>URL of server <b>Data Type:</b> string</td></tr><tr><td><code>ServiceName</code></td><td>Name of Web map service <b>Data Type:</b> string</td></tr><tr><td><code>Version</code></td><td>WMS version specification <b>Data Type:</b> string</td></tr><tr><td><code>Abstract</code></td><td>Information about server <b>Data Type:</b> string</td></tr><tr><td><code>OnlineResource</code></td><td></td></tr></table>	<code>ServerTitle</code>	Title of server <b>Data Type:</b> string	<code>ServerURL</code>	URL of server <b>Data Type:</b> string	<code>ServiceName</code>	Name of Web map service <b>Data Type:</b> string	<code>Version</code>	WMS version specification <b>Data Type:</b> string	<code>Abstract</code>	Information about server <b>Data Type:</b> string	<code>OnlineResource</code>	
<code>ServerTitle</code>	Title of server <b>Data Type:</b> string												
<code>ServerURL</code>	URL of server <b>Data Type:</b> string												
<code>ServiceName</code>	Name of Web map service <b>Data Type:</b> string												
<code>Version</code>	WMS version specification <b>Data Type:</b> string												
<code>Abstract</code>	Information about server <b>Data Type:</b> string												
<code>OnlineResource</code>													

# WMSCapabilities class

---

Online information about server

**Data Type:** string (URL)

## ContactInformation

Contact information for an individual or an organization, including an e-mail address, if provided

**Data Type:** structure

### ContactInformation Structure Array

Field Name	Data Type	Field Content
Person	String	Name of individual
Organization	String	Name of organization
E-mail	String	E-mail address

## AccessConstraints

Constraints inherent in accessing the server, such as server load limits

**Data Type:** string

## Fees

Types of fees associated with accessing server

**Data Type:** string

## KeywordList

Descriptive keywords of the server

**Data Type:** cell array of strings

## ImageFormats

Image formats supported by server

**Data Type:** cell array of strings

## LayerNames

Layer names provided by server

**Data Type:** cell array of strings

## Layer

Information about layers on WMS server. See the `WMSCapabilities.Layer` reference page for more information.

**Data Type:** WMSLayer array

## AccessDate

Date of request to server

**Data Type:** string

## Methods

`disp` Display properties

## Example

Construct a `WMSCapabilities` object from the contents of a downloaded capabilities file from the NASA SVS Image Server:

```
nasa = wmsfind('NASA SVS Image', 'SearchField', 'servertitle');
serverURL = nasa(1).ServerURL;
server = WebMapServer(serverURL);
capabilities = server.getCapabilities;
filename = 'capabilities.xml';
urlwrite(server.RequestURL, filename);

fid = fopen(filename, 'r');
capabilitiesResponse = fread(fid, 'uint8=>char');
fclose(fid);
capabilities = WMSCapabilities(serverURL, capabilitiesResponse);
```

## See Also

`WebMapServer` | `wmsinfo` | `WMSLayer`

# WMSCapabilities.disp

---

**Purpose**            Display properties

**Syntax**            `capabilities.disp()`

**Description**        `capabilities.disp()` displays the class properties. The method removes hyperlinks and expands string and cell array properties.

# WMSCapabilities.Layer property

**Purpose** Layer information

**Description** A WMSLayer array containing information about the layers available on a WMS server.

Property Name	Data Type	Property Content
ServerTitle	String	Descriptive title of server
ServerURL	String	URL of server
LayerTitle	String	Descriptive title of layer
LayerName	String	Name of layer
Latlim	Double array	Southern and northern latitude limits of layer
Lonlim	Double array	Western and eastern longitude limits of layer
Abstract	String	Information about layer
CoordRefSysCodes	Cell array	Codes of available coordinate reference systems
Details	Structure	Detailed information about layer

# wmsfind

---

**Purpose** Search local database for Web map servers and layers

**Syntax**  
`layers = wmsfind(querystr)`  
`layers = wmsfind(querystr, parameter, value, ...)`

**Description** `layers = wmsfind(querystr)` searches the `LayerTitle` and `LayerName` fields of the installed Web Map Service (WMS) Database for partial matches with the string *querystr*. WMS servers, by definition, produce maps of spatially referenced raster data. You can search for specific types of data, known as layers, such as temperature or elevation. The string *querystr* can contain the wildcard character `'*'`. The array returned by `wmsfind`, `layers`, contains one element for each layer whose name or title partially matches *querystr*. Each element is a `WMSLayer` object.

The installed WMS Database contains a subset of the `WMSLayer` properties (`ServerTitle`, `ServerURL`, `LayerTitle`, `LayerName`, `Latlim`, and `Lonlim`). The information found in the database is static and is not automatically updated; it was validated at the time of the software release.

`layers = wmsfind(querystr, parameter, value, ...)` modifies the search of the WMS database based on the values of the parameters. You can abbreviate parameter names, and case does not matter. To modify the search, specify any of the parameters listed in “Input Arguments” on page 3-731.

## Tips

- The WMS Database does not store content for the properties `'Abstract'`, `'CoordRefSysCodes'`, and `'Details'`. Therefore, you cannot use `wmsfind` to search these properties. Populate these fields by using the `wmsupdate` function. This function updates these properties by downloading information from the server. The `WMSLayer.disp` method does not automatically display these unpopulated properties. Set the `WMSLayer.disp` `'Properties'` parameter to `'all'` to view. After you have viewed the information available from `wmsupdate`, if you still want to know more about the WMS server, use the function `wmsinfo` with the specific server URL.



## Input Arguments

*querystr*

Specifies the search string, such as 'temperature'

**Data Type:** string

*parameter, value*

Modifies the search. Parameter names and values are shown below.

Parameter	Data Type	Value
'IgnoreCase'	Logical	Specifies whether to ignore case when performing string comparisons. Possible values are true or false; the default value is true.
'Latlim'	Two-element vector or scalar	<p>A two-element vector of latitude specifying the latitudinal limits of the search in the form [southern_limit northern_limit] or a scalar value representing the latitude of a single point. All angles are in units of degrees.</p> <p>If provided and not empty, a given layer appears in the results only if its limits fully contain the specified 'Latlim' limits. Partial overlap does not result in a match.</p>

(Continued)

Parameter	Data Type	Value
'Lonlim'	Two-element vector or scalar	<p>A two-element vector of longitude specifying the longitudinal limits of the search in the form [western_limit eastern_limit] or a scalar value representing the longitude of a single point. All angles are in units of degrees.</p> <p>If provided and not empty, a given layer appears in the results only if its limits contain the specified 'Lonlim' limits. Partial overlap does not result in a match.</p>
'MatchType'	String	<p>Has value 'partial' or 'exact'. For a partial string match, specify 'partial' for the 'MatchType'. For an exact match, specify 'exact'. If 'MatchType' is 'exact' and querystr is '*', a match occurs when the search field matches the character '*'. The default value is 'partial'.</p>
'SearchFields'	String or cell array of strings	<p>Valid strings are 'layer', 'layertitle', 'layername', 'server', 'serverurl', 'servertitle', or 'any'.</p> <p>The function searches the entries in the 'SearchFields' of the WMS database for a partial</p>

(Continued)

Parameter	Data Type	Value
		match with <code>querystr</code> . If you specify <code>'layer'</code> , then <code>wmsfind</code> searches both the <code>'layertitle'</code> and <code>'layername'</code> fields. If you specify <code>'server'</code> , then <code>wmsfind</code> searches both the <code>'serverurl'</code> and <code>'servertitle'</code> fields. The function returns layer information if any supplied <code>'SearchFields'</code> match. The default value is <code>{'layer'}</code> .

## Examples

Find all layers that contain temperature data and return a `WMSLayer` array:

```
layers = wmsfind('temperature');
```

---

Find all layers that contain global temperature data and return a `WMSLayer` array:

```
layers = wmsfind('global*temperature');
```

---

Find all layers that contain an exact match for `'Major Rivers'` in the `LayerTitle` field and return a `WMSLayer` array:

```
layers = wmsfind('Major Rivers', 'MatchType', 'exact', ...
  'IgnoreCase', false, 'SearchFields', 'layertitle');
```

---

Find all layers that contain a partial match for `'elevation'` in the `LayerName` field and return a `WMSLayer` array:

```
layers = wmsfind('elevation', 'SearchField', 'layername');
```

---

Find all unique servers that contain 'global\_mosaic' as a layer name:

```
layers = wmsfind('global_mosaic', ...  
    'SearchField', 'layername', 'MatchType', 'exact');  
servers = layers.servers;
```

---

Find layers that contain elevation data for Colorado and return a WMSLayer array:

```
latlim = [35,43];  
lonlim = [-111,-101];  
layers = wmsfind('elevation', ...  
    'Latlim', latlim, 'Lonlim', lonlim);
```

---

Find all layers that contain temperature data for a point in Perth, Australia, and return a WMSLayer array:

```
lat = -31.9452;  
lon = 115.8323;  
layers = wmsfind('temperature', 'Latlim', lat, 'Lonlim', lon);
```

---

Find all layers provided by the Jet Propulsion Laboratory (JPL) server and display to the command window each layer title and layer name:

```
layers = wmsfind('jpl.nasa.gov', 'SearchField', 'serverurl');  
layers disp('Properties', {'layerTitle', 'layerName'});
```

---

Find all unique URLs of government servers:

```
layers = wmsfind('*.gov*', 'SearchField', 'serverurl');  
servers = layers.servers;
```

---

Perform multiple searches. Find all layers that contain temperature in the layer name or title fields:

```
temperature = wmsfind('temperature', ...  
    'SearchField',{ 'layertitle', 'layername' });
```

Find sea surface temperature layers:

```
sst = temperature.refine('sea surface');
```

Find and display to the command window a list of global sea surface temperature layers:

```
global_sst = sst.refine('global')
```

---

Perform multiple searches and listings of the entire WMS Database. Please note that finding all layers from the WMS Database takes several minutes to execute. There are over 300,000 layers in the WMS Database.

```
layers = wmsfind('*');
```

Sort and display to the command window the unique layer titles in the WMS database:

```
layerTitles = sort(unique({layers.LayerTitle}))'
```

Refine layers to include only layers with global coverage:

```
global_layers = layers.refineLimits('Latlim', [-90 90], ...  
    'Lonlim', [-180 180]);
```

Refine `global_layers` to contain only topography layers that have global extent:

```
topography = global_layers.refine('topography');
```

Refine layers to contain only layers that have the terms “oil” and “gas” in the LayerTitle:

```
oil_gas = layers.refine('oil*gas', 'SearchField', 'layertitle');
```

## See Also

wmsinfo | WMSLayer on page 2-2 | wmsread | wmsupdate

---

<b>Purpose</b>	Information about WMS server from capabilities document
<b>Syntax</b>	<pre>[capabilities, infoRequestURL] = wmsinfo(serverURL) [capabilities, infoRequestURL] = wmsinfo(infoRequestURL) [capabilities, infoRequestURL] = wmsinfo(..., <i>parameter</i>, <i>value</i>)</pre>
<b>Description</b>	<p>[capabilities, infoRequestURL] = wmsinfo(serverURL) accesses the Internet to read a capabilities document from a Web Map Service (WMS) server. A capabilities document is an XML document that contains metadata describing the geographic content offered by the server. The wmsinfo function returns the contents of the capabilities document into capabilities, a WMSCapabilities object. The WMS server URL serverURL contains the protocol 'http://' or 'https://' and additional WMS or access keywords. You can insert the URL string infoRequestURL, composed of the ServerURL with additional WMS parameters, into a browser or urlread to return the XML capabilities document. The wmsinfo function requires an Internet connection. Periodically, the WMS server is unavailable. Retrieving the map can take several minutes.</p> <p>[capabilities, infoRequestURL] = wmsinfo(infoRequestURL) reads the capabilities document from a WMS infoRequestURL and returns the contents into capabilities.</p> <p>[capabilities, infoRequestURL] = wmsinfo(..., <i>parameter</i>, <i>value</i>) specifies a parameter-value pair that modifies the request to the server. You can abbreviate the parameter name, which is case-insensitive. The 'TimeoutInSeconds' parameter, an integer-valued, scalar double, indicates the number of seconds to elapse before a server times out. The default value for this parameter is 60 seconds, and a value of 0 causes the time-out mechanism to be ignored.</p>
<b>Tips</b>	<ul style="list-style-type: none"><li>• To specify a proxy server to connect to the Internet, select <b>File&gt;Preferences&gt;Web</b> and enter your proxy information. Use this feature if you have a firewall.</li></ul>

- `wmsinfo` communicates with the server using a `WebMapServer` handle object representing an implementation of a WMS specification. The handle object acts as a proxy to a WMS server and resides physically on the client side. The handle object accesses the server's capabilities document. The handle object supports multiple WMS versions and negotiates with the server to use the highest known version that the server can support. The handle object automatically times-out after 60 seconds if a connection is not made to the server.

## Examples

Use `wmsinfo` to read a capabilities document and display the abstract of the first layer.

```
% Read the capabilities document from the NASA Goddard
% Space Flight Center WMS server.
gsfcLayers = wmsfind('gsfc.nasa.gov', 'SearchField', 'serverurl');
capabilities = wmsinfo(gsfcLayers(1).ServerURL);

% Display the layer information in the command window.
capabilities.Layer
```

Sample output follows:

```
Index: 304
ServerTitle: 'NASA SVS Image Server'
ServerURL: 'http://aes.gsfc.nasa.gov/cgi-bin/wms?'
LayerTitle: '(2048x2048 Animation)'
LayerName: '3352_24736'
Latlim: [38.3727 39.3133]
Lonlim: [-91.1052 -89.9017]
Abstract: 'During the first half of 1993, ....'
CoordRefSysCodes: {'EPSG:4326'}
Details: [1x1 struct]

% Refine the list to include only layers with the term
% "glacier retreat" in the LayerTitle.
glaciers = capabilities.Layer.refine('glacier retreat', ...
    'SearchFields', 'LayerTitle');
```



```
% Display the abstract of the first layer.  
glaciers(1).Abstract
```

Sample output follows:

```
Since measurements of Jakobshavn Isbrae were  
first taken....
```

**See Also**

[WebMapServer](#) | [WMSCapabilities](#) | [wmsfind](#) | [WMSLayer](#) | [wmsread](#)

# WMSLayer class

---

<b>Purpose</b>	Web Map Service layer object
<b>Description</b>	A WMSLayer object describes a Web Map Service (WMS) layer or layers. Obtain a WMSLayer object by using <code>wmsfind</code> or <code>wmsinfo</code> . The function <code>wmsfind</code> returns a WMSLayer array. The function <code>wmsinfo</code> returns a WMSCapabilities object, which contains a WMSLayer array in its <code>Layer</code> property.
<b>Construction</b>	<code>layers = WMSLayer(param, val, ...)</code> constructs a WMSLayer object from the input parameter names and values. If a parameter name matches a property name of the WMSLayer class ( <code>ServerTitle</code> , <code>ServerURL</code> , <code>LayerTitle</code> , <code>LayerName</code> , <code>Latlim</code> , <code>Lonlim</code> , <code>Abstract</code> , <code>CoordRefSysCodes</code> , or <code>Details</code> ) then the values of the parameter are copied to the property. The size of the output <code>layers</code> is scalar unless all inputs are cell arrays, in which case, the size of <code>layers</code> matches the size of the cell arrays.
<b>Properties</b>	You can only set the 'Latlim' and 'Lonlim' properties, which have public set access.  <code>ServerTitle</code> Descriptive information about the server <b>Data Type:</b> string <b>Default:</b> ''  <code>ServerURL</code> The URL of the server <b>Data Type:</b> string <b>Default:</b> ''  <code>LayerTitle</code>

Descriptive information about the layer; clarifies the meaning of the raster values of the layer

**Data Type:** string

**Default:** ''

LayerName

The keyword the server uses to retrieve the layer

**Data Type:** string

**Default:** ''

Latlim

The southern and northern latitude limits of the layer in units of degrees

**Data Type:** two-element vector

**Default:** []

Lonlim

The western and eastern longitude limits of the layer in units of degrees

**Data Type:** two-element vector

**Default:** []

Abstract

Information about the layer

**Data Type:** string

**Default:** ''

# WMSLayer class

---

## CoordRefSysCodes

String codes of available coordinate reference systems

**Data Type:** cell array

**Default:** {}

## Details

Detailed information about the layer: MetadataURL, Attributes, Scale, Dimension, Style. See the `WMSLayer.Details` reference page for more information.

**Data Type:** structure

## Methods

<code>disp</code>	Display properties
<code>refine</code>	Refine search
<code>refineLimits</code>	Refine search based on geographic limits
<code>servers</code>	Return URLs of unique servers
<code>serverTitles</code>	Return titles of unique servers

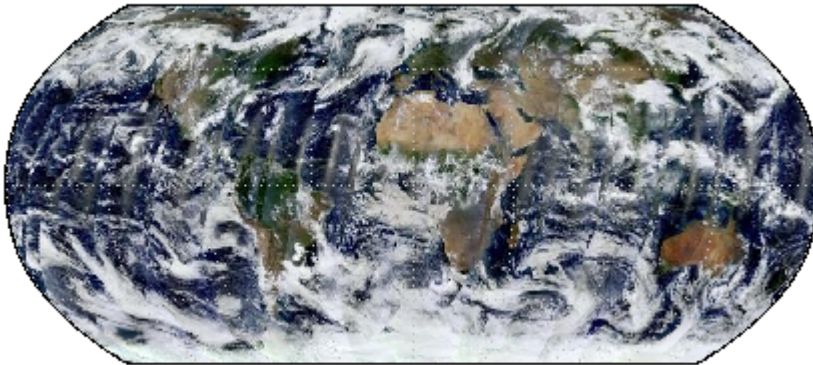
## Example

Construct a `WMSLayer` object from a WMS GetMap request URL:

```
serverURL = 'http://onearth.jpl.nasa.gov/wms.cgi?';
url = [serverURL 'SERVICE=WMS' ...
      '&LAYERS=daily_planet', ...
      '&EXCEPTIONS=application/vnd.ogc.se_xml', ...
      '&FORMAT=image/jpeg&TRANSPARENT=FALSE&HEIGHT=288', ...
      '&BGCOLOR=0xFFFFFFFF&REQUEST=GetMap&WIDTH=720&STYLES=' ...
      '&BBOX=-180.0,-72.0,180.0,72.0&SRS=EPSG:4326&VERSION=1.1.1'];

layer = WMSLayer('ServerURL', serverURL, ...
                'LayerName', 'daily_planet', ...
                'Latlim', [-72, 72], 'Lonlim', [-180,180]);
```

```
layer = wmsupdate(layer);  
[A, R] = wmsread(layer, 'ImageHeight', 288, 'ImageWidth', 720);  
figure  
worldmap world  
setm(gca,'maplatlimit',layer.Latlim, 'maplonlimit',layer.Lonlim)  
mlabel off; plabel off  
geoshow(A,R)
```



Courtesy NASA/JPL-Caltech

## See Also

[WebMapServer](#) | [WMSCapabilities](#) | [wmsfind](#) | [wmsinfo](#) | [WMSMapRequest](#) | [wmsread](#) | [wmsupdate](#)

# WMSLayer.disp

---

**Purpose** Display properties

**Syntax** `layers.disp(..., parameter, value, ...)`

**Description** `layers.disp(..., parameter, value, ...)` displays the index number followed by the property names and property values of the layer. Use optional parameters for `disp` to modify the output display.

**Input Arguments** `parameter, value`

Modify output display. Parameter names and their permissible values appear in the table below. You can abbreviate parameter names, and case does not matter.

Parameter	Data Type	Value	Default
'Properties'	String or cell array of strings	Determines which properties appear as output and the order in which they appear. Permissible values are: 'servertitle', 'servername', 'layertitle', 'layername', 'latlim', 'lonlim', 'abstract', 'coordrefsyscodes', 'details', or 'all'. You can abbreviate values, and case is insensitive. To list all the properties, set 'Properties' to 'all'.	'all'
'Label'	String	A case-insensitive string with permissible values of 'on' or 'off'. If you set 'Label' to 'on', then the property name appears followed by its value. If you set 'Label' to 'off', then only the property value appears in the output.	'on'
'Index'	String	A case-insensitive string with permissible values of 'on' or 'off'. If you set 'Index' to 'on', then <code>WMSLayer.disp</code> lists the element's index in the output. If you set 'Index' to	'on'

Parameter	Data Type	Value	Default
		'off', then WMSLayer.disp does not list the index value in the output.	

## Examples

Display LayerTitle and LayerName properties to the command window:

```
layers = wmsfind('srtm30plus');  
layers(1:5).disp( 'Index', 'off', ...  
    'Properties',{ 'layertitle', 'layername' });
```

Sample output follows:

```
LayerTitle: 'SRTM30Plus World with Backdrop'  
LayerName: '10:4'
```

---

Sort and display the LayerName property and index:

```
layers = wmsfind('elevation');  
[layerNames, index] = sort({layers.LayerName});  
layers = layers(index);  
layers.disp('Label','off', 'Properties', 'layername');
```

Sample output follows:

```
Index: 1418  
'topp:elevation_earth_300sec'  
  
Index: 1419  
'topp:elevation_europe_150sec'  
  
Index: 1420  
'topp:elevation_europe_150sec'
```

## See Also

wmsfind

# WMSLayer.refine

---

**Purpose** Refine search

**Syntax** `layers.refine(querystr, parameter, value, ...)`

**Description** `layers.refine(querystr, parameter, value, ...)` searches for elements of `layers` in which values of the `Layer` or `LayerName` properties match the string `querystr`. Use the `'MatchType'` property to control whether the method uses partial or exact matching. The default is partial matching.

**Input Arguments** `querystr`  
Specifies the search string.

**Data Type:** string

`parameter, value`

Modifies the search by specifying any of the following optional parameters. You can abbreviate parameter names and case does not matter.

Parameter	Data Type	Value	Default
'SearchFields'	Case-insensitive string or cell array of strings	Valid strings are 'abstract', 'layer', 'layertitle', 'layername', 'server', 'serverurl', 'servertitle', or 'any'.	{'layer'}
'MatchType'	Case-insensitive string with value 'partial' or 'exact'	If you specify 'MatchType' as 'partial', then a match is determined if the query string is found in the property value. If you specify 'MatchType' as 'exact', then a match is determined only if the query string exactly matches the property value. If you specify 'MatchType' as 'exact' and	'partial'



(Continued)

Parameter	Data Type	Value	Default
		querystr as '*', a match is found if the property value matches the character '*'. If you set 'IgnoreCase' to true, then WMSLayer.refine ignores case when performing string comparisons.	
'IgnoreCase'	Logical		true

## Tips

- The WMSLayer.refine method searches the entries in the 'SearchFields' properties of layers for a partial match of the entry with querystr. The WMSLayer.refine method returns layer information if any supplied 'SearchFields' match. If you specify 'layer', then the method searches both the 'LayerTitle' and 'LayerName' properties. If you specify 'server', then the method searches both the 'ServerURL' and 'ServerTitle' fields. If you specify 'any', then the method searches the properties 'Abstract', 'LayerTitle', 'LayerName', 'ServerURL', and 'ServerTitle'.

## Example

Refine a search of temperature layers to find two different sets of layers: (1) layers containing only annual sea surface temperatures, and (2) layers containing annual temperatures or sea surface temperatures.

```
temperature = wmsfind('temperature');  
annual = temperature.refine('annual');  
sst = temperature.refine('sea surface');  
annual_and_sst = sst.refine('annual');  
annual_or_sst = [sst;annual];
```

## See Also

wmsfind | WMSLayer.refineLimits

# WMSLayer.refineLimits

---

**Purpose** Refine search based on geographic limits

**Syntax** `layers.refineLimits(parameter, value, ...)`

**Description** `layers.refineLimits(parameter, value, ...)` searches for elements of layers that match specific latitude or longitude limits. The results include a given layer only if the quadrangle specified by the optional 'Latlim' and 'Lonlim' parameters fully contains the boundary quadrangle, as defined by the Latlim and Lonlim properties. Partial overlap does not result in a match. You can abbreviate 'Latlim' and 'Lonlim'. Case does not matter. All angles are in units of degrees.

**Tips**

- The default value of [] for either 'Latlim' or 'Lonlim' implies that all layers match the criteria. For example, if you specify the following, then the results include all the layers that cover the northern hemisphere.

```
layer.refineLimits('Latlim', [0 90], 'Lonlim', [])
```

**Input Arguments** *parameter*, *value*  
Specifies geographic limits of search.

Parameter	Value
'Latlim'	A two-element vector of latitude specifying the latitudinal limits of the search in the form [southern_limit northern_limit] or a scalar value representing the latitude of a single point.
'Lonlim'	A two-element vector of longitude specifying the longitudinal limits of the search in the form [western_limit eastern_limit] or a scalar value representing the longitude of a single point.

## Example

Find layers containing global elevation data:

```
elevation = wmsfind('elevation');
latlim = [-90, 90];
lonlim = [-180, 180];
globalElevation = ...
    elevation.refineLimits('Latlim', latlim, 'Lonlim', lonlim);

% Print out the server titles from the unique servers.
globalElevation.serverTitles'
```

Sample output follows:

```
ans =

    'Global'
    'NRL GIDB Portal: Missouri CARES Maps'
    'NRL GIDB Portal: NOAA NGDC Maps'
```

## See Also

wmsfind

# WMSLayer.servers

---

**Purpose** Return URLs of unique servers

**Syntax** `servers = layers.servers()`

**Description** `servers = layers.servers()` returns a cell array of URLs of unique servers.

**Examples** Find all unique URLs of government servers:

```
layers = wmsfind('* .gov*', 'SearchField', 'serverurl');
servers = layers.servers;
sprintf('%s\n', servers{:})
```

Sample output follows:

```
http://www.ga.gov.au/bin/getmap.pl?dataset=national
http://www.geoportalign.gov.ec/nacional/wms?
http://www.geoportalign.gov.ec/regional/wms?
```

---

For each server that contains a temperature layer, list the server URL and the number of temperature layers:

```
temperature = wmsfind('temperature');
servers = temperature.servers;
for k=1:numel(servers)
    querystr = servers{k};
    layers = temperature.refine(querystr, ...
        'SearchFields', 'serverurl');
    fprintf('Server URL\n%s\n', layers(1).ServerURL);
    fprintf('Number of layers: %d\n\n', numel(layers));
end
```

Sample output follows:

```
Server URL
http://svs.gsfc.nasa.gov/cgi-bin/wms?
```

Number of layers: 36

## **See Also**

`wmsfind` | `WMSLayer.refine` | `WMSLayer.serverTitles`

# WMSLayer.serverTitles

---

**Purpose** Return titles of unique servers

**Syntax** `serverTitles = layers.serverTitles()`

**Description** `serverTitles = layers.serverTitles()` returns a cell array of titles of unique servers.

**Example** List titles of unique government servers:

```
layers = wmsfind('*.gov*', 'SearchField', 'serverurl');
titles = layers.serverTitles
sprintf('%s\n', titles{:})
```

Sample output follows:

```
High Resolution Nighttime Imagery (Las Vegas)
```

**See Also** `wmsfind` | `WMSLayer.servers`

## Description

A structure containing detailed information about a layer

### Details Structure

Field Name	Data Type	Field Content
MetadataURL	String	URL containing metadata information about layer.
Attributes	Structure	Attributes of layer.
BoundingBox	Structure array	Bounding box of layer.
Dimension	Structure array	Dimensional parameters of layer, such as time or elevation.
ImageFormats	Cell array	Image formats supported by server.
ScaleLimits	Structure	Scale limits of layer.
Style	Structure array	Style parameters that determine layer rendering.
Version	String	WMS version specification.

### Attributes Structure

Field Name	Data Type	Field Content
Queryable	Logical	True if you can query the layer for feature information.
Cascaded	Double	Number of times a Cascading Map server has retransmitted the layer.
Opaque	Logical	True if the map data are mostly or completely opaque.

## WMSLayer.Details property

---

### Attributes Structure (Continued)

Field Name	Data Type	Field Content
NoSubsets	Logical	True if the map must contain the full bounding box. false if the map can be a subset of the full bounding box.
FixedWidth	Logical	True if the map has a fixed width that the server cannot change. false if the server can resize the map to an arbitrary width.
FixedHeight	Logical	True if the map has a fixed height that the server cannot change. false if the server can resize the map to an arbitrary height.

### BoundingBox Structure

Field Name	Data Type	Field Content
CoordRefSysCode	String	Code number for coordinate reference system.
XLim	Double array	X limit of layer in units of coordinate reference system.
YLim	Double array	Y limit of layer in units of coordinate reference system.



## Dimension Structure

Field Name	Data Type	Field Content
Name	String	Name of the dimension; such as time, elevation, or temperature.
Units	String	Measurement unit.
UnitSymbol	String	Symbol for unit.
Default	String	Default dimension setting. For example, if <code>default</code> is 'time' and dimension is not specified, server returns time holding.
MultipleValues	Logical	True if multiple values of the dimension may be requested. <code>false</code> if only single values may be requested.
NearestValue	Logical	True if nearest value of dimension is returned in response to request for nearby value. <code>false</code> if request value must correspond exactly to declared extent values.
Current	Logical	True if temporal data are kept current (valid only for temporal extents).
Extent	String	Values for dimension. Expressed in any of the following ways: <ul style="list-style-type: none"><li>• Single value (<code>value</code>)</li><li>• List of values (<code>value1, value2, ...</code>)</li><li>• Interval defined by bounds and resolution (<code>min1/max1/res1</code>)</li></ul>

# WMSLayer.Details property

## Dimension Structure (Continued)

Field Name	Data Type	Field Content
		<ul style="list-style-type: none"><li>List of intervals (min1/max1/res1, min2/max2/res2, ...)</li></ul>

## ScaleLimits Structure

Field Name	Data Type	Field Content
ScaleHint	Double array	Minimum and maximum scales for which it is appropriate to display layer. Expressed as scale of ground distance in meters represented by diagonal of central pixel in image.
MinScaleDenominator	Double	Minimum scale denominator of maps for which a layer is appropriate.
MaxScaleDenominator	Double	Maximum scale denominator of maps for which a layer is appropriate.

## Style Structure Array

Field Name	Data Type	Field Content
Title	String	Descriptive title of style.
Name	String	Name of style.

## Style Structure Array (Continued)

Field Name	Data Type	Field Content
Abstract	String	Information about style.
LegendURL	Structure	Information about legend graphics.

## LegendURL Structure

Field Name	Data Type	Field Content
OnlineResource	String	URL of legend graphics.
Format	String	Format of legend graphics.
Height	Double	Height of legend graphics.
Width	Double	Width of legend graphics.

# WMSMapRequest class

---

**Purpose** Web Map Service map request object

**Description** A WMSMapRequest object contains a request to a WMS server to obtain a map, which represents geographic information. The WMS server renders the map as a color or grayscale image. The object contains properties that you can set to control the geographic extent, rendering, or size of the requested map.

**Construction** `mapRequest = WMSMapRequest(layer)` constructs a WMSMapRequest object. The WMSLayer array `layer` contains only one unique `ServerURL`. The WMSMapRequest class updates the properties of `layer`, if necessary.

`mapRequest = WMSMapRequest(layer, server)` constructs a WMSMapRequest object. `layer` is a WMSLayer object, and `server` is a scalar `WebMapServer` object. The `ServerURL` property of `layer` must match the `ServerURL` property of `server`. The `server` object updates `layer` properties.

**Properties** `Server`

Initialized to the `Server` input, if supplied to the constructor; otherwise constructed using the `ServerURL` of `Layer`.

**Data Type:** scalar `WebMapServer` object

`Layer`

Initialized to the `layer` input supplied to the constructor. The `Layer` property contains one unique `ServerURL`. The `Server` property updates the properties of `Layer` when the property is set. The `ServerURL` property of `Layer` must match the `ServerURL` property of `Server`.

**Data Type:** WMSLayer array

`CoordRefSysCode`

Specifies the coordinate reference system code. If set to a value other than 'EPSG:4326', `CoordRefSysCode` must be found in the `Details.BoundingBox` structure array found in the `Layer`

property. When set to 'EPSG:4326', the XLim and YLim properties are set to [] and the Latlim and Lonlim properties are set to the geographic extent defined by the Layer array. When set to a value other than 'EPSG:4326', the XLim and YLim properties are set from the values found in the Layer.Details.BoundingBox structure and the Latlim and Lonlim properties are set to []. The WMSMapRequest class does not support automatic projections. (Automatic projections begin with the string 'auto').

**Data Type:** string

**Default:** 'EPSG:4326'

## RasterRef

References the raster map to an intrinsic coordinate system.

**Data Type:** 3-by-2 matrix

## Latlim

Contains the southern and northern latitudinal limits of the request in units of degrees. The limits must be ascending.

**Data Type:** two-element vector

**Default:** Limits that span all latitudinal limits found in the Layer.Latlim property

## Lonlim

Contains the western and eastern longitudinal limits of the request in units of degrees. The limits must be ascending and in the range [-180, 180].

**Data Type:** two-element vector

**Default:** Limits that span all longitudinal limits in the Layer.Lonlim property

## XLim

# WMSMapRequest class

---

Contains the western and eastern limits of the request in units specified by the coordinate reference system. The limits must be ascending. You can set `XLim` only if you set `CoordRefSysCode` to a value other than `EPSG:4326`.

**Data Type:** two-element vector

**Default:** []

## `YLim`

Contains the southern and northern limits of the request in units specified by the coordinate reference system. The limits must be ascending. You can set `YLim` only if you set `CoordRefSysCode` to a value other than `EPSG:4326`.

**Data Type:** two-element vector

**Default:** []

## `ImageHeight`

Specifies the height in pixels for the requested raster map. The property `MaximumHeight` defines the maximum value for `ImageHeight`. The `WMSMapRequest` class initializes the `ImageHeight` property to either 512 or to an integer value that best preserves the aspect ratio of the coordinate limits, without changing the coordinate limits.

**Data Type:** scalar, positive integer

## `ImageWidth`

Specifies the width in pixels for the requested raster map. The property `MaximumWidth` defines the maximum value for `ImageWidth`. The `WMSMapRequest` class initializes the `ImageWidth` property to either 512 or to an integer value that best preserves the aspect ratio of the coordinate limits, without changing the coordinate limits.

**Data Type:** scalar, positive integer

## Maximum Height

Contains the maximum height in pixels for the requested map. Cannot be set. The value of `MaximumHeight` is 8192.

**Data Type:** double

## Maximum Width

Contains the maximum width in pixels for the requested map. Cannot be set. The value of `MaximumWidth` is 8192.

**Data Type:** double

## Elevation

Gives the elevation extent of the requested map. When you set the property, 'elevation' must be the value of the `Layer.Details.Dimension.Name` field.

**Data Type:** string

**Default:** ''

## Time

Specifies the time extent of the requested map. See the `WMSMapRequest.Time` reference page for more information.

**Data Type:** string or double

**Default:** ''

## SampleDimension

Contains the name of a sample dimension (other than 'time' or 'elevation') and its value. `SampleDimension{1}` must be the value of the `Layer.Details.Dimension.Name` field.

**Data Type:** two-element cell array of strings

## Transparent

# WMSMapRequest class

---

Specifies whether the map background is transparent. When you set `Transparent` to `true`, the server sets all pixels not representing features or data values in that layer to a transparent value, producing a composite map. When you set `Transparent` to `false`, the server sets all non-data pixels to the value of the background color.

**Data Type:** logical scalar

**Default:** `false`

## BackgroundColor

Specifies the color of the background (non-data) pixels of the map. The values range from 0 to 255. The default value, `[255,255,255]`, specifies the background color as white. You can set `BackgroundColor` using non-`uint8` numeric values, but they are cast and stored as `uint8`.

**Data Type:** three-element vector of `uint8` values

## StyleName

Specifies the style to use when rendering the image. The `StyleName` must be a valid entry in the `Layer.Details.Style.Name` field. (The cell array of strings contains the same number of elements as does `Layer`.)

**Data Type:** string or cell array of strings

**Default:** `{}`

## ImageFormat

Specifies the desired image format used to render the map as an image. If set, the format must match an entry in the `Layer.Details.ImageFormats` structure and an entry in the `ImageRenderFormats` property. If not set, the format defaults to a value in the `ImageRenderFormats` property.

**Data Type:** string



## ImageRenderFormats

Contains the preferred image rendering formats when `Transparent` is set to `false`. The first entry is the most preferred image format. If the preferred format is not stored in the `Layer` property, then the next format from the list is selected, until a format is found. The `ImageRenderFormats` array is not used if the `ImageFormat` property is set. The `ImageRenderFormats` property cannot be set.

**Data Type:** cell array

## ImageTransparentFormats

Contains the preferred image rendering formats when `Transparent` is set to `true`. When `Transparent` is set to `true`, the `ImageFormat` property is set to the first entry in the `ImageTransparentFormats` list, if it is stored in the `Layer` property. Otherwise, the list is searched for the next element, until a match is found. If a transparent image format is not found in the list, or if the `ImageFormat` property is set to a non-default value, then `ImageFormat` is unchanged. The `ImageTransparentFormats` property cannot be set.

**Data Type:** cell array

## ServerURL

Contains the server URL for the WMS `GetMap` request. In general, `ServerURL` matches the `ServerURL` of the `Layer`. However, some WMS servers, such as the Microsoft TerraServer, require a different URL for `GetMap` requests than for WMS `GetCapabilities` requests.

**Data Type:** string

**Default:** `Layer(1).ServerURL`

## RequestURL

# WMSMapRequest class

---

Contains the URL for the WMS GetMap request. It is composed of the ServerURL with additional WMS parameter/value pairs. This property cannot be set.

**Data Type:** string

## Methods

boundImageSize                      Bound size of raster map

## Examples

Read a global, half-degree resolution sea surface temperature map for the month of November 2009. The map, from the AMSR-E sensor on NASA's Aqua satellite, uses data provided by NASA's Earth Observations (NEO) WMS server.

```
sst = wmsfind('AMSRE_SST_M');
server = WebMapServer(sst.ServerURL);
mapRequest = WMSMapRequest(sst, server);
timeRequest = '2009-11-01';
mapRequest.Time = timeRequest;
samplesPerInterval = .5;
mapRequest.ImageHeight = ...
    round(abs(diff(sst.Latlim))/samplesPerInterval);
mapRequest.ImageWidth = ...
    round(abs(diff(sst.Lonlim))/samplesPerInterval);
mapRequest.ImageFormat = 'image/png';
sstImage = server.getMap(mapRequest.RequestURL);
```

The legend for the layer can be obtained via the OnlineResource URL field in the LegendURL structure. The legend shows that the temperature ranges from -2 to 35 degrees Celsius. The WMSMapRequest object updates the layer information from the server.

```
[legend, cmap] = imread...
    (mapRequest.Layer.Details.Style(1).LegendURL.OnlineResource);
legendImg = ind2rgb(legend, cmap);
```

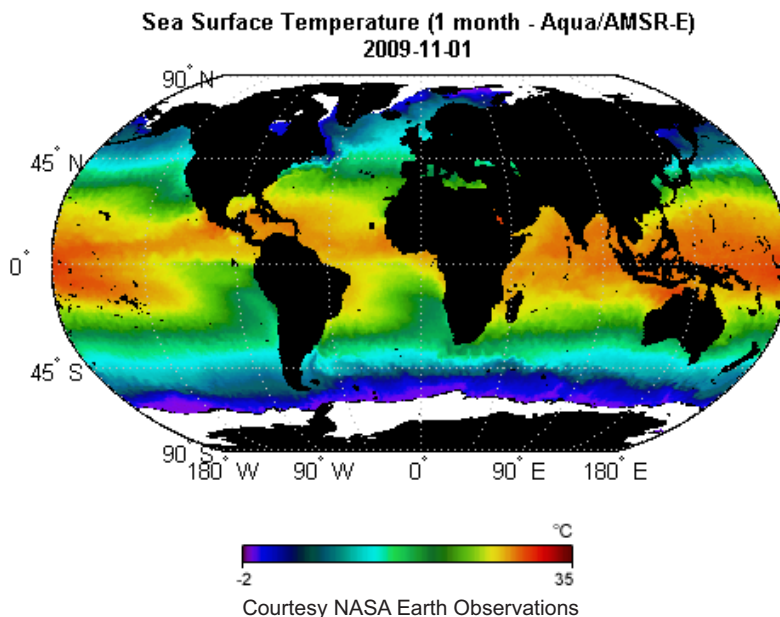
Display the temperature map and legend.

```
figure('Color','white')
worldmap world
setm(gca, 'MlabelParallel', -90, 'MlabelLocation', 90)
geoshow(sstImage, mapRequest.RasterRef);
title({mapRequest.Layer.LayerTitle, timeRequest}, ...
      'Interpreter', 'none', 'FontWeight', 'bold')

figurePosition = get(gcf, 'position');
centerWidth = figurePosition(3)/2;
left = centerWidth - size(legendImg,2)/2;
bottom = 30;
width = size(legendImg,2);
height = size(legendImg,1);
axes('Units', 'pixels', 'Position', [left bottom width height])
image(legendImg)
axis off
```

# WMSMapRequest class

---



Additional abstract information for this layer can be obtained from the MetadataURL field.

```
filename = [tempname '.xml'];  
urlwrite(mapRequest.Layer.Details.MetadataURL, filename);  
xml = xmlread(filename);  
delete(filename);  
xml.getElementsByTagName('abstract').item(0).getTextContent
```

The output appears as shown.

```
ans =
```

```
<p>Sea surface temperature is the temperature of the top  
millimeter of the ocean's surface. Sea surface temperatures  
influence weather, including hurricanes, as well as plant
```

and animal life in the ocean. Like Earth's land surface, sea surface temperatures are warmer near the equator and colder near the poles. Currents like giant rivers move warm and cold water around the world's oceans. Some of these currents flow on the surface, and they are obvious in sea surface temperature images. Special microwave technology allows the AMSR-E sensor on NASA's Aqua satellite to measure sea surface temperatures through clouds, something no satellite sensor before it was able to do across the whole globe.</p>

---

Read and display a global elevation and bathymetry layer for the Gulf of Maine at a 30 arc-seconds sampling interval. The values are in units of meters.

```
layers = wmsfind('srtmplus', 'MatchType', 'exact');
layer = layers(1);
server = WebMapServer(layer.ServerURL);
mapRequest = WMSMapRequest(layer, server);
mapRequest.Latlim = [40 46];
mapRequest.Lonlim = [-71 -65];
samplesPerInterval = 30/3600;
mapRequest.ImageHeight = ...
    round(diff(mapRequest.Latlim)/samplesPerInterval);
mapRequest.ImageWidth = ...
    round(diff(mapRequest.Lonlim)/samplesPerInterval);
mapRequest.StyleName = 'short_int';
mapRequest.ImageFormat = 'image/geotiff';
Z = server.getMap(mapRequest.RequestURL);
```

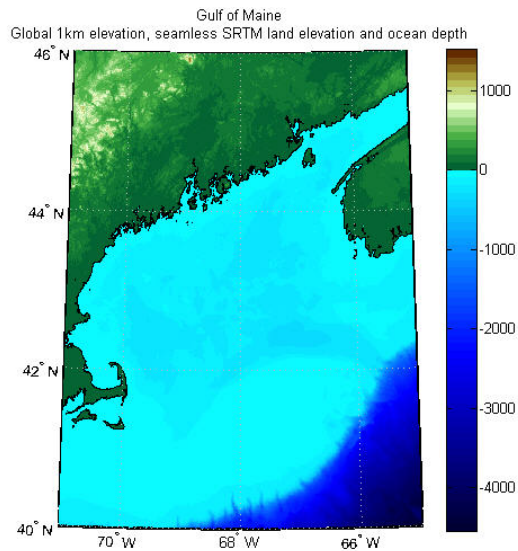
Display and contour the map at sea level (0 meters).

```
figure
worldmap(mapRequest.Latlim, mapRequest.Lonlim)
geoshow(double(Z), mapRequest.RasterRef, ...
    'DisplayType', 'texturemap')
```

# WMSMapRequest class

---

```
demcmap(double(Z))
set(gcf, 'renderer','zbuffer')
contourm(double(Z), mapRequest.RasterRef, [0 0], 'color', 'black')
colorbar
title ({'Gulf of Maine', mapRequest.Layer.LayerTitle}, ...
      'Interpreter','none')
```



## See Also

[WebMapServer](#) | [wmsfind](#) | [wmsinfo](#) | [WMSLayer](#) | [wmsread](#)

## Purpose

Bound size of raster map

## Syntax

```
mapRequest = boundsImageSize(mapRequest, imageLength)
```

## Description

`mapRequest = boundsImageSize(mapRequest, imageLength)` bounds the size of the raster map based on the scalar `imageLength`. The scalar `mapRequest` is a `WMSMapRequest` object. The double `imageLength` indicates the length in pixels for the row (`ImageHeight`) or column (`ImageWidth`) dimension. The `boundsImageSize` method calculates the row or column dimension length by using the aspect ratio of the `Latlim` and `Lonlim` properties or the aspect ratio of the `XLim` and `YLim` properties, if they are set.

The `boundsImageSize` method measures image dimensions in geographic or map coordinates. The method sets the longest image dimension to `imageLength`, and the shortest to the nearest integer value that preserves the aspect ratio, without changing the coordinate limits. The maximum value of the `MaximumHeight` and `MaximumWidth` properties becomes the maximum value of `imageLength`.

## Example

Read and display a composite of multiple layers representing the EGM96 geopotential model of the Earth, coastlines, and national boundaries from the NASA Globe Visualization server. The rendered map has a spatial resolution of 0.5 degree.

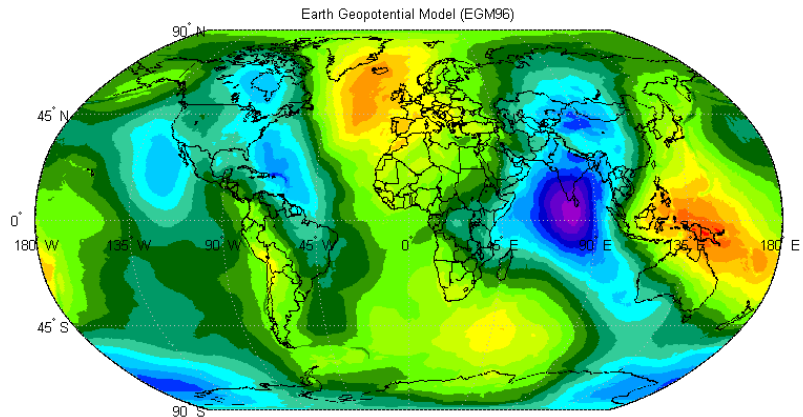
```
vizglobe = wmsfind('viz.globe', 'SearchField', 'serverurl');
coastlines = vizglobe.refine('coastline');
national_boundaries = vizglobe.refine('national*bound');
base_layer = vizglobe.refine('egm96');
layers = [base_layer;coastlines;national_boundaries];
request = WMSMapRequest(layers);
request.Transparent = true;
request = request.boundsImageSize(720);
overlayImage = request.Server.getMap(request.RequestURL);

figure
worldmap('world')
```

# WMSMapRequest.boundImageSize

---

```
geoshow(overlayImage, request.RasterRef);  
title(base_layer.LayerTitle)
```

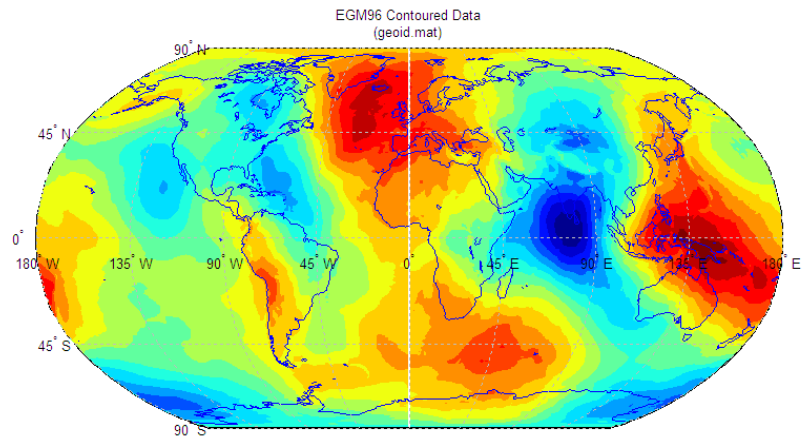


Compare the map with the contoured data from 'geoid.mat'.

```
geoid = load('geoid');  
coast = load('coast');  
figure  
worldmap('world')  
contourfm(geoid.geoid, geoid.geoidrefvec, 15)  
geoshow(coast.lat, coast.long)  
title({'EGM96 Contoured Data', '(geoid.mat)'})
```



# WMSMapRequest.boundImageSize



Downsampled from the EGM96 grid developed by NASA Goddard and the National Geospatial-Intelligence Agency (NGA)

# WMSMapRequest.Time property

**Purpose** Requested time extent

**Description** The WMSMapRequest.Time property stores time as a string or a double indicating the desired time extent of the requested map. When you set the property, 'time' must be the value of the Layer.Details.Dimension.Name field. The default value is ''.

Time is stored in the ISO® 8601:1988(E) extended format. In general, the Time property is stored in a yyyy-mm-dd format or a yyyy-mm-ddThh:mm:ssZ format, if the precision requires hours, minutes, or seconds. You can use several different string and numeric formats to set the Time property, according to the following table (where dateform number is the number used by the Standard MATLAB Date Format Definitions). Express all hours, minutes, and seconds in Coordinated Universal Time (UTC).

Dateform (number)	Input (string)	Stored format
0	dd-mm-yyyy HH:MM:SS	yyyy-mm-ddTHH:MM:SSZ
1	dd-mm-yyyy	yyyy-mm-dd
2	mm/dd/yy	yyyy-mm-dd
6	mm/dd	yyyy-mm-dd (current year)
10	yyyy	yyyy
13	HH:MM:SS	yyyy-mm-ddTHH:MM:SSZ
14	HH:MM:SS PM	yyyy-mm-ddTHH:MM:SSZ
15	HH:MM	yyyy-mm-ddTHH:MM:00Z
16	HH:MM PM	yyyy-mm-ddTHH:MM:00Z
21	mmm.dd,yyyy HH:MM:SS	yyyy-mm-ddTHH:MM:SSZ
22	mmm.dd,yyyy	yyyy-mm-dd
23	mm/dd/yyyy	yyyy-mm-dd

## WMSMapRequest.Time property

Dateform (number)	Input (string)	Stored format
26	yyyy/mm/dd	yyyy-mm-dd
29	yyyy-mm-dd	yyyy-mm-dd
30	yyyymmddTHHMSS	yyyy-mm-ddTHH:MM:SSZ
31	yyyy-mm-dd HH:MM:SS	yyyy-mm-ddTHH:MM:SSZ

Inputs using the dateform numbers 13–16 return the date set to the current year, month, and day. Use of other dateform formats, especially 19, 20, 24, and 25, results in erroneous output.

In addition to these standard MATLAB dateform formats, the `WMSMapRequest.Time` property also accepts the following inputs.

Input (string)	Description
'current'	The current time holdings of the server
numeric datenum	Numeric date value converted to yyyy-mm-dd string (dateform 29 format)
Byyyy	B.C.E. year

Use the prefixes K, M, and G, followed by a string number (thousand, million, and billion years, respectively), for geologic data sets that refer to the distant past.

**Purpose** Retrieve WMS map from server

**Syntax**

```
[A, R] = wmsread(layer)
[A, R] = wmsread(mapRequestURL)
[A, R] = wmsread(layer, parameter, value, ...)
[A, R, mapRequestURL] = wmsread(...)
```

**Description** `[A, R] = wmsread(layer)` accesses the Internet to render and retrieve a raster map from a Web Map Service (WMS) server. The `ServerURL` property of the `WMSLayer` object, `layer`, specifies the server. If `layer` has more than one element, then the server overlays each subsequent layer on top of the base (first) layer, forming a single image. The server renders multiple layers only if all layers share the same `ServerURL` value.

The WMS server returns a raster map, either a color or grayscale image, in the output `A`. The second output, a referencing matrix `R`, ties `A` to the EPSG:4326 geographic coordinate system. The rows of `A` are aligned with parallels, with even sampling in longitude. Likewise, the columns of `A` are aligned with meridians, with even sampling in latitude.

The geographic limits of `A` span the full latitude and longitude extent of `layer`. The `wmsread` function chooses the larger spatial size of `A` to match its larger geographic dimension. The larger spatial size is fixed at the value 512. In other words, assuming RGB output, `A` is 512-by-`N`-by-3 if the latitude extent exceeds longitude extent and `N`-by-512-by-3 otherwise. In both cases `N` ≤ 512. The `wmsread` function sets `N` to the integer value that provides the closest possible approximation to equal cell sizes in latitude and longitude. The map spans the full extent supported for the `layer`.

`[A, R] = wmsread(mapRequestURL)` uses the input argument `mapRequestURL` to define the request to the server. The `mapRequestURL` string contains a WMS `serverURL` with additional WMS parameters. The URL string includes the WMS parameters `BBOX` and `GetMap` and the EPSG:4326 keyword. Obtain a `mapRequestURL` from the output of `wmsread`, the `RequestURL` property of a `WMSMapRequest` object, or an Internet search.

[A, R] = wmsread(layer, *parameter*, *value*, ...) specifies parameter-value pairs that modify the request to the server. You can abbreviate parameter names, which are case-insensitive.

[A, R, mapRequestURL] = wmsread(...) returns a WMS GetMap request URL in the string mapRequestURL. You can insert the mapRequestURL into a browser to make a request to a server, which then returns the raster map. The browser opens the returned map if its mime type is understood, or saves the raster map to disk.

## Tips

- Establish an Internet connection to use wmsread. Periodically, the WMS server is unavailable. Retrieving the map can take several minutes. wmsread communicates with the server using a WebMapServer handle object representing a WMS server. The handle object acts as a proxy to a WMS server and resides physically on the client side. The handle object retrieves the map from the server. The handle object automatically times-out after 60 seconds if a connection is not made to the server.
- To specify a proxy server to connect to the Internet, select **File > Preferences > Web** and enter your proxy information. Use this feature if you have a firewall.

## Input Arguments

layer

Contains information about the layer you are retrieving, such as the server URL.

**Data Type:** WMSLayer object

mapRequestURL

Defines the request to the server.

**Data Type:** string

*parameter*, *value*

Specifies parameter-value pairs that modify the request to the server. See the permissible values.

Parameter	Data Type	Value
'Latlim'	Two-element vector	Specifies the latitude limits of the output image in the form [southern_limit northern_limit]. The limits are in degrees and must be ascending. By default, 'Latlim' is empty, and the full extent in latitude of layer is used. If Layer.Details.Attributes.NoSubsets is true, then 'Latlim' may not be modified.
'Lonlim'	Two-element vector	Specifies the longitude limits of the output image in the form [western_limit eastern_limit]. The limits are in degrees and must be ascending. By default, 'Lonlim' is empty and the full extent in longitude of layer is used. If Layer.Details.Attributes.NoSubsets is true, then 'Lonlim' may not be modified.
'ImageHeight'	Scalar, positive, integer-valued number	Specifies the desired height of the raster map in pixels. ImageHeight cannot exceed 8192. If layer.Details.Attributes.FixedHeight contains a positive number, then you cannot modify 'ImageHeight'.
'ImageWidth'	Scalar, positive, integer-valued number	Specifies the desired width of the raster map in pixels. ImageWidth cannot exceed 8192. If Layer.Details.Attributes.FixedWidth contains a positive number, then you cannot modify 'ImageWidth'.

Parameter	Data Type	Value
'CellSize'	Scalar or two-element vector	Specifies the target size of the output pixels (raster cells) in units of degrees. If you specify a scalar, the value applies to both height and width dimensions. If you specify a vector, use the form [height width]. The wmsread function issues an error if you specify both CellSize and ImageHeight or ImageWidth. The output raster map must not exceed a size of [8192,8192].
'RelTolCellSize'	Scalar or two-element vector	Specifies the relative tolerance for 'CellSize'. If you specify a scalar, the value applies to both height and width dimensions. If you specify a vector, the tolerance appears in the order [height width]. The default value is .001.
'ImageFormat'	String	Specifies the desired image format for use in rendering the map as an image. If specified, the format must match an entry in the Layer.Details.ImageFormats cell array and must match one of the following supported formats: 'image/jpeg', 'image/gif', 'image/png', 'image/tiff', 'image/geotiff', 'image/geotiff8', 'image/tiff8', 'image/png8'. If not specified, the format defaults to the first available format in the supported format list.
'StyleName'	String or cell array of strings	Specifies the style to use when rendering the image. By default, the style is set to the empty string. The StyleName must be a valid entry in the Layer.Details.Style.Name field. If you request multiple layers, each with a different style, then StyleName must be a cell array of strings.

Parameter	Data Type	Value
'Transparent'	Logical	Specifies if transparency is enabled. When you set <code>Transparent</code> to <code>true</code> , all pixels not representing features or data values are set to a transparent value. When you set <code>Transparent</code> to <code>false</code> , non-data pixels are set to the value of the background color. By default, the value is <code>false</code> .
'BackgroundColor'	Three-element vector	Specifies the color of the background (nondata) pixels of the map. If not specified, the default is <code>[255,255,255]</code> .
'Elevation'	String	Indicates the desired elevation extent of the requested map. The layer must contain elevation data, which is indicated by the <code>'Name'</code> field of the <code>Layer.Details.Dimension</code> structure. The <code>'Name'</code> field must contain the value <code>'elevation'</code> . The <code>'Extent'</code> field of the <code>Layer.Details.Dimension</code> structure determines the permissible range of values for the parameter.
'Time'	String or numeric date number	Indicates the desired time extent of the requested map. The layer must contain data with a time extent, which is indicated by the <code>'Name'</code> field of the <code>Layer.Details.Dimension</code> structure. The <code>'Name'</code> field must contain the value <code>'time'</code> . The <code>'Extent'</code> field of the <code>Layer.Details.Dimension</code> structure determines the permissible range of values for the parameter. For more information about setting this parameter, see the <code>WMSMapRequest.Time</code> property reference page.



Parameter	Data Type	Value
'SampleDimension'	Two-element cell array of strings	Indicates the name of a sample dimension (other than 'time' or 'elevation') and its string value. The layer must contain data with a sample dimension extent, which is indicated by the 'Name' field of the <code>Layer.Details.Dimension</code> structure. The 'Name' field must contain the value of the first element of 'SampleDimension'. The 'Extent' field of the <code>Layer.Details.Dimension</code> structure determines the permissible range of values for the second element of 'SampleDimension'.
'TimeoutInSeconds'	Integer-valued, scalar double	Indicates the number of seconds to elapse before a server time-out is issued. By default, the value is 60 seconds. A value of 0 causes the time-out mechanism to be ignored.

## Definitions

The EPSG:4326 coordinate reference system is based on the WGS84 (1984 World Geodetic System) datum. Latitude and longitude are in degrees and longitude is referenced to the Greenwich Meridian.

## Examples

Read and display the 'bluemarble' layer from a NASA server:

```
nasa = wmsfind('nasa', 'SearchField', 'serverurl');
layer = nasa.refine('bluemarble', 'SearchField', 'layername', ...
    'MatchType', 'exact');
[A, R] = wmsread(layer(1));
figure
axesm globe
axis off
geoshow(A, R)
title('Blue Marble')
```

Blue Marble



Courtesy NASA/JPL-Caltech

---

Read and display an orthoimage of Liberty Island in New York using the USGS National Map Seamless server.

```
latlim = [40.688416 40.691342];
lonlim = [-74.047753 -74.043214];
nyLayers = wmsfind('usgs*new*york', ...
    'SearchField', 'serverurl', ...
    'Latlim', latlim, 'Lonlim', lonlim);
layerName = 'NewYorkCity_2.0ft_Color_Mar_2006';
orthoLayer = nyLayers.refine(layerName, 'MatchType', 'exact');
numPixels = 1024;
[A,R] = wmsread(orthoLayer, 'Latlim', latlim, ...
    'Lonlim', lonlim, 'ImageHeight', numPixels, ...
    'ImageWidth', numPixels);

% Display the orthoimage in a UTM projection.
figure
```

```

axesm('utm', 'Zone', utmzone(latlim, lonlim), ...
      'MapLatlimit', latlim, 'MapLonlimit', lonlim, ...
      'Geoid', almanac('earth', 'wgs84', 'meter'))
geoshow(A,R)
axis off
title({'Liberty Island', 'Statue of Liberty'}, ...
      'FontWeight', 'bold')

```

**Liberty Island  
Statue of Liberty**



Courtesy U.S. Geological Survey

Drape Landsat imagery onto elevation data from the USGS National Elevation Dataset (NED) for an area surrounding the Grand Canyon. Read the 'global\_mosaic' and 'us\_ned' layers from the Web map server at the Jet Propulsion Laboratory.

```

% Obtain the layers of interest.
jpl = wmsfind('earth.jpl.nasa.gov', 'SearchFields', 'serverurl');

```

```
jpl = wmsupdate(jpl);
global_mosaic = jpl.refine('global_mosaic', 'MatchType', ...
    'exact');
us_ned = jpl.refine('us_ned');

% Assign geographic extent and image size.
latlim = [36 36.23];
lonlim = [-113.36 -113.13];
imageHeight = 575;
imageWidth = 575;

% Read the global_mosaic layer.
[A, R] = wmsread(global_mosaic, 'StyleName', 'visual', ...
    'Latlim', latlim, 'Lonlim', lonlim, ...
    'ImageHeight', imageHeight, 'ImageWidth', imageWidth);

% Read the USGS NED layer.
[Z, R] = wmsread(us_ned, 'ImageFormat', 'image/geotiff', ...
    'StyleName', 'real', 'Latlim', latlim, 'Lonlim', lonlim, ...
    'ImageHeight', imageHeight, 'ImageWidth', imageWidth);

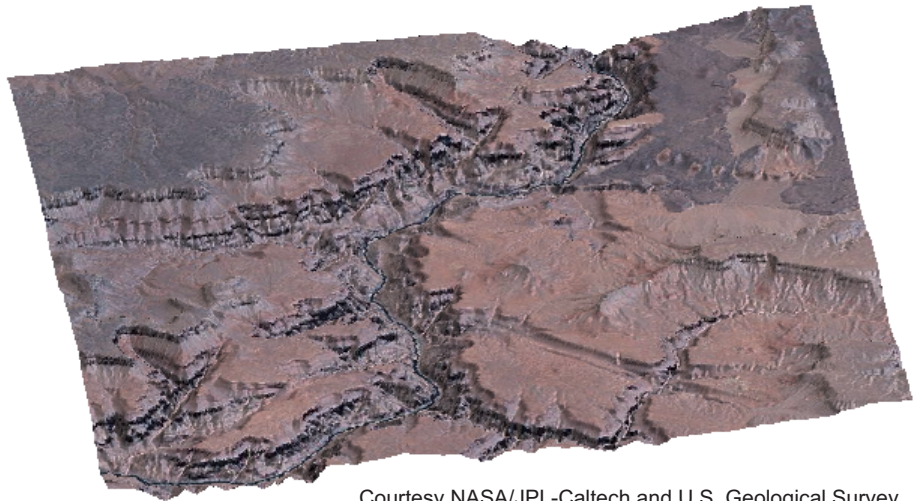
% Drape the Landsat image onto the elevation data.
figure
usamap(latlim, lonlim)
framem off; mlabel off; plabel off; gridm off
geoshow(double(Z), R, 'DisplayType', 'surface', 'CData', A);
daspectm('m',1)
title({'Grand Canyon', 'USGS NED and Landsat Global Mosaic'});
axis vis3d

% Assign camera parameters.
cameraPosition = [0.015136 0.67424 -72027];
cameraTarget = [-1.2904e-005 0.67187 3054.6];
cameraViewAngle = 8.1561;
cameraUpVector = [0.602132 0.0939748 5.05123e+006];

% Set camera and light parameters.
```

```
set(gca,'CameraPosition', cameraPosition, ...  
      'CameraTarget', cameraTarget, ...  
      'CameraViewAngle', cameraViewAngle, ...  
      'CameraUpVector', cameraUpVector);  
  
lightHandle = camlight;  
camLightPosition = [0.0011253 0.22101 -4.1188e+006];  
set(lightHandle, 'Position', camLightPosition);
```

Grand Canyon  
USGS NED and Landsat Global Mosaic



Courtesy NASA/JPL-Caltech and U.S. Geological Survey

---

Read and display a single sequence image from the MODIS instruments on the Aqua and Terra satellites that shows hurricane Katrina on August 29, 2005:

```
% Find the hurricane Katrina sequence layer.  
katrina = wmsfind('Hurricane Katrina (Sequence)');
```

```
katrina = wmsupdate(katrina(1));

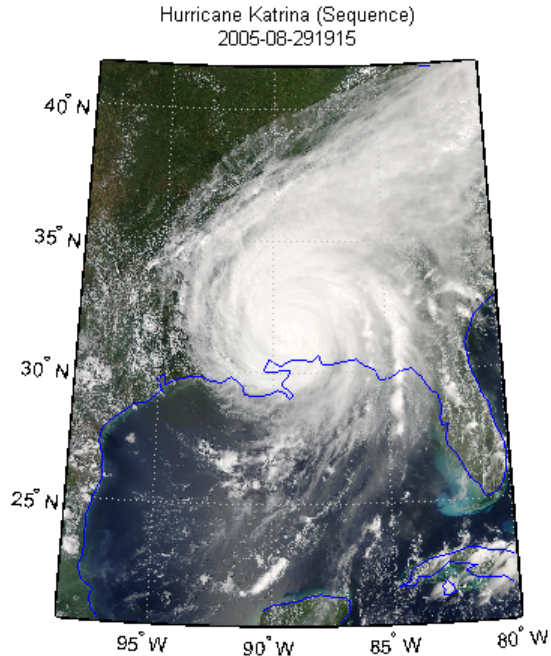
% The Dimension.Extent field shows a sequence delimited
% by commas. The sequence starts on August 24 and ends
% on August 31. The commas start at August 25 and end
% after August 30. Select the sequence corresponding to
% August 29.
commas = findstr(',', katrina.Details.Dimension.Extent);
extent = katrina.Details.Dimension.Extent;
sequence = extent(commas(end-2)+1:commas(end-1)-1);

% Obtain the time, latitude, and longitude limits
% from the values in the sequence. Split the sequence
% into a cell array of values by first finding
% all values between and including the parentheses,
% then remove the parentheses and split the values.
pat = '[(-.\d)]';
r = regexp(sequence, pat);
values = sequence(r);
values = strrep(values, '(', ' ');
values = strrep(values, ')', ' ');
values = regexp(values, '\s', 'split');
values = values(~cellfun('isempty', values));
time = values{1};
xmin = values{2};
ymin = values{3};
xmax = values{4};
ymax = values{5};

% Define latitude and longitude limits from the information
% in the sequence. The layer's geographic extent is assigned
% for the combined set of sequences. The requested map cannot
% be a subset of the layer's bounding box. In this rare case,
% set the layer's limits using the limits of the sequence.
latlim = [str2double(ymin) str2double(ymax)];
lonlim = [str2double(xmin) str2double(xmax)];
katrina.Latlim = latlim;
```

```
katrina.Lonlim = lonlim;

% Read and display the sequence map.
[A,R] = wmsread(katrina, 'SampleDimension', ...
    {katrina.Details.Dimension.Name, sequence});
figure
usamap(katrina.Latlim, katrina.Lonlim);
geoshow(A,R)
coast = load('coast');
plotm(coast.lat, coast.long)
title({katrina.LayerTitle, time})
```



Courtesy NASA/Goddard Space Flight Center Scientific Visualization Studio

## See Also

[WebMapServer](#) | [wmsfind](#) | [wmsinfo](#) | [WMSLayer](#) | [WMSMapRequest](#) | [wmsupdate](#)

# wmsupdate

---

**Purpose** Synchronize WMSLayer object with server

**Syntax** [updatedLayers, index] = wmsupdate(layers)  
[...] = wmsupdate(layers, *parameter*, *value*, ...)

**Description** [updatedLayers, index] = wmsupdate(layers) returns a WMSLayer array with its properties synchronized with values from the server. The input layers contains only one unique ServerURL. Layers no longer available on the server are removed. The logical array index contains true for each available layer. Therefore, updatedLayers has the same size as layers(index). Except for deletion, updatedLayers preserves the same order of layers as layers.

[...] = wmsupdate(layers, *parameter*, *value*, ...) specifies parameter-value pairs that modify the request. Parameter names can be abbreviated and are case-insensitive.

The function accesses the Internet to update the properties. Periodically, the WMS server is unavailable. Updating the layer can take several minutes. The function times-out after 60 seconds if a connection is not made to the server.

**Tips**

- To specify a proxy server to connect to the Internet, select **File > Preferences > Web** and enter your proxy information. Use this feature if you have a firewall.

**Input Arguments**

layers  
Contains WMSLayer objects  
**Data Type:** WMSLayer array

*parameter*, *value*  
Modifies the request. See the table below for permissible values.



Parameter	Data Type	Value	Default
'TimeoutInSeconds'	Integer-valued, scalar double	Indicates the number of seconds before a server times out. A value of 0 causes the time-out mechanism to be ignored.	60 seconds
'AllowMultipleServers'	Logical scalar	Indicates whether the layer array may contain elements from multiple servers. Use caution when setting the value to true, since you are making a request to each unique server. Each request can take several minutes to finish.	false (indicates the array must contain elements from the same server)

## Examples

Update the layers from the NASA Goddard Space Flight Center WMS SVS Image Server:

```
% Search the abstract field of the updated layers
% to find layers containing the term 'blue marble'.
% Read and display the blue marble layer containing the term
% '1024x512' in its LayerTitle.
gsfc = wmsfind('svs.gsfc.nasa.gov', 'SearchField', 'serverurl');
gsfc = wmsupdate(gsfc);
blue_marble = gsfc.refine('blue marble', 'SearchField', ...
    'abstract');
blueMarbleQuery = '1024x512';
layer = blue_marble.refine(blueMarbleQuery);

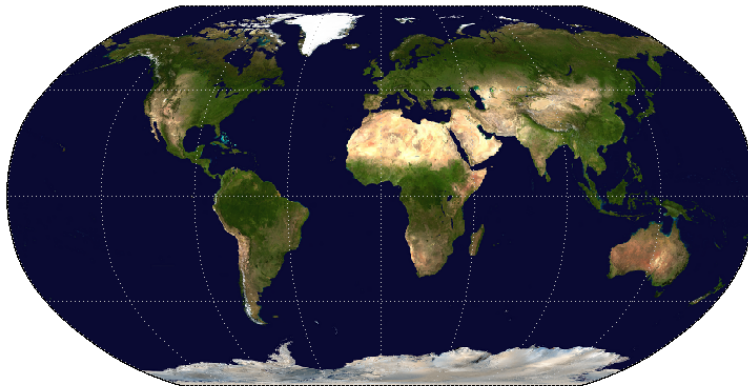
% Display the layer.
[A, R] = wmsread(layer);
figure
```

# wmsupdate

---

```
worldmap world
plabel off; mlabel off
geoshow(A, R);
title(layer.LayerTitle)
```

Complete Earth (1024x512 Image)



Courtesy NASA/Goddard Space Flight Center Scientific Visualization Studio

---

Update the properties of all the layers from the NASA servers:

```
nasa = wmsfind('nasa', 'SearchField', 'serverurl');
nasa = wmsupdate(nasa, 'AllowMultipleServers', true);
```

## See Also

[WebMapServer](#) | [wmsfind](#) | [wmsinfo](#) | [WMSLayer](#) | [wmsread](#)

**Purpose** Read worldfile and return referencing matrix

**Syntax** `R = worldfileread(worldfilename)`

**Description** `R = worldfileread(worldfilename)` reads the worldfile data from `worldfilename` and constructs the referencing matrix `R`.

`R` is a 3-by-2 affine transformation matrix that is used in `pix2map` and `map2pix` to transform pixel row and column coordinates to/from map/model coordinates according to  $[x \ y] = [\text{row} \ \text{col} \ 1] * R$ .

**Example** `R = worldfileread('concord_ortho_w.tfw')`

```
R =      1.0e+005 *
           0 -0.0000100000000000
           0.0000100000000000      0
           2.0699950000000000    9.1300050000000001
```

**See Also** `getworldfilename`, `makerefmat`, `pix2map`, `map2pix`, `worldfilewrite`

# worldfilewrite

---

**Purpose** Construct worldfile from referencing matrix

**Syntax** `worldfilewrite(R, worldfilename)`

**Description** `worldfilewrite(R, worldfilename)` calculates the worldfile entries corresponding to referencing matrix `R` and writes them into the file `worldfilename`.

`R` is a 3-by-2 affine transformation matrix that is used in `pix2map` and `map2pix` to transform pixel row and column coordinates to/from map/model coordinates according to  $[x \ y] = [row \ col \ 1] * R$ .

**Example**

```
R = worldfileread('concord_ortho_w.tfw');
worldfilewrite(R, 'concord_ortho_w_test.tfw');
```

constructs the referencing matrix `R` from `concord_ortho_w.tfw`, then reconstructs a copy of the worldfile from `R`.

**See Also** `getworldfilename`, `pix2map`, `map2pix`, `worldfileread`

**Purpose** Construct map axes for given region of world

**Syntax**

```
worldmap region
worldmap(region)
worldmap
worldmap(latlim, lonlim)
worldmap(Z, R)
h = worldmap(...)
```

**Description** `worldmap region` or `worldmap(region)` sets up an empty map axes with projection and limits suitable to the part of the world specified in `region`. `region` can be a string or a cell array of strings. Permissible strings include names of continents, countries, and islands as well as 'World', 'North Pole', 'South Pole', and 'Pacific'.

`worldmap` with no arguments presents a menu from which you can select the name of a single continent, country, island, or region.

`worldmap(latlim, lonlim)` allows you to define a custom geographic region in terms of its latitude and longitude limits in degrees. `latlim` and `lonlim` are two-element vectors of the form `[southern_limit northern_limit]` and `[western_limit eastern_limit]`, respectively.

`worldmap(Z, R)` derives the map limits from the extent of a regular data grid georeferenced by `R`. `R` is either a 1-by-3 vector containing elements:

```
[cells/degree northern_latitude_limit western_longitude_limit]
```

or a 3-by-2 referencing matrix that transforms raster row and column indices to/from geographic coordinates according to:

$$[\text{lon lat}] = [\text{row col 1}] * R$$

If `R` is a referencing matrix, it must define a (non-rotational, non-skewed) relationship in which each column of the data grid falls along a meridian and each row falls along a parallel.

`h = worldmap(...)` returns the handle of the map axes.

For cylindrical projections, `worldmap` uses `tightmap` set the axis limits tight around the map. If you change the projection, or just want more white space around the map frame, use `tightmap` again or `axis auto`.

## Examples

### Example 1

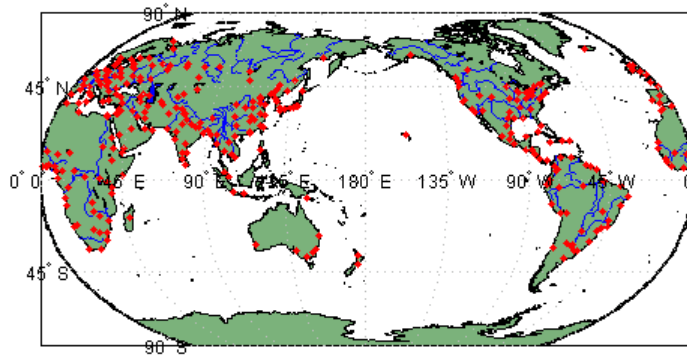
Set up a world map and draw coarse coastlines:

```
worldmap('World')
load coast
plotm(lat, long)
```

### Example 2

Set up `worldmap` with land areas, major lakes and rivers, and cities and populated places:

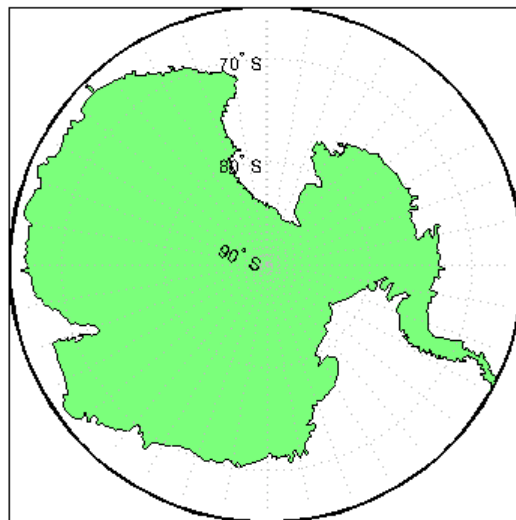
```
ax = worldmap('World');
setm(ax, 'Origin', [0 180 0])
land = shaperead('landareas', 'UseGeoCoords', true);
geoshow(ax, land, 'FaceColor', [0.5 0.7 0.5])
lakes = shaperead('worldlakes', 'UseGeoCoords', true);
geoshow(lakes, 'FaceColor', 'blue')
rivers = shaperead('worldrivers', 'UseGeoCoords', true);
geoshow(rivers, 'Color', 'blue')
cities = shaperead('worldcities', 'UseGeoCoords', true);
geoshow(cities, 'Marker', '.', 'Color', 'red')
```



### Example 3

Draw a map of Antarctica:

```
worldmap('antarctica')
antarctica = shaperead('landareas', 'UseGeoCoords', true,...
    'Selector',{@(name) strcmp(name,'Antarctica'), 'Name'});
patchm(antarctica.Lat, antarctica.Lon, [0.5 1 0.5])
```



## Example 4

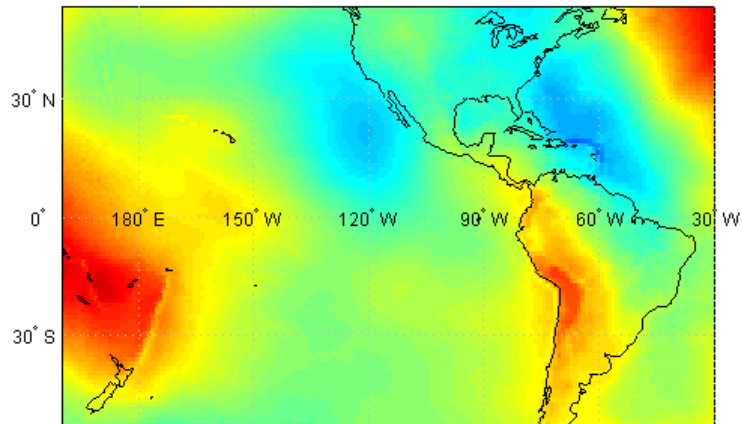
Draw a map of Africa and India with major cities and populated places:

```
worldmap({'Africa','India'})
land = shaperead('landareas.shp', 'UseGeoCoords', true);
geoshow(land, 'FaceColor', [0.15 0.5 0.15])
cities = shaperead('worldcities', 'UseGeoCoords', true);
geoshow(cities, 'Marker', '.', 'Color', 'red')
```

## Example 5

Make a map of the geoid over South America and the central Pacific:

```
worldmap([-50 50],[160 -30])
load geoid
geoshow(geoid, geoidrefvec, 'DisplayType', 'texturemap');
load coast
geoshow(lat, long)
```



## Example 6

Draw a map of terrain elevations in Korea:

```
load korea
```



```

h = worldmap(map, refvec);
set(h, 'Visible', 'off')
geoshow(h, map, refvec, 'DisplayType', 'texturemap')
colormap(demcmap(map))

```

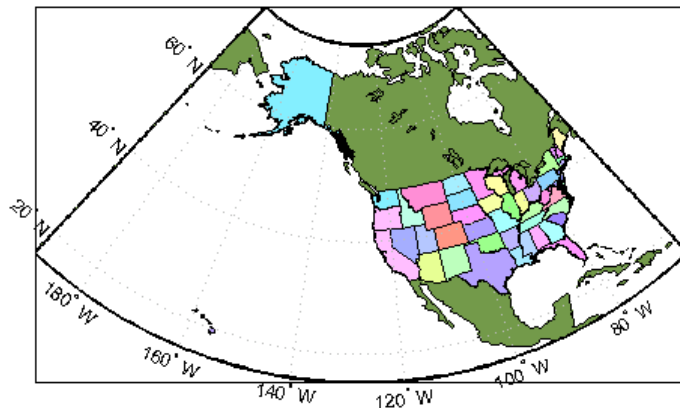
### Example 7

Make a map of the United States of America, coloring state polygons:

```

ax = worldmap('USA');
load coast
geoshow(ax, lat, long,...
'DisplayType', 'polygon', 'FaceColor', [.45 .60 .30])
states = shaperead('usastatelo', 'UseGeoCoords', true);
faceColors = makesymbolspec('Polygon',...
    {'INDEX', [1 numel(states)], 'FaceColor', ...
    polcmap(numel(states))}); % NOTE - colors are random
geoshow(ax, states, 'DisplayType', 'polygon', ...
'SymbolSpec', faceColors)

```



### See Also

axesm, framem, geoshow, gridm, mlabel, plabel, tightmap, usamap

# wrapTo180

---

**Purpose** Wrap angle in degrees to [-180 180]

**Syntax** lonWrapped = wrapTo180(lon)

**Description** lonWrapped = wrapTo180(lon) wraps angles in lon, in degrees, to the interval [-180 180] such that 180 maps to 180 and -180 maps to -180. (In general, odd, positive multiples of 180 map to 180 and odd, negative multiples of 180 map to -180.)

**See Also** wrapTo360, wrapTo2Pi, wrapToPi

<b>Purpose</b>	Wrap angle in degrees to [0 360]
<b>Syntax</b>	<code>lonWrapped = wrapTo360(lon)</code>
<b>Description</b>	<code>lonWrapped = wrapTo360(lon)</code> wraps angles in <code>lon</code> , in degrees, to the interval [0 360] such that 0 maps to 0 and 360 maps to 360. (In general, positive multiples of 360 map to 360 and negative multiples of 360 map to zero.)
<b>See Also</b>	<code>wrapTo180</code> , <code>wrapTo2Pi</code> , <code>wrapToPi</code>

# wrapTo2Pi

---

<b>Purpose</b>	Wrap angle in radians to $[0, 2\pi]$
<b>Syntax</b>	<code>lambdaWrapped = wrapTo2Pi(lambda)</code>
<b>Description</b>	<code>lambdaWrapped = wrapTo2Pi(lambda)</code> wraps angles in <code>lambda</code> , in radians, to the interval $[0, 2\pi]$ such that 0 maps to 0 and $2\pi$ maps to $2\pi$ . (In general, positive multiples of $2\pi$ map to $2\pi$ and negative multiples of $2\pi$ map to zero.)
<b>See Also</b>	<code>wrapTo180</code> , <code>wrapTo360</code> , <code>wrapToPi</code>

<b>Purpose</b>	Wrap angle in radians to $[-\pi \pi]$
<b>Syntax</b>	<code>lambdaWrapped = wrapToPi(lambda)</code>
<b>Description</b>	<code>lambdaWrapped = wrapToPi(lambda)</code> wraps angles in <code>lambda</code> , in radians, to the interval $[-\pi \pi]$ such that $\pi$ maps to $\pi$ and $-\pi$ maps to $-\pi$ . In general, odd, positive multiples of $\pi$ map to $\pi$ and odd, negative multiples of $\pi$ map to $-\pi$ .)
<b>See Also</b>	<code>wrapTo180</code> , <code>wrapTo360</code> , <code>wrapTo2Pi</code>

# zdatam

---

**Purpose** Adjust  $z$ -plane of displayed map objects

**Syntax**

```
zdatam
zdatam(hndl)
zdatam('str')
zdatam(hndl,zdata)
zdatam('str',zdata)
```

**Description** `zdatam` displays a GUI for selecting an object from the current axes and modifying its `ZData` property.

`zdatam(hndl)` and `zdatam('str')` display a GUI to modify the `ZData` of the object(s) specified by the input. `str` is any string recognized by `handlem`.

`zdatam(hndl,zdata)` alters the  $z$ -plane position of displayed map objects designated by the MATLAB graphics handle `hndl`. The  $z$ -plane position may be the  $Z$  position in the case of text objects, or the `ZData` property in the case of other graphic objects. The function behaves as follows:

- If `hndl` is an `hggroup` handle, the `ZData` property of the children in the `hggroup` are altered.
- If the handle is scalar, then `ZData` can be either a scalar ( $z$ -plane definition), or a matrix of appropriate dimension for the displayed object.
- If `hndl` is a vector, then `ZData` can be a scalar or a vector of the same dimension as `hndl`.
- If `ZData` is a scalar, then all objects in `hndl` are drawn on the `ZData`  $z$ -plane.
- If `ZData` is a vector, then each object in `hndl` is drawn on the plane defined by the corresponding `ZData` element.
- If `ZData` is omitted, then a modal dialog box prompts for the `ZData` entry.

`zdatam('str', zdata)` identifies the objects by the input `str`, where `str` is any string recognized by `handlem`, and uses `zdata` as described above to update their `ZData` property.

This function adjusts the *z*-plane position of selected graphics objects. It accomplishes this by setting the objects' `ZData` properties to the appropriate values.

**See Also**

`handlem`, `setm`

# zero22pi

---

## Purpose

Wrap longitudes to [0 360] degree interval

---

**Note** The zero22pi function has been replaced by wrapTo360 and wrapTo2Pi.

---

## Syntax

```
newlon = zero22pi(lon)
newlon = zero22pi(lon,angleunits)
```

## Description

newlon = zero22pi(lon) *wraps* the input angle lon in degrees to the 0 to 360 degree range.

newlon = zero22pi(lon,angleunits) works in the units defined by the string *angleunits*, which can be either 'degrees' or 'radians'. *angleunits* can be abbreviated and is case-insensitive.

## Examples

```
zero22pi(567.5)
```

```
ans =
    207.5
```

```
zero22pi(-567.5)
```

```
ans =
    152.5
```

```
zero22pi(-7.5,'radian')
```

```
ans =
    5.0664
```

## See Also

wrapTo2Pi, wrapTo360



**Purpose** Construct regular data grid of 0s

**Syntax** `[Z,refvec] = zerom(latlim,lonlim,scale)`

**Description** `[Z,refvec] = zerom(latlim,lonlim,scale)` returns a full regular data grid consisting entirely of 0s and a three-element referencing vector for the returned Z. The two-element vectors `latlim` and `lonlim` define the latitude and longitude limits of the geographic region. They should be of the form `[south north]` and `[west east]`, respectively. The scalar `scale` specifies the number of rows and columns per degree of latitude and longitude.

**Examples** `[Z,refvec] = zerom([46,51],[-79,-75],1)`

```
Z =  
    0    0    0    0  
    0    0    0    0  
    0    0    0    0  
    0    0    0    0  
    0    0    0    0  
refvec =  
    1    51   -79
```

**See Also** `limitm`, `nanm`, `onem`, `sizem`, `spzerom`

# axesm, axesmui

---

**Purpose** Define map axes and modify map projection and display properties

**Activation**

Command Line	Maptool	Map Display
axesm axesmui c = axesmui(...)	Display > Projection	extend-click map display

**Description**

axesm activates a Projection Control dialog box, which allows map projection definition and property modification. If no map is currently defined, axesm creates a map axes with the Robinson projection as the default.

axesmui activates the Projection Control box for the current map axes.

c is an optional output argument that indicates whether the Projection Control dialog box was closed by the cancel button. c = 1 if the cancel button is pushed. Otherwise, c = 0.

Extend-clicking a map display brings up the Projection Control dialog box for that map axes.

## Controls

The **Map Projection** pull-down menu is used to select a map projection. The projections are listed by type, and each is preceded by a four-letter type indicator:

```

Cyln = Cylindrical
Pcyl = Pseudocylindrical
Coni = Conic
Poly = Polyconic
Pcon = Pseudoconic
Azim = Azimuthal
Mazi = Modified Azimuthal
Pazi = Pseudoazimuthal

```

The **Zone** button and edit box are used to specify the UTM or UPS zone. For non-UTM and UPS projections, the two are disabled.

The **Geoid** edit boxes and pull-down menu are used to specify the geoid. Units must be in meters for the UTM and UPS projections, since this is the standard unit for the two projections. For non-UTM and UPS

projections, the geoid unit can be anything, bearing in mind that the resulting projected data will be in the same units as the geoid.

The **Angle Units** pull-down menu is used to specify the angle units used on the map projection. All angle entries corresponding to the current map projection must be entered in these units. Current angle entries are automatically updated when new angle units are selected.

The **Map Limits** edit boxes are used to specify the extent of the map data in geographic coordinates. The **Latitude** edit boxes contain the southern and northern limits of the map. The **Longitude** edit boxes contain the western and eastern limits of the map. The map limits establish the extent of the meridian and parallel grid lines, regardless of the display settings (see grid settings). Map limits are always in geographic coordinates, regardless of the map origin and orientation setting. In the normal aspect, the map display is trimmed to the minimum of the map and frame limits.

The **Frame Limits** edit boxes are used to specify the location of the map frame, measured from the center of the map projection in the base coordinate system. The **Latitude** edit boxes contain the southern and northern frame edge locations. The **Longitude** edit boxes contain the western and eastern frame edge locations. Displayed map data are trimmed at the frame limits. For azimuthal map projections, the latitude limits should be set to `inf` and the desired trim distance from the map origin. In the normal aspect, the map display is trimmed to the minimum of the map and frame limits.

The **Map Origin** edit boxes are used to specify the origin and aspect angle of the map projection. The **Lat** and **Long** boxes specify the map origin in geographic coordinates. This is the point that is placed in the center of the projection. If either box is left blank, 0 degrees is used. The **Orientation** box specifies the azimuth angle of the North Pole relative to the map origin. Azimuth is measured clockwise from the top of the projection. If the **Orientation** box is disabled, then the selected map projection requires a fixed orientation. See the *Mapping Toolbox User's Guide* for a complete description of the map origin.

The **Cartesian Origin** edit boxes are used to specify the  $x$ - $y$  offset, along with a desired scale factor of the map projection. The **False E and N** boxes specify the false easting and northing in Cartesian coordinates. These must be in the same units as the geoid. The **Scalefactor** box specifies the scale factor used in the map projection calculations.

The **Parallels** edit boxes specify the standard parallels of the selected map projection. A particular map projection may have one or two standard parallels. If the edit boxes are disabled, then the selected projection has no standard parallels or the standard parallels are fixed.

The **Aspect** pull-down menu is used to select a normal or transverse display aspect. When the aspect is normal, *north* (on the base projection) is up, and the map is displayed in a *portrait* setting. In a transverse aspect, north (in the base projection) is to the right, and the map is displayed in a *landscape* setting. This property does not control the map projection aspect. The projection aspect is determined by the map Origin property).

The **Frame** button brings up the Map Frame Properties dialog box, which allows the map frame settings to be modified.

The **Grid** button brings up the Map Grid Properties dialog box, which allows the map grid settings to be modified.

The **Labels** button brings up the Map Label Properties dialog box, which allows the parallel and meridian label settings to be modified.

The **Fill in** button is used to compute projection and display settings based on any currently specified map parameters. Only settings that are left blank are affected when this button is pushed.

The **Reset** button is used to reset the default projection properties and display settings of the current map. Default display settings include frame, grid, and label properties set to 'off'.

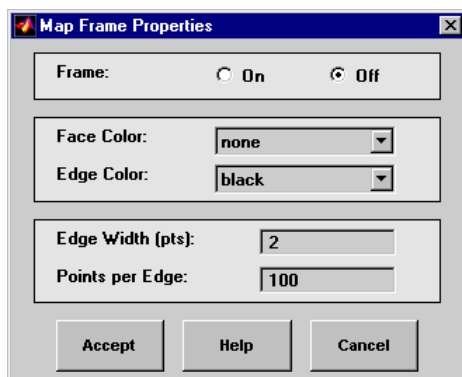
The **Apply** button is used to apply the projection and display settings to the current map, which results in the map being reprojected.

The **Help** button is used to bring up online help text for each control on the Projection Control dialog box.

The **Cancel** button disregards any modified projection or display settings and closes the Projection Control dialog box.

## Map Frame Properties Dialog Box

This dialog box allows modification of the map frame settings. It is accessed via the **Frame** button on the Projection Control dialog box.



The **Frame** selection buttons determine whether the map frame is visible.

The **Face Color** pull-down menu is used to select the background color of the map frame. Selecting **none** results in a transparent frame background, i.e., the same as the axes color. Selecting **custom** allows a custom RGB triple to be defined for the background color.

The **Edge Color** pull-down menu is used to select the color of the frame edge. Selecting **none** hides the frame edge. Selecting **custom** allows a custom RGB triple to be defined for the edge color.

The **Edge Width** edit box is used to enter the line width of the frame edge, in points.

The **Points per Edge** edit box is used to enter the number of points used to display each edge of the map frame.

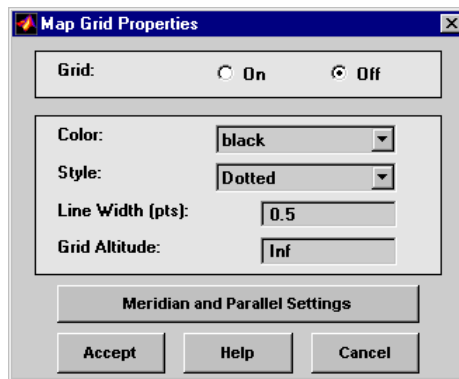
The **Accept** button accepts any modifications made to the map frame properties and returns to the Projection Control dialog box. Changes

are applied to the current map only when the **Apply** button on the Projection Control dialog box is pushed.

The **Cancel** button disregards any modifications to the map frame properties and returns to the Projection Control dialog box.

### Map Grid Properties Dialog Box

This dialog box allows modification of the map frame settings. It is accessed via the **Grid** button on the Projection Control dialog box.



The Grid selection buttons determine whether the map grid is visible.

The **Color** pull-down menu is used to select the color of the map grid lines. Selecting **custom** allows a custom RGB triple to be defined for the grid line color.

The **Style** pull-down menu is used to select the line style of the map grid lines.

The **Line Width** edit box is used to enter the width of the map grid lines, in points.

The **Grid Altitude** edit box is used to enter z-axis location of the map grid. This property can be used to place some mapped objects above or below the map grid. The default map grid altitude is `inf`, which places the grid above all other mapped objects.

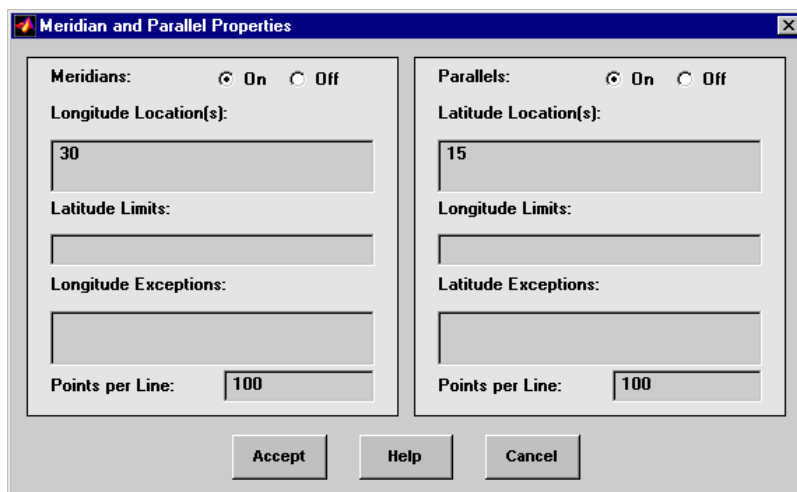
The **Meridian and Parallel Settings** button brings up the **Meridian and Parallel Properties** dialog box, which allows the properties of the meridian and parallel grid lines to be modified.

The **Accept** button accepts any modifications made to the map grid properties and returns to the Projection Control dialog box. Changes are applied to the current map only when the **Apply** button on the Projection Control dialog box is pushed.

The **Cancel** button disregards any modifications to the map grid properties and returns to the Projection Control dialog box.

## Meridian and Parallel Properties Dialog Box

This dialog box is used to modify the settings for meridian and parallel grid lines. It is accessed via the **Meridian and Parallel Settings** button on the Map Grid Properties dialog box.



The **Meridians** selection buttons determine whether the meridian grid lines are visible when the map grid is turned on.

The **Longitude Location(s)** edit box is used to specify which meridians are to be displayed if the meridian lines are turned on. If a scalar



interval value is entered, meridian lines are displayed at that interval, starting from the Prime Meridian and proceeding in east and west directions. If a vector of values is entered, meridian lines are displayed at locations given by each element of the vector.

The **Latitude Limits** edit box is used to specify the latitude limits beyond which meridian lines do not extend. If this property is left empty, all meridian lines extend to the map latitude limits (specified by the Latitude Map Limits entry on the **Projection Control** dialog box). This entry must be a two-element vector enclosed in brackets.

The **Longitude Exceptions** edit box is used to enter specific meridians of the displayed grid that are to extend beyond the latitude limits, to the map limits. This entry is a vector of longitude values.

The **Parallels** selection buttons determine whether the parallel grid lines are visible when the map grid is turned on.

The **Latitude Location(s)** edit box is used to specify which parallels are to be displayed if the parallel lines are turned on. If a scalar interval value is entered, parallel lines are displayed at that interval, starting from the Equator and proceeding in north and south directions. If a vector of values is entered, parallel lines are displayed at locations given by each element of the vector.

The **Longitude Limits** edit box is used to specify the longitude limits beyond which parallel lines do not extend. If this property is left empty, all parallel lines extend to the map longitude limits (specified by the Longitude Map Limits entry on the **Projection Control** dialog box). This entry must be a two-element vector enclosed in brackets.

The **Latitude Exceptions** edit box is used to enter specific parallels of the displayed grid that are to extend beyond the longitude limits, to the map limits. This entry is a vector of latitude values.

The **Points per Line** edit boxes are used to enter the number of points used to plot each meridian and each parallel grid line. The default value is 100 points.

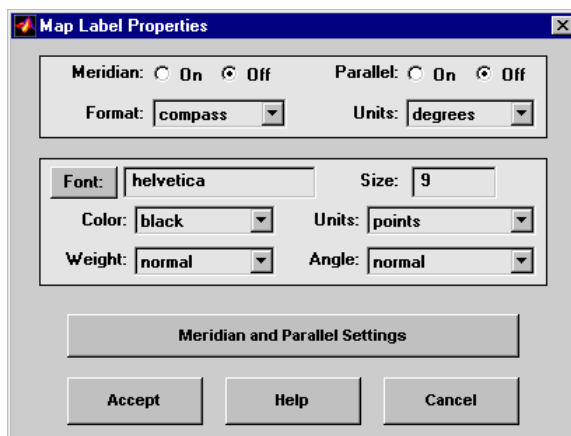
The **Accept** button accepts any modifications that have been made to the meridian and parallel grid line properties and return to the Map

Grid Properties dialog box. Changes are applied to the current map only when the **Apply** button on the Projection Control dialog box is pushed.

The **Cancel** button disregards any modifications to the meridian and parallel grid lines and returns to the Map Grid Properties dialog box.

## Map Label Properties Dialog Box

This dialog box is used to modify the settings of the meridian and parallel labels. It is accessed via the **Label** button on the Projection Control dialog box.



The **Meridian** and **Parallel** selection buttons determine whether the meridian and parallel labels are visible.

The **Format** pull-down menu is used to specify the format of the grid labels. If **compass** is selected, meridian labels are appended with E for east and W for west, and parallel labels are appended with N for north and S for south. If **signed** is chosen, meridian labels are prefixed with + for east and - for west, and parallel labels are prefixed with + for north and - for south. If **none** is selected, western meridian labels and southern parallel labels are prefixed by -, but no symbol precedes eastern meridian labels and northern parallel labels.

The label **Units** pull-down menu is used to specify the angle units used to display the parallel and meridian labels. These units, used for display purposes only, need not be the same as the angle units of the map projection.

The **Font** edit box is used to specify the character font used to display the parallel and meridian labels. If the font specified does not exist on the computer, the default of Helvetica is used. Pressing the **Font** button previews the selected font.

The font **Size** edit box is used to enter an integer value that specifies the font size of the parallel and meridian labels. This value must be in the units specified by the font **Units** pull-down menu.

The font **Color** pull-down menu is used to select the color of the parallel and meridian labels. Selecting **custom** allows a custom RGB triple to be defined for the labels.

The font **Weight** pull-down menu is used to specify the character weight of the parallel and meridian labels.

The font **Units** pull-down menu is used to specify the units used to interpret the font size entry. When set to **normalized**, the value entered in the **Size** edit box is interpreted as a fraction of the height of the axes. For example, a normalized font size of 0.1 sets the label text to a height of one tenth of the axes height.

The font **Angle** pull-down menu is used to select the character slant of the parallel and meridian labels. **normal** specifies nonitalic font. **italic** and **oblique** specify italic font.

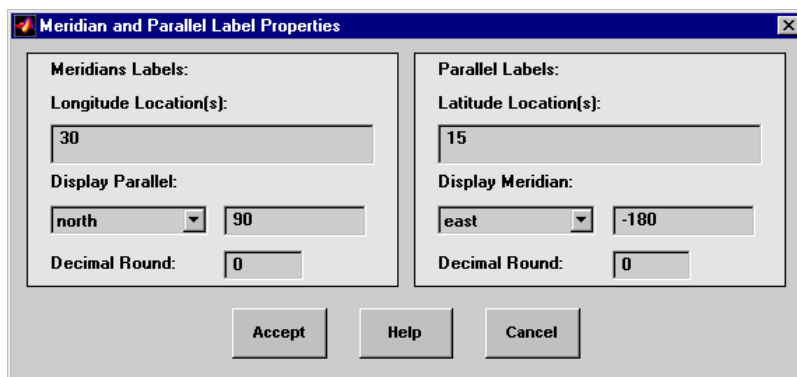
The **Meridian and Parallel Settings** button brings up the Meridian and Parallel Label Properties dialog box, which allows modification of properties specific to the meridian and parallel grid labels.

The **Accept** button accepts any modifications that have been made to the map label properties and returns to the Projection Control dialog box. Changes are applied to the current map only when the **Apply** button on the Projection Control dialog box is pushed.

The **Cancel** button disregards any modifications to the map labels and returns to the **Projection Control** dialog box.

## Meridian and Parallel Label Properties Dialog Box

This dialog box is used to modify properties specific to the meridian and parallel grid labels. It is accessed via the **Meridian and Parallel Settings** button on the Map Label Properties dialog box.



The **Longitude Location(s)** edit box is used to specify which meridians are to be labeled. Meridian labels need not coincide with displayed meridian grid lines. If a scalar interval value is entered, labels are displayed at that interval, starting from the Prime Meridian and proceeding in east and west directions. If a vector of values is entered, labels are displayed at longitude locations given by each element of the vector.

The **Display Parallel** pull-down menu and edit box are used to specify the latitude location of the meridian labels. If a scalar latitude value is provided in the edit box, the meridian labels are placed at that parallel. Alternatively, the pull-down menu can be used to select a latitude location. If north is chosen, meridian labels are placed at the maximum map latitude limit. If south is chosen, meridian labels are placed at the minimum map latitude limit.

The **Latitude Location(s)** edit box is used to specify which parallels are to be labeled. Parallel labels need not coincide with displayed parallel grid lines. If a scalar interval value is entered, labels are displayed at that interval, starting from the Equator and proceeding in north and south directions. If a vector of values is entered, labels are displayed at latitude locations given by each element of the vector.

The **Display Meridian** pull-down menu and edit box are used to specify the longitude location of the parallel labels. If a scalar longitude value is provided in the edit box, the parallel labels are placed at that meridian. Alternatively, the pull-down menu can be used to specify a longitude location. If **east** is chosen, parallel labels are placed at the maximum map longitude limit. If **west** is chosen, parallel labels are placed at the minimum map longitude limit.

The **Decimal Round** edit boxes are used to specify the power of ten to which the meridian and parallel labels are rounded. For example, a value of -1 results in labels displayed to the tenths decimal place.

The **Accept** button accepts any modifications that have been made to the meridian and parallel label properties and return to the Map Label Properties dialog box. Changes are applied to the current map only when the **Apply** button on the **Projection Control** dialog box is pushed.

The **Cancel** button disregards any modifications to the meridian and parallel labels and returns to the Map Label Properties dialog box.

The **Map Geoid** edit box is used to specify the geoid (ellipsoid) definition for the current map axes. The geoid is defined by a two-element vector of the form [semimajor-axis eccentricity]. Eccentricity must be a value between 0 and 1, but not equal to 1. A nonzero eccentricity represents an ellipsoid. The default geoid is a sphere with radius 1, represented as [1 0]. If a scalar entry is provided, it is assumed to be the radius of a sphere.

The **Accept** button accepts any modifications that have been made to the map geoid and return to the Projection Control dialog box. Changes are applied to the current map only when the **Apply** button on the Projection Control dialog box is pushed.

## axesm, axesmui

---

The **Cancel** button disregards any modifications to the map geoid and returns to the Projection Control dialog box.

### See Also

axesm

**Purpose** GUI to clear mapped objects

**Activation**

Command Line	Maptool
clmo	Tools > Delete > Object

**Description**

clmo brings up a Select Object dialog box for selecting mapped objects to delete.

**Controls**

The scroll box is used to select the desired objects from the list of mapped objects.



Pushing the **Select all** button highlights all objects in the scroll box for selection. Pushing the **OK** button deletes the selected objects from the map. Pushing the **Cancel** button aborts the operation.

**See Also**

clmo

# clrmenu

---

**Purpose** Add colormap menu to figure window

**Activation**

Command Line
clrmenu
clrmenu(h)

**Description**

clrmenu adds a colormap menu to the current figure.  
clrmenu(h) adds a colormap menu to the figure specified by the handle h.

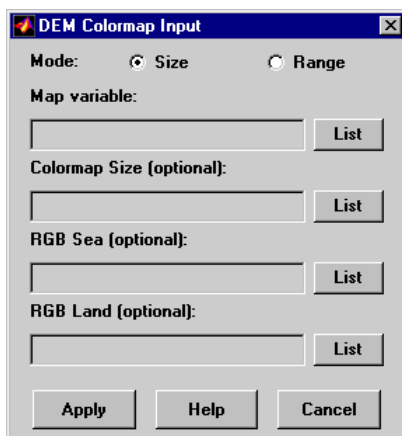
**Controls**

The following choices are included on the colormap menu:

- Gray, Hsv, Hot, Pink, Cool, Bone, Jet, Copper, Spring, Summer, Autumn, Winter, Flag, and Prism** generate colormaps.
- Rand** is a random colormap.
- Brighten** increases the brightness.
- Darken** decreases the brightness.
- Flipud** inverts the order of the colormap entries.
- Fliplr** interchanges the red and blue components.
- Permute** permutes the colormap: red > blue, blue > green, green > red.
- Spin** spins the colormap.
- Define** allows a workspace variable to be specified for the colormap.
- Remember** stores the current colormap.
- Restore** reverts to the stored colormap (initially, the stored colormap is the colormap in use when clrmenu is invoked).
- Refresh** redraws the current figure window.
- Digital Elevation** activates the DEM Color Map Input dialog box. Use it to specify a colormap for a digital elevation map, and then apply the



colormap to the current figure. The number of land and sea colors in the colormap is appropriate for the maximum elevations and depths of the data grid. The dialog box is shown and described below:



The **Mode** selection buttons are used to specify whether the length of the colormap is specified or whether the altitude range increment assigned to each color is specified.

The **Map variable** edit box is used to specify the data grid containing the elevation data.

The **Color Map Size** edit box is used in Size mode. This entry defines the length of the colormap. If omitted, a default length of 64 is used. This entry must be a scalar value.

The **Altitude Range** edit box is used in Range mode. This entry defines the altitude range increment assigned to each color. If omitted, a default increment of 100 is used. This entry must be a scalar value.

The **RGB Sea** edit box is used to define colors for data with negative values. The actual sea colors of the generated colormap are interpolated from this matrix. This entry can be a matrix of any length (n by 3). The colormap matrix of the current figure can be used by entering the string 'window' in this box. The demcmap function provides default sea colors, which are used if this entry is left blank.

The **RGB Land** edit box is used to define colors for data with positive values. The actual land colors of the generated colormap are interpolated from this matrix. This entry can be a matrix of any length (n by 3). The colormap matrix of the current figure can be used by entering the string 'window' in this box. The `demcmap` function provides default sea colors, which are used if this entry is left blank.

Pressing the **Apply** button accepts the input data, creates the colormap, and assigns it to the current figure.

Pressing the **Cancel** button disregards any input data and closes the DEM Color Map Input dialog box.

## See Also

`colorm`, `demcmap`

**Purpose** Create index map colormaps

**Activation**

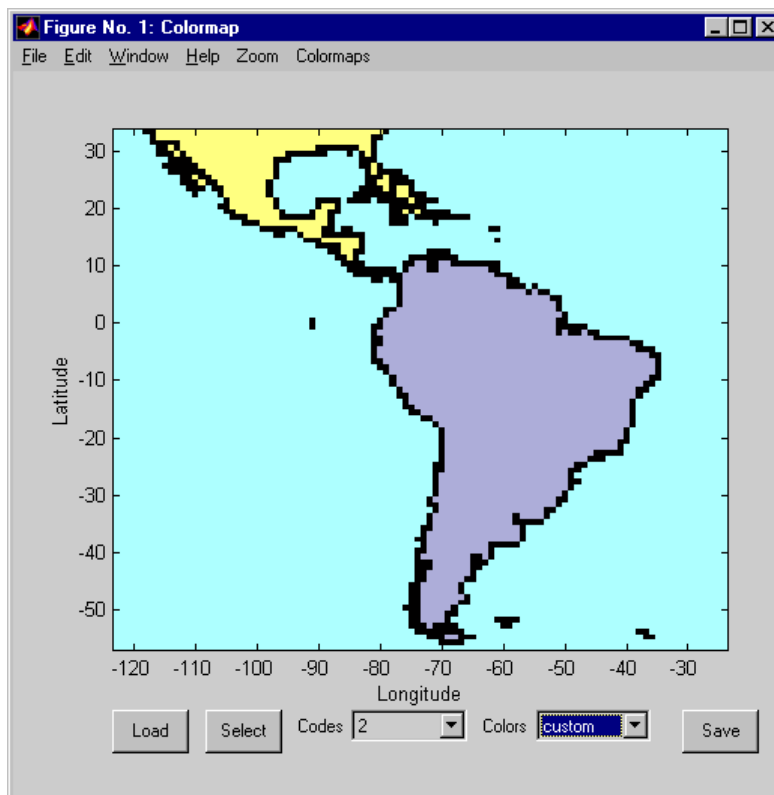
**Command Line**

```
colorm(datagrid,refvec)
```

**Description**

colorm(datagrid,refvec) displays the data grid in a new figure window and allows a colormap to be edited and saved to a new variable. datagrid and refvec are the data grid and the referencing vector of the surface. map must have positive index values into the colormap.

## Controls



The `colorm` tool displays the surface map data in a new figure window with the current colormap. **Zoom** and **Colormaps** menus are activated for that figure.

The **Zoom On/Off** menu toggles the panzoom box on and off. The box can be moved by clicking the new location or by dragging the box to the new location. The box size can be increased or decreased by dragging a corner of the box. Pressing the Return key or double-clicking in the center of the box zooms in.

The **Colormaps** menu provided a variety of colormap options that can be applied to the map. See `clrmenu` in this guide for a description of the **Colormaps** menu options.

The **Load** button activates a dialog box, used to specify a colormap variable to be applied to the displayed surface map. This colormap can then be edited and saved.

The **Select** button activates the mouse cursor and allows a point on the map to be selected. The value of that point then appears in the **Codes** pull-down menu. The color of the selected point appears in the **Color** pull-down menu and can then be edited.

The **Codes** pull-down menu is used to select a particular value in the data grid. The color associated with that value then appears in the **Color** pull-down menu and can be edited.

The **Color** pull-down menu is used to select a particular color to assign to the value currently displayed in the **Codes** pull-down menu. A custom color can be defined by selecting the `custom` option. This brings up a custom color interface with which an RGB triple can be selected.

The **Save** button is used to save the modified colormap to the workspace. A dialog box appears in which the colormap variable name is entered.

## See Also

`encodem`, `getseeds`, `maptrim`, `panzoom`, `seedm`

# demdataui

---

**Purpose** UI for selecting digital elevation data

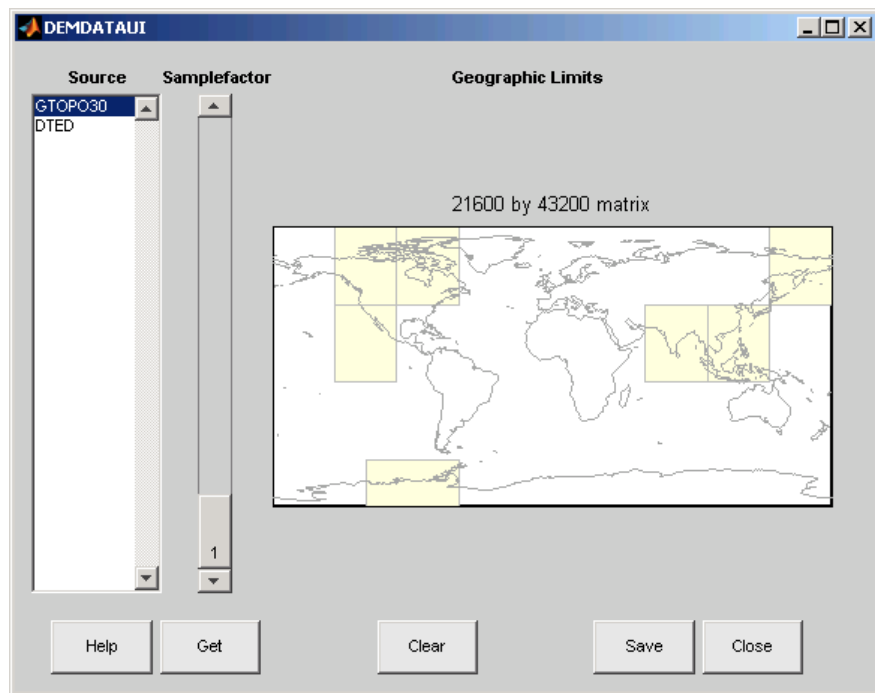
**Activation** demdataui

**Description** demdataui is a graphical user interface to extract digital elevation map data from a number of external data files. You can extract data to MAT-files or the base workspace as regular data grids with referencing vectors.

The demdataui panel lets you read data from a variety of high-resolution digital elevation maps (DEMs). These DEMs range in resolution from about 10 kilometers to 100 meters or less. The data files are available over the Internet at no cost, or (in some cases) on CD-ROMs for varying fees. demdataui reads ETOPO5, TerrainBase, GTOPO30, GLOBE, satellite bathymetry, and DTED data. See the links under See Also for more information on these data sets. demdataui looks for these geospatial data files on the MATLAB path and, for some operating systems, on CD-ROM disks.

You use the list to select the source of data and the map to select the region of interest. When you click the **Get** button, data is extracted and displayed on the map. Use the **Save** button to save the data in a MAT-file or to the base workspace for later display. The **Close** button closes the window.

## Controls



### The Map

The map controls the geographic extent of the data to be extracted. demdataui extracts data for areas currently visible on the map. Use the mouse to zoom in or out to the area of interest. See `zoom` for more on zooming.

Some data sources divide the world up into tiles. When extracting, data is concatenated across all visible tiles. The map shows the tiles in light yellow with light gray edges. When data resolution is high, extracting data for large area can take much time and memory. An approximate count of the number of points is shown above the map. Use the **Samplefactor** slider to reduce the amount of data.

## The List

The list controls the source of data to be extracted. Click a name to see the geographic coverage in light yellow. The sources list shows the data sources found when demdataui started.

demdataui searches for data files on the MATLAB path. On some computers, demdataui also checks for data files on the root level of letter drives. demdataui looks for the following data: etopo5: new\_etopo5.bil or etopo5.northern.bat and etopo5.southern.bat files. tbase: tbase.bin file. satbath: topo\_6.2.img file. gtopo30: a directory that contains subdirectories with the data files. For example, demdataui would detect gtopo30 data if a directory on the path contained the directories E060S10 and E100S10, each of which holds the uncompressed data files. globedem: a directory that contains data files and in the subdirectory /esri/hdr and the \*.hdr header files. dted: a directory that has a subdirectory named DTED. The contents of the DTED directory are more subdirectories organized by longitude and, below that, the DTED data files for each latitude tile. See the help for functions with the data source names for more on the data attributes and internet locations.

## The Samplefactor Slider

The **Sample Factor** slider allows you to reduce the density of the data. A sample factor of 2 returns every second point. The current sample factor is shown on the slider.

## The Get Button

The **Get** button reads the currently selected data and displays it on the map. Press the standard interrupt key combination for your platform to interrupt the process.

## The Clear Button

The **Clear** button removes any previously read data from the map.

## The Save Button

The **Save** button saves the currently displayed data to a MAT-file or the base workspace. If you choose to save to a file, you will be prompted for



a file name and location. If you choose to save to the base workspace, you can choose the variable name under which the data will be stored.

Data are returned as Mapping Toolbox Version 1 display structures. For information about display structure format, see “Version 1 Display Structures” on page 3-144 in the reference page for `displaym`.

Use `load` and `displaym` to redisplay the data from a file on a map axes. To display the data in the base workspace, use `displaym`. To gain access to the data matrices, subscript into the structure (for example, `datagrid = demdata(1).map; refvec = demdata(1).maplegend`). Use `worldmap` to create easy displays of the elevation data (for example, `worldmap(datagrid,refvec)`). Use `meshm` to add regular data grids to existing displays, or `surfm` or a similar function for geolocated data grids (for example, `meshm(datagrid,refvec)` or `surfm(latgrat,longrat,z)`).

### **The Close Button**

The **Close** button closes the `demdataui` panel.

### **See Also**

`etopo`, `tbase`, `gtopo30`, `globedem`, `dted`, `satbath`, `vmap0ui`

# handlem-ui

---

**Purpose** GUI for handles of specified mapped objects

**Activation**

**Command Line**

```
h = handlem
```

```
h = handlem('prompt')
```

**Description**

h = handlem brings up a Select Object dialog box, which lists all currently displayed objects. Objects can be selected and their handles returned.

h = handlem('prompt') brings up a Specify Object dialog box, which allows greater control of object selection.

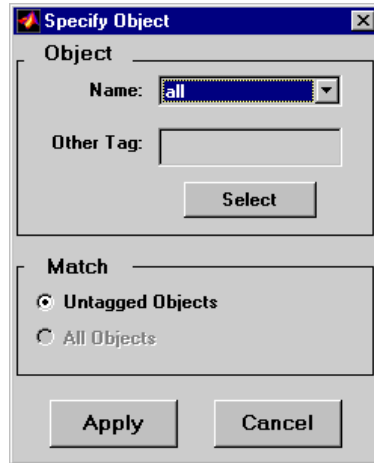
**Controls**

Select Object Dialog Box



The scroll box is used to select the desired objects from the list of mapped objects. Pushing the **Select all** button highlights all objects in the scroll box for selection. Pushing the **OK** button returns the object handles in the variable h. Pushing the **Cancel** button aborts the operation.

## Specify Object Dialog Box



The **Object** Controls are used to select an object type or tag. The **Name** pull-down menu is used to select from a list of predefined object strings. The **Other Tag** edit box is used to specify an object tag not listed in the **Name** pull-down menu. Pushing the **Select** button brings up the Select Object dialog box, which shows only the currently displayed objects for selection.

The **Match** Controls are used when a Handle Graphics object type (image, line, surface, patch, or text) is specified. The **Untagged Objects** selection button is used to return the handles of only those objects with empty tag properties. The **All Objects** selection button is used to return all object handles of the specified type, regardless of whether they are tagged.

Pushing the **Apply** button returns the handles of the specified objects. Pushing the **Cancel** button aborts the operation.

### See Also

handlem

# hidem-ui

---

**Purpose** Hide specified mapped objects

**Activation**

Command Line	Maptool
hidem	Tools > Hide > Object

**Description**

hidem brings up a Select Object dialog box for selecting mapped objects to hide (`Visible` property set to 'off').

**Controls**



The scroll box is used to select the desired objects from the list of mapped objects. Pushing the **Select all** button highlights all objects in the scroll box for selection. Pushing the **OK** button changes the `Visible` property of the selected objects to 'off'. Pushing the **Cancel** button aborts the operation without changing any properties of the selected objects.

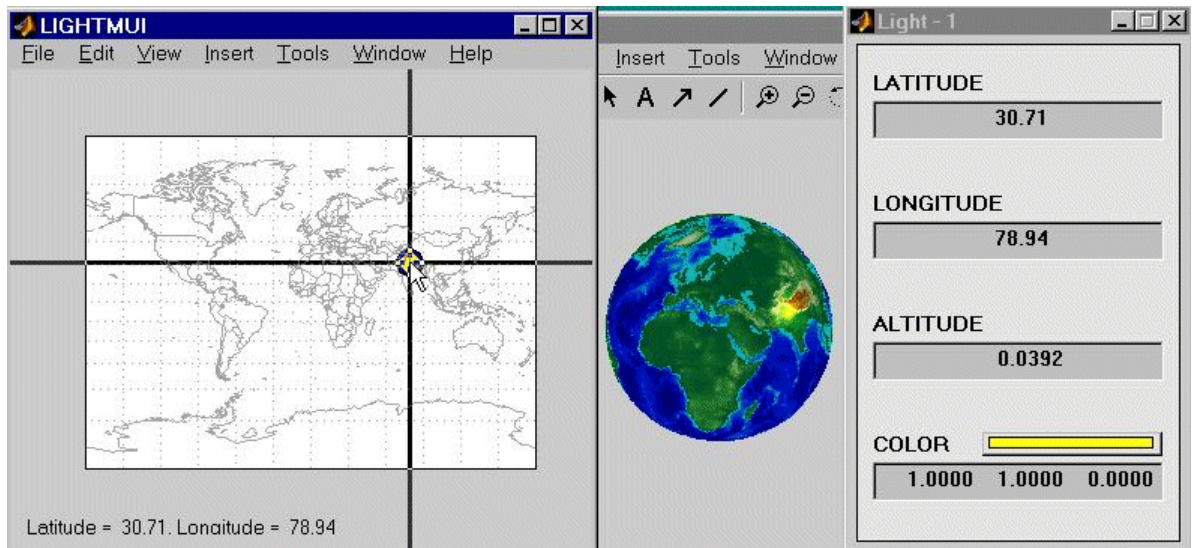
**See Also**

hidem

**Purpose** Control position of lights on globe or 3-D map

**Syntax** `lightmui(hax)`

**Description** `lightmui(hax)` creates a GUI to control the position of lights on a globe or 3-D map in map axes `hax`. You can control the position of lights by clicking and dragging the icon or by dialog boxes. Right-click the appropriate icon in the GUI to invoke the corresponding dialog box. You can change the light color by entering the RGB components manually or by clicking the pushbutton.



**See Also** `lightm`

# maptool

---

**Purpose** Add menu activated tools to map figure

## Activation

### Command Line

```
maptool(PropertyName,PropertyValue)
```

```
maptool(ProjectionFile,...)
```

```
h = maptool(...)
```

## Description

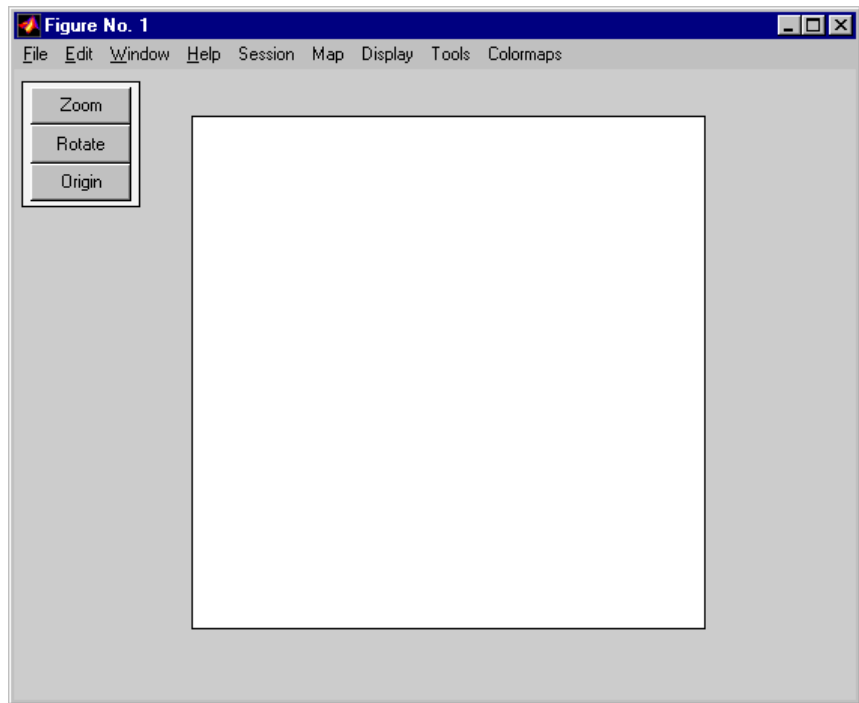
maptool creates a figure window with a map axes and activates the Projection Control dialog box for defining map projection and display properties. The figure window features a special menu bar that provides access to most of Mapping Toolbox GUIs.

maptool(*PropertyName*,*PropertyValue*,...) creates a figure window with a map axes defined by the supplied map properties. The MapProjection property must be the first input pair. maptool supports the same map properties as axesm.

maptool(*ProjectionFile*,*PropertyName*, *PropertyValue*,...) allows for the omission of the MapProjection property name. *ProjectionFile* must be the identifying string of an available map projection.

h = maptool(...) returns a two-element vector containing the handle of the maptool figure window and the handle of the map axes.

## Controls



### Session Menu

The **Load** option is used to load workspace data. Select from the workspace names provided, or use the **Specify Workspace** option to enter a different workspace.

The **Layers** option is used to load a map layers workspace and activate the `mLayers` tool. Select from the workspace names provided, or use the **Other** option to enter a different workspace. Choosing **Workspace** loads all structure variables in the current workspace.

The **Renderer** option is used to set the renderer for the maptool figure window. The Figure Renderer dialog box is activated when this option is selected.

The **Variables** option is used to view the current workspace variables.

The **Command** option brings up the Workspace Commands dialog box for entering commands to operate on the current workspace.

The **Clear** option is used to clear variables and functions from memory.

## **Map Menu**

The **Lines** option activates the Line Map Input dialog box for projecting two- and three-dimensional line objects onto the map axes.

The **Patches** option activates the Patch Map Input dialog box for projecting patch objects onto the map axes.

The **Regular Surfaces** option activates the Mesh Map Input dialog box for projecting a regular data grid onto a graticule projected onto the map axes.

The **General Surfaces** option activates the Surface Map Input dialog box for projecting a geolocated data grid onto the map axes.

The **Comet** option activates the Comet Map Input dialog box for a projecting two- or three-dimensional comet plot onto the map axes.

The **Contours** option activates the Contour Map Input dialog box for projecting a two- or three-dimensional contour plot onto the map axes.

The **Quiver 2D** option activates the Quiver Map Input dialog box for projecting a two-dimensional quiver plot onto the map axes.

The **Quiver 3D** option activates the Quiver3 Map Input dialog box for projecting a three-dimensional quiver plot onto the map axes.

The **Stem** option activates the Stem Map Input dialog box for projecting a stem plot onto the map axes.

The **Scatter** option activates the Scatter Map Input dialog box for projecting a scatter plot onto the map axes.

The **Text** option activates the Text Map Input dialog box for projecting text objects onto the map axes.

The **Light** option activates the Light Map Input dialog box for projecting light objects onto the map axes.



## Display Menu

The **Projection** option activates the Projection Control dialog box for editing map projection properties and map display settings.

The **Graticule** option is used to view and edit the graticule size for surface maps.

The **Legend** option is used to display a contour map legend.

The **Frame** option is used to toggle the map frame on and off.

The **Grid** option is used to toggle the map grid on and off.

The **Meridian Labels** option is used to toggle the meridian grid labels on and off.

The **Parallel Labels** option is used to toggle the parallel grid labels on and off.

The **Tracks** option activates the Define Tracks input box for calculating and displaying Great Circle and Rhumb Line tracks on the map axes.

The **Small Circles** option activates the Define Small Circles input box for calculating and displaying small circles on the map axes.

The **Surface Distances** option activates the Surface Distance dialog box for distance, azimuth, and reckoning calculations.

## Tools Menu

The **Hide** option is used to hide the mouse tool buttons.

The **Off** option is used to turn off the current mouse tool.

The **Zoom Tool** option is used to toggle Panzoom (panzoom) mode on and off. It is used for zooming in on a two-dimensional map display.

The **Set Limits** option is used to define the zoom out limits to the current settings on the axes.

The **Full View** option is used to zoom out to the current axes limit settings.

The **Rotate** option is used to toggle Rotate 3-D (`rotate3d`) mode on and off. Rotate 3-D mode is used to interactively rotate the view of a three-dimensional plot.

The **Origin** option is used to toggle Origin (`originui`) mode on and off. Origin mode is used to interactively modify the map origin.

The **2D View** option is used to set the default two-dimensional view (`azimuth=0`, `elevation=90`).

The **Objects** option activates the Object Sets dialog box, which allows for property manipulation of objects displayed on the map axes.

The **Edit** option activates the MATLAB Property Editor to manipulate properties of a plotted object. Choose from the **Current Object** or **Last Object** options, or choose the **Object** option to activate the Select Object dialog box.

The **Show** option is used to set the `Visible` property of mapped objects to 'on'. The **All** option shows all currently mapped objects. The **Object** option activates the Select Object dialog box.

The **Hide** option is used to set the `Visible` property of mapped objects to 'off'. Choose from the **All** or **Map** options, or choose the **Object** option to activate the Select Object dialog box.

The **Delete** option is used to clear the selected objects. The **All** option clears the current map, frame, and grid lines. The map definition is left in the axes definition. The **Map** option clears the current map, deleting objects plotted on the map but leaving the frame and grid lines displayed. The **Object** option activates the Select Object dialog box.

The **Axes** option is used to manipulate the MATLAB Cartesian axes. The **Show** option shows this axes, the **Hide** option hides this axes, and the **Color** option allows for custom color selection for this axes.

## Colormaps Menu

The **Colormaps** menu allows for manipulation of the colormap for the current figure. See the `clrmenu` reference page for details on the **Colormaps** menu options.

The **Zoom** button toggles Zoom mode on and off. Zoom mode is used for zooming in on a two-dimensional map display.

The **Rotate** button toggles Rotate 3-D mode on and off. Rotate 3-D mode is used to interactively rotate the view of a three-dimensional plot.

The **Origin** button toggles Origin mode on and off. Origin mode is used to interactively modify the map origin.

## See Also

`axesm`

# maptrim

---

**Purpose** Interactively trim and convert map data from vector to raster format

## Activation

### Command Line

```
maptrim(lat,lon)
maptrim(lat,lon,linespec)
maptrim(datagrid,refvec)
maptrim(datagrid,refvec,PropertyName,PropertyValue,...)
```

## Description

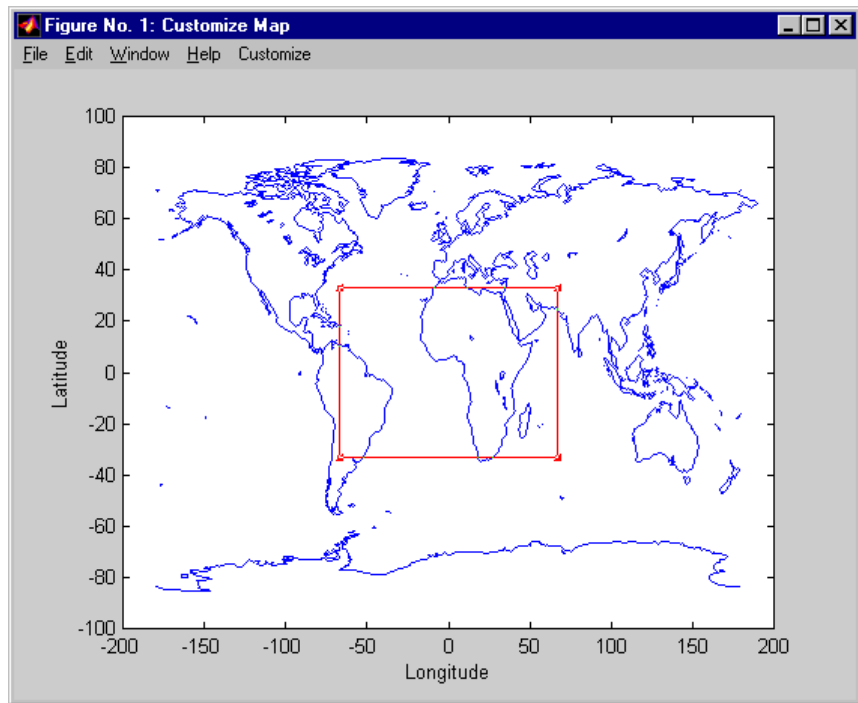
`maptrim(lat,lon)` displays the supplied map data in a new figure window and allows a region of the map to be selected and saved in the workspace. `lat` and `lon` must be vector map data. The output can be line, patch, or regular surface (matrix) data. If patch map output is selected, the inputs `lat` and `lon` must originally be patch map data.

`maptrim(lat,lon,linespec)` displays the supplied map data using the *linespec* string.

`maptrim(datagrid,refvec)` displays data grid data in a new figure window and allows a subset of this map to be selected and saved. The output is regular surface data.

`maptrim(datagrid,refvec,PropertyName,PropertyValue)` displays the data grid using the surface properties provided. The object `Tag`, `EdgeColor`, and `UserData` properties cannot be set.

## Controls

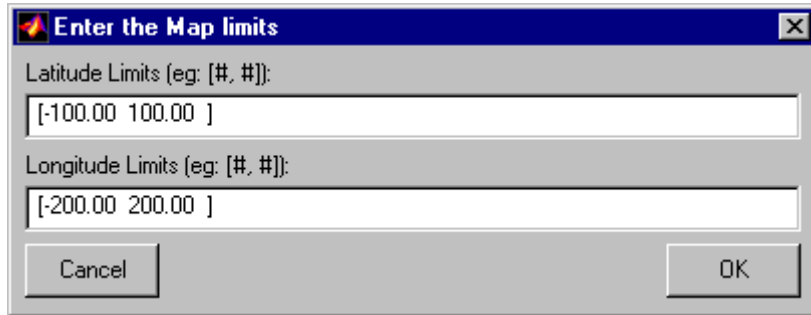


The `maptrim` tool displays the supplied map data in a new figure window and activates a **Customize** menu for that figure. The **Customize** menu has three menu options: **Zoom On/Off**, **Limits**, and **Save As**.

The **Zoom On/Off** menu option toggles the panzoom box on and off. The box can be moved by clicking the new location or by dragging the box to the new location. The box size can be increased or decreased by dragging a corner of the box. Pressing the **Return** key or double-clicking in the center of the box zooms in.

The **Limits** menu option activates the Enter Map Limits dialog box, which is used to enter the latitude and longitude limits of the desired map subset. These entries are two-element vectors, enclosed in brackets. Pressing the **OK** button zooms in to the new limits. Pressing

the **Cancel** button disregards the new limits and returns to the map display.



The **Save As** menu option is used to specify the variable names in which to save the map data subset. To save line and patch data, enter the new latitude and longitude variable names, along with the map resolution. For surface data, enter the new map and referencing vector variable names, along with the scale of the map. Latitude and longitude limits are optional.

## See Also

maptrim1, maptrimp, maptrims, panzoom

**Purpose** GUI to control plotting of display structure elements

**Activation**

Command Line	Maptool
<code>mayers('filename')</code>	Session > Layers
<code>mayers('filename',h)</code>	
<code>mayers(cellarray)</code>	
<code>mayers(cellarray,h)</code>	

**Description**

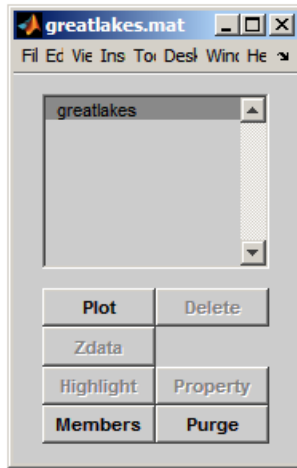
`mayers('filename')` associates all display structures, which in this context are also called map layers, in the MAT-file `filename` with the current map axes. The display structure variables are accessible only through the `mayers` tool, and not through the base workspace. `filename` must be a string.

`mayers('filename',h)` assigns the layers found in `filename` to the map axes indicated by the handle `h`.

`mayers(cellarray)` associates the layers specified by `cellarray` with the current map axes. `cellarray` must be of size `n` by 2. Each row of `cellarray` represents a map layer. The first column of `cellarray` contains the layer structure, and the second column contains the name of the layer structure. Such a cell array can be generated from data in the current workspace with the function `rootlayr`. In this case, the calling sequence would be `rootlayr; mayers(ans)`.

`mayers(cellarray,h)` assigns the layers specified by `cellarray` to the map axes specified by the handle `h`.

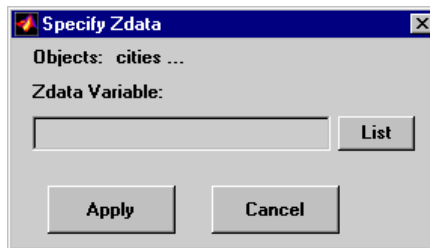
## Controls



The scrollable list box displays all of the map layers currently associated with the map axes. An asterisk next to the layer name indicates that the layer is currently visible. An h next to the layer name indicates a layer that is plotted, but currently hidden.

The **Plot** button plots the selected map layer. Once the selected layer is plotted, the button toggles between **Hide** and **Show**, to turn the **Visible** property of the plotted objects to 'off' and 'on', respectively.

The **Zdata** button activates the Specify Zdata dialog box, which is used to enter the workspace variable containing the ZData for the selected map layer. Pressing the **List** button produces a list of all current workspace variables, from which the ZData variable can be selected. This entry can also be a scalar.



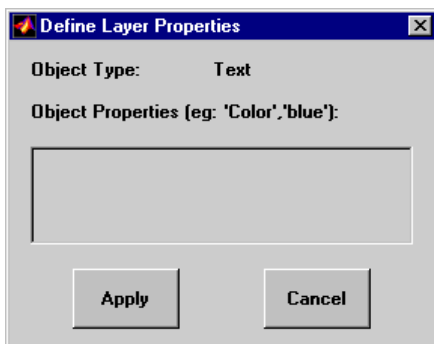


The **Highlight** button is used to toggle the selected map layer between highlighted and normal display.

The **Members** button brings up a list of members of the selected map layer. Members of a layer are defined by their **Tag** property.

The **Delete** button deletes the selected map layer from the map.

The **Property** button activates the Define Layer Properties dialog box, which is used to specify or change properties of all objects in the selected map layer. String entries must be enclosed in single quotes.



The **Purge** button deletes the selected map layer from the `mlayers` tool. Selecting **Yes** from the Confirm Purge dialog box deletes the map layer from both the `mlayers` tool and the map display. Selecting **Data Only** from the Confirm Purge dialog box deletes the map layer from the `mlayers` tool, while retaining the plotted object on the map display.

## See Also

`mobjects`, `rootlayer`

# objects

**Purpose** Manipulate object sets displayed on map axes

**Activation**

Command Line	Maptool
objects	Tools > Objects
objects(h)	

**Description**

An object set is defined as all objects with identical tags. If no tags are supplied, object sets are defined by object type.

objects allows manipulation of the object sets on the current map axes.

objects(h) allows manipulation of the objects set on the map axes specified by the handle h.

**Controls**

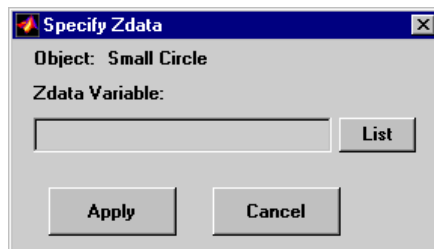


The scrollable list box displays all of the object sets associated with the map axes. An asterisk next to an object set name indicates that the object set is currently visible. An h next to an object set name indicates

an object set that is plotted, but currently hidden. The order shown in the list indicates the stacking order of objects within the same plane.

The **Hide/Show** button toggles the `Visible` property of the selected object set to 'off' and 'on', respectively, depending on the current `Visible` status.

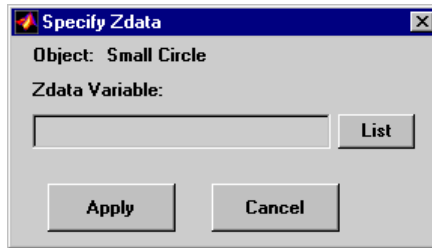
The **Zdata** button activates the Specify Zdata dialog box, which is used to enter the workspace variable containing the ZData. The ZData property is used to specify the plane in which the selected object set is drawn. Pressing the **List** button produces a list of all current workspace variables, from which the ZData variable can be selected. Alternatively, a scalar value can be entered instead of a variable.



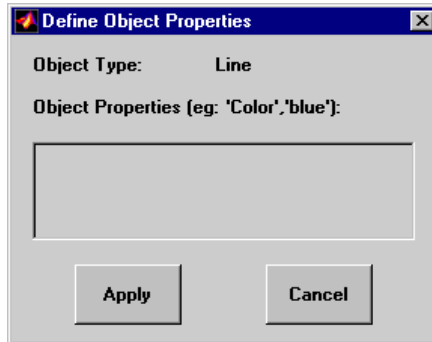
The **Highlight** button highlights all objects belonging to the selected object set.

The **Tag** button brings up an Edit Tag dialog box, which allows the tag of all members of the selected object set to be modified.

The **Delete** button clears all objects belonging to the selected object set from the map. The cleared object set remains associated with the map axes.



The **Property** button activates the Define Object Properties dialog box, which is used to specify additional properties of all objects in the selected object set. String entries must be enclosed in single quotes.



The **Update** button updates the list box display with current objects sets.

The **Stacking Order** buttons are used to modify the drawing order of the selected object set in relation to other plotted object sets in the same plane. Objects drawn first appear at the bottom of the stack, and objects drawn last appear at the top of the stack. The **Top** button places the selected object set above all other object sets in its plane. The **Up** and **Dwn** buttons move the selected object set up and down one place in the stacking order, respectively. The **Btm** button places the selected object set below all other object sets in its plane. Note that the ZData property overrides stacking order, i.e., if an object is at the top of the stacking order for its plane, it can still be covered by an object drawn in a higher plane.

**See Also**

`mlayers`

# originui

---

**Purpose** Interactively modify map origin

**Activation**

Command Line	Maptool
originui	Tools > Origin (menu) > Origin(button)
originui on	
originui off	

**Description**

originui provides a tool to modify the origin of a displayed map projection. A marker (dot) is displayed where the origin is currently located. This dot can be moved and the map reprojected with the identified point as the new origin.

originui automatically toggles the current axes into a mode where only actions recognized by originui are executed. Upon exit of this mode, all prior ButtonDown functions are restored to the current axes and its children.

originui on activates origin tool. originui off e-activates the tool. originui will toggle between these two states.

**Controls**

**Keystrokes**

originui recognizes the following keystrokes. **Enter** (or **Return**) will reproject the map with the identified origin and remain in the originui mode. **Delete** and **Escape** will exit the origin mode (same as originui off). **N,S,E,W** keys move the marker North, South, East or West by 10.0 degrees for each keystroke. **n,s,e,w** keys move the marker in the respective directions by 1 degree per keystroke.

**Mouse Actions**

originui recognizes the following mouse actions when the cursor is on the origin marker.

- Single-click and hold moves the origin marker. Double-click the marker reprojects the map with the specified map origin and remains in the origin mode (same as originui **Return**).
- Extended-click moves the marker along the Cartesian X or Y direction only (depending on the direction of greatest movement).
- Alternate-click exits the origin tool (same as originui **off**).

## Macintosh Key Mapping

- Extend-click: **Shift**+click mouse button
- Alternate-click: **Option**+click mouse button

## Microsoft Windows Key Mapping

- Extend-click: **Shift**+click left button or both buttons
- Alternate-click: **Ctrl**+click left button or right button

## X-Windows Key Mapping

- Extend-click: **Shift**+click left button or middle button
- Alternate-click: **Ctrl**+click left button or right button

## See Also

axesm, setm

# panzoom

---

**Purpose** Pan and zoom on map axes

**Activation**

Command Line	Maptool
panzoom	Tools > Zoom Tool (menu) > Zoom (button)
panzoom on	
panzoom off	
panzoom setlimits	
panzoom out	
panzoom fullview	

**Description**

panzoom toggles the pan and zoom tool on and off.

panzoom on activates the pan and zoom tool.

panzoom off deactivates the pan and zoom tool.

panzoom setlimits sets the zoom out limits to the current settings on the map axes.

panzoom out zooms out to the current map axes limit settings.

panzoom fullview resets the axes to their full view range and resets the pan and zoom tool with these settings.

The pan and zoom tool provides an interactive means of defining zoom limits on a two-dimensional map display. A box that can be resized and moved appears on the map display and is used to define the zoom area. The box cannot be moved beyond the current axes limits.

**Controls**

**Mouse Interaction**

With the cursor inside the zoom box, a single-click and drag moves the box. The zoom box can be resized by dragging the corners of the box. A double-click in the center of the box zooms in to the current boundaries of the box. A single-click outside the zoom box moves the box to that



location. An extend-click inside or outside of the zoom box zooms out by a factor of two. Alternate-click exits the pan and zoom tool.

### **Keyboard Interaction**

The following keyboard interaction is enabled if the figure containing the map axes is made the active window.

Pressing the **Return** key sets the axes to the current zoom box and remains in pan and zoom mode. The **Enter** key sets the axes to the current zoom box and exits pan and zoom mode. Pressing the **Esc** or **Delete** keys exits pan and zoom mode.

### **See Also**

zoom

# parallelui

---

**Purpose** Interactively modify map parallels

## Activation

Command Line	Maptool
<code>parallelui</code>	Tools > Parallels (menu)
<code>parallelui on</code>	
<code>parallelui off</code>	

## Description

`parallelui` toggles the parallel tool on and off.

`parallelui on` activates the parallel tool

`parallelui off` deactivates the parallel tool

The `parallelui` GUI provides a tool to modify the standard parallels of a displayed map projection. One or two red lines are displayed where the standard parallels are currently located. The parallel lines can be dragged to new locations, and the map reprojected with the locations of the parallel lines as the new standard parallels.

## Controls

Mouse Interaction

A single-click-and-drag moves the parallel lines. A double-click on one of the standard parallels reprojects the map using the new parallel locations.

## See Also

`axesm`, `setm`

## Purpose

GUIs to edit properties of mapped objects

## Activation

map display: Alternate-click mapped object (for Click-and-Drag Property Editor)

In plot edit mode, double-click mapped object (to obtain MATLAB Property Editor; click the **More Properties...** button to open the Property Inspector)

maptool: **Tools > Edit Plot** menu item (for MATLAB Property Editor)

## Description

Alternate (e.g., **Ctrl**+clicking a mapped object activates a property editor, which allows modification of some basic properties of the object through simple mouse clicks and drags. The objects supported by this editor are map axes, lines, text, patches, and surfaces, and the properties supported for each object type are shown below.

In plot edit mode, double-clicking a mapped object activates the MATLAB Property Editor for that object. From the Property Editor you can launch the Property Inspector, a GUI that lists the properties and values of the selected object and allows you to modify them.

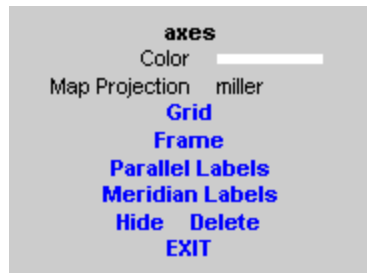
## Controls

### Click-and-Drag Property Editor

The Click-and-Drag editor lists object properties and values. The object tag appears at the top of the editor. Property names and values that appear in blue are toggles. For example, clicking **Frame** in the axes editor toggles the value of the Frame property between 'on' and 'off'.

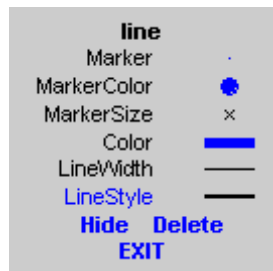
# property editors

---



## Click-and-Drag Editor for a map axes

Property values that appear on the right side of the editor box are modified by clicking and dragging. For example, to change the **MarkerColor** property of a line object, click and hold the dot next to **MarkerColor**, and drag the cursor until the dot appears in the desired color.



## Click-and-Drag Editor for a line object

The **Drag** control in the text editor is used to reposition the text string. In drag mode, use the mouse to move the text to a new location, and click to reposition the text. The **Edit** control in the text editor activates a **Text Edit** window, which is used to modify text.



## Click-and-Drag Editor for a text object

The **Marker** property name in the patch editor is used to toggle the marker on and off. The property value to the right of **Marker** can be modified by clicking and dragging until the desired marker symbol appears.



## Click-and-Drag Editor for a patch object

The **Graticule** control on the surface editor activates a Graticule Mesh dialog box, which is used to alter the size of the graticule.

To move the property editor around the figure window, hold down the **Shift** key while dragging the editor box. Alternate-clicking the background of the property editor closes the **Click-and-Drag** editing session.

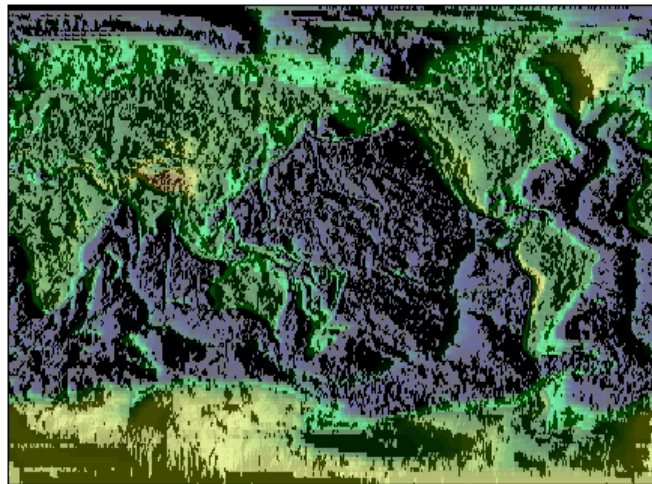
## Guide Property Editor

The MATLAB Property Inspector (the `inspect` function) allows you to view and modify property values for most properties of the selected

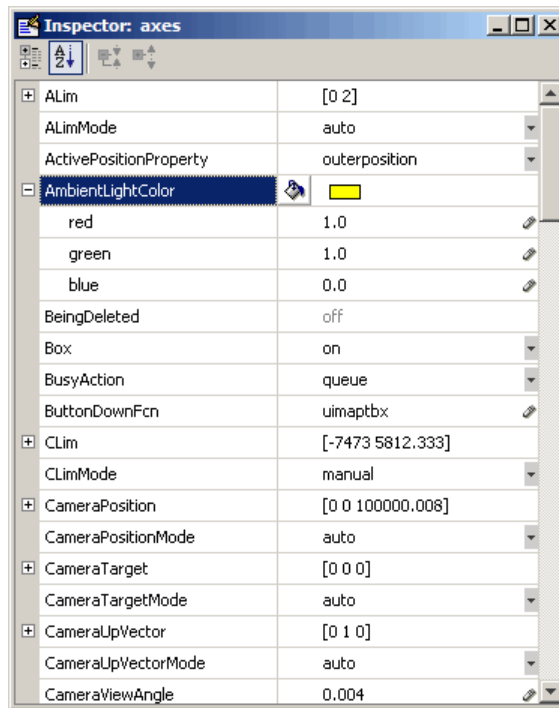
# property editors

---

object. Use it to expand and collapse the hierarchy of objects, showing an object's parents and children. A plus sign (+) before a property indicates that it can be expanded to show its components, for example the axes `AmbientLightColor` applied to the surface object displayed below. A minus sign (-) before an object indicates an object can be collapsed to hide its components. To activate the Object Browser, check the **Show Object Browser** check box. The **Property List** shows all the property names of the selected object and their current values. To activate the **Property List**, check the **Show Property List** check box. To change a property value, use the edit boxes above the Property List. Pressing the **Close** button closes the Guide Property Editor and applies the property modifications to the object.



**A lit surface object in a map axes**



## Property Inspector view of axes object

**See Also** `propedit`, `inspect`, `uimaptbx`

**Purpose** GUI to interactively perform data queries

## Activation

### Command Line

```
qrydata(cellarray)
qrydata(titlestr,cellarray)
qrydata(h,cellarray)
qrydata(h,titlestr,cellarray)
qrydata(...,cellarray1,cellarray2,...)
```

## Description

A data query is used to obtain the data corresponding to a particular (x,y) or (lat,lon) point on a standard or map axes.

`qrydata(cellarray)` activates a data query dialog box for interactive queries of the data set specified by `cellarray` (described below).

`qrydata` can be used on a standard axes or a map axes. (x,y) or (lat,lon) coordinates are entered in the dialog box, and the data corresponding to these coordinates is then displayed.

`qrydata(titlestr,cellarray)` uses the string `titlestr` as the title of the query dialog box.

`qrydata(h,cellarray)` and `qrydata(h,titlestr,cellarray)` associate the data queries with the axes specified by the handle `h`, which in turn allows the input coordinates to be specified by clicking the axes.

The input `cellarray` is used to define the data set and the query. The first cell must contain the string used to label the data display line. The second cell must contain the type of query operation, either a predefined operation or a valid user-defined function name. This input must be a string. The predefined query operations are 'matrix', 'vector', 'mapmatrix', and 'mapvector'.

The 'matrix' query uses the MATLAB `interp2` function to find the value of the matrix `Z` at the input (x,y) point. The format of the `cellarray` input for this query is:



{ 'label', 'matrix', X, Y, Z, *method* }. X and Y are matrices specifying the points at which the data Z is given. The rows and columns of X and Y must be monotonic. *method* is an optional argument that specifies the interpolation method. Possible *method* strings are 'nearest', 'linear', or 'cubic'. The default is 'nearest'.

The 'vector' query uses the `interp2` function to find the value of the matrix Z at the input (x,y) point, then uses that value as an index to a data vector. The value of the data vector at that index is returned by the query. The format of `cellarray` for this type of query is: { 'label', 'vector', X, Y, Z, vector }. X and Y are matrices specifying the points at which the data Z is given. The rows and columns of X and Y must be monotonic. `vector` is the data vector.

The 'mapmatrix' query interpolates to find the value of the map at the input (lat,lon) point. The format of `cellarray` for this query is: { 'label', 'mapmatrix', datagrid, refvec, *method* }. `datagrid` and `refvec` are the data grid and the corresponding referencing vector. *method* is an optional argument that specifies the interpolation method. Possible *method* strings are 'nearest', 'linear', or 'cubic'. The default is 'nearest'.

The 'mapvector' query interpolates to find the value of the map at the input (lat,lon) point, then uses that value as an index to a data vector. The value of the vector at that index is returned by the query. The format of `cellarray` for this type of query is { 'label', 'mapvector', datagrid, refvec, vector }. `datagrid` and `refvec` are the data grid and the corresponding referencing vector. `vector` is the data vector.

User-defined query operations allow for functional operations using the input (x,y) or (lat,lon) coordinates. The format of `cellarray` for this type of query is { 'label', *function*, other arguments... } where the other arguments are the remaining elements of `cellarray` as in the four predefined operations above. *function* is a user-created function and must refer to a MATLAB function with the signature `z = fcn(x,y,other_arguments...)`.

`qrydata(...,cellarray1,cellarray2,...)` is used to input multiple cell arrays. This allows more than one data query to be performed on a given point.

## Controls



### Sample data query dialog box

If an axes handle `h` is not provided, or if the axes specified by `h` is not a map axes, the currently selected point is labeled as **Xloc** and **Yloc** at the top of the query dialog box. If `h` is a map axes, the current point is labeled as **Lat** and **Lon**. Displayed below the current point are the results from the queries, each labeled as specified by the 'label' input arguments.

The **Get** button appears if an axes handle `h` is provided. Pressing this button activates a mouse cursor, which is used to select the desired point by clicking the axes. Once a point is selected, the queries are performed and the results are displayed.

The **Process** button appears if the handle `h` is not provided. In this case, the  $(x,y)$  coordinates of the desired point are entered into the edit boxes. Pressing the **Process** button performs the data queries and displays the results.

Pressing the **Close** button closes the query dialog box.

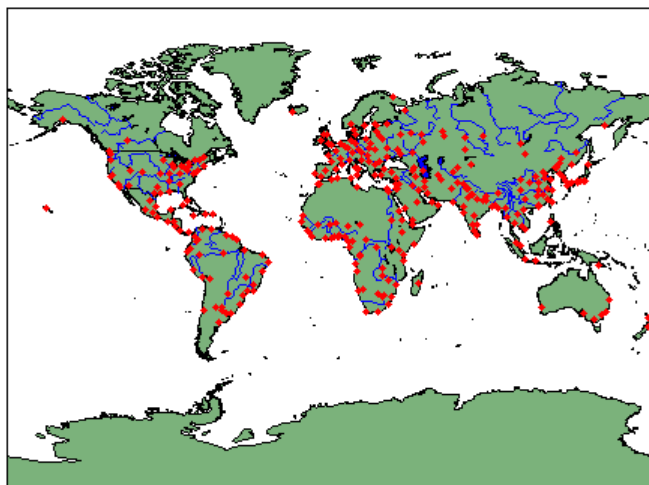
## Examples

This example illustrates use of a user-defined query to display city names for map points specified by a mouse click. The query is evaluated by a user-supplied file called `qrytest.m`, described below:

```
axesm miller
land = shaperead('landareas', 'UseGeoCoords', true);
geoshow(land, 'FaceColor', [0.5 0.7 0.5])
lakes = shaperead('worldlakes', 'UseGeoCoords', true);
geoshow(lakes, 'FaceColor', 'blue')
rivers = shaperead('worldrivers', 'UseGeoCoords', true);
geoshow(rivers, 'Color', 'blue')
cities = shaperead('worldcities', 'UseGeoCoords', true);
geoshow(cities, 'Marker', '.', 'Color', 'red')
tightmap
lat = [cities.Lat]';
lon = [cities.Lon]';
mat = char(cities.Name);
qrydata(gca, 'City Data', {'City', 'qrytest', lat, lon, mat})
```

Create the file `qrytest.m` on your path, and in it put the following code:

```
function cityname = qrytest(lt, lg, lat, lon, mat)
% function QRYTEST returns city name for mouse click
% QRYTEST will find the closest city (min radius) from
% the mouse click, within an angle of 5 degrees.
%
latdiff = lt-lat;
londiff = lg-lon;
rad = sqrt(latdiff.^2+londiff.^2);
[minrad,index] = min(rad);
if minrad > 5
    index = [];
end
switch length(index)
    case 0, cityname = 'No city located near click';
    case 1, cityname = mat(index,:);
end
```



Clicking the mouse over a city marker displays the name of the selected city. Clicking the mouse in an area away from any city markers displays the string 'No city located near click'.

## See Also

`interp2`

**Purpose** GUI to display small circles on map axes

---

**Note** scirclui is obsolete. Use scircleg instead.

---

**Activation**

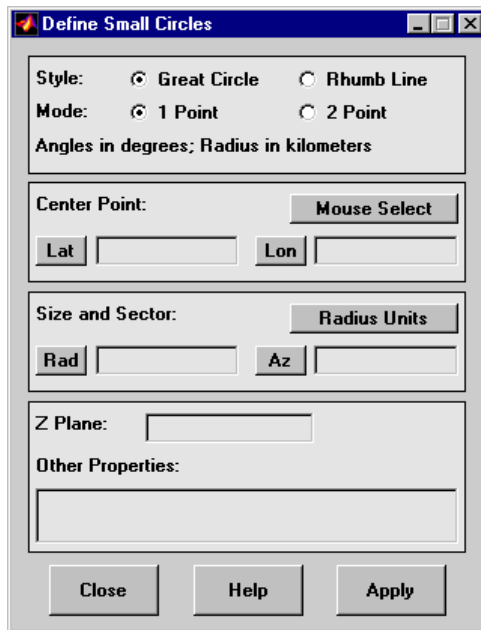
Command Line	Maptool
scirclui	Display mall Circles
scirclui(h)	

**Description**

scirclui activates the Define Small Circles dialog box for adding small circles to the current map axes.

scirclui(h) activates the Define Small Circles dialog box for adding small circles to the map axes specified by the axes handle h.

## Controls



### Define Small Circles dialog box for one-point mode

The **Style** selection buttons are used to specify whether the circle radius is a constant great circle distance or a constant rhumb line distance.

The **Mode** selection buttons are used to specify whether one point or two points are to be used in defining the small circle. If one-point mode is selected, a center point, radius, and azimuth are the required inputs. If two-point mode is selected, a center point, and perimeter point on the circle are the required inputs.

The **Center Point** controls are used in both one-point and two-point mode. The **Lat** and **Lon** edit boxes are used to enter the latitude and longitude of the center point of the small circle to be displayed. These values must be in degrees. To display more than one small circle, a vector of values can be entered, enclosed in brackets in each edit box. Pushing the **Lat** or **Lon** button brings up an expanded edit box for easier entry of long vectors. The **Mouse Select** button is used to select

a center point by clicking the displayed map. The coordinates of the selected point then appear in the **Lat** and **Lon** edit boxes and can be modified. The coordinates appear in degrees, regardless of the angle units defined for the current map projection.

The **Circle Point** controls are used only in two-point mode. The **Lat** and **Lon** edit boxes are used to enter the latitude and longitude of a point on the perimeter of the small circle to be displayed. These values must be in degrees. To display more than one small circle, a vector of values can be entered, enclosed in brackets in each edit box. Pushing the **Lat** or **Lon** button brings up an expanded edit box for easier entry of long vectors. The **Mouse Select** button is used to select a perimeter point by clicking the displayed map. The coordinates of the selected point then appear in the **Lat** and **Lon** edit boxes and can be modified. The coordinates appear in degrees, regardless of the angle units defined for the current map projection.

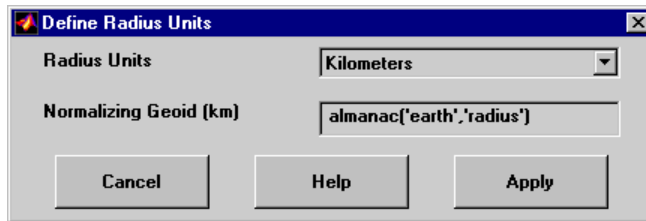
The **Size and Sector** controls are used only in one-point mode. The **Radius Units** button brings up a Define Radius Units dialog box, which allows for modification of the small circle radius units and the normalizing geoid. The **Rad** edit box is used to enter the radius of the small circle in the proper units. The **Arc** edit box is used to specify the sector azimuth, measured in degrees, clockwise from due north. If the entry is omitted, a complete small circle is drawn. When entering radius and arc data for more than one small circle, vectors of values, enclosed in brackets, are entered in each edit box. Pushing the **Rad** or **Arc** button brings up an expanded edit box for that entry, which is useful for entering long vectors.

The **Z Plane** edit box is used to enter a scalar value that specifies the plane in which to display the small circles.

The **Other Properties** edit box is used to specify additional properties of the small circles to be projected, such as 'Color', 'b'. String entries must be enclosed in quotes.

Pressing the **Apply** button accepts the input data and displays the small circles on the current map axes.

Pressing the **Cancel** button disregards any input data and closes the Define Small Circles dialog box.



### Define Radius Units Dialog Box

This dialog box, available only in one-point mode, allows for modification of the small circle radius units and the normalizing geoid.

The **Radius Units** pull-down menu is used to select the units of the small circle radius. The unit selected is displayed near the top of the Define Small Circles dialog box, and all latitude and longitude entries must be entered in these units. Users must also be sure to specify the normalizing geoid in the same units. If radians are selected, it is assumed the radius entry is a multiple of the radius used to display the current map, as defined by the map geoid property.

The **Normalizing Geoid** edit box is used to modify the radius used to normalize the small circle radius to a radian value, which is necessary for proper calculations and map display. This entry must be in the same units as the small circle radius. If the small circle radius units are in radians, then the normalizing geoid must be the same as the geoid used for the current map axes.

Pressing the **Cancel** button disregards any modifications and closes the Define Radius Units dialog box.

Pressing the **Apply** button accepts any modifications and returns to the Define Small Circles dialog box.

### See Also

scircle1, scircle2



**Purpose** GUI to fill data grids with seeded values

**Activation**

**Command Line**

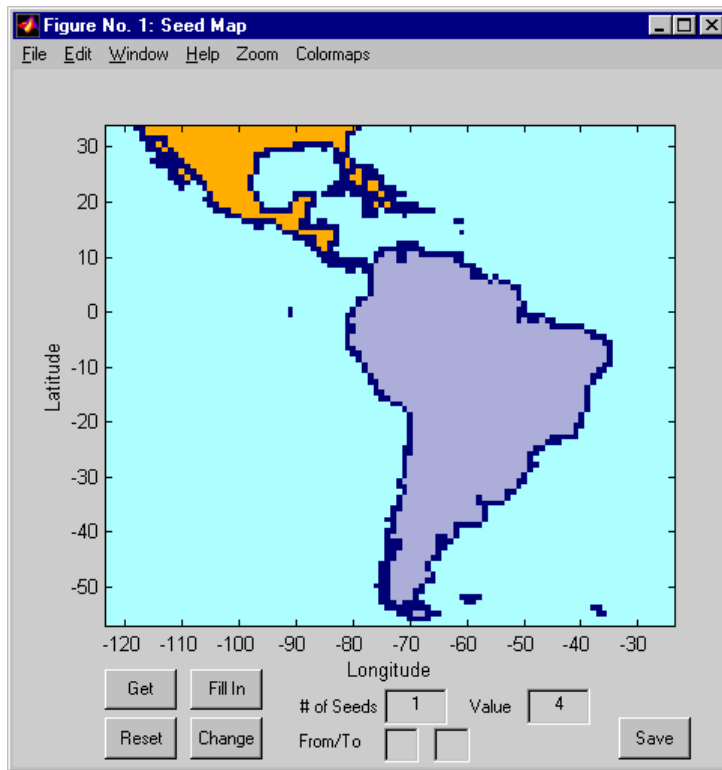
```
seedm(datagrid,refvec)
```

**Description**

Encoding is the process of filling in specific values in regions of a data grid up to specified boundaries, which are indicated by entries of 1 in the variable `map`. Encoding entire regions at one time allows indexed maps to be created quickly.

`seedm(datagrid,refvec)` displays the surface map in a new figure window and allows for seeds to be specified and the encoded map generated. The encoded map can then be saved to the workspace. `map` is the data grid and must consist of positive integer index values. `refvec` is the referencing vector of the surface.

## Controls



The **Zoom On/Off** menu toggles the zoom box on and off. The box can be moved by clicking the new location or by dragging the box to the new location. The box size can be increased or decreased by dragging a corner of the box. Pressing the **Return** key or double-clicking in the center of the box zooms in to the box limits.

The **Colormaps** menu provides a variety of colormap options that can be applied to the map. See `clrmenu` in this guide for a description of the **Colormaps** menu options.

The **Get** button allows mouse selection of points on the map to which seeds are assigned. The number of points to be selected is entered in the **# of Seeds** edit box. The value of the seed is entered in the **Value**

edit box. This seed value is assigned to each point selected with the mouse. The **Get** button is pressed to begin mouse selection. After all the points have been selected, the **Fill In** button is pressed to perform the encoding operation. The region containing the seed point is filled in with the seed value. The **Reset** button is used to disregard all points selected with the mouse before the **Fill In** button is pressed.

Alternatively, specific map values can be globally replaced by using the **From/To** edit boxes. The value to be replaced is entered in the first edit box, and the new value is entered in the second edit box. Pressing the **Change** button replaces all instances of the **From** value to the **To** value in the map.

---

**Note** Values of 1 represent boundaries and should not be changed.

---

The **Save** button is used to save the encoded map to the workspace. A dialog box appears in which the map variable name is entered.

## See Also

colorm, encodem, getseeds, maptrim

# showm-ui

---

**Purpose** Show specified mapped objects

**Activation**

Command Line	Maptool
showm	Tools > Show > Object

**Description**

showm brings up a Select Object dialog box for selecting mapped objects to show (Visible property set to 'on').

**Controls**



The scroll box is used to select the desired objects from the list of mapped objects. Pushing the **Select all** button highlights all objects in the scroll box for selection. Pushing the **OK** button changes the Visible property of the selected objects to 'on'. Pushing the **Cancel** button aborts the operation without changing any properties of the selected objects.

**See Also**

showm

**Purpose** Interactive distance, azimuth, and reckoning calculations

**Activation**

Command Line	Maptool
surfdist	Display > Surface > Distances
surfdist(h)	
surfdist([])	

**Description**

surfdist activates the Surface Distance dialog box for the current axes only if the axes has a proper map definition. Otherwise, the Surface Distance dialog box is activated, but is not associated with any axes.

surfdist(h) activates the Surface Distance dialog box for the axes specified by the handle h. The axes must be a map axes.

surfdist([]) activates the Surface Distance dialog box and does not associate it with any axes, regardless of whether the current axes has a valid map definition.

## Controls

Surface Distance

Style:  Great Circle  Rhumb Line

Mode:  1 Point  2 Point

Show Track

Angles in degrees; Range in kilometers

Starting Point:

Lat:  Lon:

Ending Point:

Lat:  Lon:

Direction:

Az:  Rng:

The **Style** selection buttons are used to specify whether a great circle or rhumb line is used to calculate the surface distance. When all other entries are provided, selecting a style updates the surface distance calculation.

The **Mode** selection buttons are used to specify whether one point or two points are to be used in defining the track distance. If one-point mode is selected, a starting point, azimuth, and range are the required inputs, and the ending point is computed. If two-point mode is selected, starting and ending points of the track are required, and the azimuth and distance along this track are then computed.

The **Show Track** check box is used to indicate whether the track is shown on the associated map display. The track is deleted when the Surface Distance dialog box is closed, or when the **Show Track** check box is unchecked and the surface distance calculations are recomputed.

The **Starting Point** controls are used for both one-point and two-point mode. The **Lat** and **Lon** edit boxes are used to enter the latitude and longitude of the starting point of the track. These values must be in degrees. Only one starting point can be entered. The **Mouse Select** button is used to select a starting point by clicking the displayed map. The coordinates of the selected point then appear in the **Lat** and **Lon** edit boxes and can be modified. The coordinates appear in degrees, regardless of the angle units defined for the current map projection.

The **Ending Point** controls are enabled only for two-point mode. The **Lat** and **Lon** edit boxes are used to enter the latitude and longitude of the ending point of the track. These values must be in degrees. Only one ending point can be entered. The **Mouse Select** button is used to select an ending point by clicking the displayed map. The coordinates of the selected point then appear in the **Lat** and **Lon** edit boxes and can be modified. The coordinates appear in degrees, regardless of the angle units defined for the current map projection. During one-point mode, the Ending Point controls are disabled, but the ending point that results from the surface distance calculation is displayed.

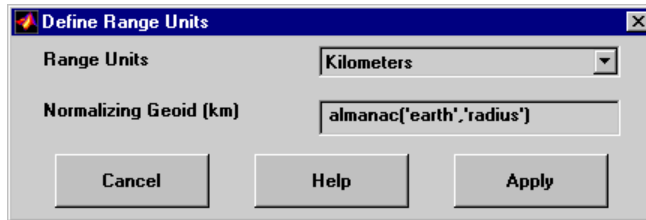
The **Direction** controls are enabled only for one-point mode. The **Range Units** button brings up a Define Range Units dialog box which allows for modification of the range units and the normalizing geoid. The **Az** edit box is used to enter the azimuth, which sets the initial direction of the track from the starting point. Azimuth is measured in degrees clockwise from due north. The **Rng** edit box is used to specify the reckoning range of the track, in the proper units. The azimuth and reckoning range, along with the starting point, are used to compute the ending point of the track in one-point mode. During two-point mode, the **Direction** controls are disabled, but the azimuth and range values resulting from the surface distance calculation are displayed.

Pressing the **Close** button disregards any input data, deletes any surface distance tracks that have been plotted, and closes the Surface Distance dialog box.

Pressing the **Compute** button accepts the input data and computes the specified distances.

## Define Range Units Dialog Box

This dialog box, available only for one-point mode, allows for modification of the range units and the normalizing geoid.



The **Range Units** pull-down menu is used to select the units of the reckoning range. The unit selected is displayed near the top of the Surface Distance dialog box, and all latitude and longitude entries must be entered in these units. Users must also be sure to specify the normalizing geoid in the same units. If radians are selected, it is assumed the range entry is a multiple of the radius of the normalizing geoid. In this case, the normalizing geoid must be the same as the geoid used to display the current map.

The **Normalizing Geoid** edit box is used to modify the radius used to normalize range entries to radian values, which is necessary for proper calculations and map display. This entry must be in the same units as the range units. If the range units are in radians, then the normalizing geoid must be the same as the geoid used for the current map axes.

Pressing the **Cancel** button disregards any modifications and closes the Define Range Units dialog box.

Pressing the **Apply** button accepts any modifications and returns to the Surface Distance dialog box.



**Purpose** GUI to edit tag property of mapped object

**Activation****Command Line**

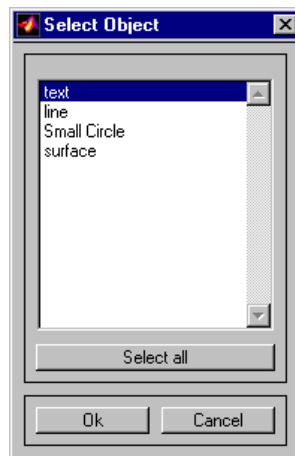
tagm

tagm(h)

**Description**

tagm brings up a Select Object dialog box for selecting mapped objects and changing their Tag property. Upon selecting the objects, the Edit Tag dialog box is activated, in which the new tag is entered.

tagm(h) activates the Edit Tag dialog box for the objects specified by the handle h.

**Controls****Select Object Dialog Box**

The scroll box is used to select the desired objects from the list of mapped objects. Pushing the **Select all** button highlights all objects in the scroll box for selection. Pushing the **Ok** button activates the Edit Tag dialog box. Pushing the **Cancel** button aborts the operation without changing any properties of the selected objects.



## **Edit Tag Dialog Box**

The new tag string is entered in the edit box. Pressing the **Apply** button changes the Tag property of all selected objects to the new tag string. Pressing the **Cancel** button closes the Edit Tag dialog box without changing the Tag property of the selected objects.

## **See Also**

tagm

**Purpose** GUI to display great circles and rhumb lines on map axes

---

**Note** trackui is obsolete. Use trackg instead.

---

**Activation**

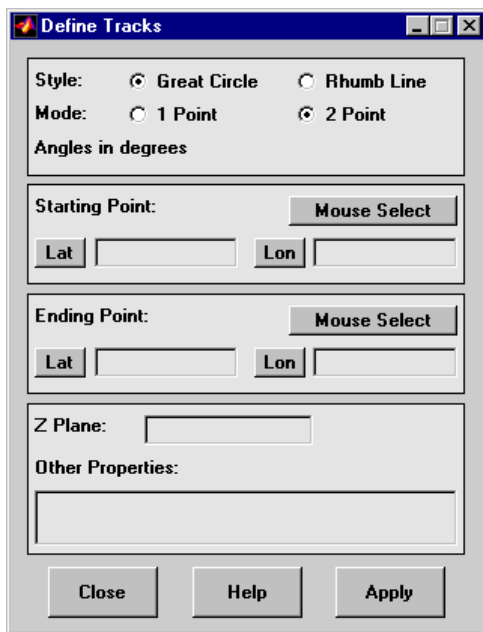
Command Line	Maptool
trackui	Display > Tracks
trackui(h)	

**Description**

trackui activates the Define Tracks dialog box for adding great circle or rhumb line tracks to the current map axes.

trackui(h) activates the Define Tracks dialog box for adding great circle or rhumb line tracks to the map axes specified by the axes handle h.

## Controls



### Define Tracks dialog box for two-point mode

The **Style** selection buttons are used to specify whether a great circle or rhumb line track is displayed.

The **Mode** selection buttons are used to specify whether one point or two points are to be used in defining the track. If one-point mode is selected, a starting point, azimuth, and range are the required inputs. If two-point mode is selected, starting and ending points are required.

The **Starting Point** controls are used for both one-point and two-point mode. The **Lat** and **Lon** edit boxes are used to enter the latitude and longitude of the starting point of the track to be displayed. These values must be in degrees. To display more than one track, a vector of values can be entered, enclosed in brackets in each edit box. Pushing the **Lat** or **Lon** button brings up an expanded edit box for easier entry of long vectors. The **Mouse Select** button is used to select a starting point by clicking the displayed map. The coordinates of the selected point

then appear in the **Lat** and **Lon** edit boxes and can be modified. The coordinates appear in degrees, regardless of the angle units defined for the current map projection.

The **Ending Point** controls are used only for two-point mode. The **Lat** and **Lon** edit boxes are used to enter the latitude and longitude of the ending point of the track to be displayed. These values must be in degrees. To display more than one track, a vector of values can be entered, enclosed in brackets, in each edit box. Pushing the **Lat** or **Lon** button brings up an expanded edit box for easier entry of long vectors. The **Mouse Select** button is used to select an ending point by clicking the displayed map. The coordinates of the selected point then appear in the **Lat** and **Lon** edit boxes and can be modified. The coordinates appear in degrees, regardless of the angle units defined for the current map projection.

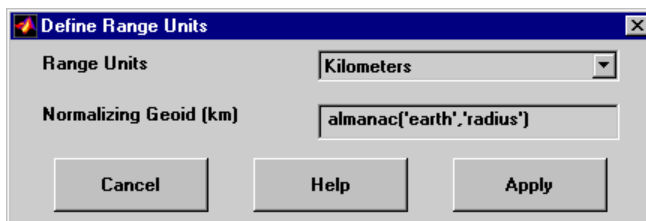
The **Direction** controls are used only for one-point mode. The **Range Units** button brings up a Define Range Units dialog box, which allows for modification of the range units and the normalizing geoid. The **Az** edit box is used to enter the azimuth, which sets the initial direction of the track from the starting point. Azimuth is measured in degrees clockwise from due north. The **Rng** edit box is used to specify the range of the track, in the proper units. If the range entry is omitted, a complete track is drawn. When inputting azimuth and range data for more than one track, vectors of values, enclosed in brackets, are entered in each edit box. Pushing the **Az** or **Rng** button brings up an expanded edit box for that entry, which is useful for entering long vectors.

The **Z Plane** edit box is used to enter a scalar value that specifies the plane in which to display the tracks.

The **Other Properties** edit box is used to specify additional properties of the tracks to be projected, such as 'Color', 'b'. String entries must be enclosed in quotes.

Pressing the **Apply** button accepts the input data and displays the tracks on the current map axes.

Pressing the **Cancel** button disregards any input data and closes the Define Tracks dialog box.



## Define Range Units Dialog Box

This dialog box, available only for one-point mode, allows for modification of the range units and the normalizing geoid.

The **Range Units** pull-down menu is used to select the units of the track range. The unit selected is displayed near the top of the Define Tracks dialog box, and all latitude and longitude entries must be entered in these units. Users must also be sure to specify the normalizing geoid in the same units. If radians are selected, it is assumed the range entry is a multiple of the radius used to display the current map.

The **Normalizing Geoid** edit box is used to modify the radius used to normalize range entries to radian values, which is necessary for proper calculations and map display. This entry must be in the same units as the range units. If the range units are in radians, then the normalizing geoid must be the same as the geoid used for the current map axes.

Pressing the **Cancel** button disregards any modifications and closes the Define Range Units dialog box.

Pressing the **Apply** button accepts any modifications and returns to the Define Tracks dialog box.

## See Also

track1, track2



# utmzoneui

---

**Purpose** Choose or identify UTM zone by clicking map

**Activation**

Command Line
utmzoneui
utmzoneui(InitZone)

**Description**

zone = utmzoneui will create an interface for choosing a UTM zone on a world display map. It allows for clicking an area for its appropriate zone, or entering a valid zone to identify the zone on the map.

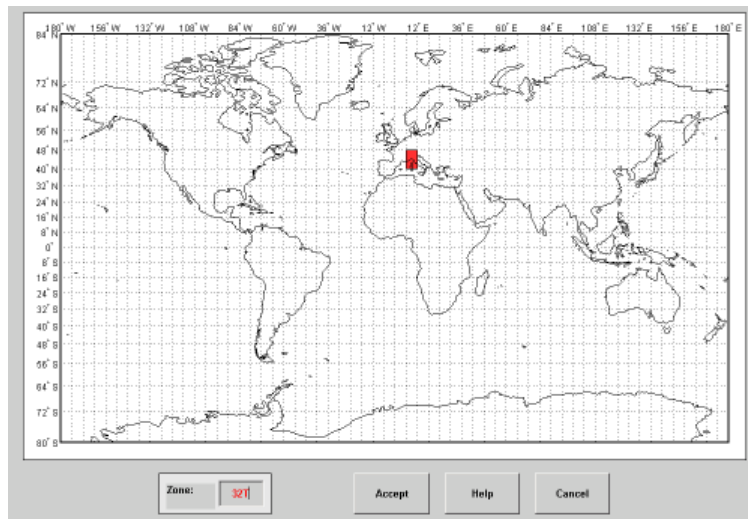
zone = utmzoneui(InitZone) will initialize the displayed zone to the zone string given in InitZone.

To interactively pick a UTM zone, activate the interface, and then click any rectangular zone on the world map to display its UTM zone. The selected zone is highlighted in red and its designation is displayed in the **Zone** edit field. Alternatively, type a valid UTM designation in the **Zone** edit field to select and see the location of a zone. Valid zone designations consist of an integer from 1 to 60 followed by a letter from C to X.

Typing only the numeric portion of a zone designation will highlight a column of cells. Clicking **Accept** returns a that UTM column designation. You cannot return a letter (row designation) in such a manner, however.



## Controls



## Remarks

The syntax of `utmzoneui` is similar to that of `utmzone`. If `utmzone` is called with no arguments, the `utmzoneui` interface is displayed for you to select a zone. Note that `utmzone` can return latitude-longitude coordinates of a specified zone, but that `utmzoneui` only returns zone names.

## See Also

<code>ups</code>	Universal Polar Stereographic (UPS) Projection.
<code>utm</code>	Universal Transverse Mercator (UTM) Projection.
<code>utmgeoid</code>	Select ellipsoid for a given UTM zone.
<code>utmzone</code>	Select a UTM zone.

# vmap0ui

---

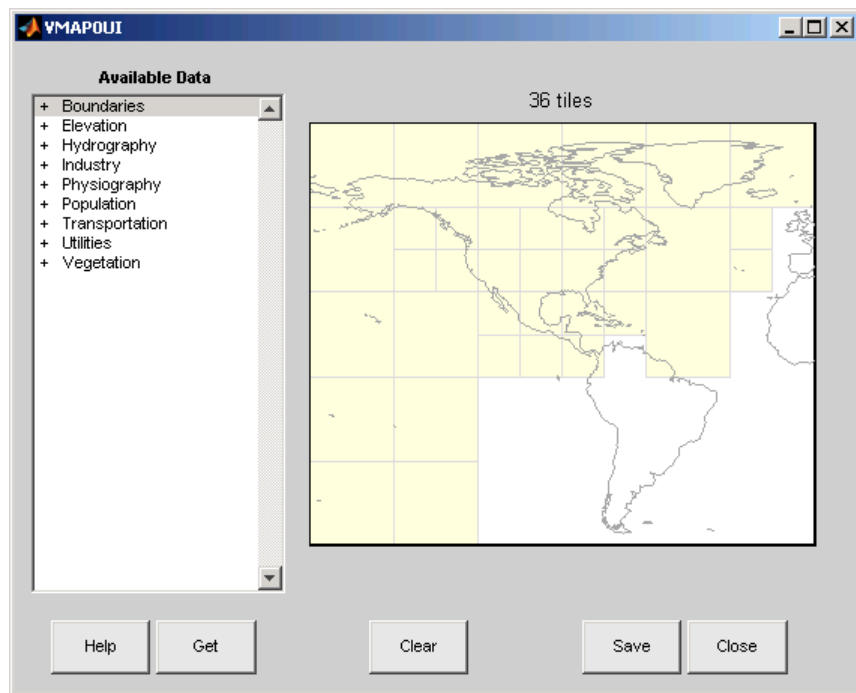
**Purpose** UI for selecting data from Vector Map Level 0

**Description** `vmap0ui(dirname)` launches a graphical user interface for interactively selecting and importing data from a Vector Map Level 0 (VMAPO) data base. Use the string `dirname` to specify the directory containing the data base. For more on using `vmap0ui`, click the **Help** button after the interface appears.

`vmap0ui(devicename)` or `vmap0ui devicename` uses the logical device (volume) name specified in string `devicename` to locate CD-ROM drive containing the VMAPO CD-ROM. Under the Windows operating system it could be 'F:', 'G:', or some other letter. Under Macintosh OS X it should be '/Volumes/VMAP'. Under other UNIX systems it could be '/cdrom/'.

`vmap0ui` can be used on Windows without any arguments. In this case it attempts to automatically detect a drive containing a VMAPO CD-ROM. If `vmap0ui` fails to locate the CD-ROM device, then specify it explicitly.

## Controls



The vmap0ui screen lets you read data from the Vector Map Level 0 (VMAP0). The VMAP0 is the most detailed world map database available to the public.

You use the list to select the type of data and the map to select the region of interest. When you click the **Get** button, data is extracted and displayed on the map. Use the **Save** button to save the data in a MAT-file or to the base workspace for later display. The **Close** button closes the window.

### The Map

The **Map** controls the geographic extent of the data to be extracted. vmap0ui extracts data for areas currently visible on the map. Use the mouse to zoom in or out to the area of interest. Type `help zoom` for more on zooming.

The VMAP0 divides the world into tiles of about 5-by-5 degrees. When extracting, data is returned for all visible tiles, including those parts of the tile that are outside the current view. The map shows the VMAP0 tiles in light yellow with light gray edges. The data density is high, so extracting data for a large number of tiles can take much time and memory. A count of the number of visible tiles is above the map.

## The List

The **List** controls the type of data to be extracted. The tree structure of the list reflects the structure of the VMAP0 database. Upon starting vmap0ui, the list shows the major categories of VMAP data, called themes. Themes are subdivided into features, which consist of data of common graphic types (patch, line, point, or text) or cultural types (airport, roads, railroads). Double-click a theme to see the associated features. Features can have properties and values, for example, a railroad tracks property, with values single or multiple. Double-click a feature to see the associated properties and values. Double-clicking an open theme or feature closes it. When a theme is selected, vmap0ui gets all the associated features. When a feature is selected, vmap0ui gets all of that feature's data. When properties and values are selected, vmap0ui gets the data for any of the properties and values that match (that is, the union operation).

## The Get Button

The **Get** button reads the currently selected VMAP0 data and displays it on the map. Use the **Cancel** button on the progress bar to interrupt the process. For a quicker response, press the standard interrupt key combination for your platform.

## The Clear Button

The **Clear** button removes any previously read data from the map.

## The Save Button

The **Save** button saves the currently displayed VMAP0 data to a MAT-file or the base workspace. If you choose to save to a file, you are prompted for a filename and location. If you choose to save to the

base workspace, you are notified of the variable names that will be overwritten.

Data are returned as Mapping Toolbox display structures with variable names based on theme and feature names. You can update vector display structures to geographic data structures. For information about display structure format, see “Version 1 Display Structures” on page 3-144 in the reference page for `displaym`. The `updategeostruct` function performs such conversions.

Use `load` and `displaym` to redisplay the data from a file on a map axes. You can also use the `mlayers` GUI to read and display the data from a file. To display the data in the base workspace, use `displaym`. To display all the display structures, use `rootlayr; displaym(ans)`. To display all of the display structures using the `mlayers` GUI, type `rootlayr; mlayers(ans)`.

### The Close Button

The **Close** button closes the `vmap0ui` panel.

## Examples

- 1 Launch `vmap0ui` and automatically detect a CD-ROM on Microsoft Windows:

```
vmap0ui
```

- 2 Launch `vmap0ui` on Macintosh OS X (need to specify volume name):

```
vmap0ui('Volumes/VMAP')
```

## See also

`displaym`, `extractm`, `mlayers`, `vmap0data`

# zdatam-ui

---

**Purpose** GUI to adjust  $z$ -plane of mapped objects

## Activation

Command Line
zdatam
zdatam( <i>h</i> )
zdatam( <i>str</i> )

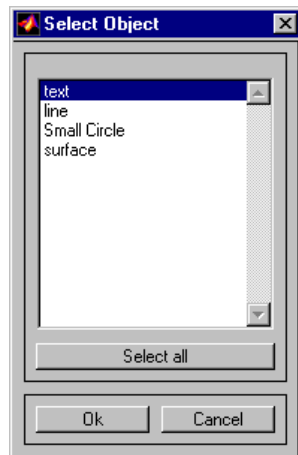
## Description

zdatam brings up a Select Object dialog box for selecting mapped objects and adjusting their ZData property. Upon selecting the objects, the Specify Zdata dialog box is activated, in which the new ZData variable is entered. Note that not all mapped objects have the ZData property (for example text objects).

zdatam(*h*) activates the Specify Zdata dialog box for the objects specified by the handle *h*.

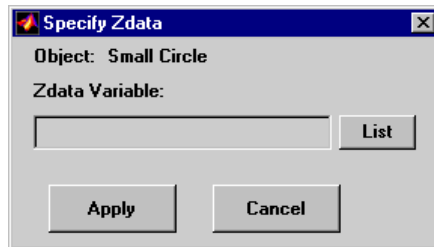
zdatam(*str*) activates the Specify Zdata dialog box for the objects identified by *str*, where *str* is any string recognized by handlem.

## Controls



**Select Object Dialog Box**

The scroll box is used to select the desired objects from the list of mapped objects. Pushing the **Select all** button highlights all objects in the scroll box for selection. Pushing the **OK** button activates another Specify Zdata dialog box. Pushing the **Cancel** button aborts the operation without changing any properties of the selected objects.



### Specify ZData Dialog Box

The **Zdata Variable** edit box is used to specify the name of the ZData variable. Pressing the **List** button produces a list of all current workspace variables, from which the ZData variable can be selected. A scalar value or a valid MATLAB expression can also be entered. Pressing the **Apply** button changes the ZData property of all selected objected to the new values. Pressing the **Cancel** button closes the Specify ZData dialog box without changing the ZData property of the selected objects.

### See Also

zdatam





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